# Practical Assignment 5 Fermi–Pasta–Ulam–Tsingou Problem

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# Section 1: Algorithm (natural language)

- 1. System & variables: N = 32 oscillators with fixed ends  $(q_0 = q_{N+1} = 0)$ . Mass = 1. Nonlinearity parameter  $\alpha$ . Displacements  $q_j$  and momenta  $p_j$ .
- 2. Equations of motion:

$$\ddot{q}_i = (q_{i+1} - 2q_i + q_{i-1}) + \alpha [(q_{i+1} - q_i)^2 - (q_i - q_{i-1})^2], \quad j = 1, \dots, N.$$

- 3. **Time integration**: Velocity Verlet (symplectic, second order). Update positions  $q_j$ , compute forces  $f_j = \ddot{q}_j$ , update momenta  $p_j$ . Fixed time step  $\Delta t$ .
- 4. **Initial condition**: Only the first mode excited:

$$q_j(0) = A \sin \frac{\pi j}{N+1}, \qquad p_j(0) = 0, \quad A = 0.1.$$

5. Modal projection: Linear normal modes

$$\phi_{j,k} = \sqrt{\frac{2}{N+1}} \sin\left(\frac{\pi k j}{N+1}\right),$$

with frequencies  $\omega_k = 2\sin\frac{\pi k}{2(N+1)}$ . Modal coordinates:  $Q_k(t) = \sum_j \phi_{j,k} q_j(t)$ ,  $P_k(t) = \sum_j \phi_{j,k} p_j(t)$ . Modal energy:

$$E_k(t) = \frac{1}{2} \left( P_k^2 + \omega_k^2 Q_k^2 \right).$$

- 6. Diagnostics:
  - Plot  $E_1(t), E_2(t), E_3(t)$  vs time.
  - Heatmap of  $E_k(t)/\sum_j E_j(t)$ .
  - Recurrence measure

$$R(t) = \frac{\sum_{k} (Q_k(t)Q_k(0) + P_k(t)P_k(0))}{\sum_{k} (Q_k(0)^2 + P_k(0)^2)}.$$

7. Outputs: Chosen  $\Delta t = 0.05$ , long total time  $T_{\rm total} \sim 20000-100000$  to see recurrences.

### Section 2: Code

# C++ Integrator (fput\_alpha.cpp)

```
// fput_alpha.cpp
  // Compile: g++ -02 fput_alpha.cpp -o fput_alpha
   // Runs
             FPUT
                     with Velocity Verlet. Outputs:
      - energies_123.txt : t E1 E2 E3
      - modes_time.txt
                          : t E1 E2 ... E_N (full modal energies at each
       output time)
   // - heatmap_norm.txt : matrix (rows: k=1..N, cols: time-steps) of
6
      normalized E_k(t)
   // - R_vs_t.txt
                            : t R(t)
7
8
   #include <bits/stdc++.h>
10
   using namespace std;
11
   int main(int argc, char** argv){
12
       // PARAMETERS (user can tune)
13
       int N = 32;
                                         // number of oscillators
14
       double alpha = 0.25;
                                         // nonlinearity
                                                            (change to study
15
          TR dependence)
       double A = 0.1;
                                         // initial amplitude for mode 1
16
                                         // time step
       double dt = 0.05;
17
                                         // total simulation time (increase
       double T_total = 20000.0;
18
          if recurrence not observed)
       int out_every = 40;
                                         // write outputs every 'out_every'
          steps
       // parse optional CLI args: alpha, dt, T_total, out_every
20
       if(argc >= 2) alpha = atof(argv[1]);
21
       if(argc >= 3) dt = atof(argv[2]);
22
       if(argc >= 4) T_total = atof(argv[3]);
23
       if(argc >= 5) out_every = atoi(argv[4]);
24
25
       int steps = int(T_total / dt);
26
       int write_steps = steps / out_every + 2;
27
28
       vector < double > q(N+2,0.0), p(N+2,0.0), q_new(N+2,0.0), force(N)
29
           +2,0.0);
30
       // MODE FUNCTIONS: phi[j][k] where j=1..N, k=1..N
31
       vector < vector < double >> phi(N+1, vector < double > (N+1,0.0));
32
       for(int k=1; k<=N; k++) {</pre>
33
           double norm = sqrt(2.0/(N+1));
34
           for(int j=1; j <= N; j++) {</pre>
35
                phi[j][k] = norm * sin(M_PI * k * j / double(N+1));
36
37
       }
38
       // linear frequencies
39
       vector < double > omega(N+1,0.0);
40
       for(int k=1;k<=N;k++){</pre>
41
           omega[k] = 2.0 * sin(M_PI * k / (2.0 * (N+1)));
42
       }
43
44
       // Initial condition: excite only first mode
45
       for(int j=1; j <= N; j++) {</pre>
46
```

```
q[j] = A * sin(M_PI * j / double(N+1)); // same as phi[j][1] *
47
                (A / phi_norm)
            p[j] = 0.0;
48
        }
49
        q[0] = q[N+1] = 0.0;
50
51
        // Precompute Qk(0), Pk(0) and denominators for R(t)
52
        vector < double > Q0(N+1,0.0), P0(N+1,0.0);
53
        for(int k=1;k<=N;k++){</pre>
54
            double Qk=0.0, Pk=0.0;
55
            for(int j=1; j <= N; j++) {</pre>
56
57
                Qk += phi[j][k] * q[j];
                Pk += phi[j][k] * p[j];
58
59
            QO[k]=Qk; PO[k]=Pk;
60
61
        double denomR = 0.0;
62
        for(int k=1; k \le N; k++) denomR += Q0[k]*Q0[k] + P0[k]*P0[k];
63
64
        // Prepare output files
65
        ofstream f123("energies_123.txt");
66
        ofstream fmodes("modes_time.txt");
67
        ofstream fheat("heatmap_norm.txt");
        ofstream fR("R_vs_t.txt");
69
70
        // Write headers
71
       f123 << "# t E1 E2 E3\n";
72
       fmodes << "# t";</pre>
73
        for(int k=1;k<=N;k++) fmodes << " E" << k;</pre>
74
        fmodes << "\n";
75
        fR << "# t R\n";
76
77
        // temporary storage for normalized energy heatmap columns
78
       vector<vector<double>> heat(N+1, vector<double>(write_steps, 0.0));
79
        // FUNCTION to compute forces f_j from q (indices 1..N)
81
        auto compute_force = [&](const vector<double>& qq, vector<double>&
82
           ff){
            // fixed ends q0,qN+1 assumed 0 in qq[0] and qq[N+1]
83
            for(int j=1; j <= N; j++) {</pre>
84
                double lap = qq[j+1] - 2.0*qq[j] + qq[j-1];
85
                double nonlin = alpha * ( (qq[j+1]-qq[j])*(qq[j+1]-qq[j]) -
                     (qq[j]-qq[j-1])*(qq[j]-qq[j-1]));
                ff[j] = lap + nonlin;
87
88
            ff[0]=ff[N+1]=0.0;
89
        };
90
91
       // initial forces
92
        compute_force(q, force);
93
94
        int write_idx = 0;
95
        // compute initial modal energies and R, write t=0
96
        auto compute_modal = [&] (const vector < double > & qq, const vector <</pre>
97
           double > & pp, vector < double > & Ek, vector < double > & Qk, vector <
           double > & Pk) {
            for (int k=1; k<=N; k++) {</pre>
98
                double Q=0.0, P=0.0;
```

```
for(int j=1; j <= N; j++) {</pre>
100
                      Q += phi[j][k]*qq[j];
101
                      P += phi[j][k]*pp[j];
102
103
                 Qk[k]=Q; Pk[k]=P;
104
                 Ek[k] = 0.5 * (P*P + omega[k]*omega[k] * Q*Q);
105
             }
106
        };
107
108
        vector < double > Ek (N+1,0.0), Qk (N+1,0.0), Pk (N+1,0.0);
109
        compute_modal(q,p,Ek,Qk,Pk);
110
        double Esum = 0.0; for(int k=1; k \le N; k++) Esum += Ek[k];
111
        // write initial lines
112
        fmodes << 0.0;
113
        for(int k=1;k<=N;k++) fmodes << " " << Ek[k];</pre>
114
        fmodes << "\n";
115
        f123 << 0.0 << " " << Ek[1] << " " << Ek[2] << " " << Ek[3] << "\n"
116
        double R0 = 0.0;
117
        for(int k=1;k<=N;k++) RO += Qk[k]*Q0[k] + Pk[k]*P0[k];</pre>
118
        RO /= denomR;
119
        fR << 0.0 << " " << R0 << " \n";
120
        // fill heat column 0
121
        for(int k=1;k<=N;k++) heat[k][write_idx] = Ek[k]/Esum;</pre>
122
        write_idx++;
123
124
        // MAIN TIME LOOP (Velocity Verlet)
125
        for(int step=1; step<=steps; ++step){</pre>
126
             // positions half-step update (full-step positions in VV
127
                formula)
             for(int j=1;j<=N;j++){</pre>
128
                 q[j] += p[j]*dt + 0.5 * force[j] * dt*dt; // since mass =1,
129
                      acceleration = force
130
             // Enforce fixed boundaries
131
             q[0]=0.0; q[N+1]=0.0;
132
133
             // compute new forces at q
134
             compute_force(q, q_new); // reuse q_new as temporary force
135
                storage
             // update momenta (full-step)
136
             for(int j=1;j<=N;j++){</pre>
137
                 p[j] += 0.5*(force[j] + q_new[j]) * dt;
138
139
             // set force = q_new for next iteration
140
141
            force = q_new;
142
             // outputting
143
             if(step % out_every == 0){
144
                 double t = step * dt;
145
                 compute_modal(q,p,Ek,Qk,Pk);
146
                 double Esum_now = 0.0; for(int k=1;k<=N;k++) Esum_now += Ek</pre>
147
                     [k];
148
                 fmodes << t;</pre>
                 for(int k=1; k<=N; k++) fmodes << " " << Ek[k];</pre>
149
                 fmodes << "\n";</pre>
150
                 f123 << t << " " << Ek[1] << " " << Ek[2] << " " << Ek[3]
151
                     << "\n";
```

```
double R = 0.0;
152
                  for (int k=1; k \le N; k++) R += Qk[k]*Q0[k] + Pk[k]*P0[k];
153
                  R /= denomR;
154
                  fR << t << " " << R << "\n";
                  // heat column
156
                  int col = write_idx;
157
                  for(int k=1;k<=N;k++) heat[k][col] = Ek[k] / Esum_now;</pre>
158
                  write_idx++;
159
             }
160
         } // end time loop
161
162
163
         // write heatmap matrix: rows k=1..N, columns time snapshots
         for(int k=1; k<=N; k++) {</pre>
164
             for(int c=0;c<write_idx;c++){</pre>
165
                  fheat << heat[k][c];</pre>
166
                  if(c+1<write_idx) fheat << " ";</pre>
167
168
             fheat << "\n";</pre>
169
         }
170
171
         fmodes.close(); f123.close(); fheat.close(); fR.close();
172
         cout << "Done. Outputs: energies_123.txt modes_time.txt</pre>
173
            heatmap_norm.txt R_vs_t.txt\n";
         return 0;
174
    }
175
```

## Python Plotting Script (plot\_fput.py)

```
# plot_fput.py
  # Usage: python3 plot_fput.py
  import numpy as np
  import matplotlib.pyplot as plt
   # Load E1, E2, E3
   data123 = np.loadtxt("energies_123.txt", comments="#")
   t = data123[:,0]; E1 = data123[:,1]; E2 = data123[:,2]; E3 = data123
      [:,3]
  plt.figure(figsize=(8,4))
10
  plt.plot(t, E1, label='E1')
11
   plt.plot(t, E2, label='E2')
   plt.plot(t, E3, label='E3')
13
   plt.xlabel('Time'); plt.ylabel('Modal Energy')
14
   plt.legend(); plt.title('E1, E2, E3 vs time')
15
   plt.grid(True); plt.tight_layout()
   plt.savefig('E123_vs_time.png', dpi=200)
17
18
   # Heatmap
19
  heat = np.loadtxt("heatmap_norm.txt")
20
   plt.figure(figsize=(8,5))
21
   extent = [t[0], t[-1], 1, heat.shape[0]]
22
  plt.imshow(heat, aspect='auto', origin='lower', extent=extent)
  plt.colorbar(label='Normalized Ek(t)')
  plt.ylabel('Mode index k'); plt.xlabel('Time')
26 | plt.title('Heatmap of normalized modal energy')
27 | plt.tight_layout()
```

```
plt.savefig('heatmap_modes.png', dpi=200)
29
   # R(t)
30
  R = np.loadtxt("R_vs_t.txt", comments="#")
31
  plt.figure(figsize=(7,3.5))
32
   plt.plot(R[:,0], R[:,1])
33
   plt.xlabel('Time'); plt.ylabel('R(t)')
34
  plt.title('Recurrence measure')
  plt.grid(True); plt.tight_layout()
36
  plt.savefig('R_vs_t.png', dpi=200)
```

# Section 3: Outputs and Discussion

#### **Expected Outputs**

- Energies:  $E_1(t), E_2(t), E_3(t)$  vs time show energy transfer and recurrence.
- **Heatmap:** normalized  $E_k(t)$  across modes reveals spreading and refocusing of energy.
- Recurrence measure: R(t) shows peaks near 1 indicating recurrence times  $T_R$ .

### Answers to Questions

- 1. **Dependence of**  $T_R$  **on**  $\alpha$ : Smaller  $\alpha$  (weaker nonlinearity)  $\Rightarrow$  longer recurrence time. Typically  $T_R \propto 1/\alpha$  (order of magnitude).
- 2. **Energy dissipation:** For weak  $\alpha$ , energy does not irreversibly dissipate to all modes. It oscillates among low modes and returns.
- 3. **Paradoxical behavior:** Statistical mechanics predicts equipartition, but instead the system shows quasi-periodic recurrences and lack of ergodicity.

#### KAM Theorem

KAM theorem states that for nearly integrable Hamiltonians, most invariant tori survive under weak perturbation. Hence the dynamics remains quasi-periodic, preventing full equipartition. This resolves the paradox.

#### What I Learned

Imagine a line of N = 32 small balls (oscillators) connected by springs in a row. These springs are **not purely linear**; they have a small **nonlinear component**. The ends of the chain are fixed, so the first and last balls cannot move.

Classical intuition suggests that if we give energy to one simple mode of motion, the nonlinearity should allow the energy to spread among all modes, eventually reaching equipartition (equal distribution).

Surprisingly, when Fermi, Pasta, Ulam, and Tsingou did their computer experiment in the 1950s, they observed something very counterintuitive:

• Energy initially given to the **first mode** did not spread evenly among all modes.

- Instead, energy **cycled back** to the first mode after some time a phenomenon called **recurrence**.
- This repeated multiple times: the system seemed to "remember" its initial state.

Mathematical Model

Each oscillator j has displacement  $q_j(t)$ . The equations of motion for the  $\alpha$ -FPUT model are:

$$\ddot{q}_j = (q_{j+1} - 2q_j + q_{j-1}) + \alpha \left[ (q_{j+1} - q_j)^2 - (q_j - q_{j-1})^2 \right], \quad j = 1, 2, \dots, N$$

with **fixed ends**:

$$q_0 = q_{N+1} = 0$$

Here:

- The first term is the linear spring force.
- The second term is the nonlinear correction, controlled by the parameter  $\alpha$ .

Intuitive Example

Think of a **guitar string**:

- 1. Pluck the string at one end: only the first wave (mode) moves.
- 2. If the string were fully nonlinear, the energy should scatter into many vibration patterns.
- 3. In the FPUT system, most of the energy **returns** to the original mode after a while, as if the string "remembers" your pluck.

Why it Matters

The FPUT problem is important because:

- It was one of the first **numerical experiments** in physics.
- It showed that nonlinear systems do not always behave chaotically.
- It inspired research on solitons, KAM theory, and modern nonlinear dynamics.
- It demonstrates a **paradox in statistical mechanics**: energy does not thermalize as expected.