

## Stability of an algorithm-

- The meaning of  $O(\epsilon_{\text{mach}})$  The notation  $\varphi(t) = O(\psi(t))$  asserts that  $\exists$  some positive constant  $C$  such that for all  $t$  close to some understood limit (such as  $t \rightarrow 0$  or  $t \rightarrow \infty$ )  
 $|P(t)| \leq C \cdot |\psi(t)|.$   
 (It is important to note that  $C$  is a uniform constant which works for all  $t$ .)

Thus, when we write

$$\| \text{term} \| = O(\epsilon_{\text{mach}})$$

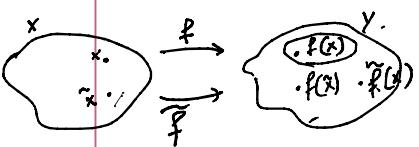
we mean that  $\exists$  some tre constant  $C$  s.t.

$$\| \text{term} \| \leq C \cdot \epsilon_{\text{mach}}.$$

- An algorithm can be viewed as a function  $\tilde{f}: X \rightarrow Y$  where  $X$  &  $Y$  are normed v.s. of data & solutions respectively.  
 ( $f: X \rightarrow Y$  is the problem under consideration)

Defn: An algorithm  $\tilde{f}$  is said to be accurate if

rel. error  
in computation using  $\tilde{f}$  → 
$$\frac{\| f(x) - \tilde{f}(x) \|}{\| f(x) \|} = O(\epsilon_{\text{mach}}).$$



Defn: An algorithm  $\tilde{f}$  is said to be stable (forward stable) if for every  $x \in X$ ,

$$\frac{\|\tilde{f}(x) - f(\tilde{x})\|}{\|f(\tilde{x})\|} = \Theta(\epsilon_{mach}) \text{ for some } \tilde{x}$$

with  $\frac{\|x - \tilde{x}\|}{\|x\|} = \Theta(\epsilon_{mach})$

\* i.e.  $\tilde{f}$  gives nearly the right answer to nearly the right question.

$\tilde{x}$  is a slight perturbation in  $x$ .

Defn: An algorithm is said to be backward stable if

for every  $x \in X$ ,  $\tilde{f}(x) = f(\tilde{x})$  for some  $\tilde{x}$  with

$$\frac{\|x - \tilde{x}\|}{\|x\|} = \Theta(\epsilon_{mach}).$$

i.e. a backward stable algorithm gives the right answer to nearly the right question.

Note: ① Backward stability  $\Rightarrow$  forward stability

② Backward error analysis is easier to carry out.

Some examples -

① Subtraction :  $f(x_1, x_2) = x_1 - x_2$ .  $\leftarrow$  by hand.

$\tilde{f}(x_1, x_2) = fl(x_1) \ominus fl(x_2)$   $\leftarrow$  computer

(i)  $fl(x_1) = x_1(1 + \epsilon_1)$  &  $fl(x_2) = x_2(1 + \epsilon_2)$

(from fund. ppty. of fl. pt. repr.) where  $|\epsilon_1| \& |\epsilon_2| \leq \epsilon_{mach}$ .

(ii)  $fl(x_1) \ominus fl(x_2) = (fl(x_1) - fl(x_2))(1 + \epsilon_3)$ ,

(fund. ppty. of fl. pt. arithmetic) where  $|\epsilon_3| \leq \epsilon_{mach}$ .

Putting these together:

$$\begin{aligned}
 \tilde{f}(x_1, x_2) &= f_1(x_1) - f_1(x_2) = (x_1(1+\varepsilon_1) - x_2(1+\varepsilon_2))(1+\varepsilon_3) \\
 &= x_1(1+\varepsilon_1)(1+\varepsilon_3) - x_2(1+\varepsilon_2)(1+\varepsilon_3) \\
 &\quad \underbrace{1+\varepsilon_1+\varepsilon_3+\varepsilon_1\varepsilon_3}_{\leq 2\varepsilon_{\text{mach}} + \varepsilon_{\text{mach}}^2} \quad \underbrace{1+\varepsilon_2+\varepsilon_3+\varepsilon_2\varepsilon_3}_{\leq 2\varepsilon_{\text{mach}} + \varepsilon_{\text{mach}}^2} \\
 &= \underbrace{x_1(1+\varepsilon_4)}_{\tilde{x}_1} - \underbrace{x_2(1+\varepsilon_5)}_{\tilde{x}_2} = \tilde{x}_1 - \tilde{x}_2 \\
 &\text{where } |\varepsilon_4|, |\varepsilon_5| \leq 2\varepsilon_{\text{mach}} + \varepsilon_{\text{mach}}^2 = \tilde{f}(\tilde{x}_1, \tilde{x}_2)
 \end{aligned}$$

The computed result =  $\tilde{x}_1 - \tilde{x}_2$ , where  $\frac{|\tilde{x}_1 - x_1|}{|x_1|} = \Theta(\varepsilon_{\text{mach}})$

$\therefore$  Subtraction is backward stable.

$$\frac{|\tilde{x}_2 - x_2|}{|x_2|} = \Theta(\varepsilon_{\text{mach}}).$$

② Inner product:- can show that for vectors  $x, y \in \mathbb{C}^m$ ,

$\alpha = x^*y$  is backward stable.

(forward)

③ Outer product - is stable but not backward stable.

$$x, y \in \mathbb{C}^m, f(x, y) = xy^* = A.$$

$$\begin{pmatrix} \vdots & \vdots \\ x & y^* \end{pmatrix} = \begin{pmatrix} \cdot & \cdot \\ \vdots & \vdots \end{pmatrix}$$



$$(x + \delta x)(y + \delta y)^* \leftarrow \tilde{A}$$

④ Example 15.4 , page 110 T-B. \*

\* ⑤ An unstable algorithm - page 110, T-B.

Accuracy of a backward stable algorithm. (floating pt. error analysis.)

What can be said about the accuracy of a backward stable algorithm?

Theorem: Suppose a backward stable algorithm is applied to solve a problem  $f: X \rightarrow Y$  with condition number  $K$  on a computer that satisfies the fund. prop. of fl. pt. repr. & fl. pt. arithmetic. Then the relative errors satisfy -

$$\frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|} = O(K(x) \cdot \epsilon_{\text{mach}})$$

Proof: By defn. of backward stability,  $\tilde{f}(x) = f(\tilde{x})$  for some  $\tilde{x} \in X$  s.t.  $\frac{\|\tilde{x} - x\|}{\|x\|} = O(\epsilon_{\text{mach}})$ .

Recall,  $K(x) = \sup_{\delta x \neq 0} \left( \frac{\|sf\| / \|f(x)\|}{\|\delta x\| / \|x\|} \right)$  take  $\delta x = \tilde{x} - x$ .

$$K(x) \geq \frac{\|f(\tilde{x}) - f(x)\|}{\|f(x)\|} \quad / \quad \frac{\|\tilde{x} - x\|}{\|x\|}$$

$f(\tilde{x}) = \tilde{f}(x)$

$$\therefore \frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|} \leq O(K(x) \cdot \epsilon_{\text{mach}}).$$

Thus, if an alg. is backward stable, then the accuracy of the answer depends on the condition number at  $x$ .

Work involved in an algorithm.

flops. / cost of moving the data      cost of storing the data

G-L : 1.2.1 - 1.2.7  
1.1.10 - 1.1.17  
1.4 & 1.5

- communication - avoidance  
- updation -

BLAS - basic lin-alg. subroutines  
"levels"  
LA PACK library.

level 1 - saxpy : scalar  $\alpha$  times  $x$  plus  $y$ , ( $x, y$  vectors)

BLAS.

$$\alpha \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} + \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

$2n$ .

$$y = \alpha x + y. \quad (\text{update form})$$

level 2 - gaxpy : generalized saxpy -  $A$  is a matrix.

BLAS.

$$y = Ax + y.$$

$\Theta(mn)$ .

$mn + m + n$ .

level 3 - matrix-matrix multi.

BLAS.

	data	work	
level - 1	$\Theta(n)$ linear	$\Theta(n)$ linear	
level - 2	$\Theta(mn)$ quadratic	$\Theta(mn)$ quadratic	$m \times r$ $r \times n$
level - 3	$\Theta(mn)$ quadratic	$\Theta(mnr)$ cubic.	how many flops reqd. for multi. 2 matrices.