## Program File:

//These lines are defining symbolic names for various GPIO pins on the ESP32 board. These names //are used to make the code more readable and maintainable.

#define D\_23\_SDA 23

#define D\_22\_SCL 22

#define D\_25\_A28 25

#define D\_26\_A29 26

#define D\_27\_A27 27

#define TX\_0 01

#define RX\_0 03

#define D\_21 21

#define D\_19 19

#define D\_18 18

#define D\_05 05

#define TX\_2 17

#define RX\_2 16

#define D\_04\_A20 04

#define D\_02\_A22 02

#define D\_15\_A23 15

#define D\_12\_A25 12

#define D\_13\_A24 13

#define D\_14\_A26 14

#define V\_P\_A10 36

#define V\_N\_A13 39

#define D\_32\_A14 32

#define D\_33\_A15 33

#define D\_34\_A16 34

#define D\_35\_A17 35

```
//These lines define Blynk configuration settings such as the template ID, template name, and authentication token. It also includes necessary libraries for WiFi communication and Blynk integration.//
```

```
#define BLYNK_TEMPLATE_ID "TMPL3Qoacc5-c"
#define BLYNK_TEMPLATE_NAME "iot based wireless vehicle charging station"
#define BLYNK_AUTH_TOKEN "oOMXRVMxN-dwV3ajowRUfkqk1hZtmGdo"
#define BLYNK_PRINT Serial
#include <WiFi.h>
#include <WiFiClient.h>
//#include <ESP32WiFi.h>
#include <BlynkSimpleEsp32.h>
// Variables for Blynk authentication and WiFi credentials are declared.
char auth[] = BLYNK_AUTH_TOKEN;
char ssid[] = "BestProject";
char pass[] = "12345678";
//Variables sense_2 and sense_4 are defined to represent the GPIO pins connected to sensors for
detecting vehicles at two different spots.
int sense_2 = 15, Ir;
int sense_4 = 4, Ir2;
/*
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 16, 2); //sometimes the LCD adress is not 0x3f. Change to 0x27 if it
dosn't work.
```

\*/

```
//This line includes the LiquidCrystal library for controlling LCD displays and initializes
an instance of the LiquidCrystal class for the LCD display connected to specific GPIO
pins.//
#include <LiquidCrystal.h>
LiquidCrystal lcd(D_05, D_18, D_19, D_21, D_22_SCL, D_23_SDA);
        (RS, E, D4, D5, D6, D7)
int p = 0;
int val;
//These lines define symbolic names for PWM pins used to control the charging
mechanisms for the two spots.//
#define PWM_12 12
#define PWM_13 13
int brightness = 0; // how bright the PWM_12 is
int fadeAmount = 10; // how many points to fade the PWM_12 by
int frequency = 10000;
bool charge_flag_1 = 0, charge_flag_2 = 0;
WidgetLED S_S1(V3); WidgetLED S_S2(V4);
BLYNK_WRITE(V1)
{
 int v1 = param.asInt();
```

//Flags to indicate whether charging is requested for spot 1 and spot 2 are initialized.

if (v1 == 1) {

charge\_flag\_1 = 1;

```
}
else {
  charge_flag_1 = 0;
}
}
BLYNK_WRITE(V2)
{
int v2 = param.asInt();
if (v2 == 1) {
  charge_flag_2 = 1;
}
 else {
  charge_flag_2 = 0;
}
}
void setup()
{
 pinMode(PWM_12, OUTPUT);
```

```
pinMode(PWM_13, OUTPUT);
 // lcd.init();
                      //Init the LCD
 // lcd.backlight();
                         //Activate backlight
 lcd.begin(16, 2);
 // Serial.begin(9600);
 pinMode(sense_2, INPUT);
 pinMode(sense_4, INPUT);
 // pinMode(D_26_A29, INPUT);
 Blynk.begin(auth, ssid, pass);
#define scrollength 40
 for (int i = scrollength; i > 15; i--)
 {
  lcd.clear();
  delay(70);
  lcd.setCursor(i, 1); lcd.print("
                                   wireless vehicle charging station");
  delay(50);
 }
}
```

```
void loop()
{
 lcd.setCursor(0, 0); lcd.print("Spot1 Spot2");
 ///////// Spot 1 ///////////
 if (digitalRead(sense_2) == LOW)
{
  S_S1.on();
  if (charge_flag_2 == 1)
 {
   lcd.setCursor(0, 1); lcd.print("Charge");
   analogWrite(PWM_13, 110);
  }
  else
  {
   lcd.setCursor(0, 1); lcd.print(" OFF ");
   analogWrite(PWM_13, 0);
```

```
}
}
else
{
 lcd.setCursor(0, 1); lcd.print(" OFF ");
 analogWrite(PWM_13, 0);
 S_S1.off();
}
///////// Spot 2 ////////////
if (digitalRead(sense_4) == LOW)
{
 S_S2.on();
 if (charge_flag_1 == 1 )
```

```
{
  lcd.setCursor(10, 1); lcd.print("Charge");
  analogWrite(PWM_12, 110);
 }
 else
 {
  lcd.setCursor(10, 1); lcd.print(" OFF ");
  analogWrite(PWM_12, 0);
 }
}
else
{
 lcd.setCursor(10, 1);
 lcd.print(" OFF ");
 analogWrite(PWM_12, 0);
```

```
S_S2.off();
}
}
```