## EE 382N-11: Distributed Systems

Fall 2017

# Lecture 4: September 12

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## 4.1 Outline

- Mutual Exclusion
- Lamport's Algorithm
- Ricart and Agrawala's Algorithm
- Quorum-based Algorithm

## 4.2 Mutual Exclusion

#### 4.2.1 Definitions

- Critical Section (CS): Parts of a program that share resources [1].
- Mutual Exclusion: Two processes should not be in critical section at any time (concurrently) [2].

#### 4.2.2 Properties

- 1. Safety: System never gets into a "bad" state (two processes should not be in CS concurrently).
- 2. Liveness: Something "good" will eventually happen (every request is eventually granted).
- 3. Fairness: Different requests are granted in the order they are made [2].

# 4.3 Lamport's Algorithm

#### 4.3.1 Resource Allocation

Mutual exclusion deals with resource allocation. To decide order and break ties/conflicts we can use logical clock timestamp and process identifiers.

## • Centralized Resource Allocation

One process becomes the coordinator/server and the rest are the clients. The coordinator stores a queue of all received requests to be able to grant the requests in order.

1. Client  $\rightarrow$  Server: Request resource

- 2. Server  $\rightarrow$  Client: Grant resource
- 3. Client  $\rightarrow$  Server: Release resource when done

Due to message delay the fairness property is not guaranteed. Requests are granted in the order they are received at the server, not necessarily in the order the requests were made.

**Exercise:** Modify the centralized algorithm such that it satisfies the fairness property from above. *Hint: use vector clock.* 

#### • Distributed Resource Allocation

Each process  $P_i$  stores a queue Q which contains all outstanding requests ordered by request timestamp. On request, do:

- 1. Create request timestamp ts := logical clock()
- 2. Insert request into  $Q_i$
- 3. Send ("request", (ts, i)) to all processes

### On receiving request from $P_i$ , do:

- 1. Insert the request into  $Q_i$
- 2. Send acknowledge ack to  $P_i$

#### $P_i$ can enter CS if:

- 1. Its request is at the top of  $Q_i$
- 2. Received ack from all processes

#### To release CS, do:

- 1. Remove my request from  $Q_i$
- 2. Send "release" message to all processes

## On receiving "release" from $P_j$ , do:

1. Remove corresponding request from  $Q_i$ 

**Assumption:** By preserving FIFO (First In First Out) property, the queue stores all the outstanding requests ordered by request timestamps.

## 4.3.2 Proving Lamport's

**Theorem:** Lamport's Algorithm satisfies the safety property.

**Proof:** We have two requests, one from  $P_i$  and one from  $P_j$ . Since we are using logical clock, one is earlier than the other.

Assume: Request from  $P_j$  is earlier than request from  $P_i$ . Now if we assume that both  $P_i$  and  $P_j$  have entered the critical section then  $P_j$  must have sent ack following one of two cases as seen in Figure 4.1.

- 1. Case 1:  $P_j$  sends ack before sending its own request. If this case occurs it means that  $P_j$  would have received a request before its own and that  $P_j$ 's request would be later in  $Q_j$  and would not have entered CS.
- 2. Case 2:  $P_j$  sends its request and then later sends ack.  $P_i$  would have already received request from  $P_j$  by the time it got ack and would not have entered CS since in  $Q_i$ ,  $P_i$  is later than  $P_j$ .

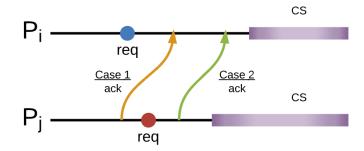


Figure 4.1:  $P_j$  can either send an ack before or after its request

# 4.3.3 Complexity

**Direct Dependency Clock**:  $\forall s, t : s \neq t : cs(s) \land cs(t) \land s || t \Rightarrow false$ 

Messenger/CS: 3(n-1) messages

- Request
- Ack
- Release

# 4.4 Ricart & Agrawala's Algorithm

# 4.4.1 Complexity

Ricart & Agrawala's algorithm decreases complexity to 2(n-1) with a few key advantages:

- 1. delays sending ack and combines with release into an "okay" message
- 2. does not assume FIFO message reception
- 3. keeps "pending" queue of requests which have not been responded to

# 4.4.2 Algorithm

PendingQ: queue of identifiers, initialized to empty queue.

On request, do:

- 1. Create request timestamp ts := logical clock()
- 2. Send ("request", (ts, i)) to all processes

On receiving request from  $P_j$  and both want to use CS, do:

- 1. if (hists < myts) reply "okay"
- 2. else insert his request into PendingQ

#### $P_i$ can enter CS if:

1. receives "okay" from (n-1) processes

#### To release CS, do:

- 1. send "okay" to all processes in PendingQ
- 2. clear PendingQ

On receiving "release" from  $P_j$ , do:

1. Remove corresponding request from  $Q_i$ 

# 4.5 Quorum Based Algorithms

## 4.5.1 Maekawa's Algorithm

 $R_i$ : request set for  $P_i$ 

Non-Empty Intersection Property:  $\forall i, j : R_i \cap R_j \neq \{\}$ 

Use lattice of  $\sqrt{N}$  rows by  $\sqrt{N}$  columns, where N is the number of processes. Choose all nodes along row of  $P_i$  and column of  $P_i$  as seen in Figure 4.2. There will always be two intersection points between the request sets of any two processes.

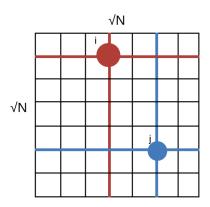


Figure 4.2: Intersection of  $P_i$  and  $P_j$  is found by both request sets made up of the column and row for each process

Complexity:  $O(\sqrt{N})$ 

This decreases complexity by quite a bit but processes need to be able to take back votes if a request with earlier timestamp comes to prevent deadlocks.

# 4.5.2 Crumbling Wall

To generalize Maekawa's Algorithm we can look at ways of not taking a full row and a full column. Try generalizing in these ways:

- $R_i$ : my full row and only those in my column below me
- $R_i$ : my full row and one representative from each row below me
- $\underline{R_i}$ : any full row and one representative from each row below the chosen row

A quorum in a crumbling wall is the union of one full row and a representative from every row below the full rows (original definition from textbook section 7.4.2). As long as 1 quorum (row/column) is alive, the crumbling wall can continue. This is seen in Figure 4.3.

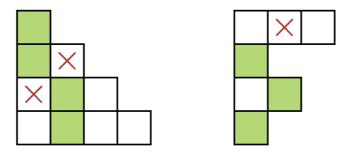


Figure 4.3: A couple different possible organizations for the crumbling wall generalization

# References

- [1] Wikipedia, "Critical Section", https://en.wikipedia.org/wiki/Critical\_section
- [2] V. J. GARG, "Chapter 6: Mutual Exclusion: Using Timestamps", and "Chapter 7: Mutual Exclusion: Tokens and Quorums", *Elements of Distributed Computing* 5 1st ed. New York: John Wiley & Sons, Inc., 2002, pp. 65-91.