




-  Interacted objects
-  Navigation
-  Navigation and carrying object



Goal predicates:

ON(milk, kitchentable): 1

INSIDE(cupcake, stove): 1

ON(chicken, kitchentable): 1

CLOSE(stove) TurnON(stove)

Actions:

- | | |
|------------------------------|--------------------------------|
| ① [walk] <kitchen cabinet 1> | [put] <chicken> <kitchentable> |
| [open] <kitchen cabinet 1> | [walk] <bedroom> |
| ② [walk] <kitchen cabinet 2> | ⑥ [walk] <cabinet> |
| [open] <kitchen cabinet 2> | [open] <cabinet > |
| ③ [walk] <kitchen cabinet 3> | [grab] <cupcake> |
| [open] <kitchen cabinet 3> | [walk] <kitchen> |
| [grab] <milk> | ⑦ [walk] <stove> |
| ④ [walk] <kitchentable> | [put] <cupcake> <stove> |
| [put] <milk> <kitchentable> | [close] <stove> |
| ⑤ [walk] <chicken> | [turnon] <stove> |
| [walk] <kitchentable> | |