

## PDEs

Separation of Variables :  $y(x,t) = X(x)T(t)$

ex.) 1D wave equation  $\frac{\partial^2 y}{\partial t^2} = \alpha^2 \frac{\partial^2 y}{\partial x^2}$

$$\Rightarrow \frac{1}{X(x)} X_{xx} = \frac{1}{\alpha^2} \frac{1}{T(t)} T'' = -k^2$$

$$\Rightarrow 2 \text{ ODEs : } X_{xx} + k^2 X = 0$$

$$T_{tt} + \alpha^2 k^2 T = 0$$

$$\text{ODE 1: } X_{xx} + k^2 X = 0 \quad w/ \quad X(0) = 0, \quad X(L) = 0$$

$$X(x) = C_1 \cos(kx) + C_2 \sin(kx) = C_2 \sin(kx)$$

$$\Rightarrow X(x) = C_n \sin\left(\frac{n\pi x}{L}\right) \quad n=1, 2, \dots, \infty$$

$$\text{ODE 2: } T_{tt} + k^2 \alpha^2 T = 0 \quad T_t(0) = 0$$

$$\Rightarrow T(t) = D_1 \cos(\alpha k t) + D_2 \sin(\alpha k t)$$

$$T_t(t) = -\alpha k D_1 \sin(\alpha k t) + \alpha k D_2 \cos(\alpha k t)$$

$$T_t(0) = D_2 \alpha k = 0 \Rightarrow D_2 = 0$$

$$\Rightarrow T(t) = D_1 \cos(\alpha k t) \quad w/ \quad k = \frac{n\pi}{L} \quad n=1, 2, \dots$$

$$\begin{aligned}
 \text{Then, } y(x,t) &= X(x)T(t) \\
 &= \sum_{n=1}^{\infty} C_n \sin\left(\frac{n\pi}{L} x\right) D_n \cos\left(\frac{\alpha n\pi}{L} t\right) \\
 &= \sum_{n=1}^{\infty} w_n \sin\left(\frac{n\pi}{L} x\right) \cos\left(\frac{\alpha n\pi}{L} t\right)
 \end{aligned}$$

$$\text{I.C. } y(x,0) = f(x)$$

$$y(x,0) = \sum_{n=1}^{\infty} w_n \sin\left(\frac{n\pi}{L} x\right) = f(x) = \cos(x)$$

This is just the Fourier Series  
for an odd function over  
 $[0, L]$

$$\Rightarrow w_n = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{n\pi}{L} x\right) dx$$

$$\text{ex.) let } f(x) = \sin(x) \quad \text{w/ } L = \pi$$

$$y(x,t) = \sum_{n=1}^{\infty} w_n \sin(nx) \cos(\alpha t)$$

$$w_n = \frac{2}{\pi} \int_0^{\pi} \sin(x) \sin(nx) dx \Rightarrow w_1 = 1$$

$$w_n = 0, n \geq 2$$

$$\Rightarrow y(x,t) = \sin(x) \cos(\alpha t)$$

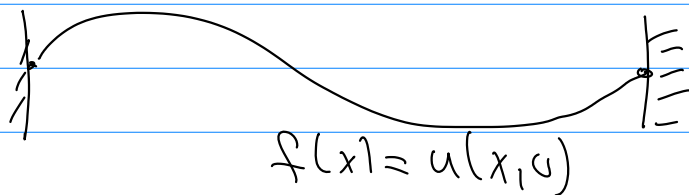
# Heat Equation

$$\frac{\partial u}{\partial t} = \alpha \partial^2 u \rightarrow 1D \rightarrow \frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2}$$

$\alpha = \text{thermal conductivity} > 0$

$u = \text{temperature}$

$$w) \quad u(0, t) = 0, \quad u(L, t) = 0, \quad u(x, 0) = f(x)$$



$$\text{let } u(x, t) = X(x) T(t)$$

$$u_t = X(x) T_t \quad u_{xx} = X_{xx} T(t)$$

$$\Rightarrow X(x) T_t = \alpha X_{xx} T(t)$$

$$\Rightarrow \frac{1}{\alpha T(t)} T_t = \frac{1}{X(x)} X_{xx} = -k^2$$

$$\text{ODE 1: } X_{xx} + k^2 X = 0 \quad \begin{array}{l} X(0) = 0 \\ X(L) = 0 \end{array}$$

$$X(x) = C_1 \cos(kx) + C_2 \sin(kx)$$

$$X(0) = C_1 = 0$$

$$X(L) = C_2 \sin(kL) = 0 \Rightarrow k = \frac{n\pi}{L} \quad n=1, 2, \dots$$

$$\Rightarrow X_n(x) = C_n \sin\left(\frac{n\pi}{L} x\right) \quad n=1, 2, \dots$$

$$\text{ODE 2: } \frac{dT}{dt} = -k^2 \alpha T$$

$$\int \frac{dT}{T} = \int -k^2 \alpha dt \Rightarrow T(t) = e^{-k^2 \alpha t} + D,$$

we can argue that  $D_1 = 0$  so  
that  $u(x, \infty) = 0$

$$\Rightarrow T(t) = e^{-k^2 \alpha t} \quad \text{w/ } k = \frac{n\pi}{L}, \quad n=1, 2, \dots$$

$$\Rightarrow u(x, t) = X(x) T(t)$$

$$= \sum_{n=1}^{\infty} \omega_n e^{-\left(\frac{n^2 \pi^2}{L^2} \alpha t\right)} \sin\left(\frac{n\pi}{L} x\right)$$

$$u(x, 0) = \sum_{n=1}^{\infty} \omega_n \sin\left(\frac{n\pi}{L} x\right) = f(x)$$

$\omega_n =$  Fourier Coefficients

$$w_n = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{n\pi}{L} x\right) dx$$

ex<sub>1</sub>) let  $f(x)=100$ ,  $\alpha=1$ ,  $L=\pi$

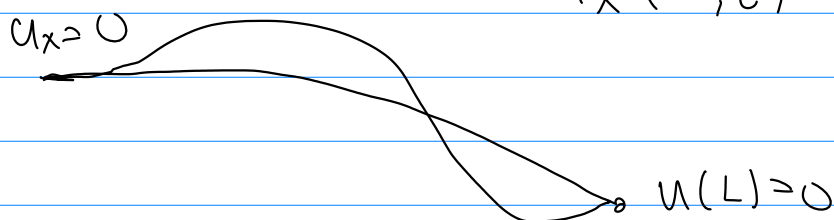
$$w_n = \frac{2}{\pi} \int_0^{\pi} (100) \sin(nx) dx = \frac{200}{n\pi} (1 - (-1)^n)$$

$$\Rightarrow u(x,t) = \sum_{n=1}^{\infty} \frac{200}{n\pi} (1 - (-1)^n) \sin(nx) e^{-n^2 t}$$

$$= \frac{400}{\pi} \left[ \sin(x) e^{-t} + \sin(3x) e^{-9t} + \dots \right]$$

Now look at a different condition:  
An insulated end

Find  $u(x,t)$  for a rod w/ an insulated end:  
 $u(x,0) = f(x)$   
 $u(L,t) = 0$   
 $u_x(0,t) = 0$



$$u(x,t) = X(x) T(t)$$

$$u_x(0,t) = X_x(0) T(t) = 0 \Rightarrow X_x(0) = 0$$

$$u(L,t) = X(L) T(t) = 0 \Rightarrow X(L) = 0$$

$$u(x,0) = f(x) = X(x) T(0)$$

$$\text{ODE: } X_{xx} + k^2 X = 0 \quad \begin{matrix} X_x(0) = 0 \\ X(L) = 0 \end{matrix}$$

$$X(x) = C_1 \cos(kx) + C_2 \sin(kx)$$

$$X_x(x) = -k C_1 \sin(kx) + k C_2 \cos(kx)$$

$$X_x(0) = k C_2 = 0 \Rightarrow C_2 = 0$$

$$X(L) = C_1 \cos(kL) = 0 \Rightarrow k = \frac{(2n-1)\pi}{2L}$$

$$n=1, 2, \dots, \\ -k^2 \propto t$$

$$\text{ODE 2: } T_t = -k^2 \propto T \Rightarrow T(t) = e$$

$$\Rightarrow u(x,t) = X(x) T(t)$$

$$= \sum_{n=1}^{\infty} \omega_n e^{(-k^2 \propto t)} \cos\left[\frac{(2n-1)\pi}{2L} x\right] \quad \text{w/ } k = \frac{(2n-1)\pi}{2L}$$

$$\text{w/ } u(x, 0) = \sum_{n=1}^{\infty} w_n \cos\left[\frac{(2n-1)\pi}{2L} x\right] = f(x)$$

Determine  $w_n$  via cosine series functions.

Procedure: Split solution,  
Solve individual ODEs & apply all but one condition,  
Apply final condition on final solution.

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### Types of Boundary Conditions

- ① Dirichlet: The value of the function is supplied at the boundary. If the boundary condition is zero  $\rightarrow$  homogeneous B.C.
- ② Neumann: First derivative of the function is known at the boundary.
- ③ Robin: A combination of Dirichlet & Neumann.

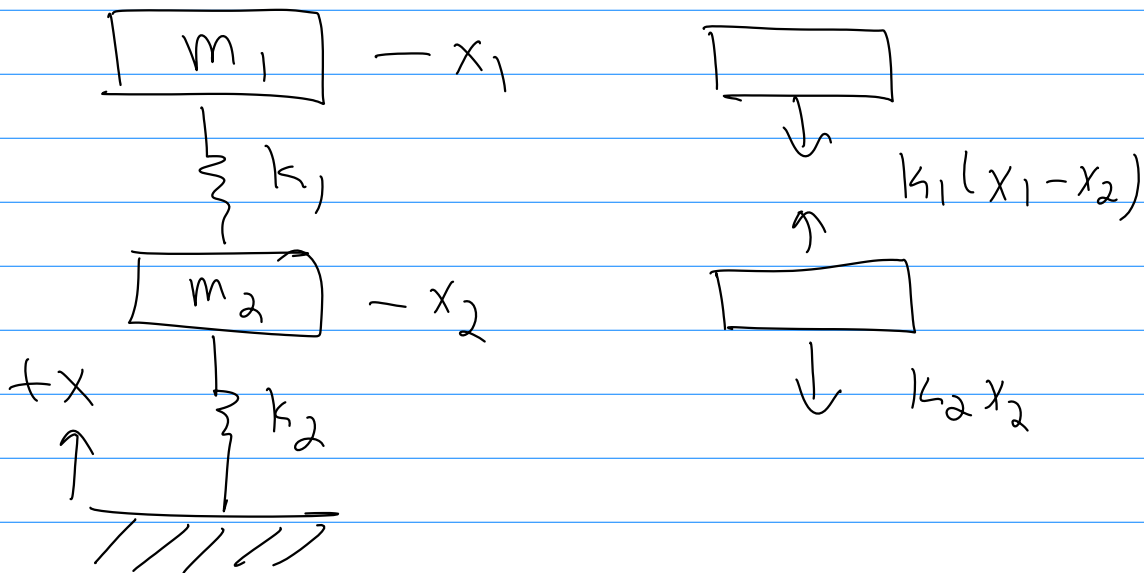
## Systems of ODEs.

These come up in two ways!

- ① A system of order-1 or higher ODEs,
- ② A higher-order ( $\geq 2$ ) ODE that is written as a system of order-1 ODEs,

## Systems of high-order ODEs.

A 2-mass-2 spring System:



Equations of motion :

$$m_1 \frac{d^2 x_1}{dt^2} = -k_1(x_1 - x_2)$$

$$m_2 \frac{d^2 x_2}{dt^2} = k_1(x_1 - x_2) - k_2 x_2$$



$$\Rightarrow \begin{bmatrix} m_1 & 0 \\ 0 & m_2 \end{bmatrix} \begin{bmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{bmatrix} + \begin{bmatrix} k_1 & -k_1 \\ -k_1 & k_1 + k_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

For simplicity, assume

$$x_i(t) = a_i \sin(\omega t) \quad i = 1, 2$$

$$\Rightarrow \ddot{x}_i(t) = -\omega^2 a_i \sin(\omega t)$$

$$\underbrace{\begin{bmatrix} k_1 & -k_1 \\ -k_1 & k_1 + k_2 \end{bmatrix}}_{\underline{K}} \underbrace{\begin{bmatrix} a_1 \sin \omega t \\ a_2 \sin \omega t \end{bmatrix}}_{\underline{x}} = \omega^2 \underbrace{\begin{bmatrix} m_1 & 0 \\ 0 & m_2 \end{bmatrix}}_{\underline{M}} \underbrace{\begin{bmatrix} a_1 \sin \omega t \\ a_2 \sin \omega t \end{bmatrix}}_{\underline{x}}$$

$$\Rightarrow \underbrace{\underline{M}^{-1}}_{\sim} \underbrace{\underline{K}}_{\sim} \underline{x} = \lambda \underline{x}$$

$$\underline{A} \underline{x} = \lambda \underline{x} \quad \leftarrow \text{eigen problem}$$

$$\Rightarrow (\underline{A} - \lambda \underline{I}) \underline{x} = 0 \quad \leftarrow \underline{A} - \lambda \underline{I} \text{ must be singular to have non-trivial solutions.}$$

If  $\underline{x} = \underline{0}$ , trivial solution is possible,

$$\text{In reality, } x_i(t) = a_i \cos(\omega t) + b_i \sin(\omega t) \quad i = 1, 2$$

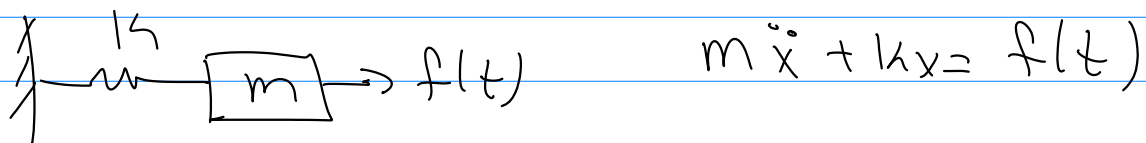
This makes it difficult to apply boundary conditions.

To make the application of boundary & initial conditions easier, move to a system of 1<sup>st</sup> - order ODEs.

(2) Systems of order-1 ODEs,

How can we convert order-2 or higher ODE?

Look at a single mass-spring system:



Introduce  $v = \dot{x} \Rightarrow \ddot{x} = \dot{v}$

$$\Rightarrow m\dot{v} + kx = f(t)$$
$$\dot{x} = v$$

$$\begin{bmatrix} \dot{x} \\ \dot{v} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -k/m & 0 \end{bmatrix} \begin{bmatrix} x \\ v \end{bmatrix} + \begin{bmatrix} 0 \\ f(t) \end{bmatrix}$$

$$\underline{\dot{u}} = \underline{A} \underline{u} + \underline{f}(t)$$

Note that any higher order ODE can be decomposed like this:

$$\text{ex.) let } a \ddot{x} + b \dot{x} + c x + dx = f(t)$$

$$u_1 = x \quad u_2 = \dot{x} = \dot{u}_1 \quad u_3 = \ddot{x} = \ddot{u}_2$$

$$\Rightarrow \dot{u}_1 = u_2$$

$$\ddot{u}_2 = u_3$$

$$a \ddot{u}_3 + b u_3 + c u_2 + d u_1 = f(t)$$

$$\Rightarrow \begin{bmatrix} \dot{u}_1 \\ \dot{u}_2 \\ \dot{u}_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -d/a & -c/a & -b/a \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ f(t)/a \end{bmatrix}$$

$$\underline{\dot{u}} = \underline{A} \underline{u} + \underline{f}(t)$$

$$\text{Focus on } \underline{\dot{u}} = \underline{A} \underline{u} + \underline{f}(t)$$

As before, solution will be

$$\underline{u}(t) = \underline{u}_h(t) + \underline{u}_p(t)$$

↑  
homogeneous  
sol

↑  
particular  
sol

Homogeneous Part: let  $\underline{u}_h(t) = \underline{x} e^{\lambda t}$

$$\Rightarrow \dot{\underline{u}}_h = \lambda \underline{x} e^{\lambda t}$$

$$= \underline{A} \underline{u}_h$$

$$\lambda \underline{x} e^{\lambda t} = \underline{A} (\underline{x} e^{\lambda t}) \Rightarrow \lambda \underline{x} = \underline{A} \underline{x}$$

$$\Rightarrow \underline{A} \underline{x} = \lambda \underline{x} \leftarrow \text{eigen problem}$$

$$\Rightarrow (\underline{A} - \lambda \underline{I}) \underline{x} = 0 \leftarrow \text{need non-trivial}$$

$\underline{x} \Rightarrow \underline{A} - \lambda \underline{I}$   
must be singular,

Follow previous procedure for  
real, repeated & imaginary  
eigen values.

For the particular solution, use method  
of undetermined coefficients.

$$\text{ex) if } \underline{f}(t) = \begin{bmatrix} 2e^{-3t} \\ 3t \end{bmatrix}$$

$$\text{Then try } \underline{x}_p(t) = \underline{a}t + \underline{b} + \underline{c}e^{-3t}$$

Instead of unknown coefficients, you  
have unknown vectors.

plus into the  $\dot{\underline{y}} = \underline{A}\underline{y} + \underline{f}(t)$  &

Solve for  $\underline{a}, \underline{b}, \underline{c}$

This helps for initial conditions because  
those are given directly,

$$\text{Ox}_1) \quad x(0) = \alpha \quad \& \quad \dot{x}(0) = \beta$$

$$x(0) = \alpha \quad \& \quad v(0) = \beta$$