

Adapting New Categories for Food Recognition with Deep Representation

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Abstract—

I. INTRODUCTION

II. RELATED WORKS

The motivation of transfer knowledge between different domains is to apply the previous information from the source domain to the target one, assuming that there exists certain relationship, explicit or implicit, between the feature space of these two domains [1]. Technically, previous work can be concluded into solving the following three issues: what, how and when to transfer [2].

What to transfer. Previous work tried to answer this question from three different aspects: selecting transferable instances, learning transferable feature representations and transferable model parameters. Instance-based transfer learning assume that part of the instances in the source domain could be re-used to benefit the learning for the target domain. Lim et al. proposed a method of augmenting the training data by borrowing data from other classes for object detection [3]. Learning transferable features means to learn common feature that can alleviate the bias of data distribution in target domain. Recently, Long et al. proposed a method that can learn transferable features with deep neural network and showed some impressive results on the benchmarks [4]. Parameter transfer approach assumes that the parameters of the model for the source task can be transferred to the target task. Yang et al. proposed Adaptive SVMs by transferring parameters from the auxiliary classifier from trained from source domain[5]. On top of Yang's work, Ayatar et al proposed PMT-SVM that can determine the transfer regularizer according to the target data automatically [6]. Tommasi et al. proposed Multi-KT that can utilize the parameters from multiple source models for the target classes [2]. Kuzborskij et al. proposed a similar method to learn new categories by leveraging over the known source [7].

When and how to transfer. The question *when to transfer* arises when we want to know if the information acquired from previous task is relevant to the new one (i.e. in what situation, knowledge should not be transferred). In some extreme situation, where the source domain and target one are not relevant, brutal-force transferring the knowledge between them could even degrade the performance of the classifier in target domain. This is often referred to as negative transfer. *How to transfer* the prior knowledge effectively should be

carefully designed to prevent inefficient and negative transfer. Some previous work consists in using generative probabilistic method [8] [9] [10]. Bayesian learning methods can predict the target domain by combining the prior source distribution to generate a posterior distribution. Alternatively, some previous max margin methods show that it is possible to learn from a few examples by minimizing the Leave-One-Out (LOO) error for the training model [7] [11]. Previous work shows that there is a closed-form implementation of LOO cross-validation that can generate unbiased model estimation for LS-SVM [12].

Our work correspond to the context above. In this paper, we propose a method based on parameter transfer approach. We address our work on how to prevent negative transfer when the prior knowledge is not relevant to our target task. We mathematically proof that, without any data distribution assumption, the superior bound of the training loss for our transfer method is the loss of a method learning directly (i.e. without using any prior knowledge). This indicates that when the prior knowledge hurts the transfer procedure, our method can avoid negative transfer automatically.

III. PROBLEM STATEMENT

Our method works in the following scenario. There is a image dataset (source data) containing N categories and a classifier trained from this dataset to distinguish these N categories. This (source) classifier and the features used to learn it is publicly accessible while the dataset itself is private (unknown distribution). Now we collect our own image dataset (target data) coming from $N + 1$ categories. This target dataset consists of N identical categories to the source data and one new category related to the previous N categories. In order to train a new classifier for our new task, we would expect our classifier to get better results with respect to

- Maximize positive transfer. Since we know that these two task share some information, our classifier should transfer useful information as much as possible.
- Minimize negative transfer. The data distribution of the source data is unknown. In the extreme situation, the data distribution of the two task could be totally different. Then the knowledge from previous task is negative transfer and should be disposed.

In this paper, we focus our work on transferring the knowledge with LS-SVM as the classifier for multi-class transfer

problem. In the following we briefly introduce the mathematical setting of our problem and show

A. LS-SVM Setting and Definition

Here we introduce the notations used in the rest of the paper. We use any letter with apostrophe to denote the information from the source data, e.g. if $f(x)$ denotes the model for the target task, $f'(x)$ denotes the model for the source one.

TABLE I. USEFUL NOTATIONS IN THIS PAPER

$f'(x)$	binary function for source task
$f(x)$	binary function for target task
$\phi(x)$	function mapping the input sample into a high dimensional feature space.
$K(x, x)$	kernel matrix with $\phi(x_i) \cdot \phi(x_j)$ corresponding to its element (i, j)
X	instance matrix with each row representing one instance
W	$(N+1)$ -column hyperplane matrix for target task. Each column represents one hyperplane of a binary model
W'	hyperplane matrix for the source task
a'	the Lagrangian multiplier matrix for source problem. Each column represents a set of
a	the Lagrangian multiplier matrix for target problem
b', b	the bias vector for source and target task
a_i, w_i	i th column of matrix a and w
d_γ	diagonal matrix with $[\gamma_1, \dots, \gamma_N]$ in its main diagonal
β	row vector $[\beta_1, \dots, \beta_N]$
ε_{ny_i}	$\varepsilon_{ny_i} = 1$ if $n = y_i$ and 0 otherwise

Assume that, for our $(N+1)$ -category target task, $x \in \mathcal{X}$ and $y \in \mathcal{Y} = \{1, 2, \dots, N+1\}$ are the input vector and output for the learning task respectively. Meanwhile, we have a set of binary linear classifiers $f'_n(x) = \phi(x)w'_n + b'_n$, for $n = 1, \dots, N$ trained from an unknown distribution with One-Versus-All (OVA) strategy. Now we want to learn a set of new classifier $f_n(x) = \phi(x)w_n + b_n$, $n = 1, \dots, N+1$, so that example x is assigned to the category j if $j \equiv \arg \max_{n=1, \dots, N+1} \{f_n(x)\}$. In LS-SVM, the solution of the model parameters (w_n, b_n) can be found by solving the following optimization problem:

$$\min R(w_n) + \frac{C}{2} \sum_i^l (Y_{i,n} - \phi(x_i)w_n - b_n)^2$$

Where $R(w_n)$ is the regularization term to guarantee good generalization performance and avoid overfitting. \mathbf{Y} is a encoded label matrix so that $Y_{i,n} = 1$ if $y_i = n$ and -1 otherwise.

In classic LS-SVM setting, the regularization term is set to $\frac{1}{2} \|w_n\|^2$ and the optimal $w_n = \phi(X)^T \alpha_n$ while the parameters (α_n, b_n) can be found by solving

$$\begin{bmatrix} K(X, X) + \frac{1}{C} \mathbf{I} & \mathbf{1} \\ \mathbf{1}^T & 0 \end{bmatrix} \begin{pmatrix} \alpha_n \\ b_n \end{pmatrix} = \begin{pmatrix} Y_n \\ 0 \end{pmatrix} \quad (1)$$

Here \mathbf{I} is the identity matrix and $\mathbf{1}$ is a column vector with all its elements equal to 1.

Now our task can be divided into two separate part: learning the N overlapped categories and the new category. We know that the source and target share N categories. From previous work [5], the regularization term can be written as $\frac{1}{2} \|w_n - \gamma_n w'_n\|^2$. Here, γ_n is the regularization parameter controlling the amount of transfer. For the task for new category, we can use multi-source kernel learning strategy in [2]

So the multi-class transfer problem can be solved by optimizing the following objective function:

$$\begin{aligned} \min \quad & \frac{1}{2} \sum_{n=1}^N \|w_n - \gamma_n w'_n\|^2 + \frac{1}{2} \left\| w_{N+1} - \sum_{k=1}^N w'_k \beta_k \right\|^2 \\ & \frac{C}{2} \sum_{n=1}^{N+1} \sum_{i=1}^l e_{i,n}^2 \\ \text{subject to} \quad & e_{i,n} = Y_{i,n} - \phi(x_i)w_n - b_n \end{aligned} \quad (2)$$

The closed-form of the optimal solution to Eq. (2) is:

$$\begin{aligned} w_n &= \gamma_n w'_n + \sum_{i=1}^l \alpha_{in} \phi(x_i) \quad n = 1, \dots, N \\ w_{N+1} &= \sum_k^N \beta_k w'_k + \sum_i^l \alpha_{i(N+1)} \phi(x_i) \end{aligned}$$

Here α_{ij} is the element (i, j) in α .

Let ψ denotes the first term of left-hand side in Eq. (1). closed form in matrix format

$$\begin{bmatrix} \alpha \\ b \end{bmatrix} = \begin{bmatrix} \alpha' \\ b' \end{bmatrix} - \begin{bmatrix} \alpha'' \\ b'' \end{bmatrix} \begin{bmatrix} d_\gamma & \beta^T \\ 0 & 0 \end{bmatrix} \quad (3)$$

From Eq. (3) we can see that, the solution of Eq. (1) is completed once $\gamma = [\gamma_1, \dots, \gamma_N]$ and β are set.

B. Optimize γ and β

introduce LOO error estimation

introduce our objective function

Let us call ξ_i the loss of our multi-class prediction for example x_i and ξ_i can be defined as [13]:

$$\xi_i(\gamma, \beta) = \max_{n \in \{1, \dots, N+1\}} \left[1 - \varepsilon_{ny_i} + \hat{Y}_{in}(\gamma, \beta) - \hat{Y}_{iy_i}(\gamma, \beta) \right] \quad (4)$$

Where $\varepsilon_{ny_i} = 1$ if $n = y_i$ and 0 otherwise. $\xi_i(\gamma, \beta) > 0$ if example x_i is misclassified. The intuition behind this loss function is to enforce the distance between the true class and other classes to be at least 1.

And we define our objective function as:

$$\begin{aligned} \min \quad & \frac{\lambda_1}{2} \sum_{j=1}^N \|\gamma_j\|^2 + \frac{\lambda_2}{2} \sum_{j=1}^N \|\beta_j\|^2 + \sum_{i=1}^l \xi_i \\ \text{subject to} \quad & 1 - \varepsilon_{ry_i} + \hat{Y}_{ir}(\gamma, \beta) - \hat{Y}_{iy_i}(\gamma, \beta) \leq \xi_i; \\ & \lambda_1, \lambda_2 \geq 0 \end{aligned} \quad (5)$$

explanation of two parameters, further refer to [13]

By adding a dual set of variables, one for each constraint, we get the Lagrangian of the optimization problem:

$$\begin{aligned} \max \quad & L(\gamma, \beta, \xi, \eta) = \frac{\lambda_1}{2} \sum_{j=1}^N \|\gamma_j\|^2 + \frac{\lambda_2}{2} \sum_{j=1}^N \|\beta_j\|^2 + \sum_{i=1}^l \xi_i \\ & + \sum_{i,r} \eta_{i,r} \left[1 - \varepsilon_{ry_i} + \hat{Y}_{ir}(\gamma, \beta) - \hat{Y}_{iy_i}(\gamma, \beta) - \xi_i \right] \\ \text{subject to} \quad & \forall i, r \quad \eta_{i,r} \geq 0 \end{aligned} \quad (6)$$

Algorithm for optimizaiton, convex-non-differentiable

Algorithm 1 γ optimization

Input: $\psi, \alpha', \alpha'', T,$ **Output:** $\gamma = \{\gamma^1, \dots, \gamma^n\}, \beta$

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1:  $\beta \leftarrow 0, \gamma \leftarrow 1$ 
2: for  $iter = 1$  to  $T$  do
3:    $\hat{Y} \leftarrow Y - (\psi \circ I)^{-1} (\alpha' - [\alpha'' d_\gamma \quad \alpha'' \beta^T])$ 
4:    $\Delta_\gamma = 0, \Delta_\beta = 0$ 
5:   for  $i = 1$  to  $l$  do
6:      $\Delta_\gamma \leftarrow \Delta_\gamma + \lambda_1 \gamma$ 
7:      $\Delta_\beta \leftarrow \Delta_\beta + \lambda_2 \beta$ 
8:     for  $r = 1$  to  $N + 1$  do
9:        $loss_{ir} = 1 - \varepsilon_{y_i, r} + \hat{Y}_{ir} - \hat{Y}_{iy_i}$ 
10:      if  $loss_{ir} > 0$  then
11:        if  $y_i, r \in \{1, \dots, N\}$  then
12:           $\Delta_\gamma^{y_i} \leftarrow \Delta_\gamma^{y_i} - \frac{\alpha'_{iy_i}}{\psi_{ii}^{-1}}$ 
13:           $\Delta_\gamma^r \leftarrow \Delta_\gamma^r + \frac{\alpha'_{ir}}{\psi_{ii}^{-1}}$ 
14:          else if  $y_i = N + 1$  then
15:             $\Delta_\beta \leftarrow \Delta_\beta - \frac{\alpha''_{ij}}{\psi_{ij}^{-1}}$ 
16:             $\Delta_\gamma^r \leftarrow \Delta_\gamma^r + \frac{\alpha'_{ir}}{\psi_{ii}^{-1}}$ 
17:          else
18:             $\Delta_\gamma^{y_i} \leftarrow \Delta_\gamma^{y_i} - \frac{\alpha''_{iy_i}}{\psi_{ii}^{-1}}$ 
19:             $\Delta_\beta \leftarrow \Delta_\beta + \frac{\alpha'_{ii}}{\psi_{ii}^{-1}}$ 
20:          end if
21:        end if
22:      end for
23:    end for
24:     $\beta \leftarrow \beta - \frac{\Delta_\beta}{l \times iter}$ 
25:     $\gamma \leftarrow \gamma - \frac{\Delta_\gamma}{l \times iter}$ 
26:  end for
```

C. Analysis

Convergence analysis

Superior bound analysis

Theorem 1: Assume that $\bar{\xi}_i$ is the multi-class loss of example x_i when $\gamma = \beta = \mathbf{0}$. Let γ^*, β^* be the optimal solution for Eq. (6) and ξ_i^* be the multi-class loss with respect to example x_i . Then for every example x_i , we have:

$$\xi_i \leq \bar{\xi}_i$$

Proof: When $\gamma = \beta = \mathbf{0}$, from Eq. (4) we can get:

$$\bar{\xi}_i = \max_n \left[1 - \varepsilon_{ny_i} + \frac{(\alpha'_{iy_i} - \alpha'_{in})}{\psi_{ii}^{-1}} \right]$$

To obtain the optimal value of γ and β , we have to seek the saddle point of the Lagrangian problem in (6) by finding the minimum for the prime variables $\{\gamma, \beta, \xi\}$ and the maximum for the dual variables η . To find the minimum of the primal problem, we require:

$$\frac{\partial L}{\partial \xi_i} = 1 - \sum_n \eta_{in} = 0 \rightarrow \sum_n \eta_{in} = 1$$

Similarly, for γ and β , we require:

$$\begin{aligned} \frac{\partial L}{\partial \gamma_n} &= \lambda_1 \gamma_n + \sum_i \eta_{in} \theta_{in} - \sum_{i, n=y_i} \left(\sum_q \eta_{iq} \right) \theta_{in} \gamma_n \\ &= \lambda_1 \gamma_n + \sum_i \eta_{in} \theta_{in} - \sum_i \varepsilon_{ny_i} \theta_{in} = 0 \\ &\Rightarrow \gamma_n^* = \frac{1}{\lambda_1} \sum_i (\varepsilon_{ny_i} - \eta_{in}) \theta_{in} \end{aligned} \quad (7)$$

In $=_1$ we use the facts that $\sum_n \eta_{in} = 1$ and use ε_{ny_i} to replace it.

$$\begin{aligned} \frac{\partial L}{\partial \beta_n} &= \lambda_2 \beta_n + \left[\sum_{i, n} \frac{\eta_{in} \alpha''_{in}}{\psi_{ii}^{-1}} (\delta_n - \delta_{y_i}) \right] = 0 \\ &\Rightarrow \beta_n^* = \frac{1}{\lambda_2} \sum_{i, n} \frac{\eta_{in} \alpha''_{in}}{\psi_{ii}^{-1}} (\delta_{y_i} - \delta_n) \end{aligned} \quad (8)$$

substituting Eq. (4) with γ^* and β^* , we get:

$$\begin{aligned} \xi_i^*(\gamma^*, \beta^*) &= \max_n \left[1 - \varepsilon_{ny_i} + \hat{Y}_{in}(\gamma^*, \beta^*) - \hat{Y}_{iy_i}(\gamma^*, \beta^*) \right] \\ &= \max_n \left[1 - \varepsilon_{ny_i} + \frac{(\alpha'_{iy_i} - \alpha'_{in})}{\psi_{ii}^{-1}} \right. \\ &\quad \left. - \lambda_1 \|\gamma_n^*\|^2 - \lambda_2 \|\beta_n^*\|^2 \right] \\ &\leq \max_n \left[1 - \varepsilon_{ny_i} + \frac{(\alpha'_{iy_i} - \alpha'_{in})}{\psi_{ii}^{-1}} \right] = \bar{\xi}_i \end{aligned}$$

■

When setting $\gamma = \beta = \mathbf{0}$, we don't utilize any knowledge from previous task (see Eq.(2)). From Theorem 1 we can see that

IV. EXPERIMENT

A. Dataset

B. Baselines

C. transfer from good oracle

D. from bad oracle

E. mixed

V. CONCLUSION

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