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香港中文大學  
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# Modeling Functions

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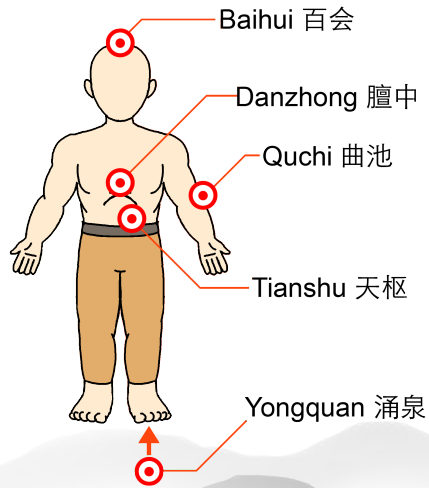
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## Three Heroes Combating Lü Bu



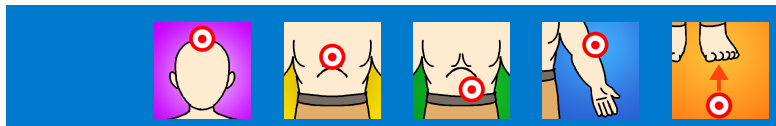


## Lü Bu's Weak Spots



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## Damage Matrix



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1

3

4

6



8

2

5

1

4



4

3

7

2

5

4



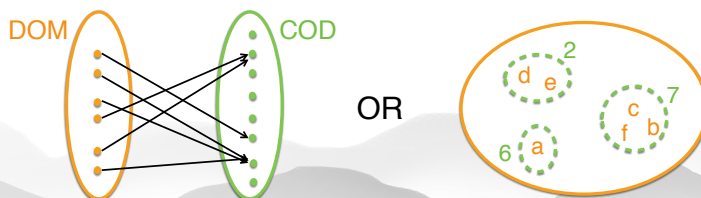
## Lü Bu and the Pure Assignment Problem

- ⌘ Liu, Guan and Zhang will each attack a **different** spot of Lü Bu to distract him
- ⌘ Find out the spots they should attack in order to maximize the damage to Lü Bu
- ⌘ The Lü Bu Problem takes the form of a **Pure Assignment Problem**
  - 3 heroes and 5 spots
  - **Assign** each hero to a spot so as to maximise damage

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## Deciding Functions

- ⌘ Many combinatorial problems have the form:
  - assign to each object in one set DOM (domain)
  - a value from another set COD (codomain)
- ⌘ We can interpret this as
  - Defining a function  $\text{DOM} \rightarrow \text{COD}$
  - Or partitioning the set DOM (in sets labelled by COD)



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## Deciding Functions

- ⌘ This function could be
  - injective: assignment problem
  - bijective (DOM = COD): matching problem
  
- ⌘ In the Lü Bu Problem, DOM is the **heroes** and COD is the **weak spots** of Lü Bu

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## Deciding Functions

- ⌘ This function could be
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- ⌘ In the Lü Bu Problem, DOM is the **heroes** and COD is the **weak spots** of Lü Bu

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## Lü Bu Problem Data and Decisions (lvbu.mzn)

### ⌘ Data

```
enum HERO;  
enum SPOT;  
array[HERO, SPOT] of int: damage;
```

### ⌘ What are the decisions?

```
array[HERO] of var SPOT: pos;
```

### ⌘ What is the objective?

```
var int: tDamages = sum(h in HERO)  
    (damage[h, pos[h]]);  
solve maximize tDamages;
```

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## Lü Bu Problem Constraints (lvbu.mzn)

### ⌘ Each spot is assigned to at most one hero

```
forall(s in SPOT)  
    (sum(h in HERO)  
        (pos[h] = s) <= 1);
```

### ⌘ Alternatively

### ⌘ Each two heroes are assigned different spots to attack

```
forall(h1, h2 in HERO where h1 < h2)  
    (pos[h1] != pos[h2]);
```

### ⌘ Which is better?

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## Global Constraints

- ⌘ Let's not choose (?)
  - Different solvers will prefer different representations
- ⌘ Record the structure of the problem
- ⌘ Let the solver determine the best way it knows how to handle this substructure
- ⌘ In modelling these substructures, we use

global constraints

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## Alldifferent

- ⌘ Global constraint version

```
alldifferent(pos);
```
- ⌘ Enforces that each hero is assigned a different spot
- ⌘ Solvers can make use of the substructure to solve better.
- ⌘ The first example of a global constraint
- ⌘ Captures the
  - assignment substructure, or alternatively
  - deciding an injective function

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## The Lü Bu Assignment Model (lvbu.mzn)

```
enum HERO;
enum SPOT;
array[HERO,SPOT] of int: damage;

array[HERO] of var SPOT: pos;

include "alldifferent.mzn";
alldifferent(pos);

var int: tDamages = sum(h in HERO)
  (damage[h,pos[h]]);
solve maximize tDamages;

output ["\ (h): \ (pos[h])\n" | h in HERO] ++
  ["Total Damages: \ (tDamages)"];
```

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## Assignment Problem

- ⌘ The **pure assignment problem** is very well studied
  - specialized polynomial (**fast**) algorithms
  - maximal weighted matching
- ⌘ If you have a pure assignment problem
  - use a specialized algorithm
- ⌘ **BUT** the real world is never pure
  - add some side constraints and these specialised algorithms almost always **break!**

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## Summary

- ⌘ Deciding a (finite) function is common
- ⌘ Deciding an injective function is a
  - assignment (sub)problem
- ⌘ The global constraint `alldifferent` captures this
- ⌘ Global constraints
  - names of combinatorial substructures
  - solvers can use their best method for capturing this
  - plenty more to come ...

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## Image Credits

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