Control Systems

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1

Contents

1 Stability

Abstract—This manual is an introduction to control systems in feedback circuits. Links to sample Python codes are available in the text.

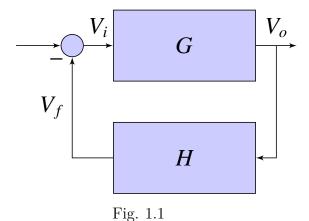
Download python codes using

svn co https://github.com/gadepall/school/ trunk/control/feedback/codes

1 Stability

1.1. An op amp having a low-frequency gain of 10^3 and a single-pole rolloff at 10^4 rad/s is connected in a negative feedback loop via a feedback network having a transmission k and a two-pole rolloff at 10^4 rad/s. Find the value of k above which the closed-loop amplifier becomes unstable.

Solution: The given oscillator has a low frequency gain 10^3 and a single-pole rolloff at 10^4 rad/s.



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So we have a open loop amplifier gain

$$G(s) = \frac{10^3}{1 + \frac{s}{10^4}} \tag{1.1.1}$$

Given feedback network transmission gain k and two-pole rolloff at 10⁴ rad/s. So, the feedback factor would be

$$H(s) = \frac{k}{\left(1 + \frac{s}{10^4}\right)^2} \tag{1.1.2}$$

The resulting loop-gain would be

$$G(s)H(s) = \frac{10^3 k}{\left(1 + \frac{s}{10^4}\right)^3}$$
 (1.1.3)

Parame-	Definition	For given
ters		case
Open	G	$\frac{10^3}{1+\frac{s}{10^4}}$
loop gain		104
Feedback	Н	$\frac{k}{(1-x)^2}$
factor		$\left(1+\frac{s}{10^4}\right)^2$
Loop	GH	$\frac{10^3 k}{(1+\frac{s}{10^4})^3}$
gain		$(1+\frac{10^4}{10^4})^2$

TABLE 1.1

The closed loop gain would be

$$T(s) = \frac{G(s)}{1 + G(s)H(s)}$$
(1.1.4)

Generalized condition for the system to be stable:

$$T(j\omega) = \frac{G(j\omega)}{1 + G(j\omega)H(j\omega)}$$
(1.1.5)

Loop gain, $L(j\omega) = G(j\omega)H(j\omega)$.

$$L(j\omega) = |G(j\omega)H(j\omega)| e^{j\phi(\omega)} \qquad (1.1.6)$$

Let the frequency at which phase angle $\phi(\omega)$ becomes 180° be ω_{180} . At $\omega = \omega_{180}$, $L(j\omega)$ is a negative real number.

• if
$$|G(j\omega_{180})H(j\omega_{180})| < 1, T(j\omega_{180}) > 1$$

 \implies system is stable.

- if $|G(j\omega_{180})H(j\omega_{180})| = 1, T(j\omega_{180}) = \infty$ \implies system is unstable.
- if $|G(j\omega_{180})H(j\omega_{180})| > 1, T(j\omega_{180}) < 1$ \implies system is unstable.

For the given system:

$$\angle G(j\omega)H(j\omega) = \angle \frac{10^3 k}{\left(1 + \frac{j\omega}{10^4}\right)^3} = -3tan^{-1}\left(\frac{\omega}{10^4}\right)$$
(1.1.7)

So,

$$180^{\circ} = -3tan^{-1} \left(\frac{\omega_{180}}{10^4} \right) \tag{1.1.8}$$

$$\implies \omega_{180} = -\sqrt{3} \times 10^4$$
 (1.1.9)

The Loop gain at ω_{180} is $G(j\omega_{180})H(j\omega_{180})$. The system becomes unstable if

$$G(j\omega_{180})H(j\omega_{180}) \ge 1$$
 (1.1.10)

$$\implies \left| \frac{10^3 k}{\left(1 + \frac{j\omega}{10^4}\right)^3} \right| \ge 1 \tag{1.1.11}$$

$$\left| \frac{10^3 k}{\left(1 - \sqrt{3} j \right)^3} \right| \ge 1 \tag{1.1.12}$$

$$\frac{10^3 k}{\left|\sqrt{1+\sqrt{3}^2}\right|} \ge 1\tag{1.1.13}$$

$$\frac{10^3 k}{8} \ge 1\tag{1.1.14}$$

$$\implies k \ge 0.008 \tag{1.1.15}$$

Hence, the value of k above which the system becomes unstable is 0.008.

1.2. Design the circuit for the given parameters Solution: Consider the open loop gain,G

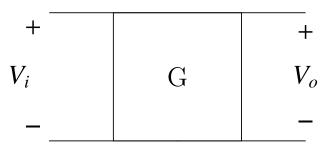


Fig. 1.2

Now,

$$V_i = V_{in} \tag{1.2.1}$$

$$G(s) = \frac{V_0}{V_i - V_-} = \frac{10^3}{1 + \frac{s}{10^4}}$$
 (1.2.2)

This is of the form $10^3 \left(\frac{R}{R+sL}\right)$. This can be realized using the circuit:

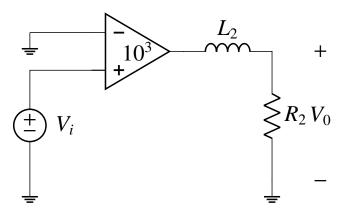


Fig. 1.2

Where the gain of the Op-Amp is 10^3 .

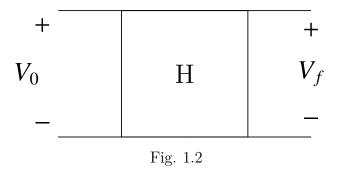
$$\frac{R_2}{L_2} = 10^4 \tag{1.2.3}$$

One set of values that would satisfy this condition would be

$$R_2 = 100\Omega \tag{1.2.4}$$

$$L_2 = 1\mu F \tag{1.2.5}$$

Consider the feedback factor, H



Now.

$$H(s) = \frac{V_f}{V_0} = \frac{k}{\left(1 + \frac{s}{10^4}\right)^2} = k \left(\frac{1}{1 + \frac{2s}{10^4} + \frac{s^2}{10^8}}\right)$$
(1.2.6)

This is of the form,

$$k\left(\frac{1}{1+sR_1C_1+s^2L_1C_1}\right) = k\left(\frac{\frac{1}{sC_1}}{R_1+sL_1+\frac{1}{sC_1}}\right)$$
(1.2.7)

This can be realized using the circuit,

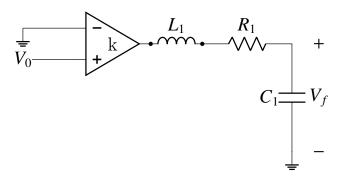


Fig. 1.2

A set of values that satisfy these equations are,

$$R_1 = 200\Omega$$
 (1.2.8)
 $C_1 = 1\mu F$ (1.2.9)
 $L_1 = 10mH$ (1.2.10)

The final circuit would be,

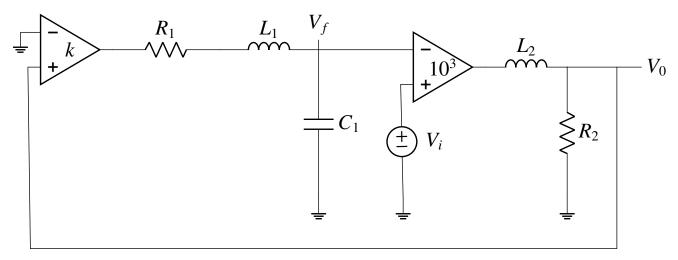


Fig. 1.2