Shruti Sharma

CONTROL SYSTEMS ENGINEER · ROBOTICS ENTHUTHIAST

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"Life is too small to be sad."

Education

BITS Pilani Pilani Campus, India

B.E. HONS. MANUFACTURING ENGINEERING

August 2016 - July (Exp.) 2020

- · Overall CGPA 7.74
- Coursework: Robotics, Neural Networks and Fuzzy Logic, Image Processing, Machine Learning, Mechatronics and Automation, Control Systems, Reverse Engineering and Rapid Prototyping etc.

A.N. Public School, India

Jaipur, India

HIGH SCHOOL - GRADE 12

August 2014-May 2015

• Percentage - 95.8, first rank in school.

Skills

Programming Python, C++, MATLAB, RobotStudio, LaTeX

Softwares ROS, Gazebo, Solidworks, AutoCad, OpenScad, dSpace, MATLAb-Simulink

Languages English, Hindi

Experience

Festo AG & Co. KG

Esslingen, Germany

BAHELOR THESIS: MODEL-BASED DESIGN AND CONTROL OF A PNEUMATIC ROBOT JOINT

July 2019 - Dec 2019

- Worked in Robotics system design with Dr Rainer Nitsche working towards the development of a 6-dof pneumatic cobot
- Developed & edited custom modular Simulink library blocks of pneumatic components built using C programming
- Developed and implemented a flatness-based position and pressure controller to control the nonlinear pneumatic drive model
- $\bullet \ \ \text{Implemented derived software model on an actual hardware configuration using dSPACE hardware system \ \text{MicroAutoBox II} \\$

Hiroshima University

Higashihiroshima, Japan

SUMMER INTERN & ILDP EXCHANGE STUDENT, SUPERVISOR: DR SHIN WAKITANI, CONTROL SYSTEMS LABORATORY

May 2018 - July 2018

- Developed a PID, I-PD, and a fuzzy controller for a non-linear system in the presence of disturbances
- Designed a mathematical model and implemented a metal temperature control system for corroboration using HIL simulation.

Projects

Autonomous Robot Navigation using RL

India

Supervisor: Dr J.L. Raheja, CEERI Pilani

Jan 2019 - May 2019

- Developed an object detection algorithm using ROS-PCL for images from a synthetic data set developed using Kinect Studio
- Used reinforcement learning algorithm: dueling double deep Q network (D3QN) for navigating robot in a simulated environment

Design of a flexible light-weight manipulator arm for assembly

India

SUPERVISOR: PROF B.K. ROUT, CRIS

August 2018 - Dec 2018

- $\bullet \quad \text{Dynamic and kinematic modelling of 2-DOF RR manipulator with joint flexibility, assumed equivalent to a torsional spring \& rigid links.}$
- Developed a PID controller to eliminate the inaccuracy introduced due to compliance.

Unmanned Aerial Vehicles, BITS Pilani

Pilani, India

DESIGN OF A MULTI-COPTER WITH A MANIPULATOR ARM, SUPERVISOR: PROF PRATEEK KALA

Sept 2018 - Nov 2018

- Developed a teleoperated hexacopter with a 2-DOF manipulator arm
- Used Pixhawk as the flight controller which was tuned using Mission Planner

Rapid Prototyping, BITS Pilani

India

SLICING ALGORITHM FOR 3-D PRINTING

March 2019 - April 2019

• Developed a program in Matlab to generate CNC code for a 3-D printer using CAD files

RECOMMENDATION SYSTEM

March 2019 - May 2019

· Worked on a collaborative filtering based recommendation system using autoencoders with PyTorch

Position of Responsibility _____

Inspired Karters - Formula Student

India

VEHICLE DYNAMICS LEAD

- Led Vehicle Dynamics of a 50 member student team
 Designed and manufactured the wheel assembly and suspension system for a Formula Style open-cockpit vehicle
- Raised 25,000 USD along with the sponsorship team for car's budget; raised 400 USD in a week to resolve a sudden engine problem
- Participated in Formula Bharat 2019; stood 4 in Cost Competition in around 70 participating team, and 17 overall nationally

Alumni Relations Cell, BITS Pilani

India

FOUNDING MEMBER AND CO-EDITOR

Aug 2017 - Aug 2018

Feb 2018 - Jan 2019

- Initiated and drafted quarterly Alumni Newsletter covering the recent Alumni news
- Organised and coordinated reunions comprising of alum batches from 1968 2000
- Implemented a strategy to update the old and scattered alumni database for getting connected with around 150,000 alumni network
- Developed an initial layout for the functioning for the cell in subsequent years; channelised funding of around one million USD

Scholarships _____

2018	First Degree Project Funding, Granted 28,000 INR for developing the multi-copter by Mechanical	India
	Engineering Department	maia
2018	SHRI S. VAISH MEMORIAL SCHOLARSHIP, Received 2,22,250 INR via Vaish Foundation to pursue	India
	my summer internship at Hiroshima University	maia
2019	Mahendra Ram Dalmia Memorial Scholarship , BITSAA scholarship, 25 per cent of my tuition fees	India
	were waived off, which is around 31,000 Indian rupees.	maia
2019	MCN Scholarship, 40 per cent and 25 per cent of my tuition fees was waived off for second	India
	semester 2016-2017 and for last five semesters from 2017-2019	muu

Extracurriculars _____

Writing Profile link

Personal Blog Sept 2018 - Present

• Drafts of conclusions and insights about randomly ever changing life