

## Assignment - 5

1Q → Modern computers still need operating system because the OS manages Hardware and provide an easy interface for users and program.

→ It creates abstraction like processes for Running program, virtual memory for efficient storage Use, and files for I/O operations.

→ The OS handle process Management (CPU scheduling), Multitasking, memory management (allocation protection) and I/O management (Device communication).

→ It hides hardware complexity, ensures Security, and enables Resource Sharing.

(\*) Tip: 125

2Q → Monolithic os divides has all system services in one

large Kernel - fast but Hard to Maintain.

→ layered os divides the system into layers, each built on the one below - easiest to debug.

→ MicroKernel OS keeps only core functions (like communication) scheduling in the Kernel, moving other to user space. It is slower But more Reliable and Secure.

→ for a Distributed Web application, a MicroKernel OS is best because failures in one service don't crash the whole system, and update are easier.

3Q → Threads are lighter than processes Because they share the same memory, so the OS doesn't need to create a new address space like it does in a process.

→ A process control block (PCB) stores a lot of

Heavy Information, while a Thread control Block (TCB) stores much less.

- Because of this, thread context switching is faster than switching B/w processes.
- processes need more Resources and protection, Making them slower to manage.
- so threads are usually more efficient, But processes give better isolation and safety.

Q Case study : LINUX OS - demonstrating a Basic system call (file creation & Read).

- ✓ python program (uses os system call through .open(), write(), Read()) .

```
# file creation and Reading using system calls .
```

```
# creating file. (writes system call)
```

```
with open ("sample.txt", "w") as f :
```

```
f. write ("Hello OS!"! This is a linun system call  
demo.") .
```

```
# Reading the file. (Read system call) .
```

```
with open ("sample.txt", "r") as f :
```

```
Data = f. Read () .
```

```
print (" file content : ", data)
```

Output :

file content : Hello OS! This is a linun system call  
Demo .

- ✓ Relevance to OS Architecture .

→ when python uses open(), Read(), or write(), it asks the Linux Kernel to perform a task.

→ These actions are called System calls, which act like a Bridge b/w the program and the OS .

- The OS ensures safe access to the file system, manages permissions and stores data correctly.
- This demonstrates how user-level programs depend on kernel services, which is a core concept in OS Architecture.

## SQ Synchronous checkpointing :

- All nodes stop together, save their state at the same time then continue.  
Like taking a group photo everyone freezes for a moment.

### • Diagram :

Node A : ... work ... [checkpoint] ... work ...  
 Node B : ... work ... [checkpoint] ... work ...  
 Node C : ... work ... [checkpoint] ... work ...  
 ↑ All checkpoints together.

### • Pseudocode :

- Coordinator → send checkpoints request to all nodes
- All nodes pause updates.
- each node save state to stable storage.
- All nodes confirm DONE.
- System Resume.

### • Recovery :

- load last global checkpoint.
- Restart all nodes from the same point in time.

## ✓ Asynchronous checkpointing :

Nodes take checkpoints whenever they want, without

stoping other.

like taking individual Selfie instead of group photo.

### Diagram

Time →

Node A : ... work ... [CP] ... work ... [CP] ...

Node B : ... work ... [CP] ...

Node C : ... work ... [CP] ... work ...

(checkpoints occur at different Times)

- Pseudocode: each node independently

if timer expires

save checkpoints

- Recovery :

May need message logs to rebuild a consistent state

6Q a)

- 1) Transparency (Access + location Transparency)

User should feel like all files are on one computer even though they are spread across many machines

- The system must hide where the file is stored
- Ensures easy file sharing and uniform access.

- 2) fault Tolerance and Reliability.

Distributed system must keep working even if one machine crashes.

- file must be Replicated or logged.
- Recovery must ensure no data loss.

- b) i) client - server Architecture (NFS style)

Client Requests file → Server stores files.

- cache on the client to reduce load.

- stateless servers improve crash recovery.

Benefits: simple, scalable, good performance.

2) Replication - Based Architecture : (Make copies of files across Multiple Sites -

- o ensures fault Tolerance
- o Read operation becomes faster.

3) Distributed Naming and Metadata servers :

stores file names separately from file data

- o uses lookup Tables (like HDFS Name Node + Data Node Model).

Benefits : faster search, load balancing.  
easier Management.

70 a) Banker's algorithm checks before granting a lock whether the system will still be in safe state. like a Banker giving loans only when he knows every customer can finish and return money. So the OS only locks accounts if all transactions can still complete, preventing deadlocks.

b) Detection Approach :

→ Build a wait-for-graph (who is waiting for whose account lock).

→ If the graph forms a cycle → Deadlocks detected  
Recovery Approach -

→ Abort or Rollback one of the Transactions holding the locks.

→ Release its lock, letting others continue.

→ Restart the aborted Transaction later.

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producer - consumer using Semaphores

We use :-

- Mutex (Binary Semaphore) - allow only one thread

to access the buffer at a Time

→ Empty Semaphore → counts empty slots (producers wait if Buffer full)

→ full Semaphores → counts filled slots (consumers wait if Buffer empty).

### Simple Diagram :

producer → [empty--] → [MUTEX] → BUFFER → [-full]  
↓  
Consumer.

Python Code : (Semaphore Solution)

```
import threading, time, random
from threading import Semaphore
```

buffer = []

Buffer-size = 5.

mutex = Semaphore(1)

empty = Semaphore(Buffer-size)

full = Semaphore(0).

def producer():

while True:

item = random.randint(1, 100)

empty.acquire()

mutex.acquire()

buffer.append(item)

print("produced:", item)

mutex.release()

full.release()

def consumer():

while True:

```

full . acquire ( )
mutem . acquire ( )
item = Buffer . pop ( 0 ) .
print ( " consumed : " , item )
mutem . Release ( ) .
empty . Release ( ) .

```

Threading . thread ( target = producer ) . start ( )  
 Threading . thread ( target = consumer ) . start ( )

Q1 a) Scheduling strategy :-

→ Use priority scheduling with preemption :-

- Security Devices (cameras, alarms) = highest priority  
 → their interrupts immediately preempt other tasks.
- Normal tasks (lights, AC) = lower priority → Runs only when no critical Tasks

Justification :- ensures instant Response to security events while delaying non-critical work.

b) IPC Methods :-

use Message Queues + shared Memory + signals :-

- Message Queues :- send alerts from Devices → OS Reliably (ordered + asynchronous)
- shared Memory :- fast Data sharing b/w processes (eg :- sensor Reading)
- signals / Interrupts :- notify OS immediately when security trigger events

Justification :- provides fast, Reliable, event - driven communication in a Smart home - IOT environment.

10Q

(FIFO)

2	1	4	2	3	4	3
2	2	2	2	3	3	3
	1	1	1	1	1	1
		4	4	4	4	4
F	F	F				

FIFO page fault = 4

(LRU)

2	1	4	2	3	4	3
2	2	2	2	2	2	2
	1	1	1	3	3	3
		4	4	4	4	4
F	F	F		F		

LRU page fault = 4

process	Burst Time (ms)	Arrival Time (ms)
P <sub>1</sub>	5	0
P <sub>2</sub>	3	1
P <sub>3</sub>	8	2
P <sub>4</sub>	6	3

a) FCFS

P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>4</sub>
0	5	8	16

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order : P<sub>1</sub> → P<sub>2</sub> → P<sub>3</sub> → P<sub>4</sub>

b) SJF (non-preemptive)

• t = 0 → P<sub>2</sub>

P <sub>1</sub>	P <sub>2</sub>	P <sub>4</sub>	P <sub>3</sub>
0	5	8	14

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• t = 5 → P<sub>2</sub>, P<sub>3</sub>, P<sub>4</sub> (choose P<sub>2</sub>)

shortest

• After P<sub>2</sub> → choose P<sub>4</sub>.• finally P<sub>3</sub>.

c) Round Robin (q = 4ms)

P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>4</sub>	P <sub>1</sub>	P <sub>3</sub>	P <sub>4</sub>
0	4	7	11	15	16	20

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P<sub>1</sub> : Runs 4 → Remaining 1

P<sub>2</sub> : Runs 3 → Done

P<sub>3</sub> : " 4 → Remaining 4

P<sub>4</sub> : " 4 → " 2

P<sub>1</sub> : " 1 → Done

P<sub>3</sub> : " 4 → Done

P<sub>4</sub> : " 2 → Done

### (5) 1) FCFS

process	WT	TAT
P <sub>1</sub>	0	5
P <sub>2</sub>	4	7
P <sub>3</sub>	6	14
P <sub>4</sub>	13	19

$$\text{Avg WT} = (0+4+6+13)/4 = 5.75$$

$$\text{Avg TAT} = 11.25$$

### 2) SJF (Non-preemptive)

process	WT	TAT
P <sub>1</sub>	0	5
P <sub>2</sub>	4	7
P <sub>3</sub>	5	11
P <sub>4</sub>	12	22

$$\text{Avg WT} = 5.25$$

$$\text{Avg TAT} = 10.75$$

### 3) Round Robin (q=1)

process	WT	TAT	Avg WT = 9.25
P <sub>1</sub>	$10 - 0 - 5 = 11$	16	Avg TAT = 14.75
P <sub>2</sub>	$7 - 1 - 3 = 3$	6	
P <sub>3</sub>	10	18	
P <sub>4</sub>	13	19	

c) FCFS -

- simple But suffer from "convo effect"
- long Jobs Block ones
- worst Responsiveness -

→ SJF -

- ~~not~~ Minimize average waiting Time

→ Round Robin -

- Best fairness and Responsiveness -
- Higher context - switch overhead.