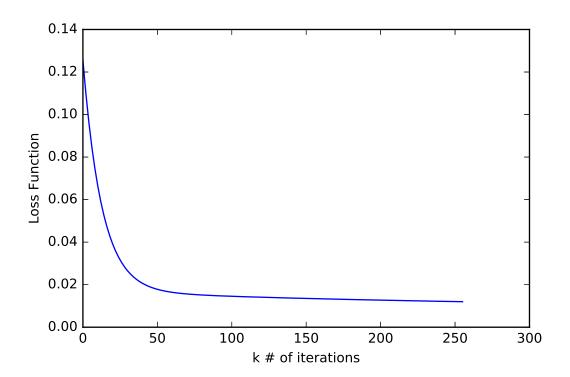
#### Homework 1

#### Answer 1.4:

#### Answer 1:

Plot of loss function  $J_k(\theta)$  VS. number of iterations (k)



## Answer 2:

Average sum of squared errors:

$$\frac{1}{2m} \sum_{i=1}^{m} (y^{(i)} - h_{\theta}(x^{(i)}))^2 = 0.01576348$$

# Answer 3:

$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{2m} g(\theta_j)$$

and,

$$g(\theta_j) = \begin{cases} 1, & \text{if } \theta_j \ge 0 \\ -1, & \theta_j < 0 \end{cases}$$

## Answer 4:

The number of non-zero parameters of ridge (1.2) and lasso (1.3) are 14. Both methods have equal number of non-zero parameters.

# Answer 5: CODE 1.2.py

import matplotlib

import matplotlib.pyplot as plt

```
import numpy as np
data0=np.loadtxt("data.txt", skiprows=19)
colmean = np.min(data0, axis = 0)
datac=data0-colmean
data = datac / (np.ptp(datac,axis=0))
datatr, datats=data[:48,:], data[48:,:]
md=np. size (data, axis=0)
m=np. size (datatr, axis=0)
n=np.size(datatr,axis=1)-1
one=np.ones(m).reshape((m,1))
y=datatr[:,n].reshape((m,1))
XX=datatr[:,1:16].reshape((m,n-1))
X=np.hstack((one,XX))
def dot2(a,b):
        n=np.size(a,axis=0)
        m=np.size(b,axis=1)
        return np.dot(a,b).reshape(n,m)
def dot3(a,b,c):
        \textbf{return} \ \text{np.dot} \, (\, \text{np.dot} \, (\, \text{a} \, , \text{b} \, ) \, , \text{c} \, )
def dot4(a,b,c,d):
        return np.dot(np.dot(a,b), np.dot(c,d))
def inv(a):
        return np.linalg.inv(a)
\mathbf{def} \operatorname{inv2}(a,b):
        return np.linalg.inv(np.dot(a,b))
def loss_fr (beta, X, y, lam):
        m=len(y)
        PT=dot2 (beta.T,X.T)
        eT = v.T - PT
        e2 = dot2(eT, eT.T)
        J=(e2/2/m) + ((lam/2/m)*dot2(beta.T, beta))
        return J
\mathbf{def} \ \mathrm{err} 2 \mathrm{r} (\mathrm{beta} , \mathrm{X}, \mathrm{y}) :
        m=len(y)
        PT=dot2 (beta.T,X.T)
        eT = y.T - PT
        e2 = dot2(eT, eT.T)
        return e^{2}/(2*m)
def rigid (X, y, beta):
        m=len(y)
        delta = []
        betah = [] ### betas ' history
        J0 = []
        ERR = []
        k=1
        d=1
        while d >= epsi:
                 Jold=loss_fr (beta, X, y, lam)
                beta = beta - ((1/m)*alpha*(dot2(X.T,((dot2(X,beta)) - y)))) 
                - (alpha*lam/m)*beta
                Jnew=loss_fr (beta, X, y, lam)
                d=(100*np.abs(Jold-Jnew)/Jold)
```

delta.append(d) betah.append(beta)

J0.append(loss\_fr(beta,X,y,lam)) ERR.append(err2r(beta,X,y))

```
return beta, betah, J0, ERR, delta, k
lam=1
alpha=0.01
epsi=0.1
init = (0+np.zeros(n)).reshape(n,1)
IP=np.identity(n)
beta_ridge=dot2(inv((lam*IP)+dot2(X.T,X)), dot2(X.T,y))
rigid=rigid (X, y, init)
lost = [i[0][0] for i in rigid [2]]
kk = [i \text{ for } i \text{ in range}(rigid[-1])]
fig, ax = plt.subplots()
ax.plot(lost)
ax.set(xlabel='k_#_of_iterations', ylabel='Loss_Function')
fig.savefig("1.2.eps", format="eps")
plt.show()
betasr = [x*0.0 \text{ if } x < 0.005 \text{ else } x \text{ for } x \text{ in } rigid[0]]
\mathbf{print} (n-\mathbf{betasr.count}(0))
one=np.ones(md-m).reshape((md-m,1))
yts=datats[:,n].reshape((md-m,1))
XXts=datats[:,1:16].reshape((md-m,n-1))
Xts=np.hstack((one, XXts))
SL_TS=err2r(np.asarray(rigid[0]), Xts, yts)
print (SL_TS)
CODE 1.3.py
#!/usr/bin/env python3
#_-*- coding: utf-8 -*-
Created on Tue Feb 5 18:41:00 2019
@author: shtabari
import numpy as np
import matplotlib.pyplot as plt
data0=np.loadtxt("data.txt", skiprows=19)
colmean = np.min(data0, axis = 0)
datac=data0-colmean
data = datac / (np.ptp(datac, axis=0))
datatr, datats=data[:48,:], data[48:,:]
md=np. size (data, axis=0)
m=np. size (datatr, axis=0)
n=np.size(datatr,axis=1)-1
one=np.ones(m).reshape((m,1))
y=datatr[:,n].reshape((m,1))
XX=datatr[:,1:16].reshape((m,n-1))
X=np.hstack((one,XX))
```

k += 1

```
def dot2(a,b):
        n=np.size(a,axis=0)
        m=np.size(b,axis=1)
        return np.dot(a,b).reshape(n,m)
def dot3(a,b,c):
        return np.dot(np.dot(a,b),c)
def dot4(a,b,c,d):
        return np.dot(np.dot(a,b), np.dot(c,d))
def inv(a):
        return np.linalg.inv(a)
\mathbf{def} \operatorname{inv2}(a,b):
        return np. linalg.inv(np. dot(a,b))
lam=1
alpha=0.01
epsi=0.1
IP=np.identity(n)
init = (0+np.zeros(n)).reshape(n,1)
def loss_fl(beta,X,y,lam):
        m=len(y)
        PT=dot2 (beta.T,X.T)
        eT = y.T - PT
        e2 = dot2(eT, eT.T)
        J=(e2/2/m) + ((lam/2/m)*np.sum(np.abs(beta)))
        return J
def err21 (beta, X, y):
        m=len(y)
        PT=dot2 (beta.T,X.T)
        eT = y.T - PT
        e2 = dot2(eT, eT.T)
        return e^2/(2*m)
def dl1 (beta):
        dl1=(np.asarray([1 if i >= 0 else -1 for i in beta]))
        return dl1.reshape(np.size(beta),1)
\mathbf{def} \; lasso(X, y, beta):
        m=len(y)
        delta = []
        betah = [] \#\#\# betas 'history
        J0 = []
        ERR = []
        k=1
        d=1
        while d > epsi:
                 Jold=loss_fl(beta,X,y,lam)
                 - ((alpha*lam/m/2)*dl1(beta))
                 J_{\text{new}} = loss_{-}fl \text{ (beta }, X, y, lam)
                 d=(100*np.abs(Jold-Jnew)/Jold)
                 delta.append(d)
                 betah.append(beta)
                 J0.append(loss_fl(beta, X, y, lam))
                 ERR. append (err21 (beta, X, y))
                 k += 1
```

#### Answer 2.1:

We consider that we have n samples at root (D) with  $n_0$  observations from class '0' and  $n_1$  observations for class '1'. Assuming, we split the root at two nodes and if there are  $n_L$  and  $n_R$  observations at left  $(D_L)$  and right  $(D_R)$  nodes with  $n_{0L}$  observations of type '0' and  $n_{1L}$  observations of type '1' with  $n_L = n_{0L} + n_{1L}$  at node  $(D_L)$ . Also,  $n_R = n_0 R + n_1 R$  at node  $D_R$  then

$$I(D) = n \frac{2n_0 n_1}{n}$$

$$I(D_L) = \frac{2n_{0L} n_{1L}}{n_L}$$

$$I(D_R) = \frac{2n_{0R} n_{1R}}{n_R}$$

and the Gini function G is

$$G = I(D) - I(D_L) - I(D_R)$$

# Code:

```
import numpy as np
n = 100
n1 = 60
nL = np.array([50, 30, 80])
n1L = np.array([30, 20, 50])
G = []
def Gini(n,n1,nL,n1L):
    n0L = np.subtract(nL,n1L)
    n0 = np.subtract(n,n1)
    nR = 100 - (nL)
    n1R = n1 - (n1L)
    nOR = nR - n1R
    G = (2*n0*n1)/n - (2*n0L*n1L)/nL - (2*n0R*n1R)/nR
    return G
for i in range(3):
    G.append(Gini(n,n1,nL[i],n1L[i]))
print(G)
```

# Output:

G # Wine, Running, Pizza [0.0, 0.38, 0.5]

Since we have a higher Gini function for pizza (0.5), so the best split is based on 'Pizza'.