

Raspberry Pi for Computer Vision

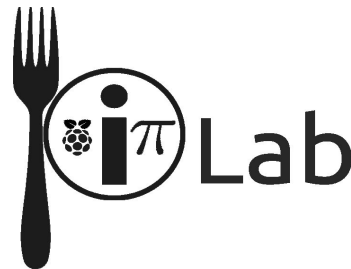
Case: Vein Visualization

PiLab Tutorial

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Shu Isaka

- Graduate Student @ Mie University
 - **Major:**
Electrical & Electronic Engineering
 - **Lab:**
Information Processing Lab
 - **Field of Study:**
Biomedical Informatics.
-

Takumi Kitajima

- Graduate Student @ Mie University.

- **Major:**

Public Health, Epidemiology
(Prev.) Electrical & Electronic Engineering.

- **Lab:**

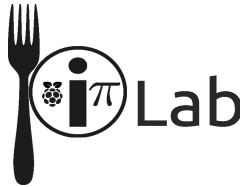
Dept. of Public Health and Occupational Medicine

- **Field of Study:**

Public Health, Epidemiology

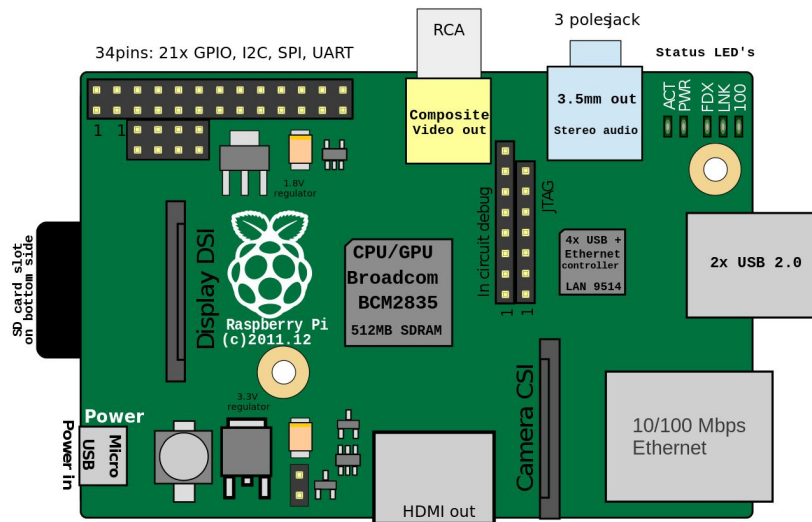
Atsushi Inoue

- Human Centric Computing → Perceptual Information Processing
 - Perceptual Logic Programming (AI platform) & Machine Learning
 - Fuzzy Logic
- Intelligent Informatics Initiative (I3)
 - Digital Entrepreneurship & E-Business
 - Information Security Management
 - Medical Informatics
- PiLab@[EWU](http://www.ewu.ac.jp)
 - Raspberry Pi, LINUX



Raspberry Pi

- Open source
- Small and lean
- Low cost
- **Versatile**
- Similar CPU as Android and iPhone
- **Easy to use**





RASPBERRY PI 3 MODEL B+

The latest revision of our third-generation single-board computer

BUY NOW >

[or buy for business](#)



RASPBERRY PI 3 MODEL B

Our third-generation single-board computer

BUY NOW >

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RASPBERRY PI 2 MODEL B

The Raspberry Pi 2 Model B is the second-generation Raspberry Pi

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RASPBERRY PI 1 MODEL B+

The Model B+ is the final revision of the original Raspberry Pi

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RASPBERRY PI 1 MODEL A+

The Model A+ is the low-cost variant of the Raspberry Pi

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RASPBERRY PI ZERO W

Single-board computer with wireless and Bluetooth connectivity

BUY NOW >



RASPBERRY PI ZERO

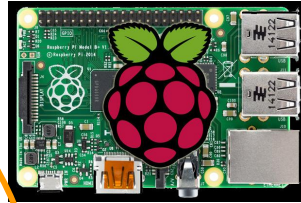
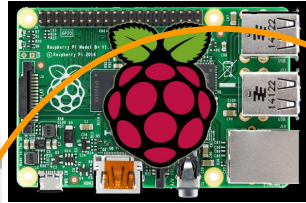
Our lowest-cost single-board computer

BUY NOW >

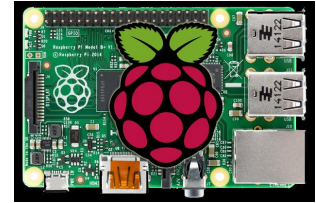
Raspberry Pi (LINUX) Networking & IoT @ Lab



LINUX Workstation



Router, Hotspot



Database, WordPress, etc.



Clients (web, apps, etc.)



Sensor stations



Networking



Servers (database, etc.)



IoT stations

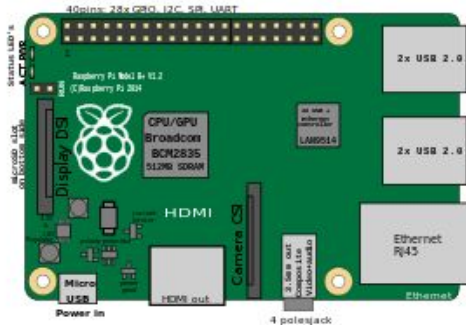
Sidenote: PiLab Setting for DIY -- a variation of headless Pi

ICS connection via Ethernet

USB Ether adapter works when no Ether ports.



Ras Pi System Disk
On micro SD card



Power from the laptop USB



BYOL or cart laptop

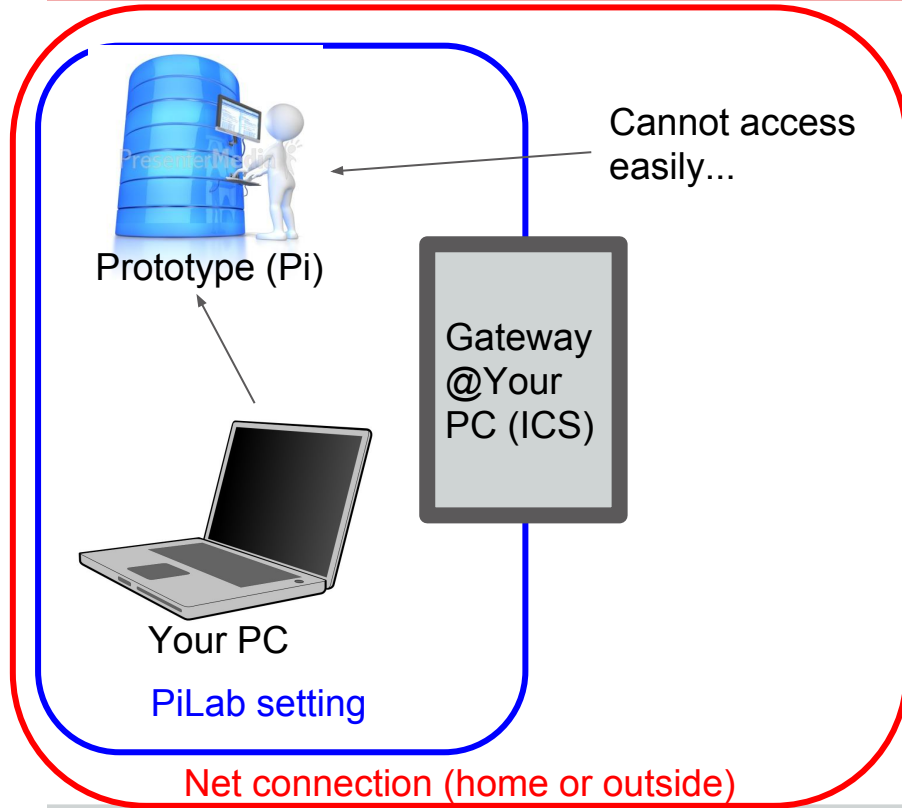


Convenient to have
USB card reader &
USB memory stick

CLI: ssh on laptop + sshd on Pi

GUI: X server or RDP client on laptop + sshd and/or xrdp on Pi

Sidenote: Prototyping individually with high mobility



[1] Download Raspbian OS image

Please start downloading the OS image for Raspberry Pi. It takes 1-30min (faster or slower depending on speed).

Raspbian Stretch With Desktop (with GUI)

ZIP -- 1.7GB (to be downloaded)

Unzip to extract .img file -- a few GB (to be extracted from the downloaded ZIP)

Note for PIXEL: unzipping a file >4GB has issues with an old unzipper. File Explore unfortunately cannot handle this. Use [7ZIP](#) for Windows 7.

SD card imaging (vs file copying)

Imaging -- duplication of the entire drive/disk.

Sudo privilege is required.

Password needs to be entered in many cases.

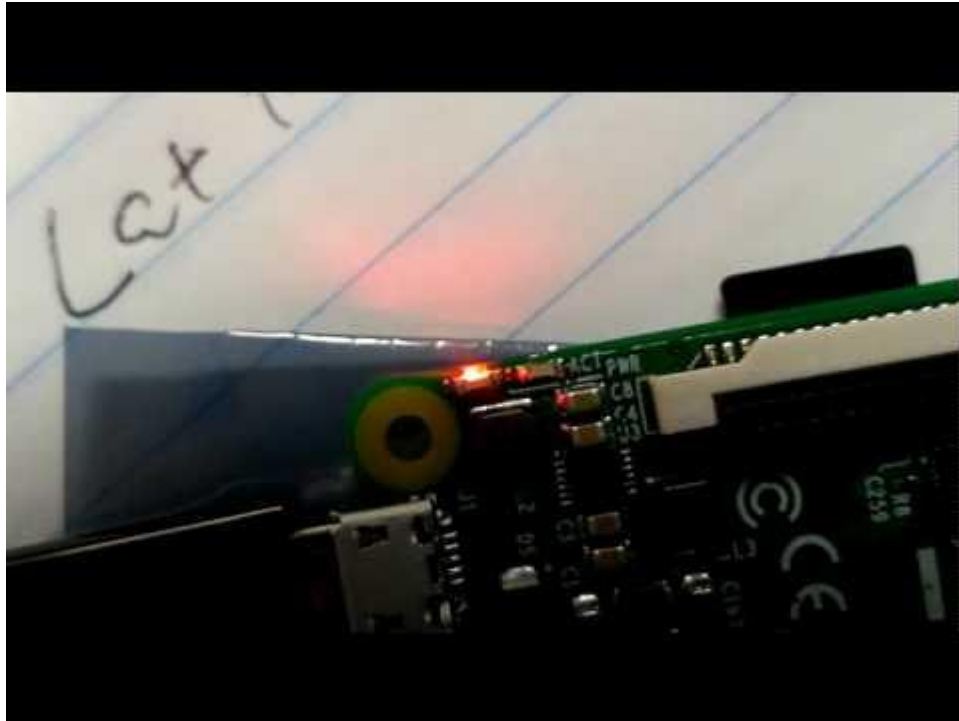
[2] SD card imaging: Etcher

Simply double click to execute Etcher (unzip is necessary for LINUX). NO INSTALLATION PROCESS.



[5] Booting Raspberry Pi

- **Remember:** NO POWER switch on Pi.
Plugging in and out the micro USB power cable.
 - Standard procedure
 1. Insert the micro SD card
 2. Plug in the Ether cable to the laptop and the Pi.
 3. Plug in the micro USB power cable (to power on)
 4. Observe the red LED (power indicator)
This should be steady.
 5. Observe the green LED (disk access indicator).
This should be actively blinking.
-



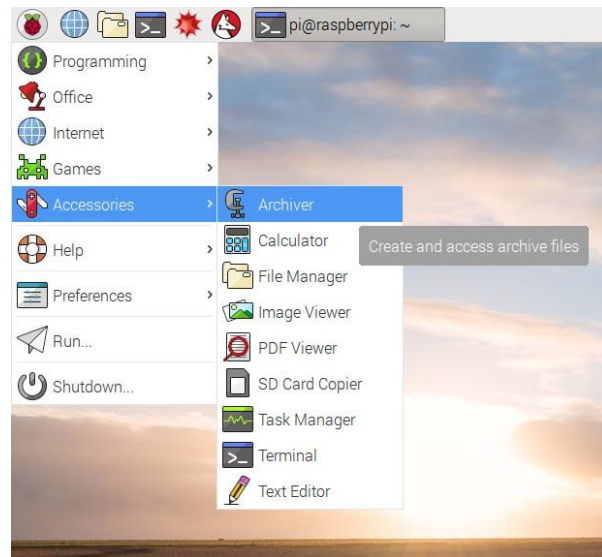
Raspbian OS Housekeeping

- Housekeeping after installation
 - '**raspi-config**' (clock, keyboard, overclocking, fs exp, etc.)
 - Update the OS
 - `sudo apt-get update`
 - `sudo apt-get upgrade -y`
 - `sudo apt-get autoremove -y`
 - `sudo apt-get clean`
 - Full upgrade (inplace of upgrade) -- takes longer
 - `sudo apt-get dist-upgrade -y`

Update after the first installation may take very long -- over 1 hour easily.

Shutdown

- In Bash, SSH
`sudo shutdown -h now`
- On desktop, In RDP
Go to the menu->Shutdown
(Shutdown)



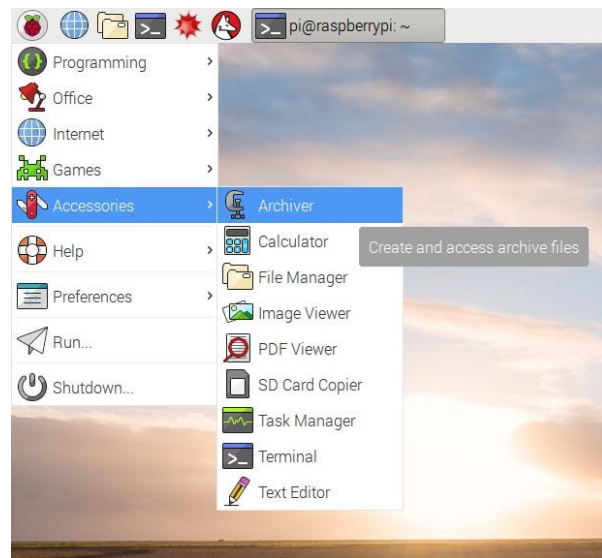
Reboot

- In Bash, SSH

```
sudo shutdown -r now
```

OR

```
sudo reboot
```
- On desktop, In RDP
Go to the menu->Shutdown
(Reboot)



Raspbian is ready!

Enjoy Pi!!

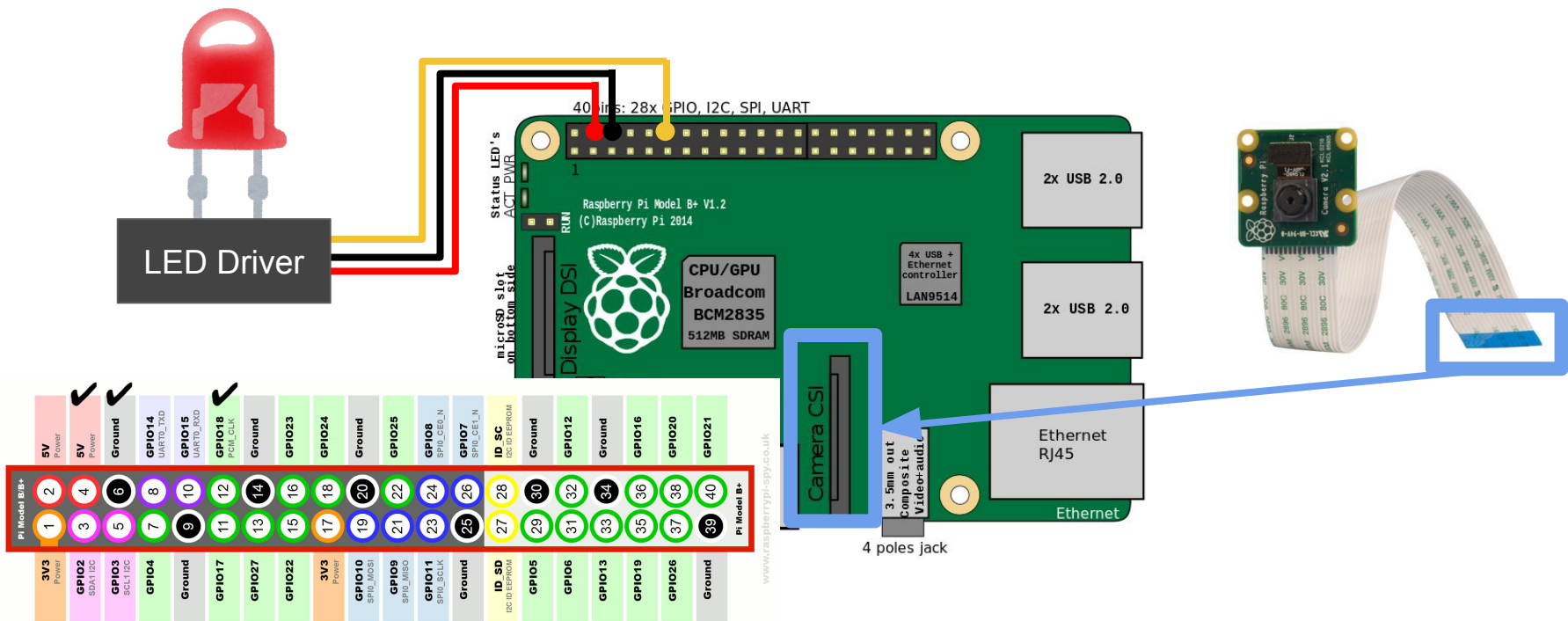


Follow task specific instructions from this point and on.

Image Processing

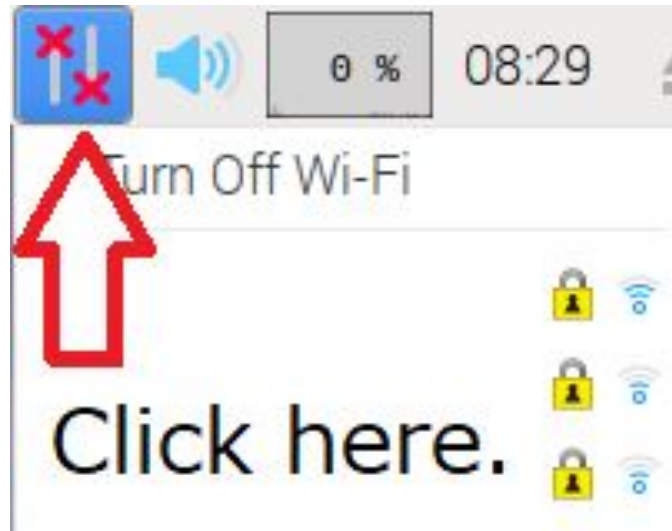
How to install & configure OpenCV
on Raspberry Pi 3 Model B

Connect Devices



Establish WiFi Connection

- ❖ Select the SSID of Kitakyuhsu International Conference Center and input password.



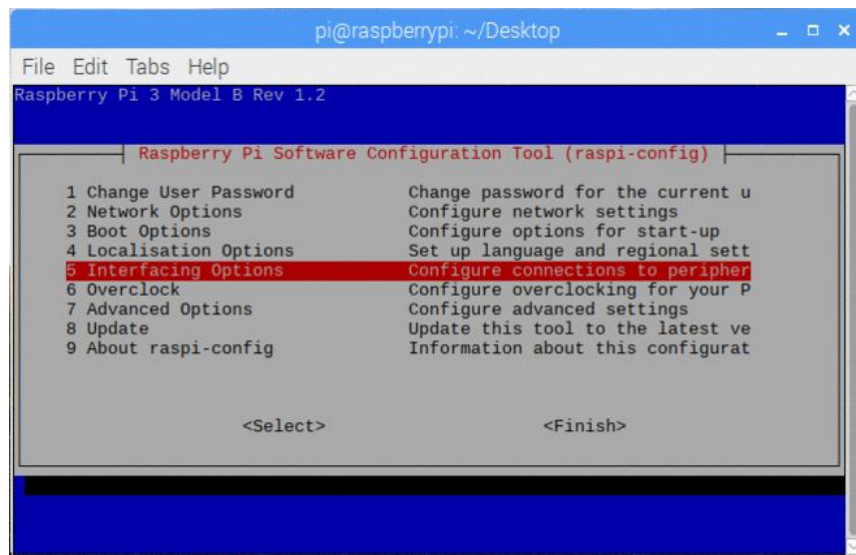
Raspberry Pi Configuration 1/2

- ❖ Open Raspberry Pi Configuration Window with this command.

```
$ sudo raspi-config
```

Raspberry Pi Configuration 2/2

❖ Raspi Camera should be enabled.



❖ After Rebooting, pls check WiFi connection

Install Packages to Raspberry Pi

- ❖ OpenCV (Image Processing Library)
- ❖ Raspberry Pi GPIO Library

```
$ sudo apt-get update  
$ sudo apt-get upgrade  
$ sudo apt-get install libopencv-dev  
$ sudo apt-get install python-opencv  
$ sudo apt-get install python-rpi.gpio
```


Clone our project from GitHub

- ❖ <https://github.com/shu-ramen/VeinVisualizationPi.git>

```
$ cd [somewhere to put project files]
$ git clone
https://github.com/shu-ramen/VeinVisualizationPi.git
$ cd VeinVisualizationPi
```

Run our Vein Visualization System

- ❖ Run our project with these commands.

```
$ cd VeinVisualizationPi  
$ python VeinVisualizer.py
```

Demonstration

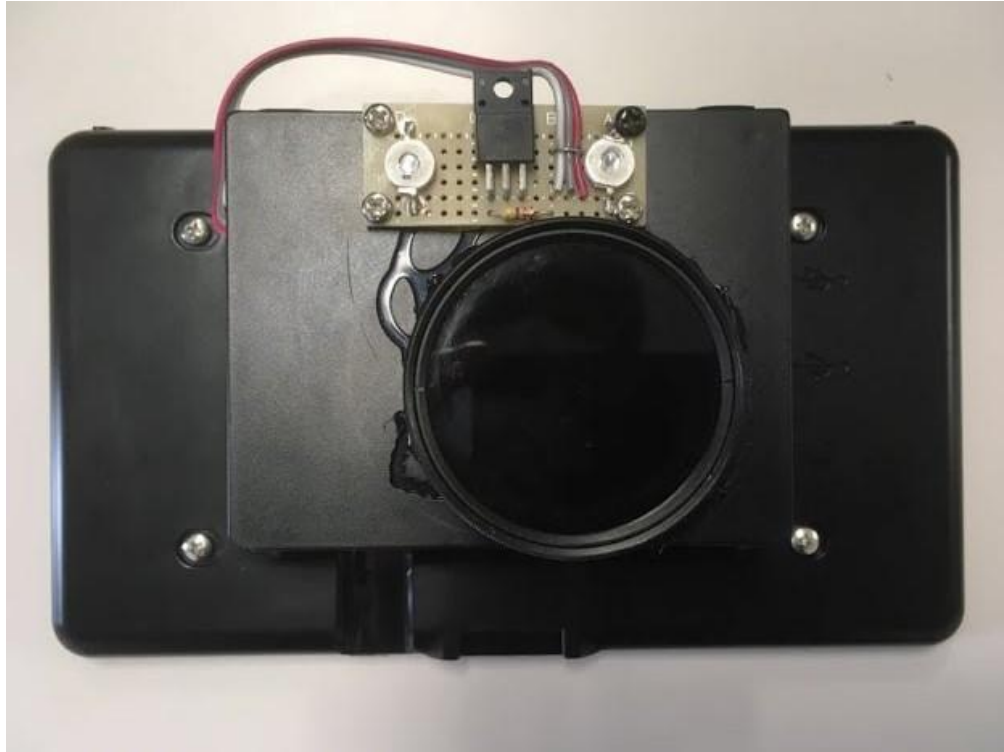


Image Processing Programming 1/7

Python Program

```
2  from picamera.array import PiRGBArray
3  from picamera import PiCamera
4  from datetime import datetime
5  import RPi.GPIO as gpio
6  import numpy as np
7  import time
8  import math
9  import cv2
10 import sys
11 import os
```

Comments

```
# PiCamera Control =  
Image Obtaining  
  
# GPIO Control = LED  
Driver  
  
# OpenCV = Image  
Processing
```

Image Processing Programming 2/7

Python Program

```
22 # PWM
23 self.pwmPort = pwmPort
24 self.pwmFrequency = pwmFrequency
25 self.pwm = 0
26
27 # camera
28 self.frameWidth = frameWidth
29 self.frameHeight = frameHeight
30 self.framerate = framerate
31 self.camera = 0
32 self.rawCapture = 0
```

Comments

```
# GPIO Port = 12
# f = 1kHz

# 320 * 240 pixels

# 16 FPS
```

Image Processing Programming 3/7

Python Program

```
212 for frame in self.camera.capture_continuous(self.rawCapture,  
                                                format="bgr",  
                                                use_video_port=True):  
  
...  
215     img_original = frame.array
```

Comments

```
# Image Capturing. ⇒ Very Very Easy!!
```

Image Processing Programming 3/7

Python Program

```
212 for frame in self.camera.capture_continuous(self.rawCapture,  
                                                format="bgr",  
                                                use_video_port=True):  
  
...  
215     img_original = frame.array
```

Comments

```
# Image Capturing. ⇒ Very Very Easy!!
```



Original Image

Image Processing Programming 4/7

Python Program

```
99 # create contrast image
100 def __contrast(self, img):
101     gray = cv2.cvtColor
        (img,cv2.COLOR_BGR2GRAY)

102     resultImg = np.array
        ( [ self.lut[value] for value in gray.flat],
          dtype=np.uint8 )

103     resultImg = resultImg.reshape(gray.shape)
104     return resultImg
```

Comments

Color Conversion
(BGR to Gray)

Contrast Adjustment
With Sigmoid Function

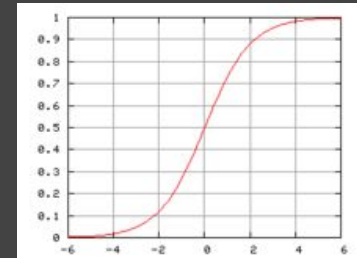


Image Processing Programming 4/7

Python Program

```
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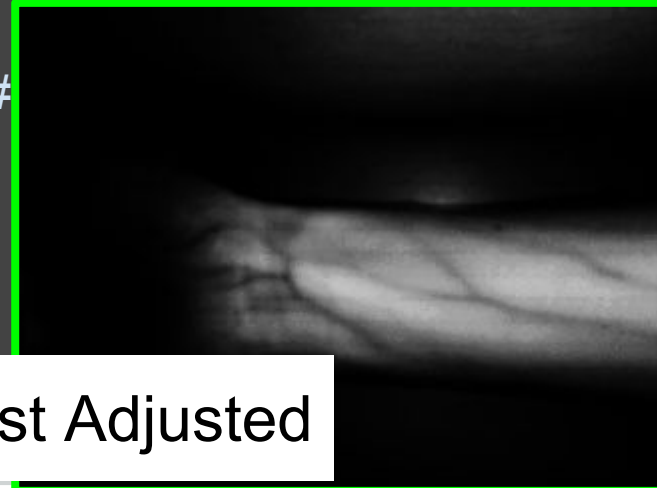
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104     return resultImg
```

Comments

```
# Color Conversion
(BGR to Gray)
```

```
#
```



Contrast Adjusted

Image Processing Programming 5/7

Python Program

```
106 # get hand mask
107 def __getHandMaskAndOutline(self, contrast):
108     ret, thresh = cv2.threshold(contrast, 0, 255, cv2.THRESH_BINARY +
                                cv2.THRESH_OTSU)
109     contours, hierarchy = cv2.findContours(thresh, cv2.RETR_TREE,
                                cv2.CHAIN_APPROX_SIMPLE)
110
111     # Get maximum size convex
112     maxIdx = -1
113     maxLen = -1
114     for i in range(len(contours)):
115         if (maxLen < len(contours[i])):
116             maxIdx = i
117             maxLen = len(contours[i])
118
119     # Create Mask
120     mask = np.zeros(contrast.shape, dtype=np.uint8)
121     mask.fill(0)
122     outline = -1
123     if maxIdx > 0:
124         outline = [ contours[maxIdx] ]
125         cv2.fillPoly(mask, outline, (255))
126
127     return mask, outline
```

Comments

Binarization

Get Contours of White Area

Get Maximum Contour
⇒ Hand Area

Create Mask of Hand Area

Image Processing Programming 5/7

Python Program

```
106 # get hand mask
107 def __getHandMaskAndOutline(self, contrast):
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127     return mask, outline
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Comments

Binarization

Get Contours of White Area

Get Maximum Contour
⇒ Hand Area

Create Mask of Hand Area

Hand Detection!!

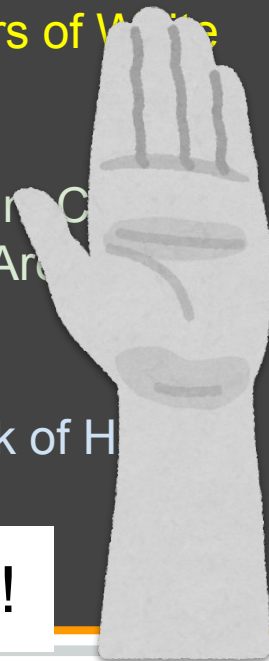


Image Processing Programming 6/7

Python Program

```
130 def __getVeinMask(self, contrast):  
131     veinMask = cv2.Canny(contrast,  
                            self.lut_b_val-40, self.lut_b_val+5)  
132     kernel = np.ones((3, 3), np.uint8)  
133     veinMask = cv2.dilate(veinMask, kernel)  
134     return veinMask
```

Comments

Edge Detection

Pixel Dilation

Image Processing Programming 6/7

Python Program

```
130 def __getVeinMask(self, contrast):  
131     veinMask = cv2.Canny(contrast,  
                            self.lut_b_val-40, self.lut_b_val+5)  
132     kernel = np.ones((3, 3), np.uint8)  
133     veinMask = cv2.dilate(veinMask, kernel)  
134     return veinMask
```

Comments

Edge Detection

Pixel Dilation



Edge Detection!!

Image Processing Programming 7/7

Python Program

```
157 def __getVein(self, handMask, outline, veinMask,  
158                                     original):  
159     if outline == -1:  
160         return original  
161     red = np.zeros(original.shape, np.uint8)  
162     red[:] = (0, 0, 255)  
...  
166     vein = cv2.bitwise_and(red, red, mask=handMask)  
167     vein = cv2.bitwise_and(vein, vein, mask=veinMask)  
168     vein = cv2.bitwise_or(original, vein)  
169  
170     cv2.drawContours(vein, outline, 0, (0, 255, 255))  
171  
172     return vein
```

Comments

If Hand Area was not detected.

Overwrap Hand Area Mask and Vein Area Mask
⇒ Vein Emphasize

Image Processing Programming 7/7

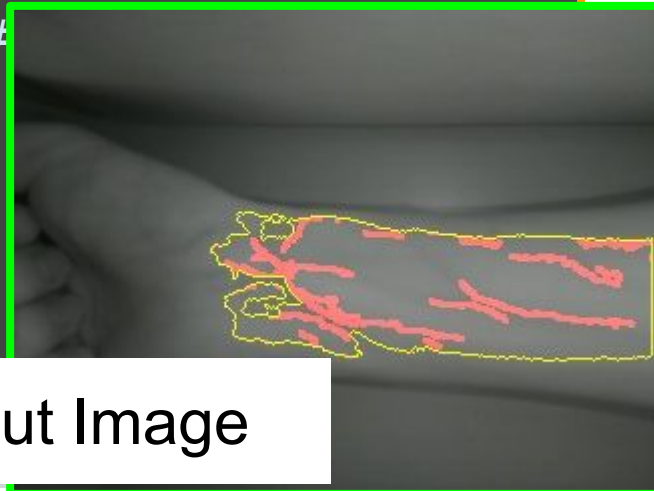
Python Program

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158                                     original):  
159     if outline == -1:  
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168     vein = cv2.bitwise_or(original, vein)  
169  
170     cv2.drawContours(vein, outline, 0, (0, 255, 255))  
171  
172     return vein
```

Comments

If Hand Area was not detected.

#



Output Image

Vein Visualization

I'll talk about...

1. About Vein Visualization
 2. How to Visualize the Vein
 3. Developing Hardware
-

I'll talk about...

1. About Vein Visualization
 2. About Visualize the Vein
 3. Developing Hardware
-

About Venipuncture

Venipuncture is medical practice.

Performed high frequency and high invasiveness.

Ex: Blood sampling , Injection of medicine



Therefore, importance of practical training is high.

Every year, caused some accidents.

Ready Made Products



<http://www.noba.com/what-is-a-veinviewer/>

“Vein Viewer”

Projection shape of Vein
On Human skin.

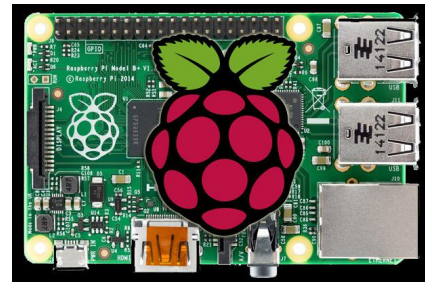
Reported increase performance for venipuncture
on the practical affairs.

Vision

Ready-made-products are extremely expensive.

Our system's Concept:

- Easy to developing
- Economy
- Connect to medical IoT platform
(this is a part of blood vessel information)

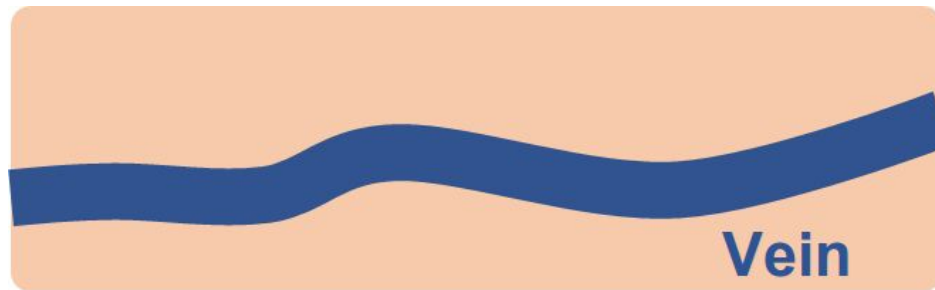
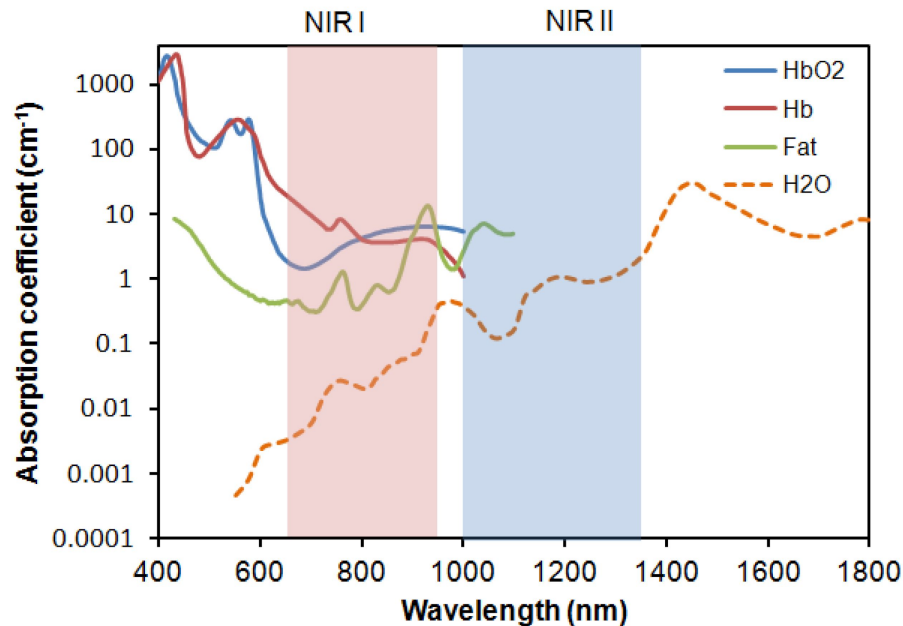


I'll talk about...

1. About Vein Visualization
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-

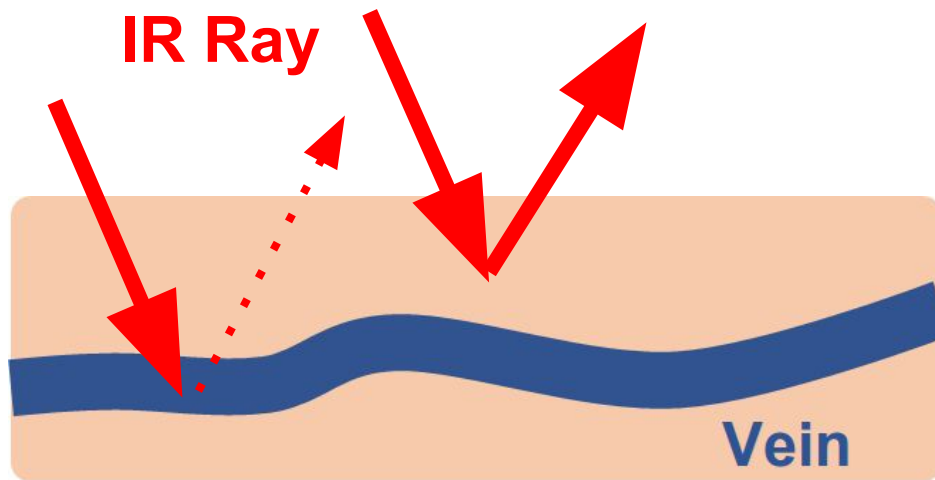
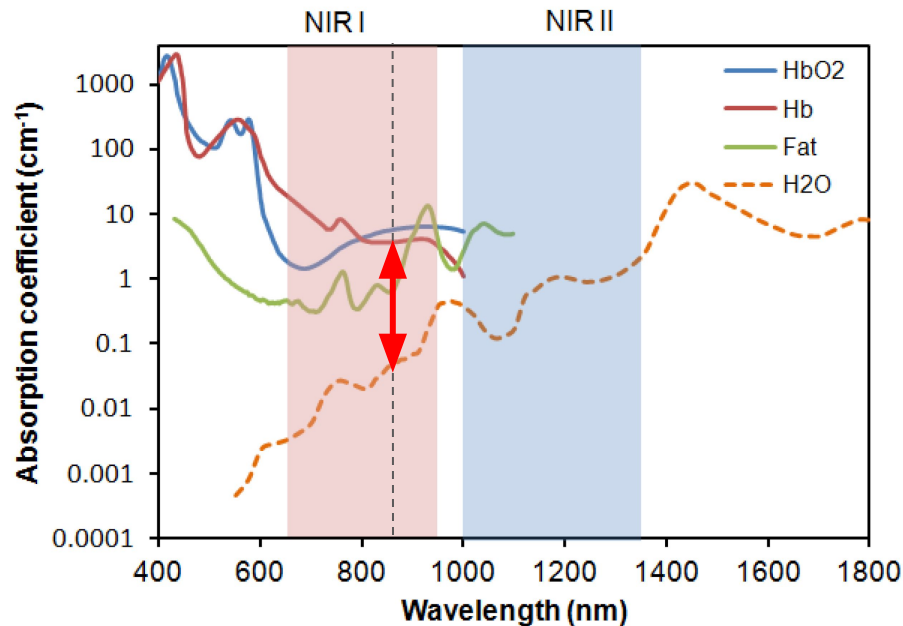
How to Visualize the Vein

The Hb and HbO₂ have high extinction coefficient on IR.



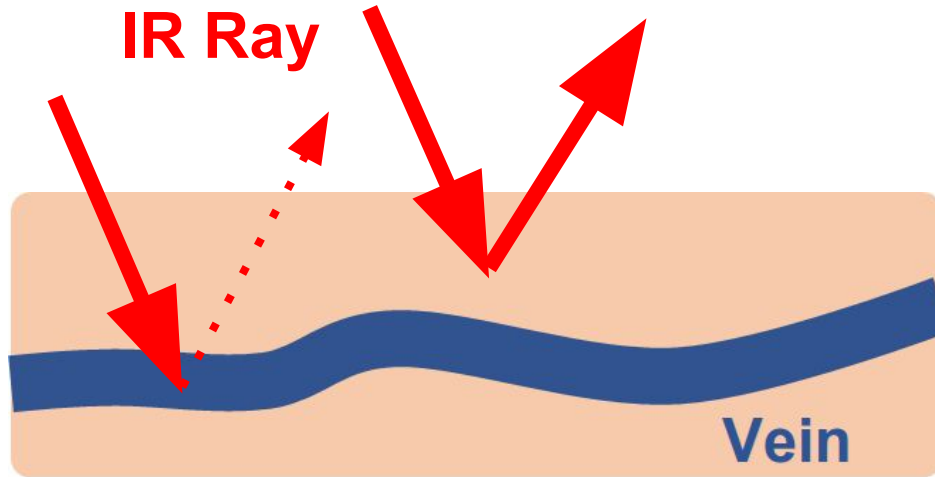
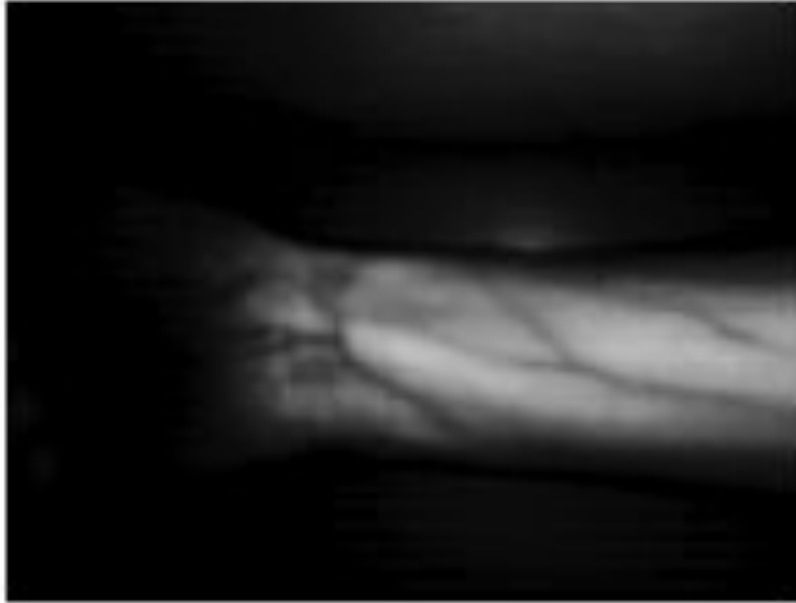
How to Visualize the Vein

The Hb and HbO₂ have high extinction coefficient on IR.

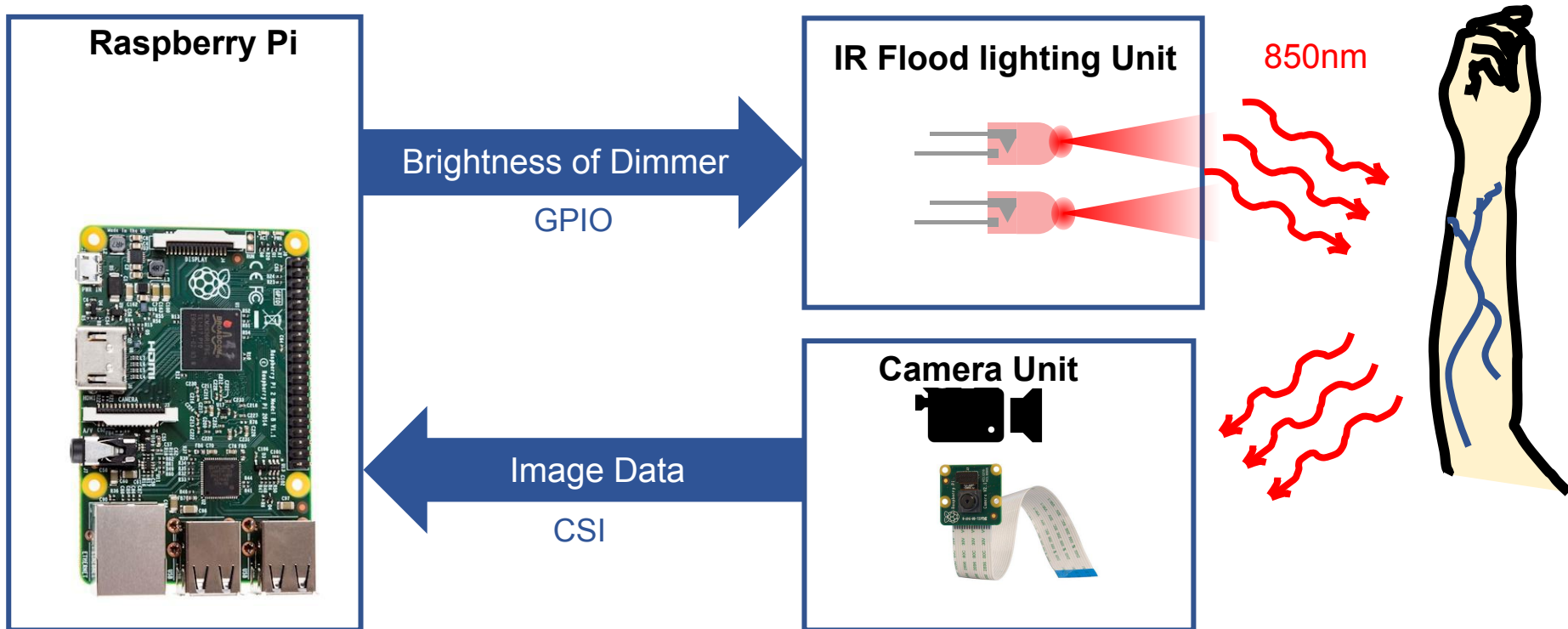


How to Visualize the Vein

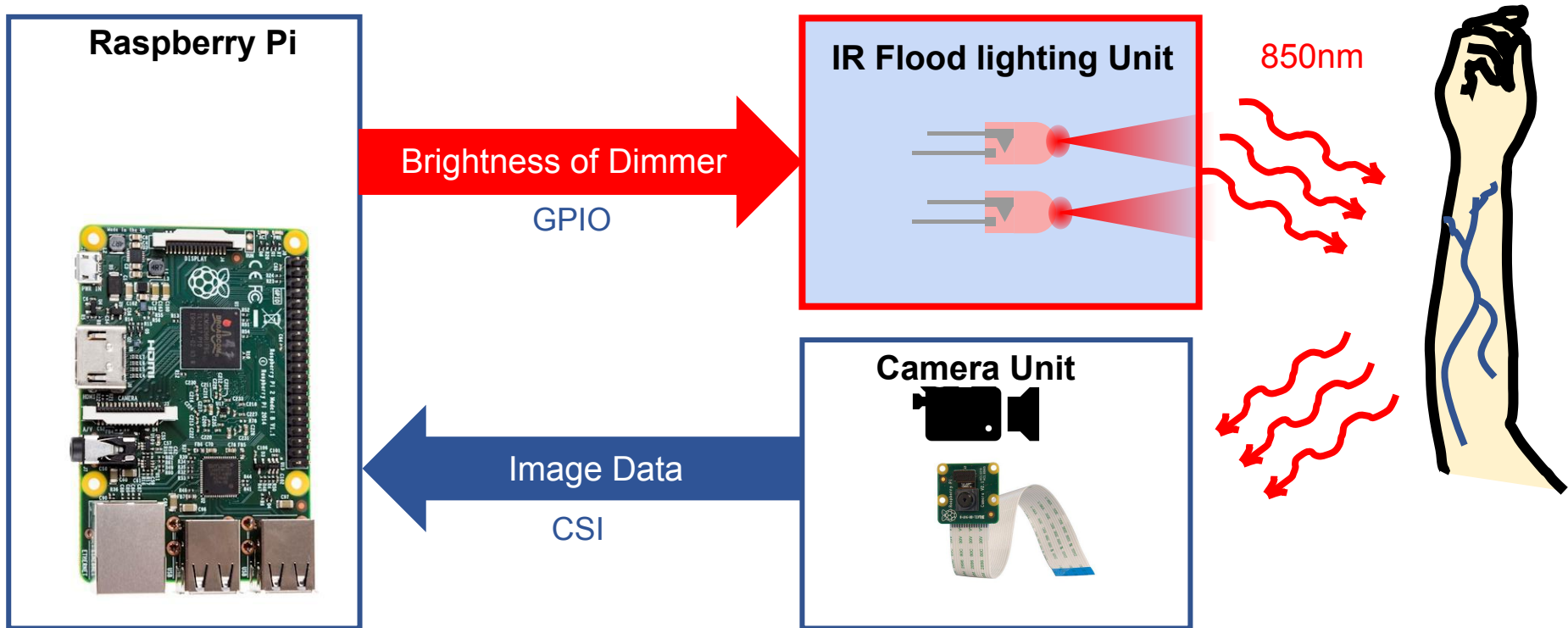
The Hb and HbO₂ have high extinction coefficient on IR.



System Diagram



System Diagram

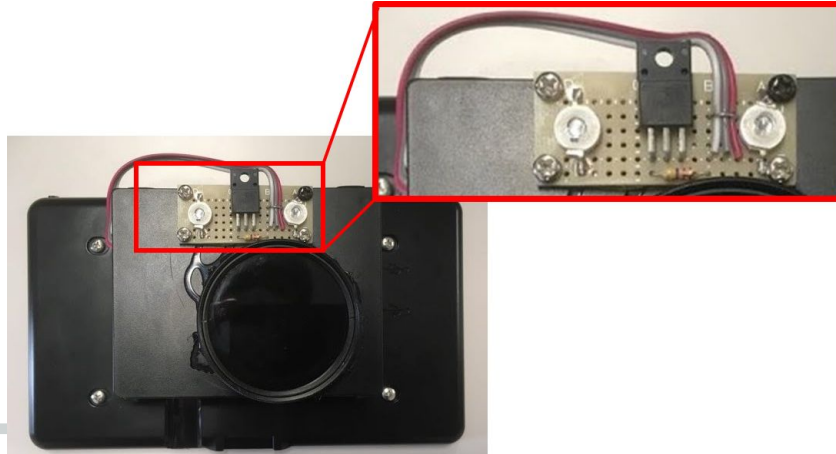


IR Flood light Unit

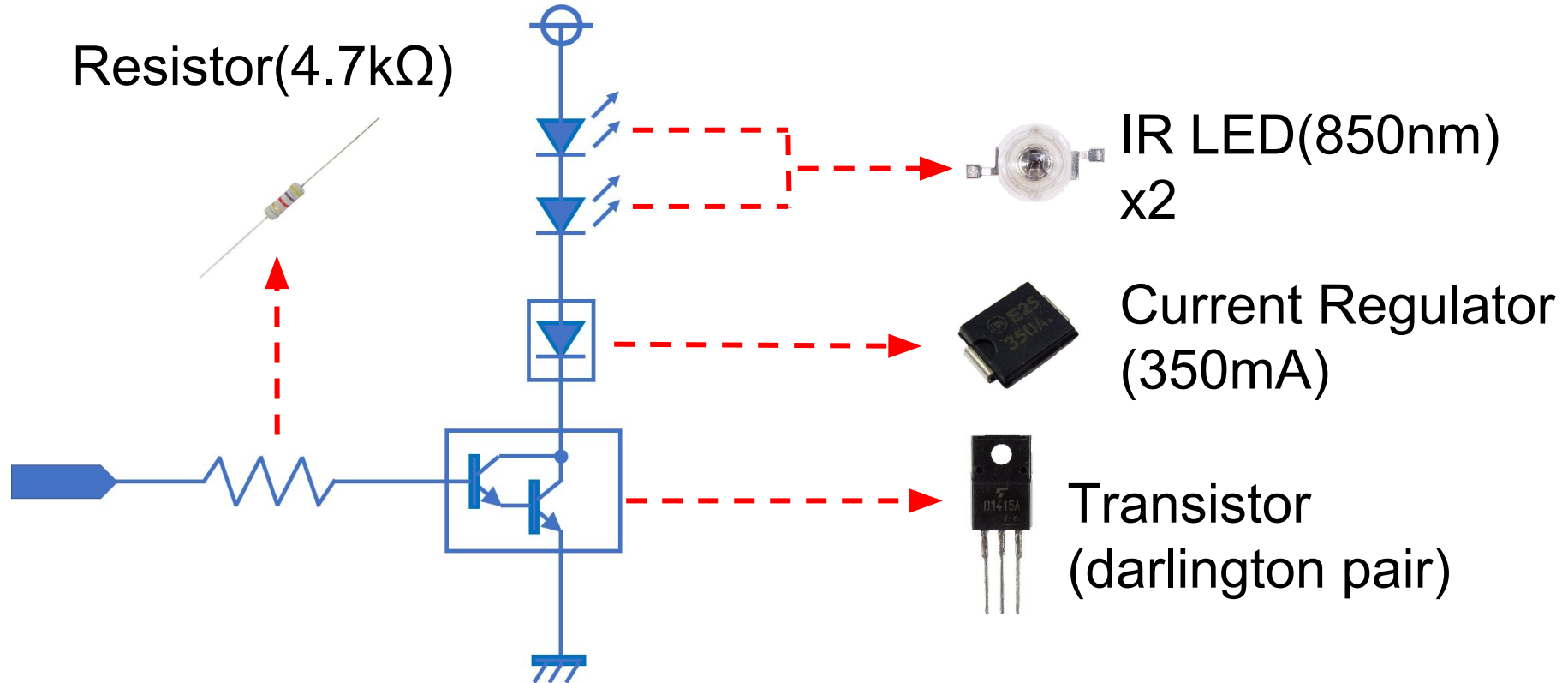
Function:

Flood lighting: Irradiate IR Ray.

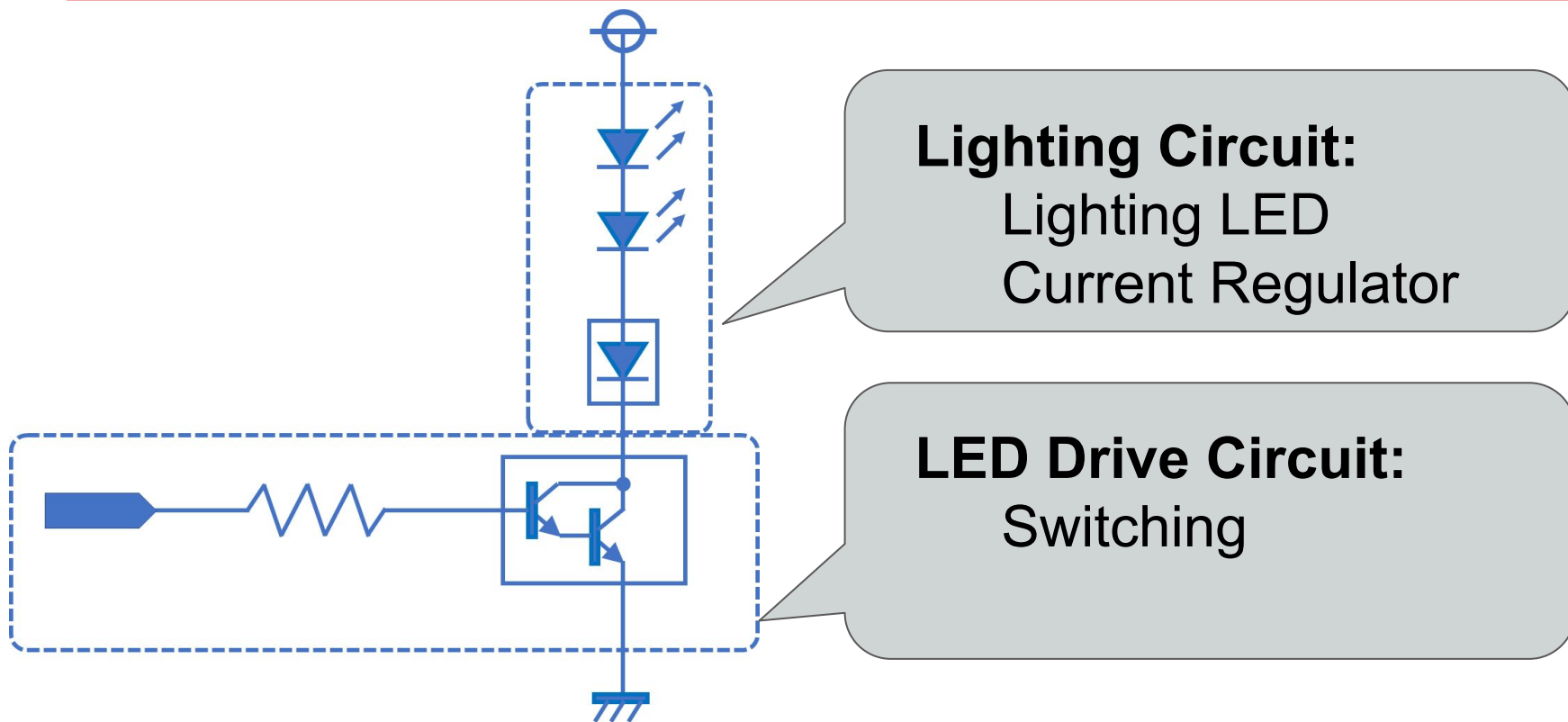
Control: Adjusting brightness of IR Ray.



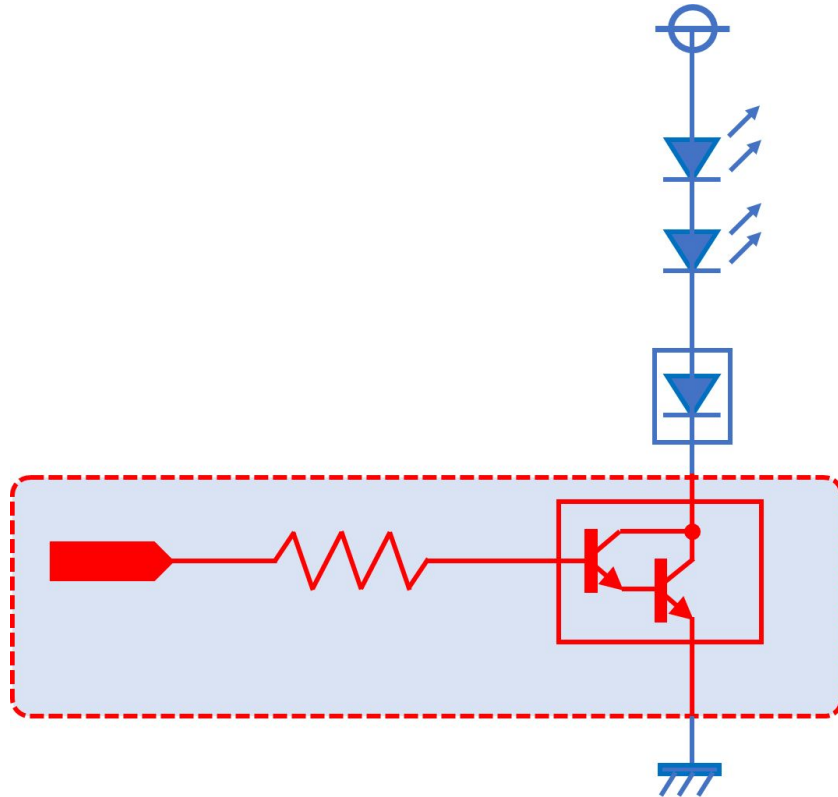
Circuit Diagram (Flooding Light Unit)



Circuit Diagram (Flooding Light Unit)



Block 1 -LED Drive Circuit



LED Drive Circuit:
Switching for
High-Power LED

Current value from GPIO Pin is not enough for LED drive

ICIEV18, Kitakyushu, Japan

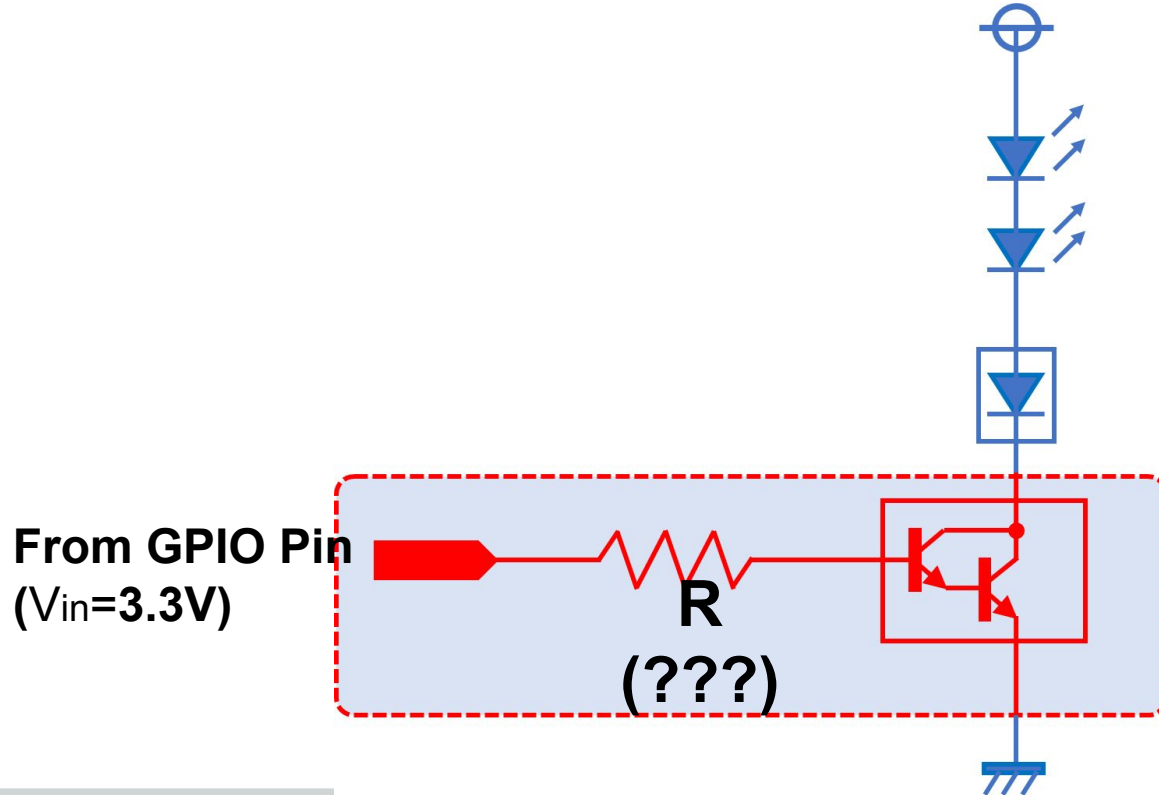
How much the current value?

- Maximum LED Lighting current is **700mA**
- However, GPIO Pin's current limit is **50mA**



In this Case, Employing Switching Circuit using Transistor.

How to Design -LED Drive Circuit



Decide Base Resistor's value

$V_{in}=3.3[V]$ (GPIO outputs Voltage),

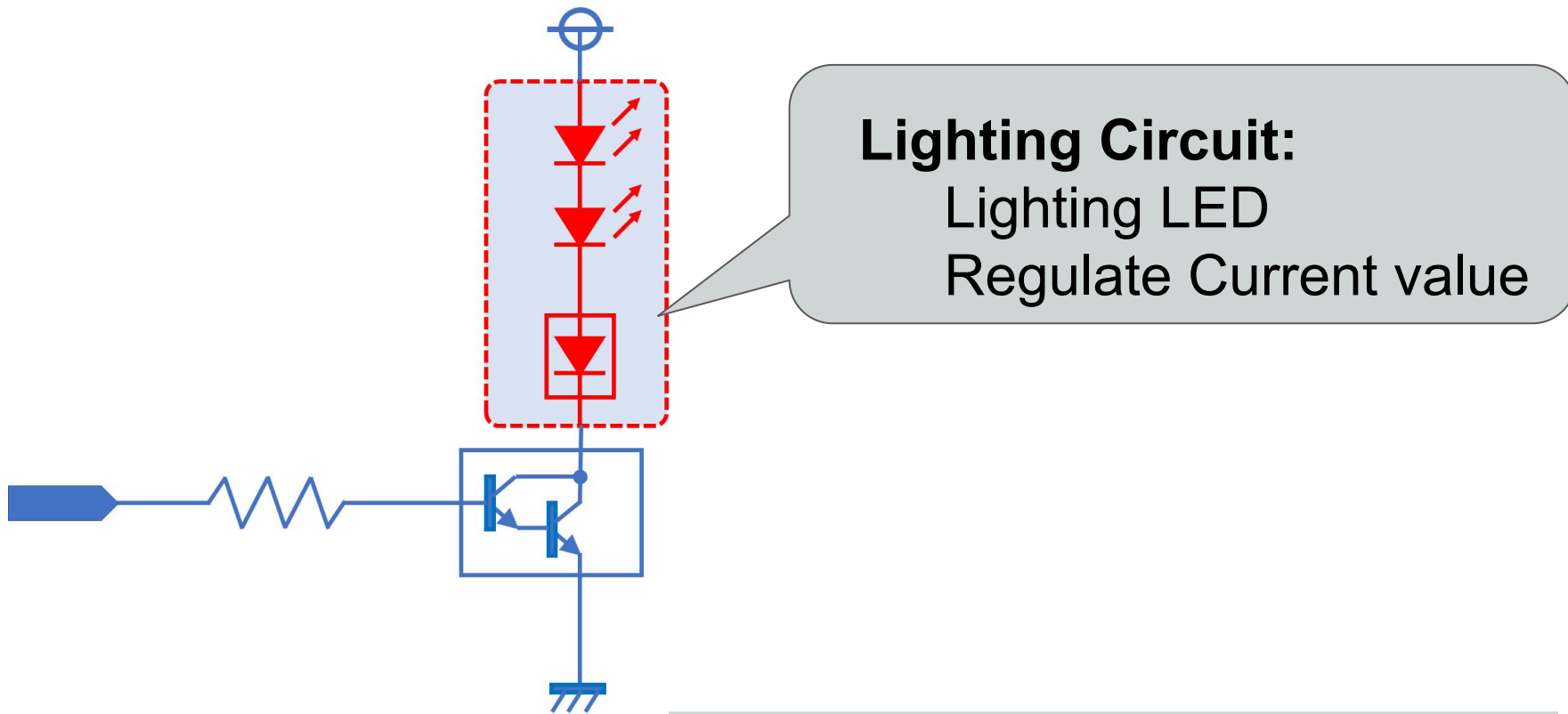
$h_{fe}=1000$ (Transistor's parameter),

Maximum Current for Drive LED=700 [mA]

$$R = \frac{V_{in}}{i_c/h_{fe}} = \frac{3.3}{0.7/1000} = 4714.28$$

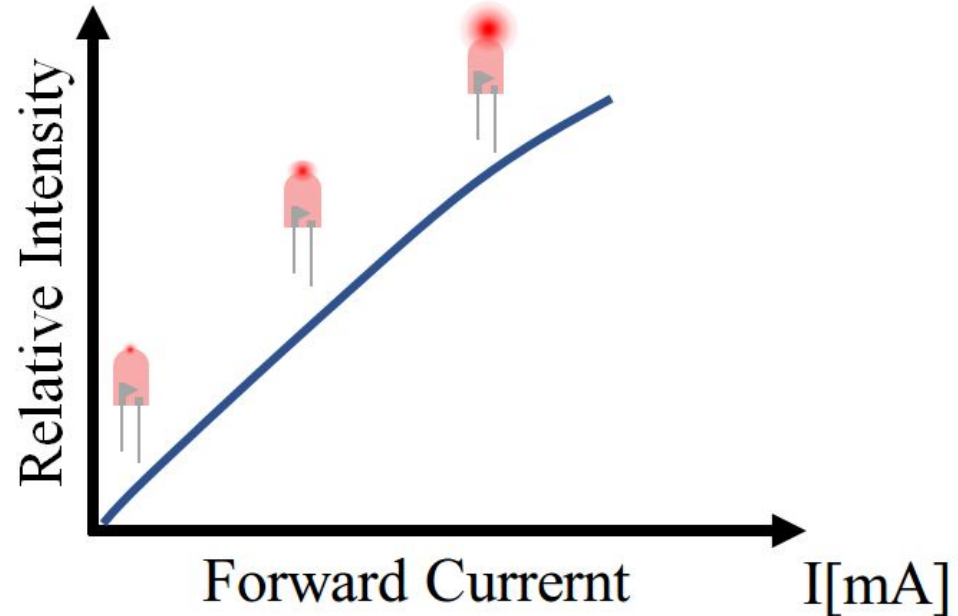
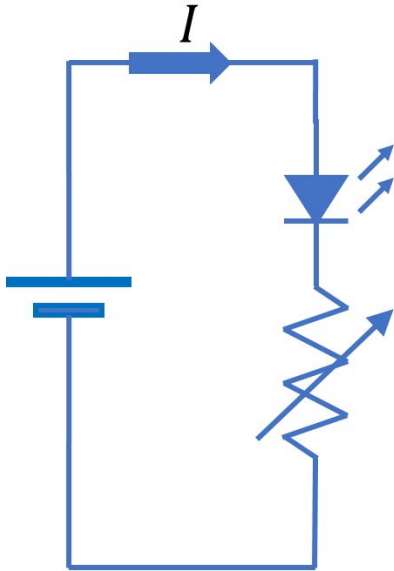
$$R=4.7k\Omega$$

Block 2-LED Circuit:



LED's Brightness is decided by Current Value

The brightness of the light of an LED is proportional to an electric current.



Heat of LED Cause Changing Current Value

When the almost semiconductor devices has heat,
The current value increase.

Hi-Power LEDs self heating caused changing
current value (= brightness).



**Therefore, We insert current regulator (350mA) to
lightning circuit to get constant current value.**

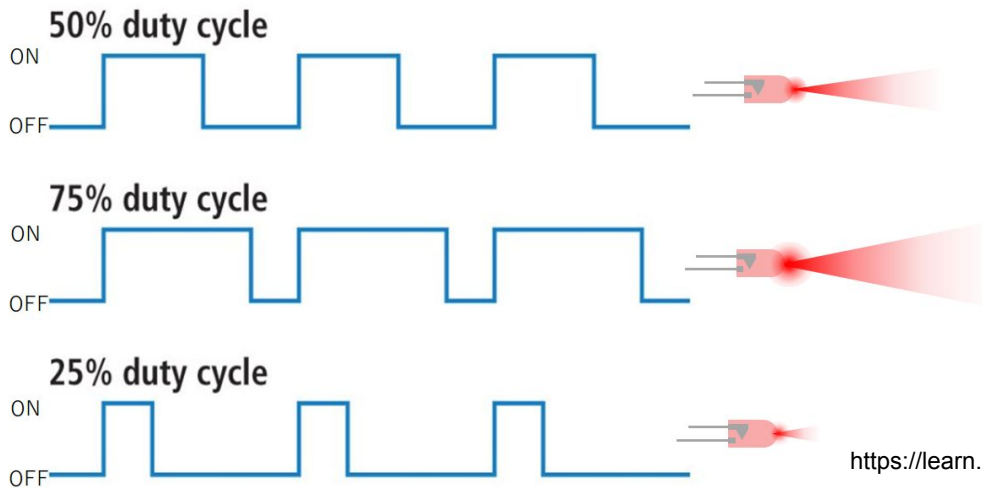


How to Adjusting Brightness

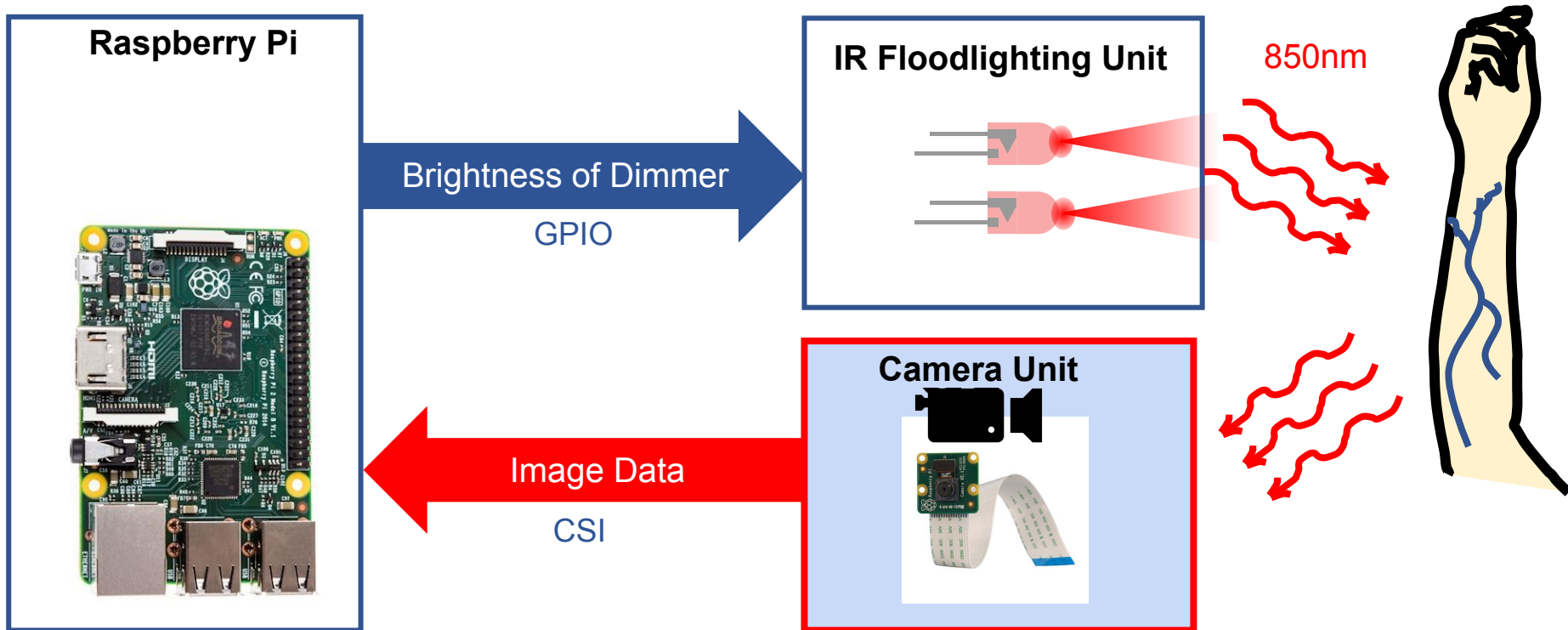
GPIO Pin outputs are only HIGH(3.3V) or LOW(0V).

PWM(Pulse Width Modulation):

High frequency switching for control power.



System Diagram

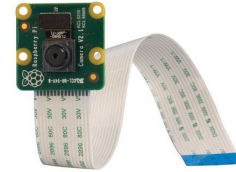


Camera Unit

Function

Camera:

Get pixel Information by Image sensor



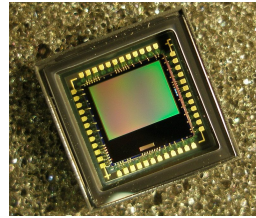
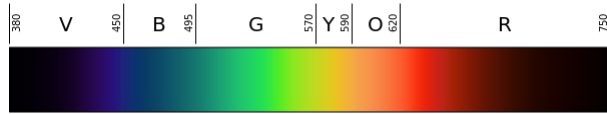
Filter:

Cut Visible light and get only IR Ray.



Almost Camera can't take IR Ray

The CMOS Image sensor can convert invisible Ray(IR , UV) to electrical signal too.

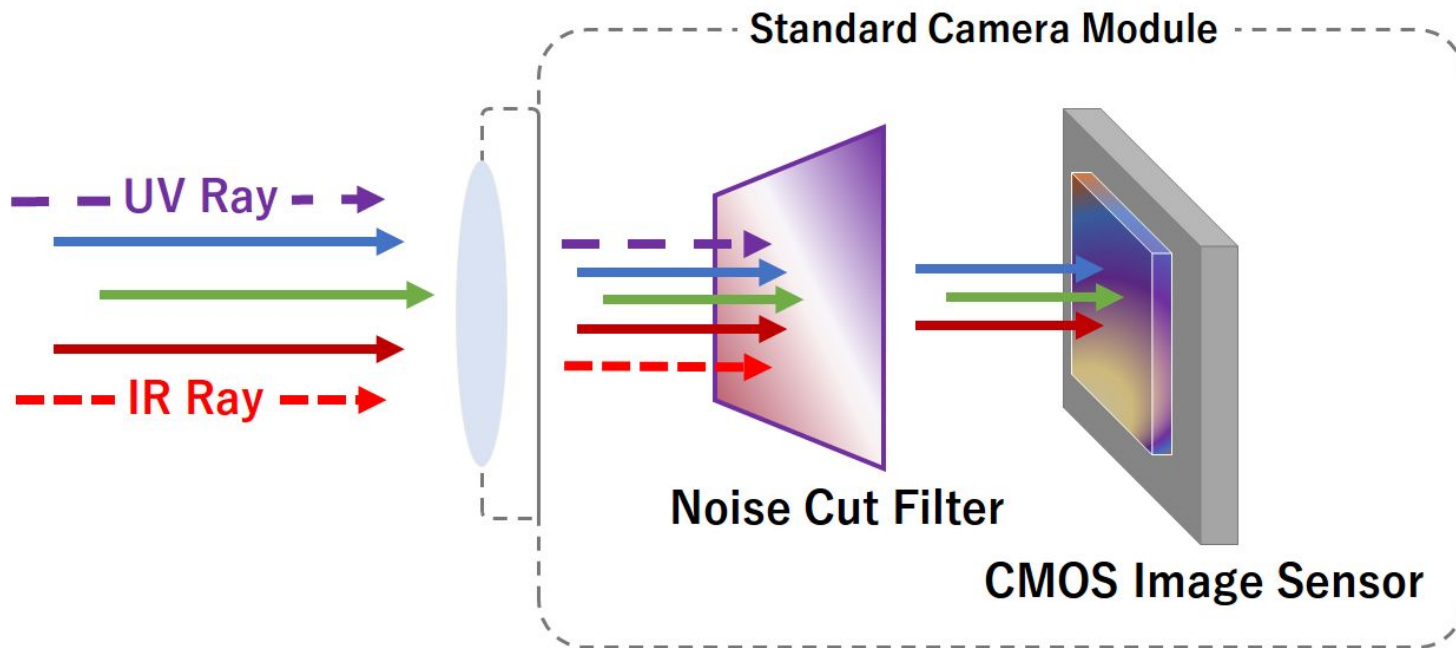


However, Invisible color informations on a Picture is noise for human.

Almost digital camera include Noise Cut Filter.

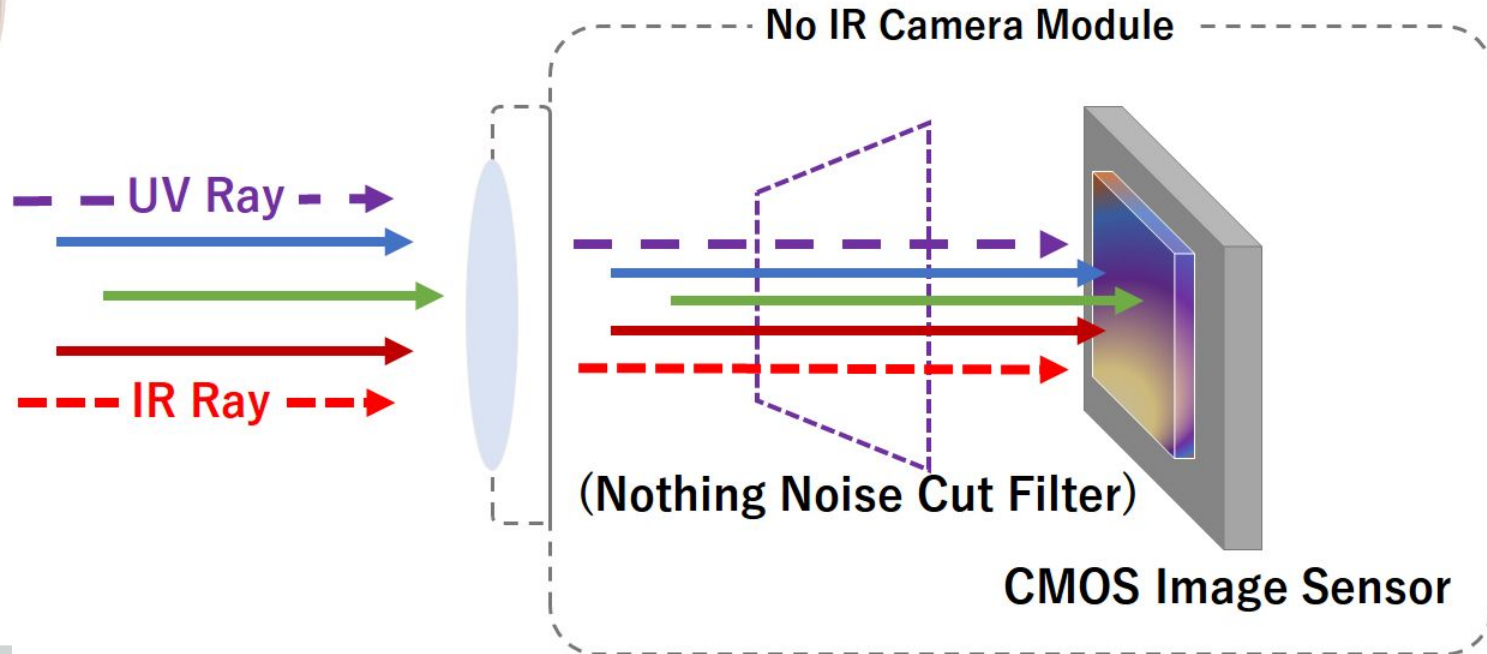
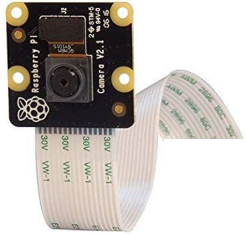
Standard Camera Module

Almost digital camera include Noise Cut Filter.



We want to IR Ray information

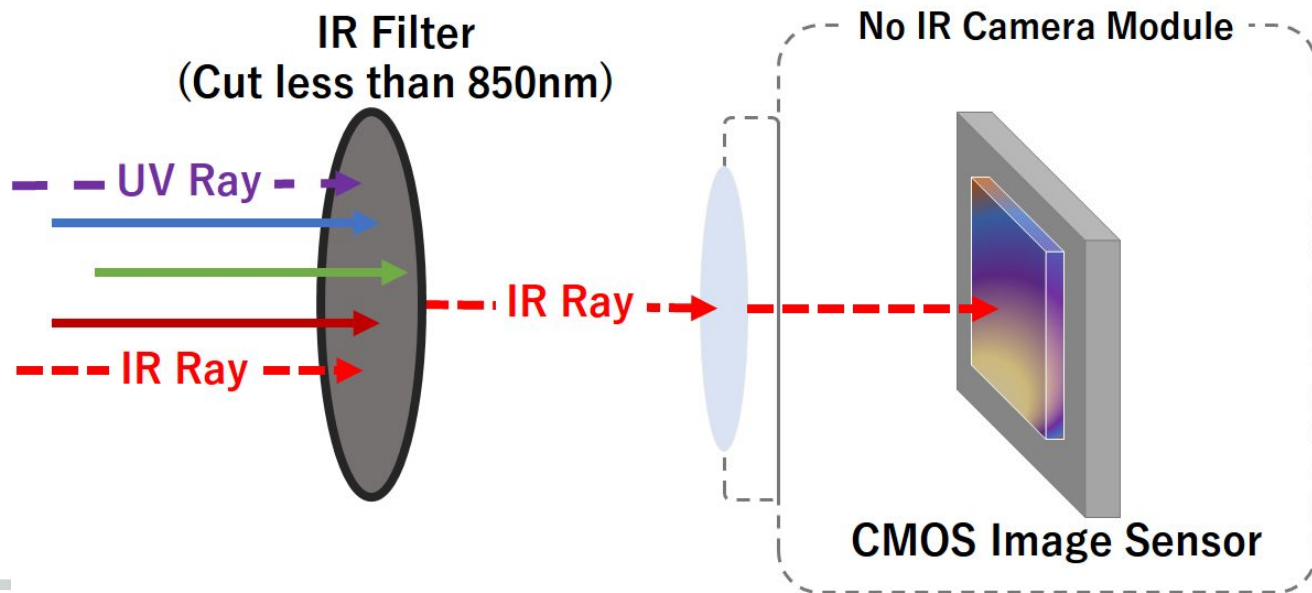
In No IR Camera, nothing Noise Cut Filter.



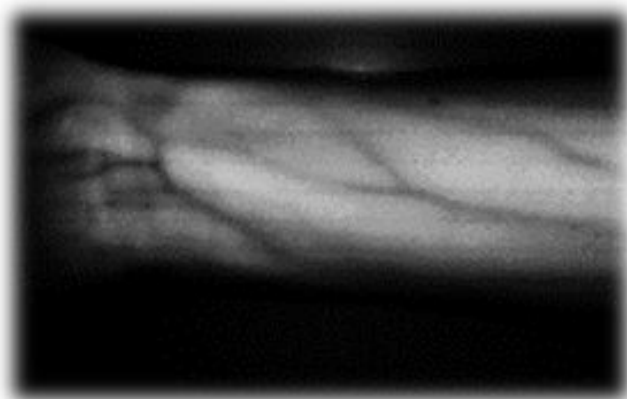
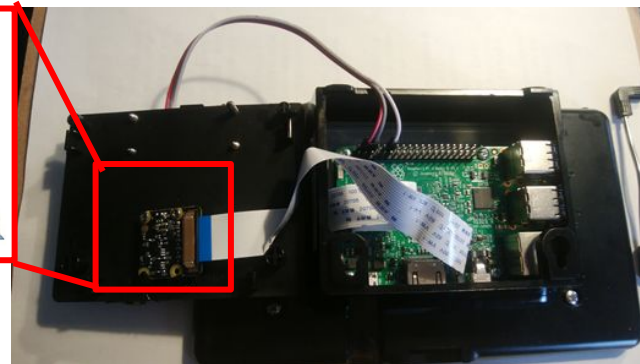
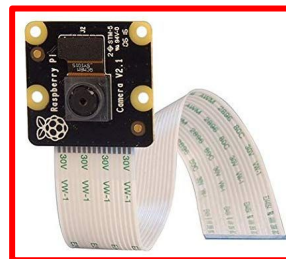
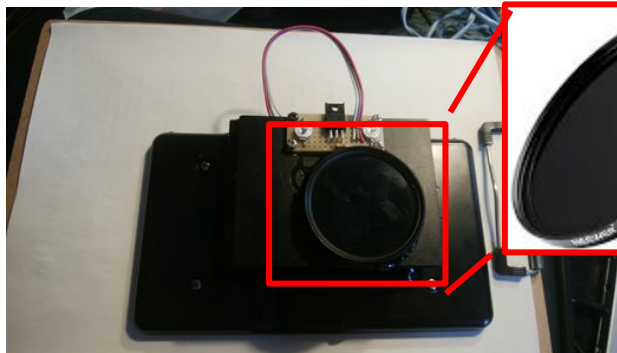
We only need IR light information!

The IR Filter cut less than specific wavelength rays.

To get clearly vein shape... To simplify algorithm...



Enjoy!



Question? Demonstration

Contact Atsushi Inoue (Business Card: <https://goo.gl/Ltho3I>, Web: <http://www.inoueatsushi.net/>)

This tutorial is based on the R&D to be presented at ICIEV 2018.

13:20-14:50 on Wednesday, June 27 @Room 22

Regular session (7-B): IoT, Control and Automation III

Paper 282 -- the last presentation.

A Modern, IoT Platform for Medical Engineering: Vein Visualization

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You are welcome to join us to discuss further.
