

view_frames Result
Recorded at time: 5024.44

odom

Broadcaster: /ekf localization
Average rate: 42.169
Buffer length: 4.98
Most recent transform: 5024.4
Oldest transform: 5019.42

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 100.0
Buffer length: 0.02
Most recent transform: 5024.4
Oldest transform: 5024.38

Broadcaster: /robot_state_publisher
Average rate: 100.0
Buffer length: 0.02
Most recent transform: 5024.4
Oldest transform: 5024.38

Broadcaster: /robot_state_publisher
Average rate: 100.0
Buffer length: 0.02
Most recent transform: 5024.4
Oldest transform: 5024.38

Broadcaster: /robot_state_publisher
Average rate: 100.0
Buffer length: 0.02
Most recent transform: 5024.4
Oldest transform: 5024.38

base_footprint

top_plate_link

front_bumper_link

imu_link

inertial_link

rear_bumper_link

top_chassis_link

user_rail_link

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_laser_mount

sensor_arch_mount_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_laser

camera_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

camera_frame_optical