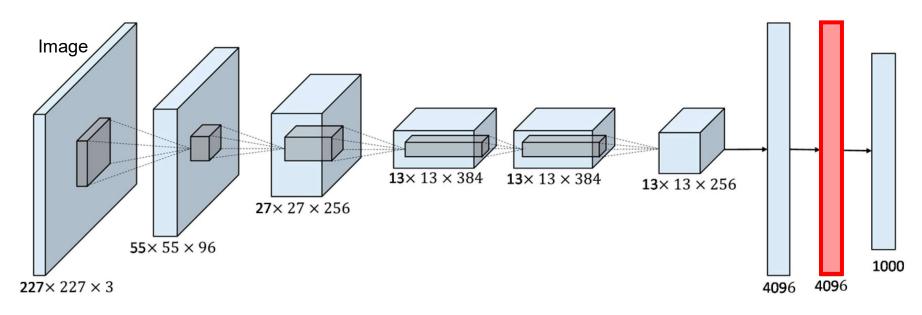
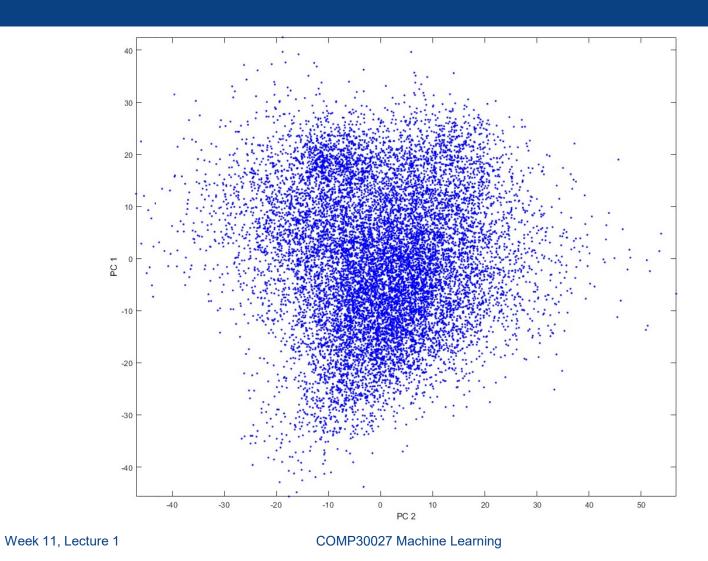


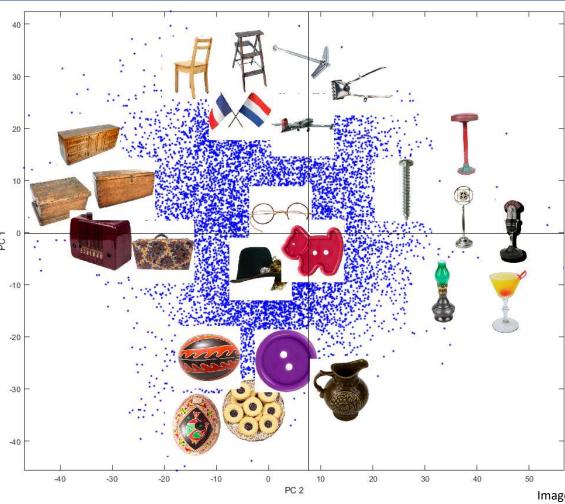
# Unsupervised learning, mixture models

Semester 1, 2021 Kris Ehinger



**Embedding** of an input = the network's response to the input at some layer





Images: Hemera Technologies

Similar images: layer 7



#### Outline

- Clustering
- Gaussian mixture model and EM algorithm
- Unsupervised evaluation

## Clustering

#### Clustering basics

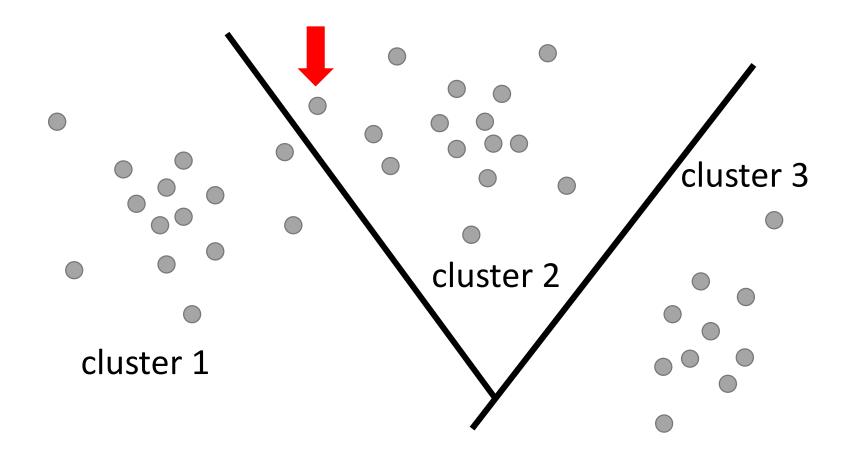
- Clustering = unsupervised learning; no explicit or implicit definition of class
- Learn structure from data alone
- But you usually bring your own assumptions about what kind of structure you expect in the data:
  - Exclusive or overlapping clusters?
  - Hierarchical clusters?
  - What defines a good "group"?

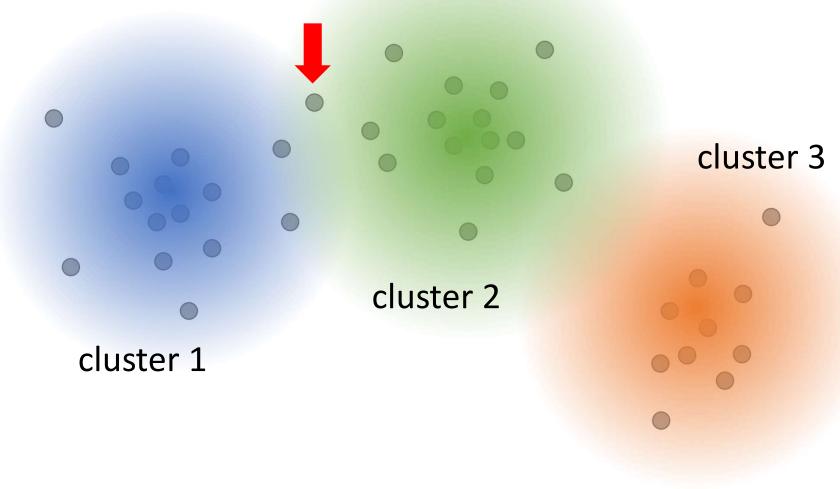
 Deterministic clustering = each instance is a member of one cluster = clusters can't overlap

| Instance | Cluster |
|----------|---------|
| 1        | 3       |
| 2        | 1       |
| :        | :       |

 Probabilistic cluster = each instance has a weight in each class = clusters overlap

| Instance | Cluster 1 | Cluster 2 | Cluster 3 |
|----------|-----------|-----------|-----------|
| 1        | 0.01      | 0.87      | 0.12      |
| 2        | 0.67      | 0.15      | 0.18      |
| <b>:</b> |           | :         |           |



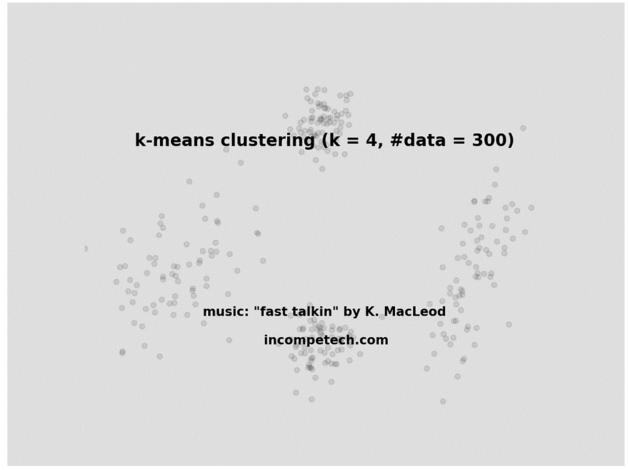


Why choose one over the other?

#### K-means clustering

- Given k, the k-means algorithm is implemented as follows (Lloyd's algorithm):
- Select k points at random as the initial cluster centroids
- 2. For each instance, compute the distance to each centroid
- Assign each instance to the cluster with nearest centroid
- Compute a new centroid for each cluster (centroid = mean of all instances in the cluster)
- 5. Go to 2, repeat until no instances are reassigned

#### K-means clustering



#### "Soft" k-means clustering

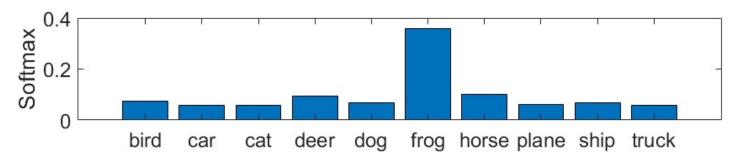
- Is it possible to have a probabilistic ("soft") version of k-means, where each instance is a member of all clusters, with some probability?
- Solution: use softmax function

$$\sigma(x_i) = \frac{e^{x_i}}{\sum_{i=1}^k e^{x_i}}$$

- Example: x = [-0.5, 0, 1.3, 2]
- After softmax:  $\sigma = [0.048, 0.079, 0.29, 0.58]$

#### Note on softmax function

- Produces a vector that has the properties of a probability distribution:
  - All values in range 0-1
  - Values sum to 1
- Common application: normalise the output of a multiclass classifier:



Are these values actual probabilities?

#### "Soft" k-means clustering

- Choose random centroids  $\mu_1, \mu_2, \dots, \mu_k$
- Probability instance  $x_i$  is in cluster j is:

$$z_{ij} = \frac{\exp[-\beta ||x_i - \mu_j||]}{\sum_{\ell} \exp[-\beta ||x_i - \mu_{\ell}||]}$$

 $\beta > 0$ , and is the "stiffness" parameter

 Update each of the centroids with a weighted average of all instances:

$$\mu_j = \frac{\sum_i z_{ij} x_i}{\sum_i z_{ij}}$$

Result: overlapping clusters

# Gaussian mixture model and EM algorithm

#### Finite mixtures

- A **finite mixture** is a distribution composed of *k* component distributions
- Used to represent subgroups or latent factors in a dataset
- Gaussian mixture model (GMM) represents a distribution as composed of k Gaussian distributions

#### Expectation maximization

- Expectation maximisation (EM) = parameter estimation method with guaranteed "positive" hillclimbing characteristics relative to the gradient of log-likelihood
- Used to estimate (hidden) parameter values, such as cluster membership
- Family of algorithms rather than a specific algorithm

- Basic idea: generalization of (soft) k-means
- E(xpectation) step:
  - Based on current estimate of the parameters, calculate the log-likelihood of the instances
- M(aximization) step:
  - Compute the parameter distribution that maximizes the log-likelihood
- Repeat until convergence

#### EM log likelihood

• The log likelihood of a given finite mixture is:

$$L = \sum_{i} \log \sum_{j} P(c_{j}) P(x_{i}|c_{j})$$

where each  $x_i$  is an instance and each  $c_i$  is a class

- This gives an estimate of the "goodness" of the cluster model; guaranteed to increase on each iteration of the EM algorithm
- Convergence: if the change in log likelihood falls below a predefined value, we consider the estimate to have converged

- Assume this data is a mixture of two normal distributions
- Each instance is drawn from one of the two distributions; probability of drawing from distribution 1 is  $\gamma$  and from 2 is  $(1 \gamma)$
- The probability density can be written as:

$$g(x) = \gamma \phi_{\mu_1, \sigma_1}(x) + (1 - \gamma)\phi_{\mu_2, \sigma_2}(x)$$

where  $\phi_{\mu,\sigma}$  is a normal distribution with mean  $\mu$  and standard deviation  $\sigma$ 

• Problem: estimate the parameters  $\gamma$ ,  $\mu_1$ ,  $\sigma_1$ ,  $\mu_2$ ,  $\sigma_2$ 

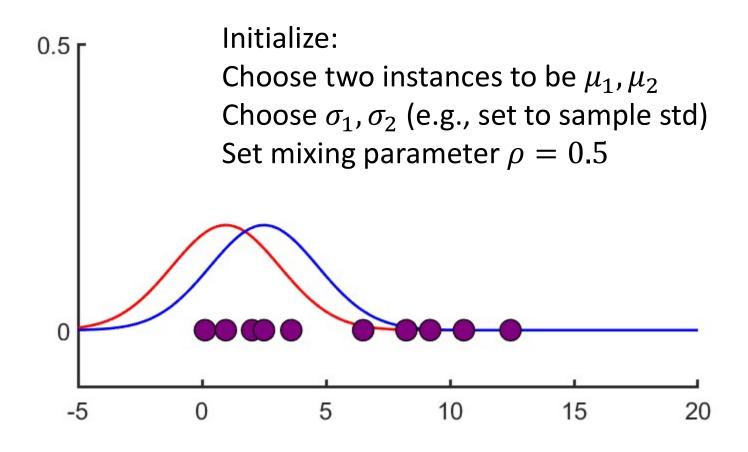
• We want to find the parameters that maximize the log likelihood of the instances  $x_i$ :

$$\sum_{i=1}^{N} \log \left[ \gamma \phi_{\mu_1, \sigma_1}(x_i) + (1 - \gamma) \phi_{\mu_2, \sigma_2}(x_i) \right]$$

 This is difficult to solve numerically, but if we know which instances come from which generating distribution, the computation is simpler:

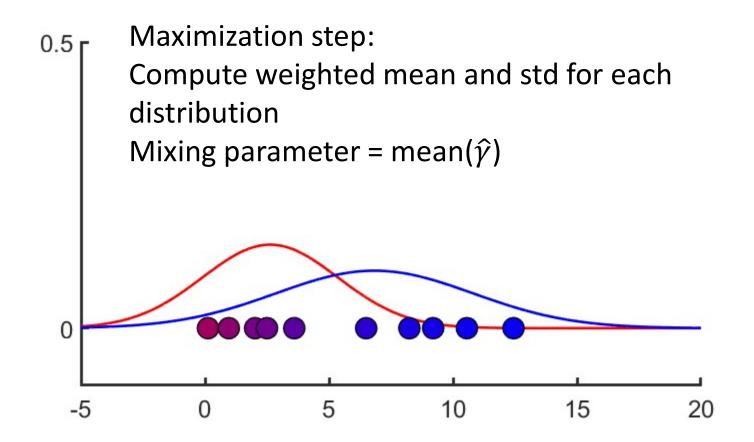
Distribution 1: 
$$\sum_{j \in D_1} \left[ \log \left( \phi_{\mu_1, \sigma_1}(x_j) \right) + \log(\gamma) \right]$$
  
Distribution 2:  $\sum_{j \in D_2} \left[ \log \left( \phi_{\mu_2, \sigma_2}(x_j) \right) + \log(1 - \gamma) \right]$ 

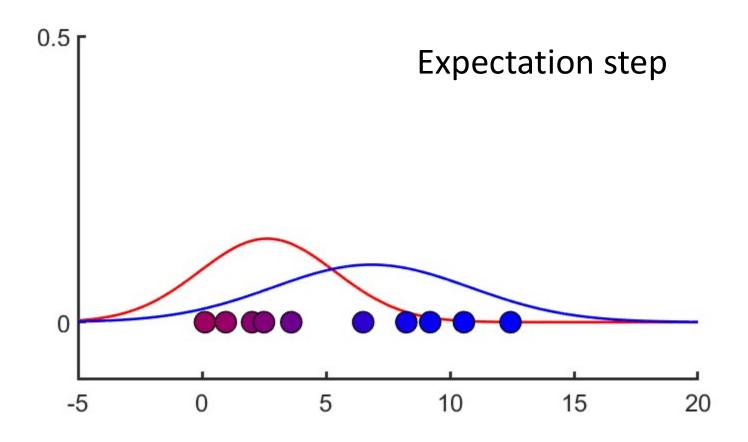
- We don't know which distribution produced each instance
- But given some parameters  $\gamma$ ,  $\mu_1$ ,  $\sigma_1$ ,  $\mu_2$ ,  $\sigma_2$  we could estimate how likely each distribution was to have generated each instance
- So, in the iterative EM algorithm:
  - Expectation step: do a soft assignment of instances to each distribution based on current parameters
  - Maximization step: update parameters based on current assignment

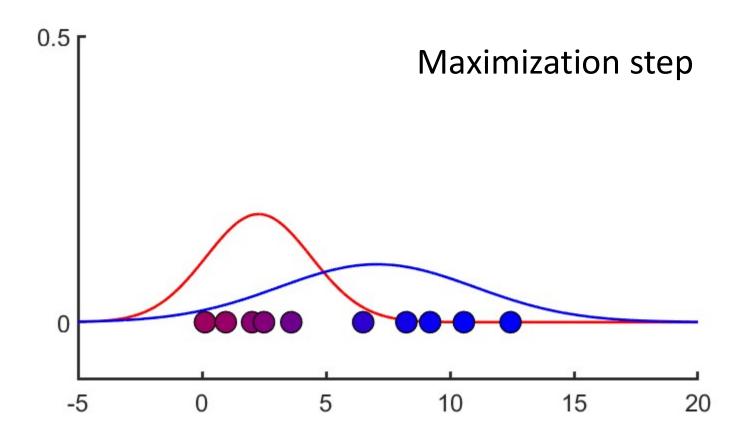


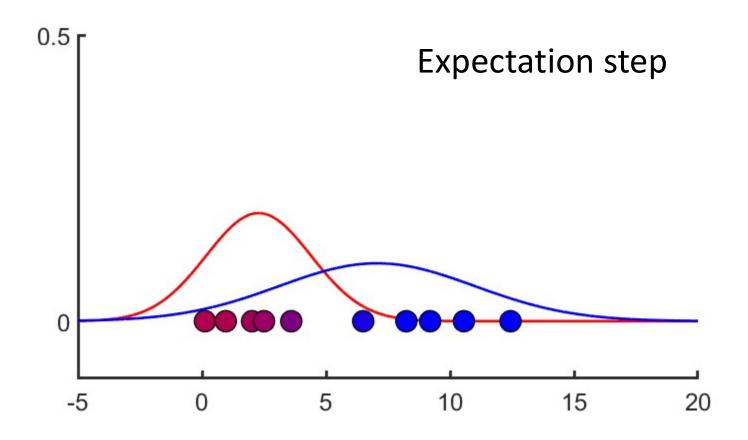
Expectation step:

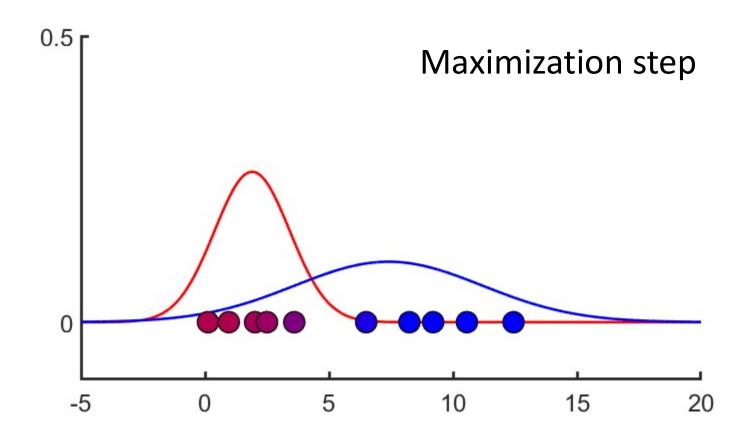
Compute responsibility = likelihood instance is from blue group:  $\hat{\gamma} = \rho \phi_{blue}(x_i)/[(1-\rho)\phi_{red}(x_i) + \rho \phi_{blue}(x_i)]$ 

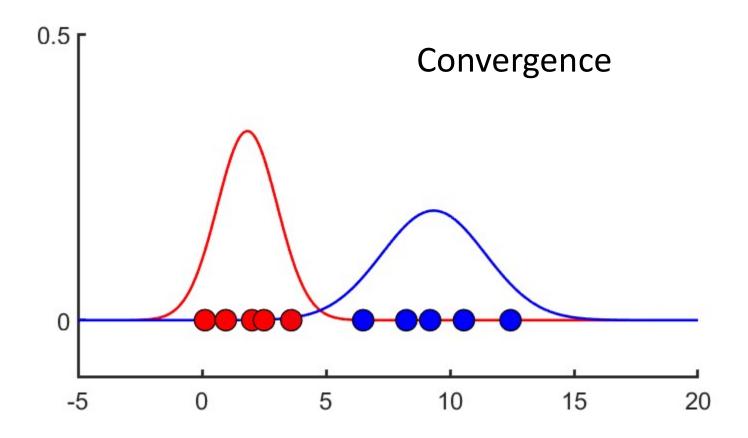












#### EM algorithm

#### Advantages

- Guaranteed "positive" hill-climbing behaviour
- Fast to converge
- Results in probabilistic cluster assignment

#### Disadvantages

- Has an element of randomness final model may differ depending on initial parameters
- Can get stuck in a local maximum; not guaranteed to find the maximum-likelihood solution
- The number of clusters (k) must be assumed

## Unsupervised evaluation

#### Why do unsupervised learning?

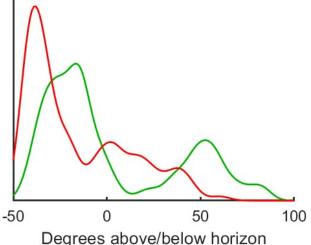
- Map high-dimensional data to a smaller set of clusters or latent factors
- Discover relationships / trends in data
- Model probability density function for probabilistic models (e.g., naïve Bayes)

## Example: KDE naïve Bayes

 Naïve Bayes classifier chooses the class that maximizes the posterior probability:

$$\hat{c} = \arg \max_{c_j \in C} P(c_j) \prod_i P(x_i | c_j)$$

• Likelihood  $P(x_i|c_j)$  can be computed by KDE:



# Why do unsupervised learning?

- Map high-dimensional data to a smaller set of clusters or latent factors
- Discover relationships / trends in data
- Model probability density function for probabilistic models (e.g., naïve Bayes)
- Generate new samples from the modelled probability distribution

#### Example: Text generation

#### Talk to Transformer

See how a modern neural network completes your text. Type a custom snippet or try one of the examples. Learn more below.

#### Custom prompt

Type something and a neural network will guess what comes next.

https://talktotransformer.com/

#### Unsupervised learning: Evaluation

- No "ground truth" labels how to tell if a model is correct, or if one model is better than another?
  - Subjective evaluation
  - Check similarity of clusters over multiple iterations
  - Cross-validation: train on a subset of data and see how well the model predicts held-out data
  - Supervised evaluation: if labels are available, compare how well the discovered clusters match the labels

 High cluster cohesion: instances in a given cluster should be closely related to each other

$$cohesion(C_i) = \frac{1}{\sum_{\mathbf{x}, \mathbf{y} \in C_i} proximity(\mathbf{x}, \mathbf{y})}$$

 High cluster separation: instances in different clusters should be distinct from each other

$$separation(C_i, C_j) = \sum_{\mathbf{x} \in C_i, \mathbf{y} \in C_{j \neq i}} proximity(\mathbf{x}, \mathbf{y})$$

## Cluster compactness

 One way to evaluate the quality of clusters (especially for k-means) is sum of squared errors (SSE):

$$SSE = \sum_{i=1}^{k} \sum_{\mathbf{x} \in C_i} proximity(\mathbf{x}, \mathbf{c_i})^2$$

where  $\mathbf{c_i}$  is the centroid of cluster  $C_i$ 

 Proximity measure is often Euclidean for numeric data, or Hamming for nominal

## Sum of squared errors: Example

| Cluster 1 centroid: |      |      |     |           |
|---------------------|------|------|-----|-----------|
| sunny               | mild | high | no  |           |
| sunny               | hot  | high | no  | 12 = 1    |
| sunny               | hot  | high | yes | $2^2 = 4$ |
| overcast            | hot  | high | no  | $2^2 = 4$ |
| rainy               | mild | high | no  | $1^2 = 1$ |
| sunny               | mild | high | no  | 0         |
| overcast            | mild | high | yes | $2^2 = 4$ |
| rainy               | mild | high | yes | $2^2 = 4$ |

| Cluster 2 centroid: |      |        |     |  |  |
|---------------------|------|--------|-----|--|--|
| overcast            | cool | normal | yes |  |  |
| rainy               | cool | normal | yes |  |  |
| overcast            | cool | normal | yes |  |  |
| sunny               | cool | normal | no  |  |  |
| overcast            | mild | normal | no  |  |  |
| sunny               | mild | normal | yes |  |  |
| overcast            | hot  | normal | no  |  |  |
| rainy               | cool | normal | no  |  |  |

$$SSE_1 = 18$$
  $SSE_2 = 20$   
 $SSE = SSE_1 + SSE_2 = 38$ 

 If labels are available, evaluate the degree to which class labels are consistent within a cluster and different across clusters

$$purity = \sum_{i=1}^{k} \frac{|C_i|}{N} \max_{j} P_i(j)$$

$$entropy = \sum_{i=1}^{k} \frac{|C_i|}{N} H(x_i)$$

where  $x_i$  is the distribution of class labels in cluster i

| Cluster | Play = yes | Play = no | Entropy | Purity |
|---------|------------|-----------|---------|--------|
| 1       | 4          | 0         | 0       | 1      |
| 2       | 4          | 4         | 1       | 0.5    |

$$entropy = -1 \log(1) - 0 \log(0) = 0$$
  
 $entropy = -0.5 \log(0.5) - 0.5 \log(0.5) = 1$   
 $purity = \max(1,0) = 1$   
 $purity = \max(0.5,0.5) = 0.5$ 

| Cluster | Play = yes | Play = no | Entropy | Purity |
|---------|------------|-----------|---------|--------|
| 1       | 4          | 0         | 0       | 1      |
| 2       | 4          | 4         | 1       | 0.5    |
| Total:  |            |           | 0.67    | 0.67   |

$$entropy = \left(\frac{4}{12}\right)0 + \left(\frac{8}{12}\right)1 = 0.67$$

$$purity = \left(\frac{4}{12}\right)1 + \left(\frac{8}{12}\right)0.5 = 0.67$$

| Cluster | Play = yes | Play = no | Entropy | Purity |
|---------|------------|-----------|---------|--------|
| 1       | 2          | 0         | 0       | 1      |
| 2       | 6          | 4         | 0.97    | 0.6    |

$$entropy = -1 \log(1) - 0 \log(0) = 0$$

$$entropy = -0.6 \log(0.6) - 0.4 \log(0.4) = 0.97$$

$$purity = \max(1,0) = 1$$

$$purity = \max(0.6,0.4) = 0.6$$

| Cluster | Play = yes | Play = no | Entropy | Purity |
|---------|------------|-----------|---------|--------|
| 1       | 2          | 0         | 0       | 1      |
| 2       | 6          | 4         | 0.97    | 0.6    |
| Total:  |            |           | 0.81    | 0.67   |

entropy = 
$$\left(\frac{2}{12}\right)0 + \left(\frac{10}{12}\right)0.97 = 0.81$$
  
purity =  $\left(\frac{2}{12}\right)1 + \left(\frac{10}{12}\right)0.6 = 0.67$ 

#### Summary

- Unsupervised learning = finding structure in unlabelled data
- Methods to fit probability distributions to data:
  - Gaussian mixture
  - Kernel density estimation
- Expectation-maximization (EM) algorithm: family of algorithms to find maximum likelihood parameters for a model