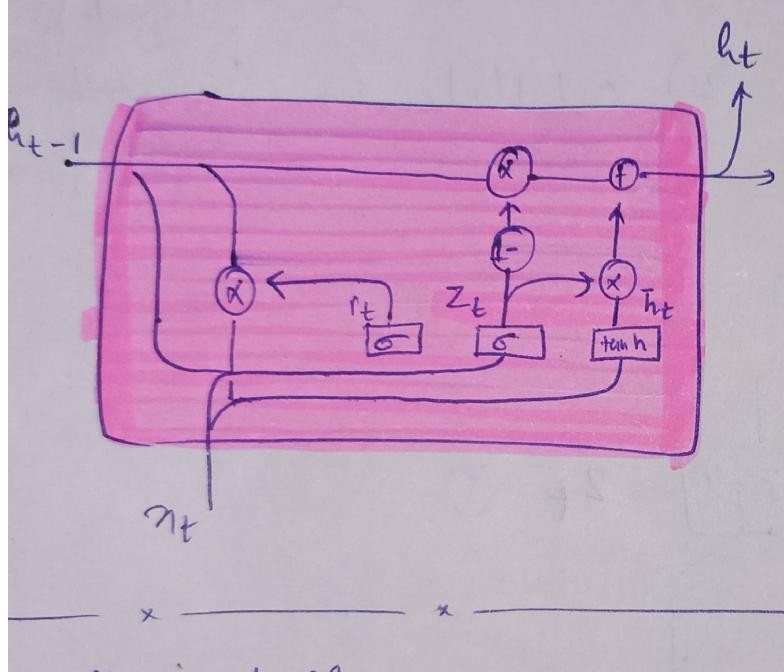


GRU → Gated Recurrent Unit :

- ↳ less Training Time.
- ↳ less parameters.
- simple Architecture
- ↳ Two gates as compared to LSTM.



→ The input x_t

Input → vector

| | | Sentiment | |
|-----|-----|-----------|--------|
| | | tent | vector |
| cat | mat | rat | 1 |
| cat | rat | mat | 0 |
| mat | rat | cat | 1 |

ONE
but exceeding

unique vocabulary → 3
cat mat rat

$$S_1 [100] [010] [001]$$

$$S_2 [100] [001] [010]$$

$$S_3 [010] [001] [100]$$

→ Advise → LSTM / GRU
↓
Confusing

→ goal → $[t]$

$$\frac{h_{t-1}}{x_t} > \frac{h_t}{-}$$

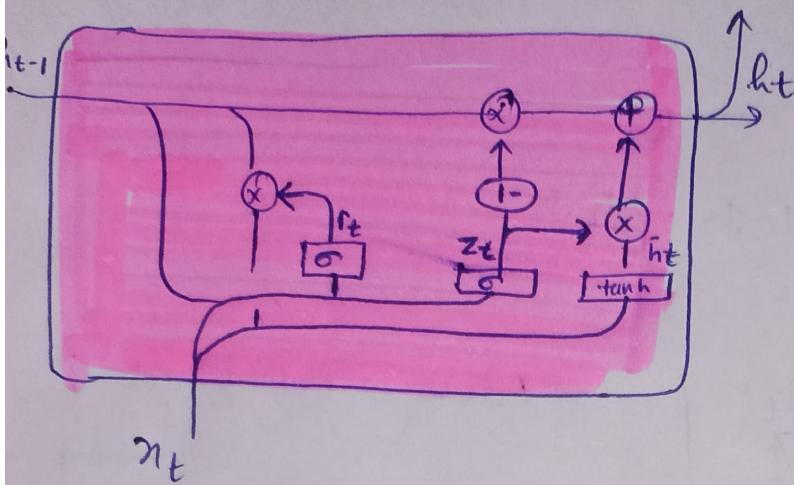
Prev hidden state → h_{t-1}
current hidden state → h_t
Timestep → t
reset gate → \otimes
update gate → \oplus
candidate hidden state → $\odot \text{ tanh}$

→ dimension always same.
except x_t .

→ $\odot \text{ tanh}$ → neural network layer.

→ $\otimes \oplus \odot$ → pointwise operators.

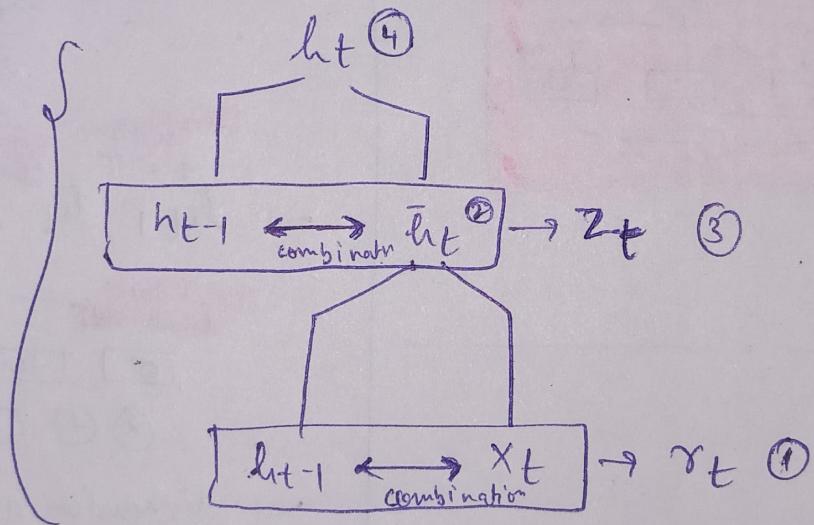
Architecture



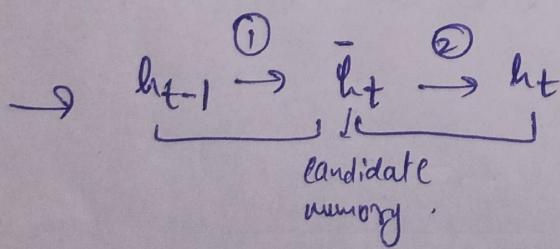
find out !!

$h_{t-1}, x_t \rightarrow h_t$

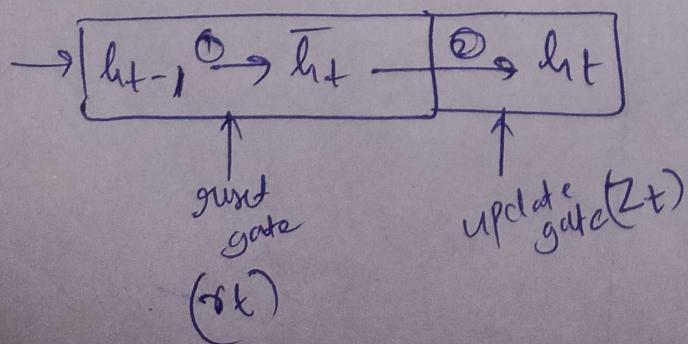
- Steps
- 1) calculate r_t (forget gate)
 - 2) calculate \tilde{h}_t (candidate hidden state)
 - 3) calculate z_t (update gate)
 - 4) calculate h_t (current hidden state)

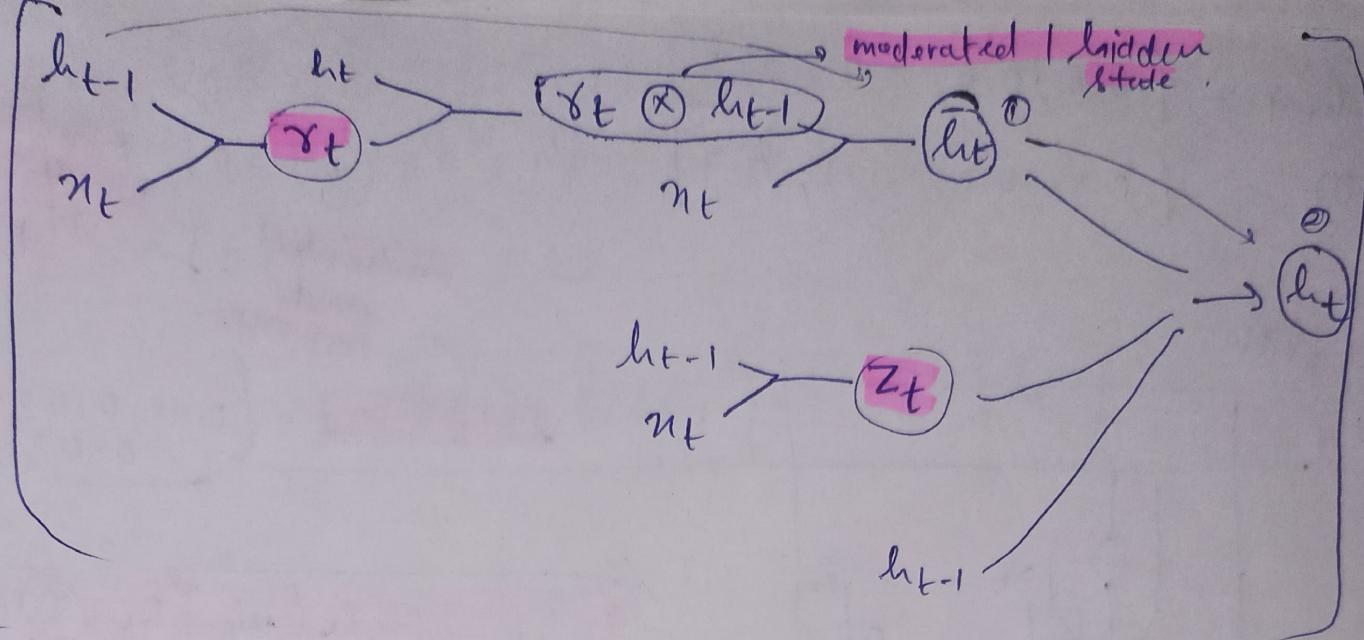


→ hidden state is just like a memory of the system.
content (store).



h_t
memory \rightarrow candidate
 R_t





* calculate the reset gate :

$\gamma_t \rightarrow$ vector $\rightarrow h_{t-1}$

↳ gate

$$h_{t-1} = [0.6, 0.6, 0.7, 0.1]$$

reset (lower) reset (higher).

$$\gamma_t = [0.8, 0.2, 0.1, 0.9]$$

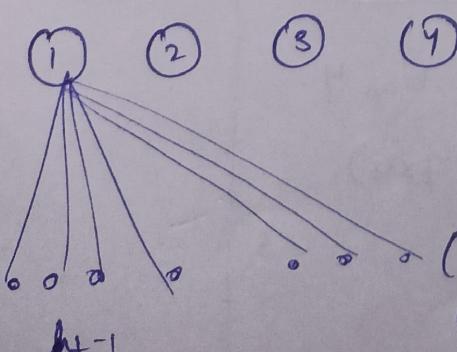
↑ 80% percent ↗ 20% --

↳ gate ↓

$$\gamma_t = \sigma(W\gamma(h_{t-1}, x_t) + b\gamma)$$

$h_{t-1} \rightarrow$ 4 dimension

$x_t \rightarrow$ 3 (no. of nodes)



$$\leftarrow (7 \times 4) = 28 + 4 \text{ bias}$$

$$(7) \times 1 \rightarrow (1 \times 7)$$

$$(1 \times 7) \times (7 \times 4)$$

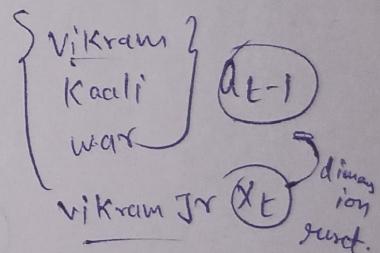
$$(1 \times 4) + (1 \times 4)$$

$$\rightarrow 8(1 \times 4)$$

[Power, confit, tracey storage]

[-----]

γ_t value $\rightarrow (0-1)$.



Matlab γ_t will control

h_{t-1} in dimension and

Reset control !!

γ_t will control Past memory

γ_t will control Reset

Based on current

Input .

$$h_{t-1} = [0.6, 0.6, 0.7, 0.1]$$

$$x_t = [0.8, 0.2, 0.1, 0.9].$$

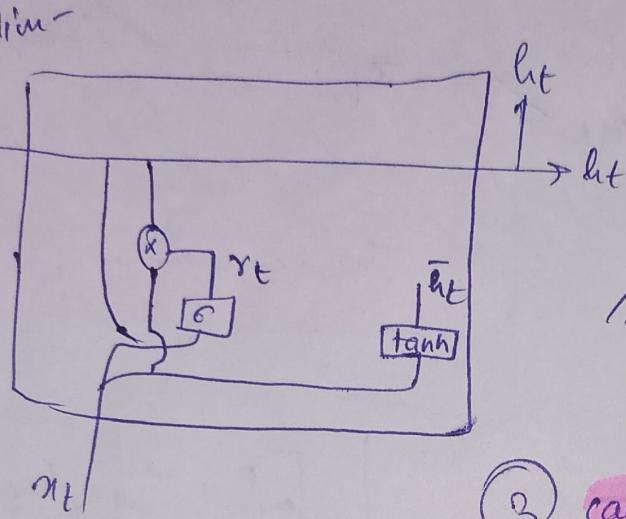
②

based on
current input.

modulated
past memory

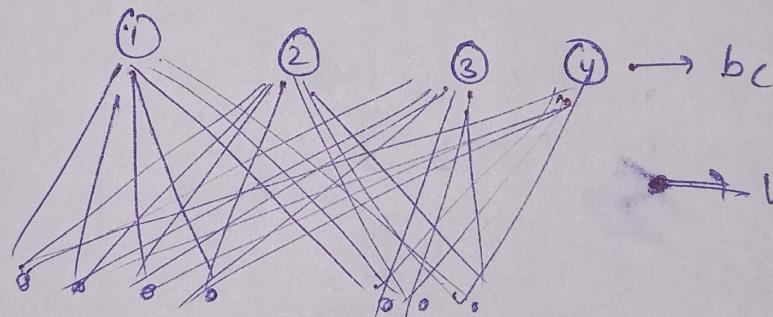
n_t

$$h_{t-1} \otimes x_t = [0.48, 0.12, 0.07, 0.09].$$



③ candidate
memory

$$\bar{h}_t = \tanh(w_c [h_{t-1} \otimes x_t, n_t] + b_c)$$



$$(h_{t-1} \otimes x_t)$$

$$h_{t-1}, n_t \rightarrow z_t \rightarrow \text{update gate}$$

$$z_t \rightarrow \sigma(w_z (h_{t-1} \otimes x_t) + b_z)$$

$$0 \quad 0 \quad 0 \quad 0 \rightarrow \text{bias } 4.$$

$$\rightarrow (7 \times 4)$$

$$0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0$$

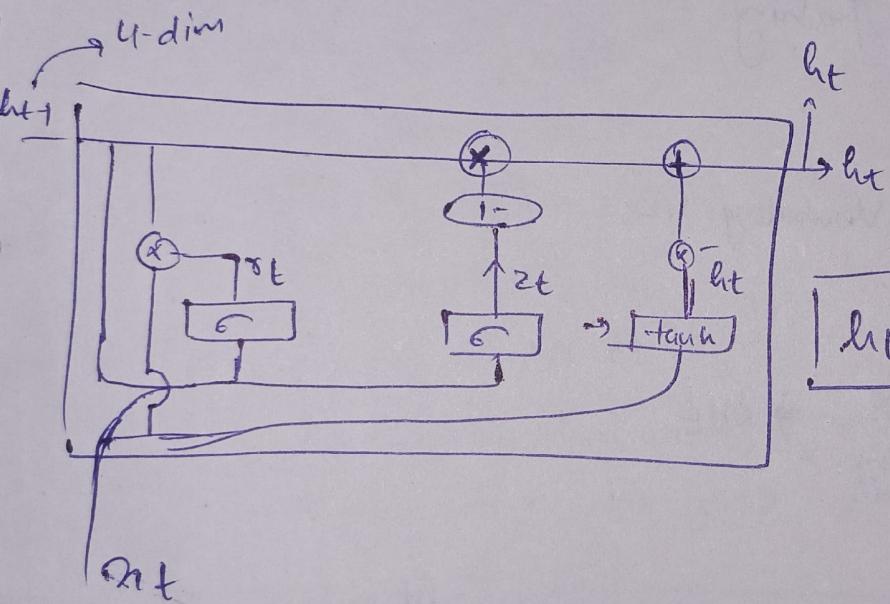
$$h_{t-1}$$

$$h_t = [0.7 \ 0.2 \ 0.1 \ 0.2]$$

$$h_{t-1} = [0.6 \ 0.6 \ 0.7 \ 0.1] \quad h_t$$

$$z_t = [0.7 \ 0.7 \ 0.8 \ 0.2]$$

$$\boxed{h_t = (1 - z_t) \odot h_{t-1} + z_t \odot \bar{h}_t}$$



$$\boxed{h_t = (1 - z_t) \odot h_{t-1} + z_t \odot \bar{h}_t}$$