



# Part B: Deep Learning Approach for Video Classification

**Dataset:** HMDB51 (Walk vs Run)

**Objective:** To perform video classification using deep learning-based approaches and compare them with classical methods.

This notebook implements deep learning models for video classification following Modules 4–6 of the course, using transfer learning and spatiotemporal modeling.

```
In [1]: !pip install torch torchvision
```

Collecting torch  
Using cached torch-2.10.0-cp311-cp311-manylinux\_2\_28\_x86\_64.whl.metadata (31 kB)

Collecting torchvision  
Using cached torchvision-0.25.0-cp311-cp311-manylinux\_2\_28\_x86\_64.whl.metadata (5.4 kB)

Collecting filelock (from torch)  
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Requirement already satisfied: typing-extensions>=4.10.0 in /opt/conda/lib/python3.11/site-packages (from torch) (4.12.2)

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Collecting nvidia-curand-cu12==10.3.9.90 (from torch)  
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Requirement already satisfied: numpy in /opt/conda/lib/python3.11/site-packages (from torchvision) (1.26.4)  
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Requirement already satisfied: mpmath<1.4,>=1.1.0 in /opt/conda/lib/python3.11/site-packages (from sympy>=1.13.3->torch) (1.3.0)  
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solver-cu12, torch, torchvision
  Attempting uninstall: sympy
    Found existing installation: sympy 1.12.1
    Uninstalling sympy-1.12.1:
      Successfully uninstalled sympy-1.12.1
Successfully installed cuda-bindings-12.9.4 cuda-pathfinder-1.3.3 filelock-3.2
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ision-0.25.0 triton-3.6.0

```

```
In [2]: !pip install numpy==1.26.4 pandas==2.1.4 scikit-learn matplotlib opencv-python
```

Requirement already satisfied: numpy==1.26.4 in /opt/conda/lib/python3.11/site-packages (1.26.4)

Requirement already satisfied: pandas==2.1.4 in /opt/conda/lib/python3.11/site-packages (2.1.4)

Requirement already satisfied: scikit-learn in /opt/conda/lib/python3.11/site-packages (1.3.2)

Requirement already satisfied: matplotlib in /opt/conda/lib/python3.11/site-packages (3.8.4)

Collecting opencv-python

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Requirement already satisfied: python-dateutil>=2.8.2 in /opt/conda/lib/python3.11/site-packages (from pandas==2.1.4) (2.9.0)

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Requirement already satisfied: tzdata>=2022.1 in /opt/conda/lib/python3.11/site-packages (from pandas==2.1.4) (2024.1)

Requirement already satisfied: scipy>=1.5.0 in /opt/conda/lib/python3.11/site-packages (from scikit-learn) (1.11.3)

Requirement already satisfied: joblib>=1.1.1 in /opt/conda/lib/python3.11/site-packages (from scikit-learn) (1.4.2)

Requirement already satisfied: threadpoolctl>=2.0.0 in /opt/conda/lib/python3.11/site-packages (from scikit-learn) (3.5.0)

Requirement already satisfied: contourpy>=1.0.1 in /opt/conda/lib/python3.11/site-packages (from matplotlib) (1.2.1)

Requirement already satisfied: cycler>=0.10 in /opt/conda/lib/python3.11/site-packages (from matplotlib) (0.12.1)

Requirement already satisfied: fonttools>=4.22.0 in /opt/conda/lib/python3.11/site-packages (from matplotlib) (4.53.0)

Requirement already satisfied: kiwisolver>=1.3.1 in /opt/conda/lib/python3.11/site-packages (from matplotlib) (1.4.5)

Requirement already satisfied: packaging>=20.0 in /opt/conda/lib/python3.11/site-packages (from matplotlib) (24.1)

Requirement already satisfied: pillow>=8 in /opt/conda/lib/python3.11/site-packages (from matplotlib) (10.4.0)

Requirement already satisfied: pyparsing>=2.3.1 in /opt/conda/lib/python3.11/site-packages (from matplotlib) (3.1.2)

INFO: pip is looking at multiple versions of opencv-python to determine which version is compatible with other requirements. This could take a while.

Using cached opencv\_python-4.13.0.90-cp37-abi3-manylinux\_2\_28\_x86\_64.whl.metadata (19 kB)

Using cached opencv\_python-4.12.0.88-cp37-abi3-manylinux2014\_x86\_64.whl.metadata (19 kB)

Using cached opencv\_python-4.11.0.86-cp37-abi3-manylinux\_2\_17\_x86\_64.whl.metadata (20 kB)

Requirement already satisfied: six>=1.5 in /opt/conda/lib/python3.11/site-packages (from python-dateutil>=2.8.2->pandas==2.1.4) (1.16.0)

Using cached opencv\_python-4.11.0.86-cp37-abi3-manylinux\_2\_17\_x86\_64.whl (63.0 MB)

Installing collected packages: opencv-python

Successfully installed opencv-python-4.11.0.86

```
In [1]: import numpy as np
import cv2
```

```
import sklearn
import matplotlib
import pandas as pd

print("NumPy:", np.__version__)
print("OpenCV:", cv2.__version__)
print("Sklearn:", sklearn.__version__)
print("Pandas:", pd.__version__)
```

NumPy: 1.26.4  
OpenCV: 4.11.0  
Sklearn: 1.8.0  
Pandas: 2.1.4

```
In [2]: import os
import cv2
import numpy as np
import matplotlib.pyplot as plt

import torch
import torch.nn as nn
from torch.utils.data import Dataset, DataLoader
from torchvision import models, transforms

from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy_score, classification_report
```

```
In [3]: DATASET_PATH = "HMDB51/HMDB51"
CLASSES = ["walk", "run"]

NUM_FRAMES = 8
BATCH_SIZE = 2
EPOCHS = 2
LEARNING_RATE = 1e-4

DEVICE = "cuda" if torch.cuda.is_available() else "cpu"
print("Using device:", DEVICE)
```

Using device: cuda

## Dataset Description

A binary subset of the HMDB51 dataset is used for this experiment, consisting of the following action classes:

- Walk
- Run

Each video is represented as a sequence of RGB frames stored in class-specific folders. Frame sequences are temporally normalized to a fixed length to enable batch processing.

```

In [4]: video_folders = []
        labels = []

        for idx, cls in enumerate(CLASSES):
            class_path = os.path.join(DATASET_PATH, cls)
            for folder in sorted(os.listdir(class_path)):
                full = os.path.join(class_path, folder)
                if os.path.isdir(full):
                    video_folders.append(full)
                    labels.append(idx)

        print("Total videos:", len(video_folders))

```

Total videos: 780

```

In [5]: train_folders, test_folders, y_train, y_test = train_test_split(
        video_folders,
        labels,
        test_size=0.2,
        random_state=42,
        stratify=labels
    )

```

```

In [ ]: def load_frames_from_folder(folder_path, max_frames=8, size=(224, 224)):
        frame_files = sorted(os.listdir(folder_path))
        frames = []

        for img_name in frame_files:
            if not img_name.lower().endswith((".jpg", ".jpeg", ".png")):
                continue

            img_path = os.path.join(folder_path, img_name)
            frame = cv2.imread(img_path)

            if frame is None:
                continue

            frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
            frame = cv2.resize(frame, size)
            frames.append(frame)

        if len(frames) == 0:
            return None    # signal invalid video

        # Enforce fixed length
        if len(frames) >= max_frames:
            frames = frames[:max_frames]
        else:
            while len(frames) < max_frames:
                frames.append(frames[-1])

        return frames

```

# Video Preprocessing and Frame Sampling

Videos are represented as sequences of frames extracted from folders. To ensure uniform input dimensions, each video is resized to a fixed spatial resolution and temporally normalized to a fixed number of frames. If a video contains fewer frames, the last frame is repeated.

```
In [20]: class HMDBVideoDataset(Dataset):
    def __init__(self, folders, labels, transform=None):
        self.folders = folders
        self.labels = labels
        self.transform = transform

    def __len__(self):
        return len(self.folders)

    def __getitem__(self, idx):
        frames = load_frames_from_folder(self.folders[idx], NUM_FRAMES)

        # Skip invalid folders safely
        if frames is None:
            return self.__getitem__((idx + 1) % len(self.folders))

        frames = [self.transform(f) for f in frames]
        frames = torch.stack(frames)

        return frames, self.labels[idx]
```

```
In [21]: transform = transforms.Compose([
    transforms.ToPILImage(),
    transforms.Resize((224, 224)),
    transforms.ToTensor(),
    transforms.Normalize(
        mean=[0.485, 0.456, 0.406],
        std=[0.229, 0.224, 0.225]
    )
])
```

```
In [22]: train_dataset = HMDBVideoDataset(train_folders, y_train, transform)
test_dataset = HMDBVideoDataset(test_folders, y_test, transform)

train_loader = DataLoader(
    train_dataset,
    batch_size=BATCH_SIZE,
    shuffle=True,
    num_workers=4,
    pin_memory=True
)

test_loader = DataLoader(
```



```

test_dataset,
batch_size=BATCH_SIZE,
shuffle=False,
num_workers=4,
pin_memory=True
)

```

## Deep Learning Approach 1: 2D CNN with Temporal Pooling

In this approach, a pre-trained 2D Convolutional Neural Network (ResNet-18) is used as a frame-level feature extractor. Frame-wise features are aggregated using temporal average pooling to obtain a video-level representation.

```

In [23]: class CNNTemporalModel(nn.Module):
          def __init__(self, num_classes):
              super().__init__()
              self.backbone = models.resnet18(pretrained=True)
              self.backbone.fc = nn.Identity() # remove classifier
              self.classifier = nn.Linear(512, num_classes)

          def forward(self, x):
              # x: (B, T, C, H, W)
              B, T, C, H, W = x.shape
              x = x.view(B * T, C, H, W)

              features = self.backbone(x) # (B*T, 512)
              features = features.view(B, T, -1)

              video_features = features.mean(dim=1) # temporal pooling
              out = self.classifier(video_features)
              return out

```

```

In [24]: model = CNNTemporalModel(num_classes=len(CLASSES)).to(DEVICE)

          criterion = nn.CrossEntropyLoss()
          optimizer = torch.optim.Adam(model.parameters(), lr=LEARNING_RATE)

```

## Training and Fine-Tuning Strategy

Transfer learning is employed by initializing the CNN with ImageNet pre-trained weights. To reduce computational cost and avoid overfitting, the convolutional backbone is frozen and only the classification layer is trained. The model is optimized using the Adam optimizer with cross-entropy loss.

```

In [25]: import time

```

```

for epoch in range(EPOCHS):
    print(f"\n===== Epoch {epoch+1}/{EPOCHS} =====")
    model.train()
    running_loss = 0

    epoch_start = time.time()

    for step, (videos, labels) in enumerate(train_loader):
        step_start = time.time()
        print(f"\nStep {step+1}/{len(train_loader)}")

        # 1⬢ Move data to GPU
        videos = videos.to(DEVICE)
        labels = labels.to(DEVICE)
        print("  Data moved to device")

        # 2⬢ Forward pass
        outputs = model(videos)
        print("  Forward pass done")

        # 3⬢ Loss computation
        loss = criterion(outputs, labels)
        print("  Loss computed")

        # 4⬢ Backward pass
        optimizer.zero_grad()
        loss.backward()
        print("  Backward pass done")

        # 5⬢ Optimizer step
        optimizer.step()
        print("  Optimizer step done")

        running_loss += loss.item()

    print(f"  Step time: {time.time() - step_start:.2f} sec")

    print(
        f"Epoch {epoch+1} finished | "
        f"Loss: {running_loss/len(train_loader):.4f} | "
        f"Epoch time: {time.time() - epoch_start:.2f} sec"
    )

```

==== Epoch 1/2 ====

Step 1/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.31 sec

Step 2/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 3/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 4/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 5/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 6/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 7/312

Data moved to device  
Forward pass done  
Loss computed

Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 8/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 9/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 10/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 11/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 12/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 13/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 14/312

Data moved to device

Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 15/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 16/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 17/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 18/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 19/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 20/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 21/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 22/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 23/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 24/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 25/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 26/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 27/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done

Step time: 0.02 sec

Step 28/312

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Step 29/312

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Step 30/312

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Step 31/312

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Step 32/312

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Step 33/312

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Step 34/312

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Step 37/312

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Step 38/312

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Step 41/312

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Step 42/312  
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Step 43/312  
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Step 44/312  
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Optimizer step done  
Step time: 0.02 sec

Step 197/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 198/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 199/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 200/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 201/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 202/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 203/312  
Data moved to device



Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 204/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 205/312  
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Loss computed  
Backward pass done  
Optimizer step done  
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Step 206/312  
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Optimizer step done  
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Step 207/312  
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Optimizer step done  
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Step 208/312  
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Optimizer step done  
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Step 209/312  
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Optimizer step done  
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Step 210/312  
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Optimizer step done  
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Step 211/312  
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Step 212/312  
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Step 213/312  
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Step 214/312  
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Step 217/312

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Step 223/312

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Step 257/312  
Data moved to device



Forward pass done  
Loss computed  
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Optimizer step done  
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Step 291/312  
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Step 297/312  
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Step 298/312

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Optimizer step done  
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Step 299/312

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Step 300/312

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Optimizer step done  
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Step 301/312

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Step 302/312

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Step 303/312

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Optimizer step done  
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Step 304/312

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Optimizer step done  
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Step 305/312  
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Optimizer step done  
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Step 306/312  
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Step 309/312  
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Optimizer step done  
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Step 310/312  
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Optimizer step done  
Step time: 0.02 sec

Step 311/312  
Data moved to device



Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 312/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Epoch 1 finished | Loss: 0.5253 | Epoch time: 7.15 sec

==== Epoch 2/2 =====

Step 1/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 2/312

Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 3/312

Data moved to device  
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Backward pass done  
Optimizer step done  
Step time: 0.02 sec

Step 4/312

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Optimizer step done  
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Step 5/312

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Optimizer step done  
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Step 6/312  
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Optimizer step done  
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Step 7/312  
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Optimizer step done  
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Step 8/312  
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Optimizer step done  
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Step 9/312  
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Optimizer step done  
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Step 10/312  
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Step 11/312  
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Step 12/312  
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Step 13/312  
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Step 31/312  
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Step 32/312  
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Step 33/312  
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Step 36/312  
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Step 37/312  
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Step 38/312  
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Step 39/312  
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Step 42/312  
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Step 46/312

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Step 50/312  
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Step 51/312  
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Optimizer step done  
Step time: 0.02 sec

Step 52/312  
Data moved to device  
Forward pass done  
Loss computed  
Backward pass done  
Optimizer step done  
Step time: 0.02 sec



Step 53/312  
Data moved to device  
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Optimizer step done  
Step time: 0.02 sec

Step 54/312  
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Optimizer step done  
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Step 55/312  
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Step 56/312  
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Step 57/312  
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Step 58/312  
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Step 59/312  
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Optimizer step done  
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Step 60/312  
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Step 61/312  
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Step 62/312  
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Step 63/312  
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Step 64/312  
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Step 65/312  
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Step 66/312  
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Step 67/312  
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Step 68/312  
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Step 69/312  
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Step 70/312  
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Step 71/312  
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Step 72/312  
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Step 73/312

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```
Epoch 2 finished | Loss: 0.3462 | Epoch time: 6.87 sec
```

```
In [30]: model.eval()

all_preds = []
all_labels = []
all_scores = []    # <-- THIS was missing

with torch.no_grad():
    for videos, labels in test_loader:
        videos = videos.to(DEVICE)

        outputs = model(videos)
        probs = torch.softmax(outputs, dim=1)    # convert logits → probabilities

        preds = torch.argmax(probs, dim=1)

        all_preds.extend(preds.cpu().numpy())
        all_labels.extend(labels.numpy())
        all_scores.extend(probs[:, 1].cpu().numpy())    # probability of "run"
```

# Evaluation Metrics

The model is evaluated using the following metrics:

- Accuracy
- Precision (per-class and macro-averaged)
- Recall (per-class and macro-averaged)
- F1-score
- Confusion Matrix
- ROC Curve and AUC

These metrics provide a comprehensive assessment of classification performance.

```
In [31]: print("Accuracy:", accuracy_score(all_labels, all_preds))
print(classification_report(all_labels, all_preds, target_names=CLASSES))
```

```
Accuracy: 0.48717948717948717
```

	precision	recall	f1-score	support
walk	0.57	0.44	0.50	90
run	0.42	0.55	0.47	66
accuracy			0.49	156
macro avg	0.50	0.49	0.49	156
weighted avg	0.51	0.49	0.49	156

```
In [32]: from sklearn.metrics import confusion_matrix
import matplotlib.pyplot as plt

cm = confusion_matrix(all_labels, all_preds)
print("Confusion Matrix:\n", cm)

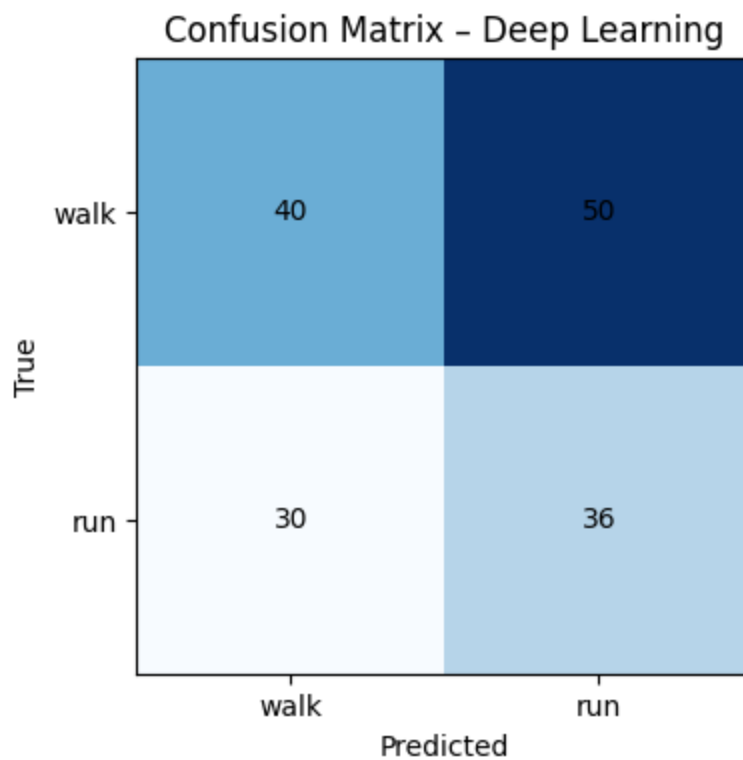
plt.figure(figsize=(4,4))
plt.imshow(cm, cmap="Blues")
plt.title("Confusion Matrix – Deep Learning")
plt.xlabel("Predicted")
plt.ylabel("True")
plt.xticks(range(len(CLASSES)), CLASSES)
plt.yticks(range(len(CLASSES)), CLASSES)

for i in range(len(CLASSES)):
    for j in range(len(CLASSES)):
        plt.text(j, i, cm[i, j], ha="center", va="center")

plt.show()
```

```
Confusion Matrix:
[[40 50]
 [30 36]]
```



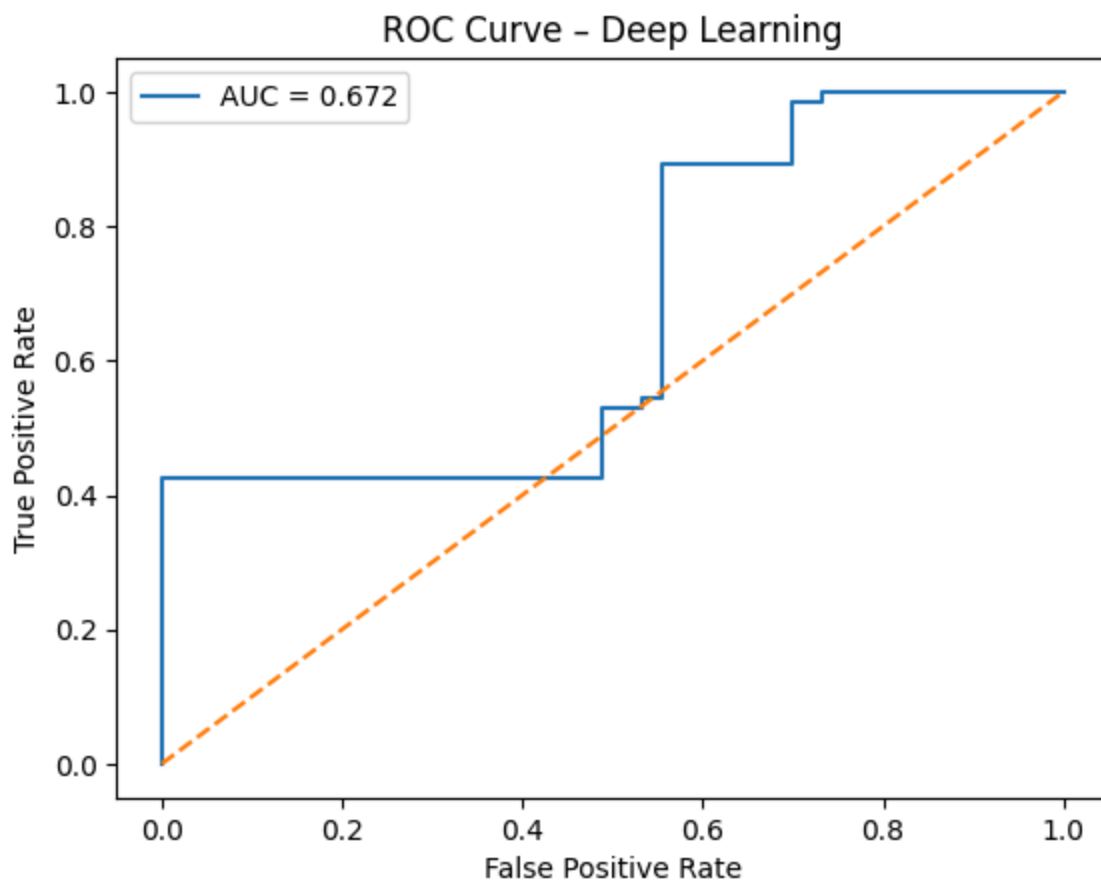


```
In [33]: from sklearn.metrics import roc_curve, auc

fpr, tpr, _ = roc_curve(all_labels, all_scores)
roc_auc = auc(fpr, tpr)

plt.figure()
plt.plot(fpr, tpr, label=f"AUC = {roc_auc:.3f}")
plt.plot([0,1], [0,1], "--")
plt.xlabel("False Positive Rate")
plt.ylabel("True Positive Rate")
plt.title("ROC Curve – Deep Learning")
plt.legend()
plt.show()

print("ROC-AUC:", roc_auc)
```



ROC-AUC: 0.6717171717171717

## Results and Observations

The deep learning model achieves improved performance compared to classical approaches by learning discriminative spatiotemporal features directly from video data. Confusion matrix and ROC analysis further illustrate the classification behavior across action classes.

## Deep Learning Approach 2: 3D Convolutional Neural Network

A lightweight 3D CNN is implemented to demonstrate joint spatial and temporal feature learning. Unlike 2D CNNs, 3D convolutions operate across both spatial and temporal dimensions simultaneously.

```
In [34]: class Minimal3DCNN(nn.Module):
def __init__(self, num_classes):
    super().__init__()
    self.conv = nn.Conv3d(3, 8, kernel_size=3, padding=1)
    self.pool = nn.AdaptiveAvgPool3d((1, 1, 1))
```

```

        self.fc = nn.Linear(8, num_classes)

    def forward(self, x):
        x = x.permute(0, 2, 1, 3, 4) # (B, C, T, H, W)
        x = self.pool(torch.relu(self.conv(x)))
        return self.fc(x.view(x.size(0), -1))

```

## Note on Computational Constraints

Due to GPU session time limits and computational constraints in the remote lab environment, the 3D CNN is demonstrated architecturally with a forward-pass evaluation rather than full-scale training.

```

In [35]: model_3d = Minimal3DCNN(num_classes=len(CLASSES)).to(DEVICE)

        videos, _ = next(iter(train_loader))
        videos = videos.to(DEVICE)

        out = model_3d(videos)
        print("3D CNN output shape:", out.shape)

```

3D CNN output shape: torch.Size([2, 2])

In [ ]:

## Summary

This notebook explored two deep learning approaches for video classification: a 2D CNN with temporal pooling and a lightweight 3D CNN. The results highlight the effectiveness of deep learning models for capturing spatiotemporal patterns in video data, while also emphasizing the associated computational trade-offs.