## 1

## EE3025-Assignment 1

## C Shruti - EE18BTECH11006

Download all python codes from

https://github.com/shruti-chepuri/EE3025/blob/main/Assignment 1/codes

and latex-tikz codes from

https://github.com/shruti-chepuri/EE3025/tree/main/Assignment\_1

(5.3) The system h(n) is said to be stable if

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty \tag{0.0.1}$$

Is the system defined by (3.2) stable for impulse response in (5.1)?

1 Solution

Given system:

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2)$$
 (1.0.1)

$$y(n) = 0$$
 for  $y < 0$  (1.0.2)

Applying Z-transform:

$$Y(z) + \frac{1}{2}z^{-1}Y(z) = X(z) + z^{-2}X(z)$$
 (1.0.3)

$$Y(z) = \frac{2(z^2 + 1)}{z(2z + 1)}X(z)$$
 (1.0.4)

Finding H(z):

$$H(z) = \frac{Y(z)}{X(z)} \tag{1.0.5}$$

$$H(z) = \frac{2(z^2 + 1)}{z(2z + 1)}$$
 (1.0.6)

$$H(z) = \frac{1 + z^{-2}}{1 + \frac{1}{2}z^{-1}}$$
 (1.0.7)

Impulse response of this system(h(n)):

$$h(n) = Z^{-1} \left( \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{z^{-2}}{1 + \frac{1}{2}z^{-1}} \right)$$
 (1.0.8)

$$h(n) = \left(\frac{-1}{2}\right)^n u(n) + \left(\frac{-1}{2}\right)^{n-2} u(n-2)$$
 (1.0.9)

Given stability criteria:

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty \tag{1.0.10}$$

Substituting h(n) we have,

$$\sum_{n=-\infty}^{\infty} |(\frac{-1}{2})^n u(n) + (\frac{-1}{2})^{n-2} u(n-2)| < \infty \quad (1.0.11)$$

$$\sum_{n=-\infty}^{\infty} \left| \left( \frac{1}{2} \right)^n u(n) + \left( \frac{1}{2} \right)^{n-2} u(n-2) \right| < \infty \quad (1.0.12)$$

$$2\sum_{n=-\infty}^{\infty} |(\frac{1}{2})^n u(n)| < \infty \quad (1.0.13)$$

$$2(\frac{1}{1-\frac{1}{2}}) = 4 < \infty \quad (1.0.14)$$

So, the system is stable.

Verification in Z plane:

When h(n) is bounded i.e

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty \tag{1.0.15}$$

(1.0.3) 
$$\sum_{n=-\infty}^{\infty} |h(n)z^{-n}|_{|z|=1} < \infty$$
 (1.0.16)

(1.0.4) 
$$\sum_{n=-\infty}^{\infty} |h(n)z^{-n}|_{|z|=1} < |\sum_{n=-\infty}^{\infty} h(n)z^{-n}|_{|z|=1}$$
 (1.0.17)

$$\implies |H(z)|_{|z|=1} < \infty \tag{1.0.18}$$

from triangle inequality. This shows us that the unit circle should lie in the ROC for the system to be stable. Now,

$$H(z) = \frac{2(z^2 + 1)}{z(2z + 1)}$$
 (1.0.19)

$$Poles = 0, -\frac{1}{2} \tag{1.0.20}$$

$$Zeros = +1j, -1j$$
 (1.0.21)

Hence from the Z plane plot the system is stable. Verification:

BIBO Stability: For a given system and for every

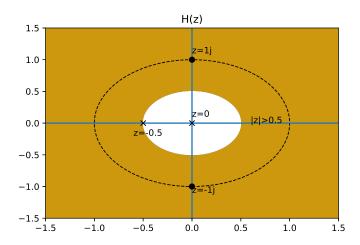


Fig. 0: Unit circle lies in ROC

bounded input, if the output is bounded then it is stable. For a system to be stable the output should be bounded for every bounded input.(BIBO stability). Consider a bounded input sequence x(n)

$$x(n) < B_x(finite) \tag{1.0.22}$$

Then by using the convolution property,

$$|y(n)| = |\sum_{-\infty}^{\infty} h(k)x(n-k)|$$
 (1.0.23)

$$|y(n)| \le B_x \sum_{-\infty}^{\infty} |h(k)| \tag{1.0.24}$$

This holds only if

$$\sum_{n=1}^{\infty} |h(n)| < \infty \tag{1.0.25}$$

then we have 
$$|y(n)| \le B_y < \infty$$
 (1.0.26)

Thus the output is bounded for bounded input if the impulse response is absolutely summable.

Verification:- Given bounded input x(n).,

$$x(n) = \{1, 1, 2, 4, 3, 1\}$$
 (1.0.27)

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2)$$
 (1.0.28)

x(n) is bounded.

The system returns bounded output for the given bounded input. Implies, the system is stable.

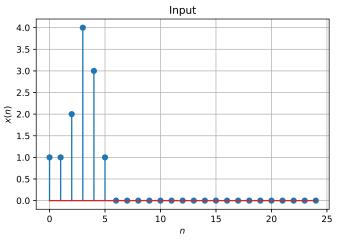


Fig. 0: Given input

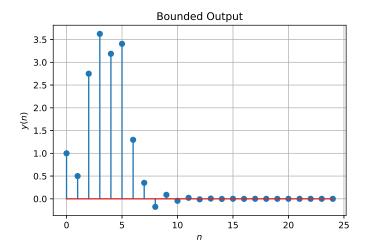


Fig. 0: Bounded output