

Outdoor Scene Classification based on CNN

Project guide

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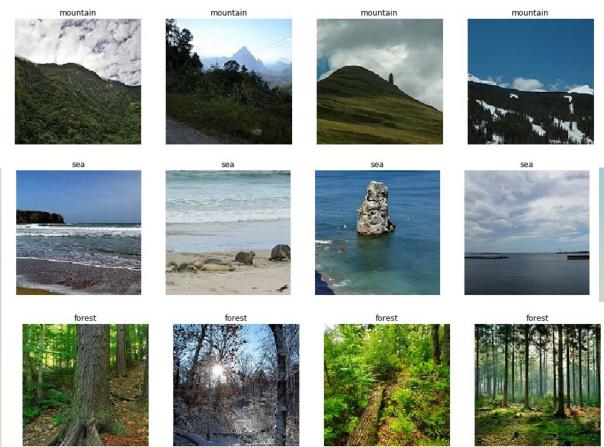


Motivation

- Classification is very important as we use it in daily life.
 It makes things easier to find and recognise.
 Differentiation of objects is what allows us to classify them into groups.
- Image Classification is one of the core problems in Computer Vision that, despite its simplicity, has a large variety of practical applications.
- Moreover, as we can see, many other seemingly distinct Computer Vision tasks (such as object detection, segmentation) can be reduced to image classification.



Image dataset





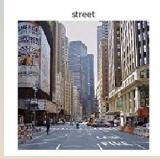


















Dataset:

This Data contains around 25k images of size 150x150 distributed under 6 categories. {'buildings' -> 0, 'forest' -> 1, 'glacier' -> 2, 'mountain' -> 3, 'sea' -> 4, 'street' -> 5 }

The Train, Test and Prediction data is separated in each zip files. There are around 14k images in Train, 3k in Test and 7k in Prediction.

Preprocessing:

Resize all the input images to 150x150

Requirements

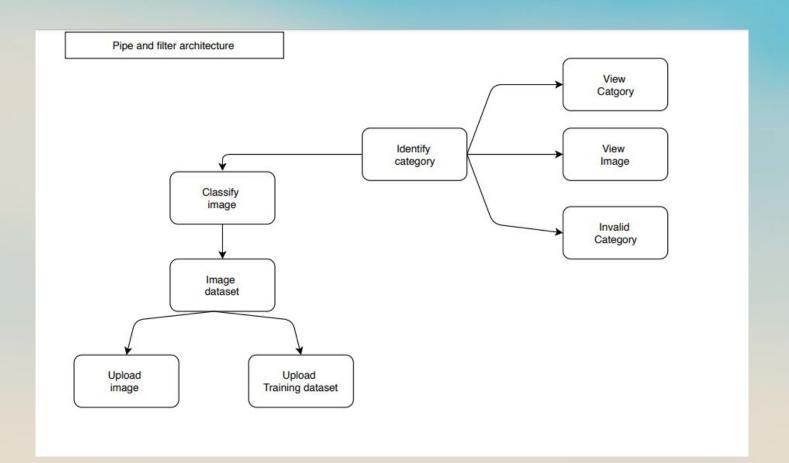
- A. Functional Requirements
 - User level
 - User shall be able to view images.
 - User shall be able to see the category under which it belongs to.

- System level
 - System shall be able to store data.
 - System shall be able to extract features.
 - System shall be able to resize the images.
 - System shall be able to categorise the images.

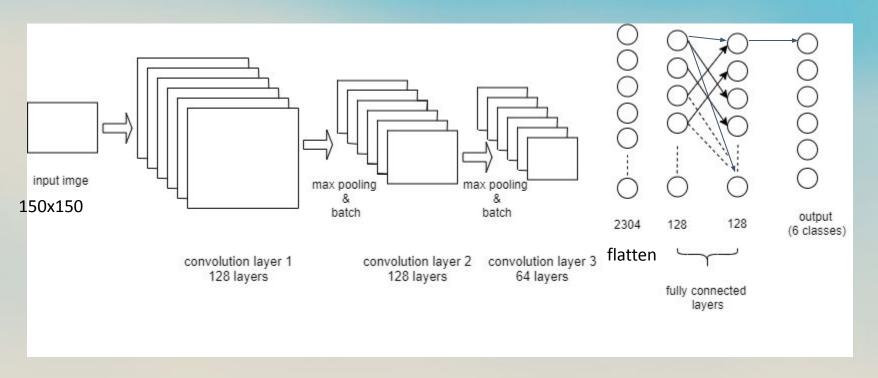
Non-Functional Requirements

- Ease of use
- The system should be able to expand for further storing.
- The system should be compatible with any browser on any environment.
- The system should be able to perform a failure-free operation for a specified period of time in a specified environment.

Architecture



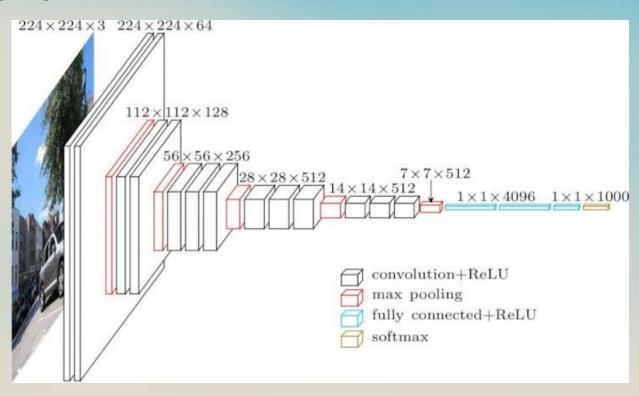
Convolutional Neural Network



Output visualisations

| conv2d_1 (Conv2D) | (None, | 148, 148, 128) | 3584 |
|------------------------------|--------|----------------|--------|
| max_pooling2d_1 (MaxPooling2 | (None, | 74, 74, 128) | 0 |
| batch_normalization_1 (Batch | (None, | 74, 74, 128) | 512 |
| conv2d_2 (Conv2D) | (None, | 72, 72, 128) | 147584 |
| max_pooling2d_2 (MaxPooling2 | (None, | 36, 36, 128) | 0 |
| batch_normalization_2 (Batch | (None, | 36, 36, 128) | 512 |
| conv2d_3 (Conv2D) | (None, | 34, 34, 64) | 73792 |
| max_pooling2d_3 (MaxPooling2 | (None, | 6, 6, 64) | 0 |
| flatten_1 (Flatten) | (None, | 2304) | 0 |
| dense_1 (Dense) | (None, | 128) | 295040 |

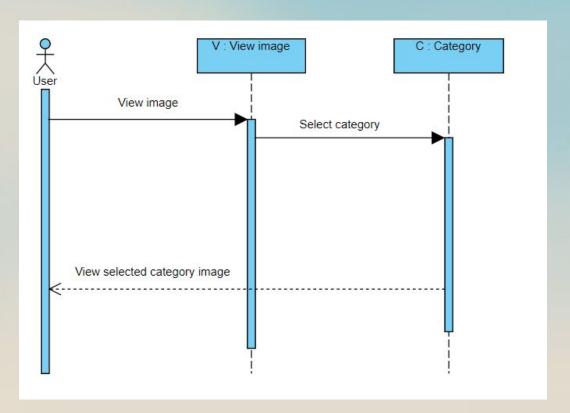
VGG16



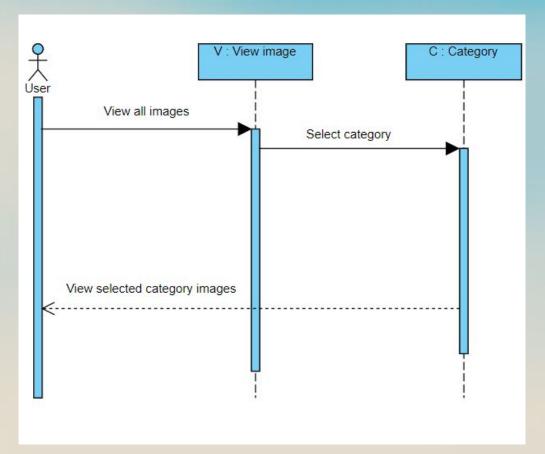
| Layer (type) | Output Shape | Param # |
|---------------------|-------------------|----------|
| vgg16 (Model) | (None, 4, 4, 512) | 14714688 |
| flatten_1 (Flatten) | (None, 8192) | 0 |
| dense_1 (Dense) | (None, 180) | 1474740 |
| dense_2 (Dense) | (None, 100) | 18100 |
| dense_3 (Dense) | (None, 50) | 5050 |
| dropout_1 (Dropout) | (None, 50) | 0 |
| dense_4 (Dense) | (None, 6) | 306 |

Sequence Diagram

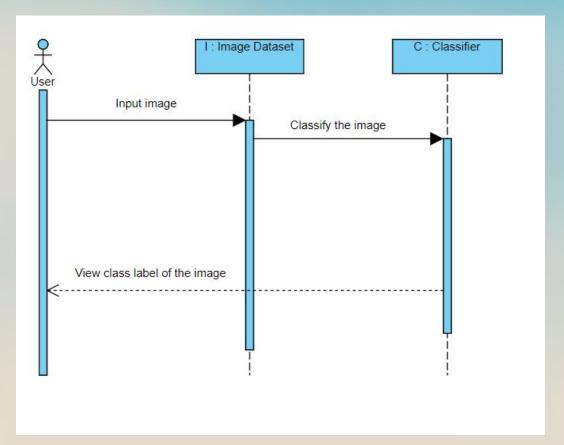
Sequence diagram for view image



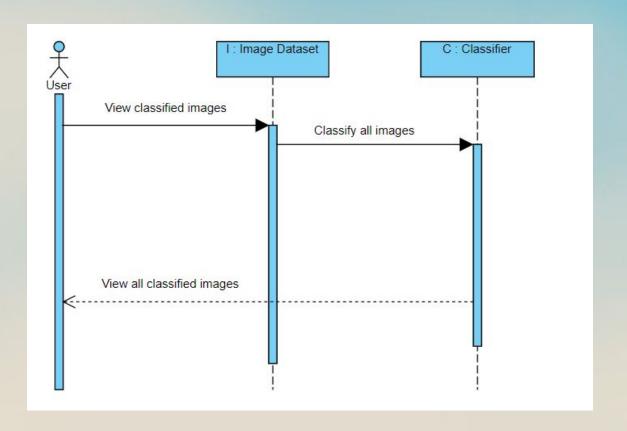
Sequence diagram to view all images.



Sequence diagram to categorize the image.



Sequence diagram for classify all images.



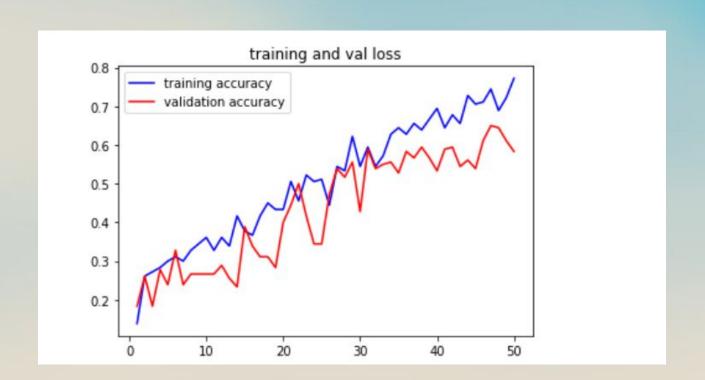
Status of implementation

CNN using 180 sample dataset

```
Epoch 11/20
18/18 [==========] - 5s 259ms/step - loss: 1.1254 - accuracy: 0.5722 - val loss: 1.5289 - val accuracy: 0.5
Epoch 12/20
111
Epoch 13/20
18/18 [==========] - 5s 257ms/step - loss: 1.0669 - accuracy: 0.5944 - val loss: 1.0264 - val accuracy: 0.5
833
Epoch 14/20
18/18 [==========] - 4s 246ms/step - loss: 0.9645 - accuracy: 0.6278 - val loss: 1.6021 - val accuracy: 0.5
611
Epoch 15/20
278
Epoch 16/20
18/18 [==========] - 4s 243ms/step - loss: 1.0602 - accuracy: 0.6278 - val loss: 1.5115 - val accuracy: 0.5
833
Epoch 17/20
18/18 [==========] - 4s 239ms/step - loss: 0.8839 - accuracy: 0.6778 - val loss: 1.5035 - val accuracy: 0.5
889
Epoch 18/20
833
Epoch 19/20
18/18 [=========] - 4s 245ms/step - loss: 0.9635 - accuracy: 0.6556 - val loss: 1.1756 - val accuracy: 0.5
056
Epoch 20/20
18/18 [==========] - 4s 240ms/step - loss: 0.8739 - accuracy: 0.6500 - val loss: 0.8842 - val accuracy: 0.5
111
```

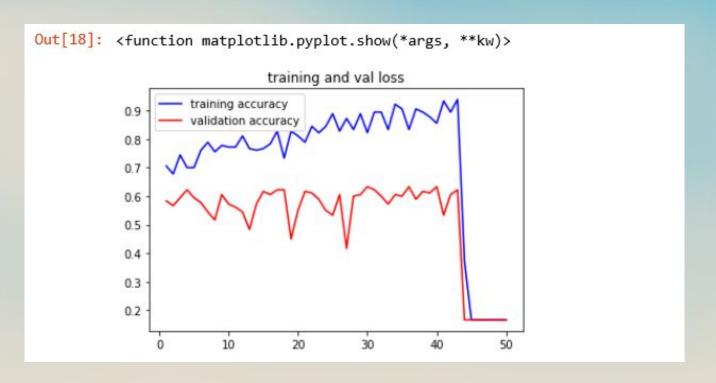
| Layer (type) | Output | Shape | Param # |
|---|--------|---------------|---------|
| conv2d_4 (Conv2D) | (None, | 148, 148, 32) | 896 |
| activation_6 (Activation) | (None, | 148, 148, 32) | 0 |
| max_pooling2d_4 (MaxPooling2 | (None, | 74, 74, 32) | 0 |
| conv2d_5 (Conv2D) | (None, | 72, 72, 32) | 9248 |
| activation_7 (Activation) | (None, | 72, 72, 32) | 0 |
| max_pooling2d_5 (MaxPooling2 | (None, | 36, 36, 32) | 0 |
| conv2d_6 (Conv2D) | (None, | 34, 34, 64) | 18496 |
| activation_8 (Activation) | (None, | 34, 34, 64) | 0 |
| max_pooling2d_6 (MaxPooling2 | (None, | 17, 17, 64) | 0 |
| flatten_2 (Flatten) | (None, | 18496) | 0 |
| dense_3 (Dense) | (None, | 64) | 1183808 |
| activation_9 (Activation) | (None, | 64) | 0 |
| dropout_2 (Dropout) | (None, | 64) | 0 |
| dense_4 (Dense) | (None, | 6) | 390 |
| activation_10 (Activation) | (None, | | 0 |
| Total params: 1,212,838 Trainable params: 1,212,838 | | | |

```
0.5611
Epoch 45/50
18/18 [=========== ] - 5s 269ms/step - loss: 0.7973 - accuracy: 0.7056 - val loss: 0.9434 - val accuracy:
0.5389
Epoch 46/50
18/18 [=========== ] - 5s 271ms/step - loss: 0.7712 - accuracy: 0.7111 - val loss: 1.5107 - val accuracy:
0.6111
Epoch 47/50
18/18 [============ - - 5s 287ms/step - loss: 0.7185 - accuracy: 0.7444 - val loss: 2.0767 - val accuracy:
0.6500
Epoch 48/50
18/18 [=========== ] - 5s 286ms/step - loss: 0.9956 - accuracy: 0.6889 - val loss: 1.2893 - val accuracy:
0.6444
Epoch 49/50
18/18 [========== - - 5s 299ms/step - loss: 0.8007 - accuracy: 0.7222 - val loss: 1.3065 - val accuracy:
0.6111
Epoch 50/50
18/18 [============ - - 5s 300ms/step - loss: 0.6717 - accuracy: 0.7722 - val loss: 2.8436 - val accuracy:
0.5833
```

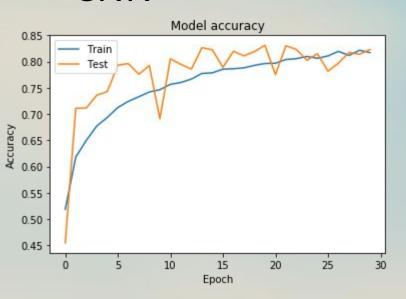


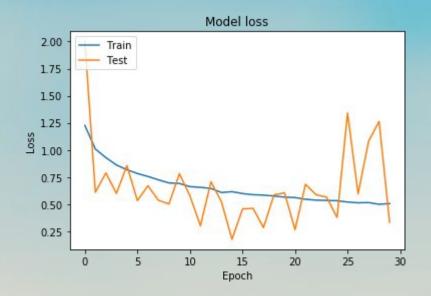
| wodet:edneut191_p | | | |
|------------------------------|--------|---------------|---------|
| Layer (type) | Output | | Param # |
| conv2d_18 (Conv2D) | | 148, 148, 32) | 896 |
| activation_28 (Activation) | (None, | 148, 148, 32) | 0 |
| max_pooling2d_18 (MaxPooling | (None, | 74, 74, 32) | 0 |
| conv2d_19 (Conv2D) | (None, | 72, 72, 32) | 9248 |
| activation_29 (Activation) | (None, | 72, 72, 32) | 0 |
| max_pooling2d_19 (MaxPooling | (None, | 36, 36, 32) | 0 |
| conv2d_20 (Conv2D) | (None, | 34, 34, 64) | 18496 |
| activation_30 (Activation) | (None, | 34, 34, 64) | 0 |
| max_pooling2d_20 (MaxPooling | (None, | 17, 17, 64) | 0 |
| conv2d_21 (Conv2D) | (None, | 15, 15, 128) | 73856 |
| activation_31 (Activation) | (None, | 15, 15, 128) | 0 |
| max_pooling2d_21 (MaxPooling | (None, | 7, 7, 128) | 0 |
| conv2d_22 (Conv2D) | (None, | 5, 5, 256) | 295168 |
| activation_32 (Activation) | (None, | 5, 5, 256) | 0 |
| max_pooling2d_22 (MaxPooling | (None, | 2, 2, 256) | 0 |
| flatten_6 (Flatten) | (None, | 1024) | 0 |
| dense_11 (Dense) | (None, | 64) | 65600 |
| activation_33 (Activation) | (None, | 64) | 0 |
| dropout_6 (Dropout) | (None, | 64) | 0 |
| dense_12 (Dense) | (None, | 6) | 390 |
| activation_34 (Activation) | (None, | | 0 |

Overfitting



Results CNN



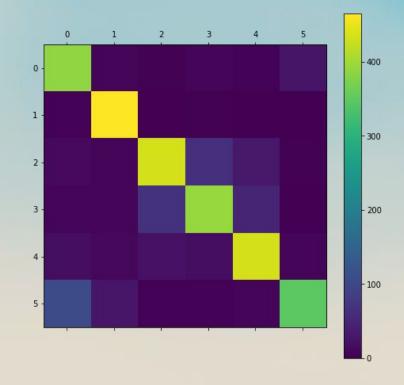


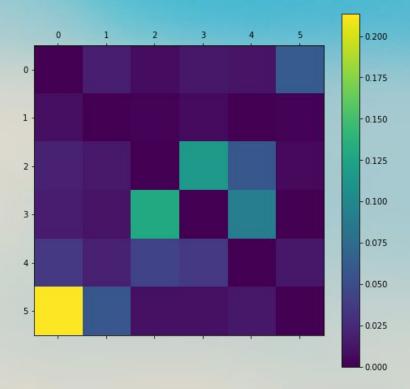
The model does not seem to overfit, it has a better accuracy on the validation set

```
437/437 [============ ] - 789s 2s/step - loss: 0.5440 - accuracy: 0.8040 - val loss: 0.6835 - val accuracy: 0.
8302
Epoch 23/30
437/437 [===========] - 790s 2s/step - loss: 0.5364 - accuracy: 0.8056 - val loss: 0.5863 - val accuracy: 0.
8231
Epoch 24/30
437/437 [============ ] - 786s 2s/step - loss: 0.5344 - accuracy: 0.8098 - val loss: 0.5648 - val accuracy: 0.
8026
Epoch 25/30
437/437 [============ ] - 794s 2s/step - loss: 0.5318 - accuracy: 0.8063 - val loss: 0.3771 - val accuracy: 0.
8150
Epoch 26/30
437/437 [============= ] - 789s 2s/step - loss: 0.5188 - accuracy: 0.8108 - val loss: 1.3408 - val accuracy: 0.
7817
Epoch 27/30
437/437 [===========] - 785s 2s/step - loss: 0.5123 - accuracy: 0.8195 - val loss: 0.5945 - val accuracy: 0.
7972
Epoch 28/30
437/437 [============ - 789s 2s/step - loss: 0.5140 - accuracy: 0.8118 - val loss: 1.0801 - val accuracy: 0.
8174
Epoch 29/30
8140
Epoch 30/30
8231
```

The confusion matrix will show us the most frequent mistakes made by this classifier

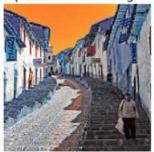
| | В | F | G | M | S | St | |
|---------|-------------|----------|---------|---------|----------|----------|---|
| В | [[388 | 8 | 3 | 6 | 5 | 27 |] |
| F | [4 | 465 | 1 | 3 | 0 | 1 |] |
| G | [11 | 8 | 435 | 64 | 32 | 3 |] |
| M | [9 | 6 | 68 | 394 | 48 | 0 |] |
| S St | [18 [107 | 10 29 | 22 5 | 18 5 | 435 7 | 7 348 |] |



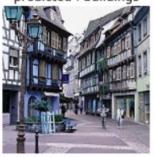


This matrix shows us that the most common confusions are between **streets and buildings**, there are also confusions between **glaciers and mountains**.

predicted : buildings



predicted : buildings



predicted : buildings



predicted : buildings



predicted : buildings

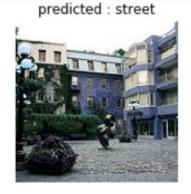


Images of streets classified as buildings

Let's look at some badly classified images

#Images of buildings classified as streets

errors(y_pred,0,5,10)











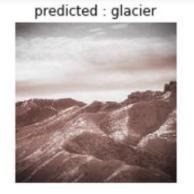
Images of buildings classified as streets

#Images of mountains classified as glaciers
errors(y_pred,3,2,10)







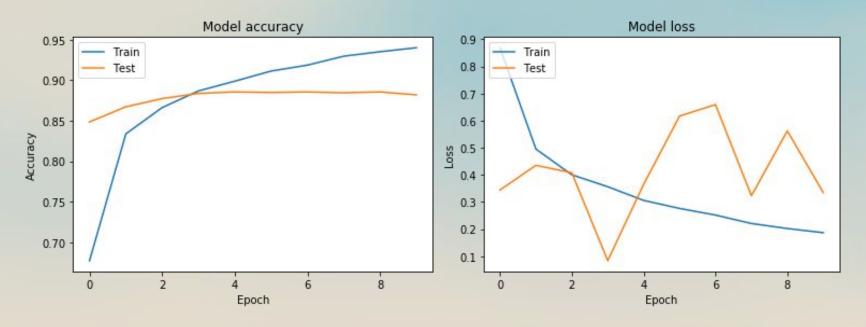




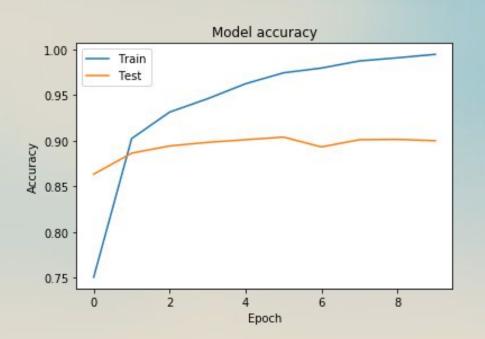
Images of mountains classified as glaciers

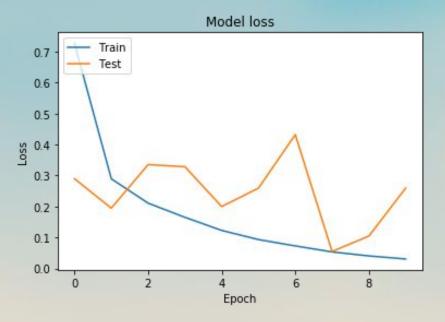
Transfer learning (VGG16)

<u>Training:</u>



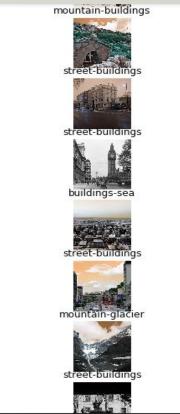
Testing





Accuracy:91%

269 wrongly predicted output.

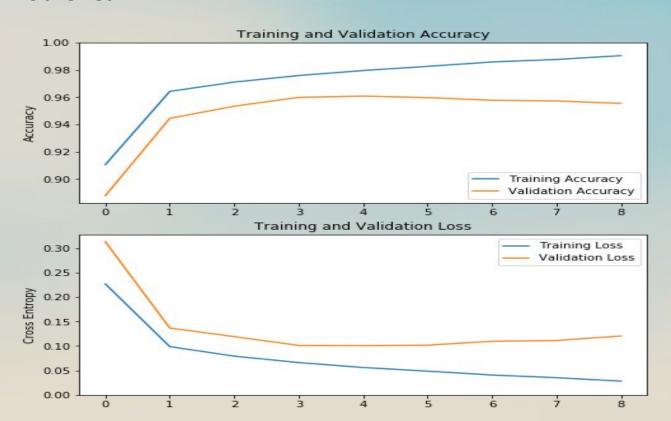








MobileNet



Conclusion

In this project, we have used different classification models for classifying images into their respective categories. But, in the final classification, a few of the images were misclassified. Therefore, in order to improve the accuracy of classification, it is necessary to include additional knowledge about discarding the image.

In future work, it would be interesting to include additional feature information.

References

