

# Information and Coding Theory: Quick reference

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## Part I

# Introduction

### 1 Notation

Hamming distance  $d(x,y)$ .

### 2 Themes

Designing efficient and reliable data transmission, for compression and error correction. Suitability of codes for particular purposes.

For Cryptography, see cryptography ref.

### 3 Information

#### 3.1 Self Information of an event

Aka surprisal. Measure of information content associated with event  $e$ : rarer the event, more the info, and in case of independence  $\perp (e, f) : h(e, f) = h(e) + h(f)$ . In the latter case,  $\Pr(e,f) = \Pr(e)\Pr(f)$ ; thence get derivation:  $h(e) = h(X = x) = \log(\frac{1}{\Pr(e)})$ .

##### 3.1.1 As code-length for recording event

###### 3.1.1.1 Coding problem

Suppose that we wanted to record information that an event occurred, but we wanted to use as few bits in expectation as possible. We want to satisfy this: the more common the event, fewer the bits one would need to transmit the event's occurrence.

### 3.1.1.2 Coding algorithm

We observe that there can be at most  $1/p$  events with probability  $p$ . So, assigning  $\left\lceil \log\left(\frac{1}{Pr(e)}\right) \right\rceil$  bits to communicate the occurrence of an event ensures that we have a way of encoding all possible events, while using fewer bits to encode commoner events.

This is a code with the least expected code-length, as shown in the entropy section.

### 3.1.2 Unit

Inspired by the code-length interpretation of surprisal. Depending on whether  $\log_2$  or  $\ln$  is used in definition: bits or nats.

## 3.2 Entropy of an RV $X$

### 3.2.1 Definition

#### 3.2.1.1 Desired properties

Uncertainty associated with an RV: Should not change if probability rearranged for different values of  $X$ : symmetry; should increase with number of values  $X$  can take; if  $X \perp Y$ , uncertainty of  $(X, Y)$  should be sum of uncertainties.

#### 3.2.1.2 As expected surprisal

$H(X) = E[h(X)] = E_X[-\log(Pr(X = x))]$   
 $= -\sum Pr(X = x_i) \log(Pr(X = x_i))$ ; is the only measure which satisfies this [Find proof].

#### 3.2.1.3 Extension to 0 values

Extend definition for  $Pr(X = x_i) = 0$ :  
 $\lim_{Pr(X=x_i) \rightarrow 0} Pr(X = x_i) \log(Pr(X = x_i)) = 0$ , so set  $Pr(X = x_i) \log(Pr(X = x_i)) = 0$ : so expansibility property: No change in entropy due to adding 0 probability events  $X = x_i$ .

### 3.2.2 Expected Information/ code-length

Entropy of  $X$  is the average amount of information/ surprisal communicated by the corresponding random process.

It is the least expected number of bits required to transmit the value of the random process.

*Proof.* : Non negativity of Information divergence.

**3.2.2.1 Cross entropy**

Even though  $X$  may have distribution  $D$ , an alternative code appropriate for random variable corresponding to distribution  $E$  can potentially be used to encode events  $X = x$ . But, the expected code length is higher if this is done. This inspires a way of measuring divergence between distributions - Information (KL) Divergence/ Code-length divergence  $KL(E||D)$ . This is described in probability theory survey.

**3.2.3 As cross entropy relative to U**

$H(X) = \log |\text{ran}(X)|$  if  $X \sim U$ .  $KL(X||U) = \log |\text{ran}(X)| - H(X)$ ; but  $KL(X, U) \geq 0$ , so  $U$  has max entropy, reduction in entropy is  $KL(X, U)$ .

Non uniform distribution has less entropy than uniform distribution. Can use this to reduce the number of bits needed to transmit information.

**3.2.4 Concavity in case of discrete distribution p**

$H(p) = \sum_i p_i \log(1/p_i)$ : concave in  $p_i$  as  $\nabla^2 H(p) \succeq 0$ . Consider RV  $X \sim \text{bernoulli}(p)$ : entropy cup shaped, with max at  $p=0.5$ .

**3.2.5 Asymptotic equipartition property (AEP)**

Take binary distribution with entropy  $H$ , iid sample  $\{X_i\}$ , get sequence  $(X_i)$ . Then, sequences will either have probability  $2^{-nH}$ , or  $\approx 0$ . So, need only  $nH$  bits, rather than  $n$  bits. Pf: Set  $Y_i = \log \frac{1}{Pr(X_i)}$ ; By law of large numbers  $n^{-1} \sum Y_i \rightarrow H$ ; so  $-Pr((X_i) = (x_i)) \rightarrow nH$ .

**3.3 Joint and cross entropy****3.3.1 Joint entropy**

$H(X, Y) = E_{x,y}[-\log(Pr(X = x, Y = y))]$ .

Additivity, as required: If  $X \perp Y$ :  $H(X, Y) = H(X) + H(Y)$ ; subadditivity:  $H(X, Y) \leq H(X) + H(Y)$ .

**3.3.2 Cross entropy**

$H_C(X, Y) = E_x[-\log(Pr(Y = y))]$ : avg bits required to transmit  $X$  using protocol designed for  $Y$ . Compare with information divergence: that is the number of extra bits required to transmit  $X$  using a protocol designed for  $Y$ .

**3.4 Conditional entropy of X given Y**

$H(X|Y) = E_y[H(X|Y = y)] = E_y[E_x[-\log(Pr(X = x|Y = y))]] = H(X, Y) - H(Y)$ : Aka equivocation; Avg uncertainty in  $X$ , after seeing  $Y$ .

### 3.5 Mutual information of X wrt Y

$I(X; Y) = E_{x,y} \log \left[ \frac{Pr(X=x, Y=y)}{Pr(X=x)Pr(Y=y)} \right] = H(X) - H(X|Y) = H(X) + H(Y) - H(X, Y)$  - visualize with a venn diagram!: reduction in uncertainty about X due to knowledge of Y. It is symmetric.

This is the expected value of the information gain / code-length divergence:  $E_x[H(Y) - H(Y|X = x)]$ ; and is therefore loosely called information gain when considered in the context of classification problems in machine learning.

#### 3.5.1 As deviation from independent distribution

$I(X; Y) = K(Pr(X = x, Y = y) || Pr(X = x)Pr(Y = y))$ ; so  $I(X; Y) \neq 0$  iff  $X \perp Y$ . So, it is non negative.

#### 3.5.2 Conditional Mutual information wrt Z

$I(X; Y|Z) = E_z[I(X; Y|Z = z)]$ .

### 3.6 Other information metrics

Hamming weight of x:  $wt(x)$ . Hamming distance:  $d(x, y) = wt(x \oplus y)$ .

### 3.7 Communication complexity

#### 3.7.1 The problem

A talks to B; A knows a; B knows b; want to find  $f(a, b)$  with min communication and even  $\infty$  local computation. a, b are n bit numbers.

Easy solution is to send a and b. But these may be large. So want to use some protocol depending on f.

#### 3.7.2 Applications

VLSI, scenarios where communication is very costly.

#### 3.7.3 The communication protocol tree

$A \leftrightarrow B$  communication can be represented as this: A and B take turns sending messages, the message sent at step i is  $m_i = f_i(a, b)$ . Maybe distribution M over (a, b) specified and want to minimize expected communication, maybe want min worst case communication.

So, can look at all possible communication sequences using a protocol tree.

#### 3.7.4 Deterministic vs randomized protocols

Bits transmitted by deterministic protocol, for worst possible (a, b) :=  $D(f)$ . If distribution M specified:  $D_M(f)$ : avg bits used.

Randomized protocols may use public randomness or private random bits. Bits used by them for worst  $(a, b) := R(f)$ . Randomized protocols much more powerful than deterministic ones: See equality testing example.

Having public random bits is not much more powerful: you can replace public random bit using protocol with private random bit using protocol with only  $+ \log n$  bits penalty.

### 3.7.5 Computing f for k input pairs

Want to do better than  $kD(f)$  from trivial algorithm. Deterministic protocol:  $\Omega(k\sqrt{D(f)})$ . Randomized protocol:  $\tilde{O}(R(f)\sqrt{k})$ .

### 3.7.6 Examples

#### 3.7.6.1 Checking equality

$f(a, b) : b \stackrel{?}{=} a$ . Any det protocol needs  $n$  bits. So use fingerprinting (see Randomized algs ref).

A uses rand  $r$ , sends fingerprint  $(F(a, r), r)$  to B.

To show that  $F$  is good: Make  $\hat{F}(a) = ((F(a, r_1), r_1), \dots, (F(a, r_s), r_s))$ ; pick rand element and send. For all  $a \neq b$ , show Hamming dist  $\delta(\hat{F}(a), \hat{F}(b))$  large.

## Part II

# Coding

## 4 Fingerprinting

This codes can also be used as error detection codes.

### 4.1 Chinese reminder code

Codes which use  $a \bmod p$ , with rand  $p$ .  $\hat{F}(a)$  elements will use diff fields; so not preferred.

#### 4.1.1 Checking equality

A picks rand prime  $p$  between 1 and  $k = n^3$ ; Sends  $(a \bmod p, p)$  to B; B says '=' if  $a \equiv b \bmod p$ .

$Pr_p(a \equiv b \bmod p | a \neq b) \leq n^{-1}$ : num( $p$  with  $a \equiv b \bmod p$  when  $b \neq a$ ) or,  $num(p | (a-b)) \leq n^{-1}$  as  $a-b \in [0, 2^n - 1]$ ; so  $Pr(p | a-b) < \frac{n}{\prod(n^3)} \leq \frac{n \ln n}{n^3} \leq \frac{1}{n}$

Using Prime number theorem.

## 4.2 Univar polynomial code

(Reed Solomon) Codes which make univar polynomial  $p_a$  over  $\mathbb{F}_p$ , ( $\deg \leq n$ ), from  $a$ , prime  $p$ , with  $a$ 's bits representing coefficients.

### 4.2.1 Checking equality

Fix  $p$ . A picks rand  $r$  from  $F_p$ , sends  $(p_a(r), r)$  to B, B accepts if  $p_b(r) = p_a(r)$ .  
 $Pr((p_b - p_a)(r) = 0) \leq \frac{n}{p}$ : max  $n$  roots.

## 4.3 Multivar polynomial code

(Reed Muller). [Incomplete]

## 5 Source coding

Compression. See the example about checking equality.

## 6 Channel Codes

### 6.1 Code design

In most cases, this is an art, rather than a science. Not many things are proved; instead one runs long simulations to show goodness of a code.

### 6.2 Modelling a channel

Transmitted  $x$  is transmuted to  $y$ ; want to model this process.

#### 6.2.1 Channel capacity

Aka Shannon limit or capacity. The tightest upper bound on the amount of information that can be reliably transmitted over a communications channel.

#### 6.2.2 Binary symmetric channel

$Pr(x_i \neq y_i) = p$ .

#### 6.2.3 Erasure channel

$Pr(y_i = x_i) = p$ , with  $1-p$  probability,  $y_i = ?$  (erased). This can model packet loss.

### 6.3 Model message distribution

Usually assume uniform distribution over messages.

### 6.4 Tolerating errors

Design codes and protocols for error detection and correction.

#### 6.4.1 ARQ

If error detected, ask for retransmission.

#### 6.4.2 Forward error correction

Receiver never sends any message back to transmitter. Error correcting code (ECC) attached with data used to fix errors.

#### 6.4.3 Decoding

Set of codes  $C \subseteq \{F\}_2^n$ .  $x$  is received. Select  $c \in C$  closest to  $x$ .

**List decoding** Output a list of codes within a certain distance of the mangled code.

#### 6.4.4 Joint source-channel coding

Encoding of a redundant information source for transmission over a noisy channel, and the corresponding decoding. [**Incomplete**]

### 6.5 Properties

#### 6.5.1 Minimum Hamming Distance $d$

Aka distance of the code, Hamming metric. Closely related to the error correcting ability of the code.

More efficient encoding and decoding. [**Find proof**]

#### 6.5.2 Code rate

Code rate  $k/n$ . High rate code if this is high.

### 6.6 Types

#### 6.6.1 Block vs Convolutional codes

Block codes:  $k$ -bit info to  $n$ -bit code. Block length  $n$ .

Convolutional code:  $k$  bit info to  $n$  bit code.

### 6.6.2 Bound on code size of block codes

(Gilbert-Varshamov). Take code with length  $n$ , distance  $d$ , size (not dimension) of the code  $A_q(n, d)$ . Then  $A_q(n, d) \geq \frac{q^n}{\sum_{j=0}^{d-1} \binom{n}{j} (q-1)^j}$  [Find proof].

The best rate vs distance tradeoff.

### 6.6.3 w error correcting code

A code which can correct  $w$  erroneous bits.

**w error correcting linear code** Given  $n \times m$  generator matrix  $G$  and  $m$  bit  $y$ , find  $n$  bit  $x$  such that  $d(xG, y) \leq w$ , if it exists. This is possible only if corresponding  $d \geq 2w + 1$ .

### 6.6.4 Cyclic code

Right shifting a code  $c \in C$  also yields a code in  $C$ .

## 7 $[n, k, d]$ Linear code C

A type of block code. Block Length  $n$ , message length  $k$ , min Hamming distance  $d$ : encode  $k$  bit msg in  $n$  bit message.

$d$  is the min Hamming wt of any non zero code vector [Find proof].

### 7.1 A linear subspace of valid codes

A linear subspace  $C$  with dimension  $k$  of vector space  $F_q^n$  over finite field  $F_q$ . The channel takes you away from this subspace, find the vector closest to the received message in the subspace.

All vector and scalar ops are in  $F_q$ . For Binary linear codes, use the field  $F_2$ .

#### 7.1.1 Basis codes

Can be represented as span of basis codes. Basis codes form rows of  $k \times n$  generating matrix  $G$ . Standard form of  $G$ :  $G$  is of the augmented matrix  $[I_k : A]$ , with  $k \times (n-k)$   $A$ . To encode  $x$ , find  $xG$ .

#### 7.1.2 Random $[n, k]$ code

$k$  vectors chosen randomly from  $\{0, 1\}^n$ . Or, full rank  $G$  is chosen randomly. Achieves whp Gilbert Varshmov bound on rate vs distance tradeoff.

### 7.2 Decoding

Check/ parity check matrix  $H$ :  $n \times (n-k)$ , with left kernel  $C$ ;  $H = [-A^T : I_{n-k}]$  in std form.  $GH=0$ . To check  $y$ , verify:  $yH = 0$ .



For corrupted  $y$ , there is an error vector  $e$  with  $wt(e) \leq \frac{d-1}{2}$  such that  $y \oplus e = xG$  for some  $x$ . To decode, look at its syndrome:  $yH = (x + e)H = eH$ . Then solve for  $e$  or look it up in a table. Then find  $x$ .

### 7.2.1 $[p, q]$ regular code

Make a bipartite graph: bits in variable  $x$  on one hand, and nodes corresponding to parity checks in  $H$  on the other. If this is a  $[p, q]$  regular graph, you have a  $[p, q]$  regular code.

### 7.2.2 Decoding

Avg case hardness unknown. Worst case decoding is NP hard. Even finding  $d$  is believed hard.

### 7.2.3 As inference over factor graph

**Make a factor graph** Make nodes for the transmitted codeword bits  $x$ , and for the corresponding received/ corrupted codeword bits  $y$ . Make factors corresponding to the parity checks for  $y$ : eg: if  $H$  contains a check which says  $\oplus_{i \in S} x_i$ , make a factor  $f_S$ , such that any  $x$  where this is not satisfied has probability 0. Relationship between  $x_i$  and  $y_i$  can be modelled using a symmetric error: maybe  $y_i$  is corrupted with probability  $p$ .

**The inference problem**  $y$  is observed,  $x$  is unobserved - to be inferred. Can use loopy belief propogation for doing this.

**Guarantees for  $[p, q]$  regular codes** As the block size  $n$  increases, can be sure that loopy belief propogation properly decodes: shown using the 'density evolution' argument. Loopy belief propogation gets into trouble because of cycles; but if you consider the computation tree corresponding to a node, maybe convergence achieved well before a cyclical message is received!