

a program to implement depth limited search.

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In [1]: ADJ = {}
        """
        SRRXG
        RXXRX
        RRRXR
        XXRRR
        RRRRX
        """
        ADJ['S'] = ['2', '6']
        ADJ['2'] = ['S', '3']
        ADJ['3'] = ['2', '8']
        ADJ['G'] = ['10']
        ADJ['6'] = ['S', '11']
        ADJ['8'] = ['3', '13']
        ADJ['10'] = ['G', '15']
        ADJ['11'] = ['6', '12']
        ADJ['12'] = ['11', '13', '17']
        ADJ['13'] = ['8', '12']
        ADJ['15'] = ['10', '20']
        ADJ['17'] = ['12', '22']
        ADJ['19'] = ['20', '24']
        ADJ['20'] = ['15', '19']
        ADJ['21'] = ['22']
        ADJ['22'] = ['17', '21', '23']
        ADJ['23'] = ['22', '24']
        ADJ['24'] = ['19', '23']
        print("adj",ADJ)
        # keep track of visited nodes
        visited = {str(i) : False for i in range(1,26)}
        visited['S'] = False
        visited['G'] = False

        def dls(start, goal,limit):
            depth = 0

            OPEN=[]
            CLOSED=[]
            OPEN.append(start)
            visited["S"] = True
            while OPEN != []: # Step 2
                if depth<=limit:
                    current = OPEN.pop()

                    if current == goal:
                        print("Goal Node Found")
                        return True
                    else:
                        lst = successors(current)
                        for i in lst:
                            # try to visit a node in future, if not already been to it
                            if(not(visited[i])):
                                OPEN.append(i)

                                visited[i] = True
                        depth +=1

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    else:
        print("Not found within depth limit")
        return False
    print(OPEN)
    #print("node visited",i,sep='>',end='\n')
    return False

def successors(city):
    return ADJ[city]

def test():
    start = 'S'
    goal = 'G'
    limit=int(input("ENTER THE DEPTH LIMIT"))
    print("Starting a dls from \n[ " + start+" ]")
    print(dls(start, goal,limit))

if __name__ == "__main__":
    test()

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adj {'S': ['2', '6'], '2': ['S', '3'], '3': ['2', '8'], 'G': ['10'], '6':
['S', '11'], '8': ['3', '13'], '10': ['G', '15'], '11': ['6', '12'], '12':
['11', '13', '17'], '13': ['8', '12'], '15': ['10', '20'], '17': ['12', '2
2'], '19': ['20', '24'], '20': ['15', '19'], '21': ['22'], '22': ['17', '21',
'23'], '23': ['22', '24'], '24': ['19', '23']}

```

ENTER THE DEPTH LIMIT200

Starting a dls from

[S]

['2', '6']

['2', '11']

['2', '12']

['2', '13', '17']

['2', '13', '22']

['2', '13', '21', '23']

['2', '13', '21', '24']

['2', '13', '21', '19']

['2', '13', '21', '20']

['2', '13', '21', '15']

['2', '13', '21', '10']

['2', '13', '21', 'G']

Goal Node Found

True

In []: