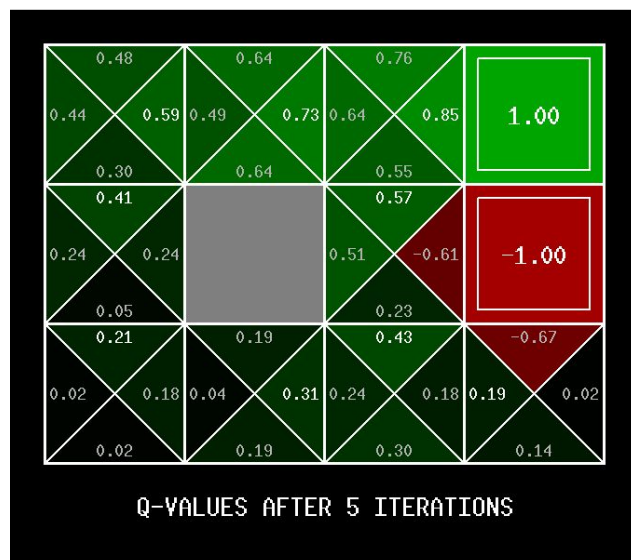
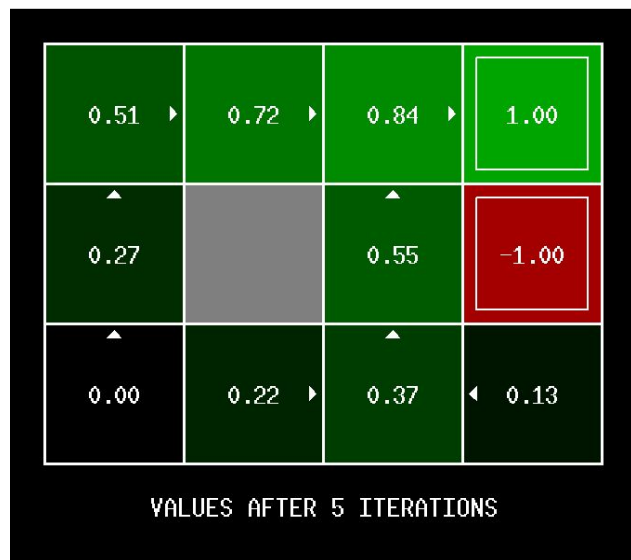


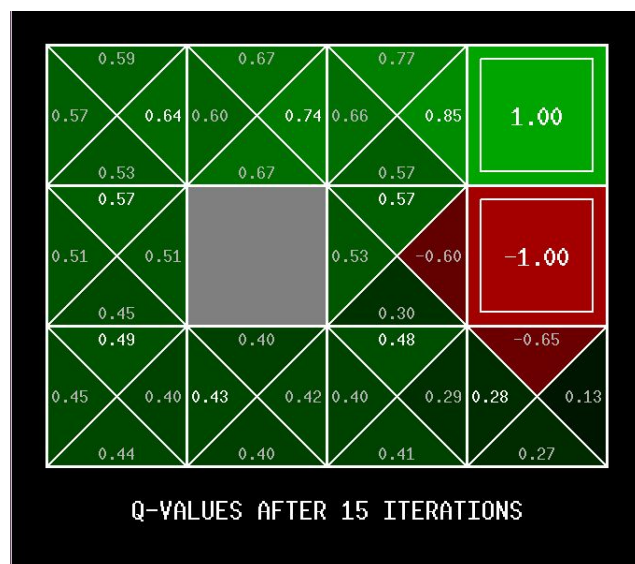
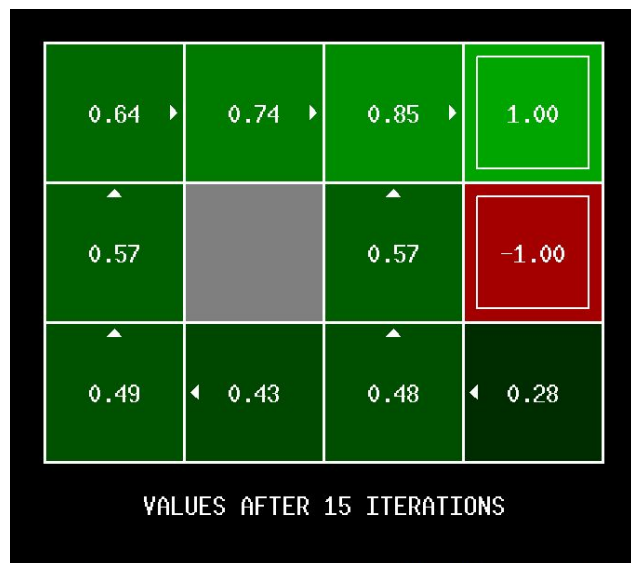
# ASSIGNMENT-4

-SHUBHAM KUMAR

QUES 1.



To test my implementation, I have run it for 5 iterations. And the screenshots are above. Q-values are numbers in square quarters, and policies are arrows out from each square.



It converges at 15th iteration.

## 1.2.



Running it to the default values.

### Unsuccessful Attempts

- Discount same, noise = 0.1, 0.3





- noise = 0.2 , discount = 1 , 0.8





### Successful Attempt



Noise = 0.01 Discount = 0.9 (same) : As, the fig shows the agent will cross the bridge. Changing discount doesn't help because the goal is fixed. And the path between source and goal is fixed i.e. straight line.

We have to reduce the noise, so that the agent goes to west and doesn't move to north or south. We are reducing degree of randomness.

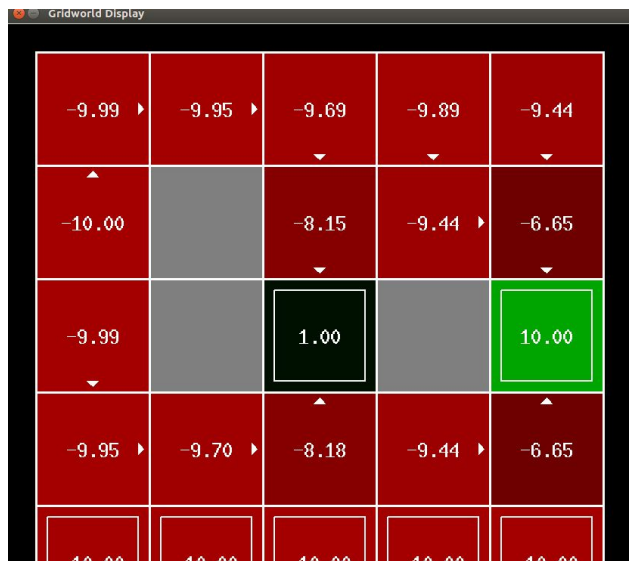
## 1.3.

### 1. Wrong attempts.

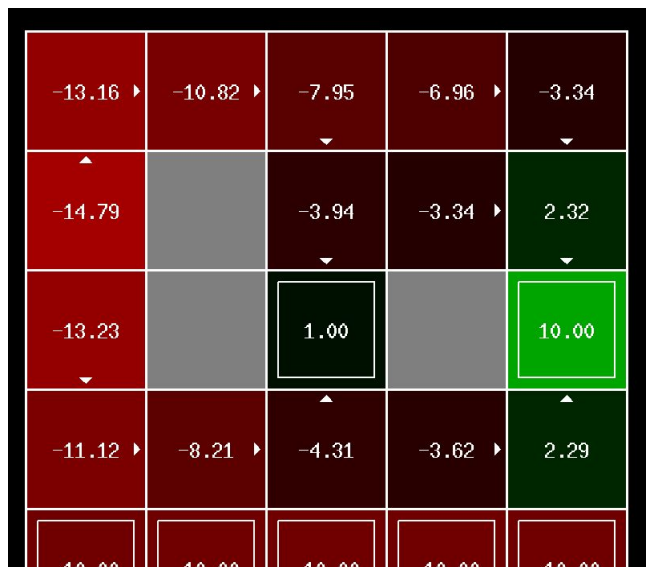
- Taking too much discount



Final : 0.2, 0.18, -6.99, because we want to go to close terminal, therefore discount is small. To avoid going into cliff, our noise is less. Living reward should be negative and big number because we want to be closer to cliff.



## 2. Wrong attempt



Final ans: 0.2, 0.18, -0.3 living reward is kept high to take longer path avoiding the cliffs.



### 3. Wrong attempt:



Final ans: 0.9, 0.01, 0.01

We are risking the cliff, therefore, noise should be less. Whereas the discount should be kept high to reach 10. And living reward should be low, to follow lower path.



5.33 ▶	5.92 ▶	6.57 ▶	7.29 ▶	8.10 ▼
▲ 4.80		7.26 ▶	8.10 ▶	9.00 ▼
5.07 ▼		1.00		10.00
5.63 ▶	6.33 ▶	7.11 ▶	8.02 ▶	9.00 ▲
-10.00	-10.00	-10.00	-10.00	-10.00

#### 4. Wrong answer

5.33 ▶	5.92 ▶	6.57 ▶	7.29 ▶	8.10 ▼
▲ 4.80		7.26 ▶	8.10 ▶	9.00 ▼
5.07 ▼		1.00		10.00
5.63 ▶	6.33 ▶	7.11 ▶	8.02 ▶	9.00 ▲
-10.00	-10.00	-10.00	-10.00	-10.00

Final ans: 0.9 , 0.2 , 0.3; going north then east, therefore more discount and living reward.

6.66 ▶	7.07 ▶	7.50 ▶	8.01 ▶	8.51 ▼
▲ 6.34		7.29 ▶	8.51 ▶	▼ 9.19
▲ 6.05		1.00		10.00
▲ 5.69	▲ 4.65	4.32 ▶	6.57 ▶	▲ 9.00
10.00	10.00	10.00	10.00	10.00

## 5. Wrong ans

6.12 ▶	6.60 ▶	7.09 ▶	7.68 ▶	8.26 ▼
▲ 5.74		6.97 ▶	8.26 ▶	▼ 9.06
▲ 5.40		1.00		10.00
▲ 5.00	▲ 3.99	4.07 ▶	6.36 ▶	▲ 8.87
10.00	10.00	10.00	10.00	10.00

Final ans: 0.99 , 0.12, 1

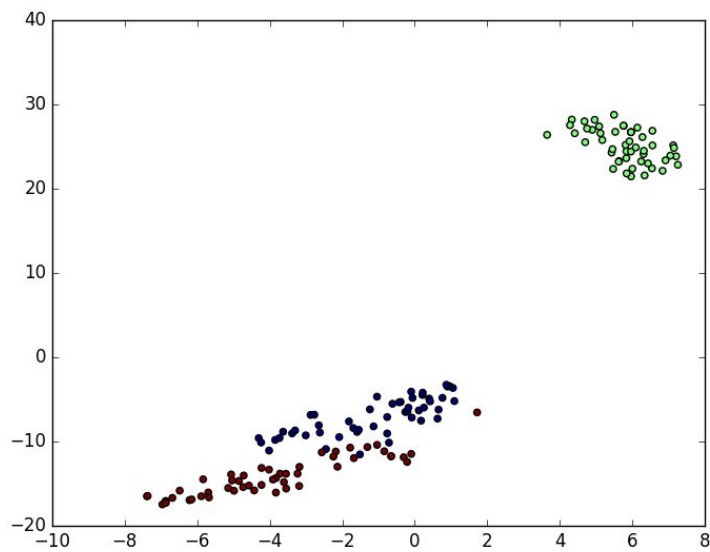


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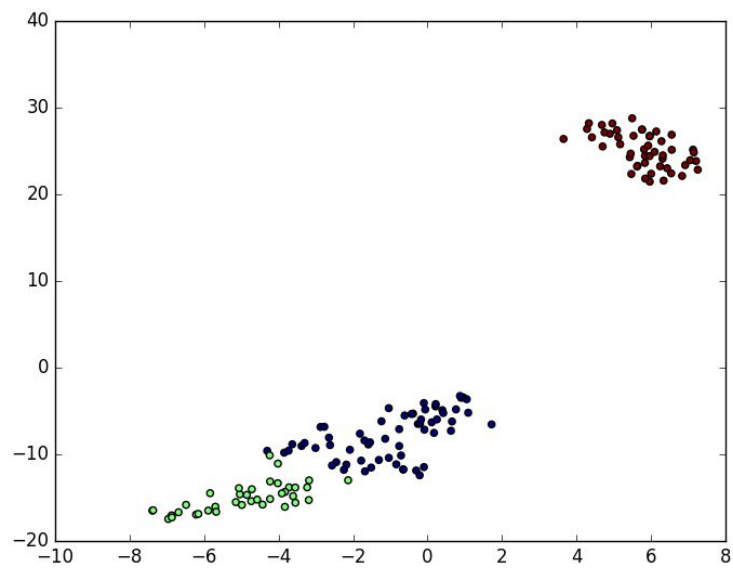
## QUES 2.

*IRIS*

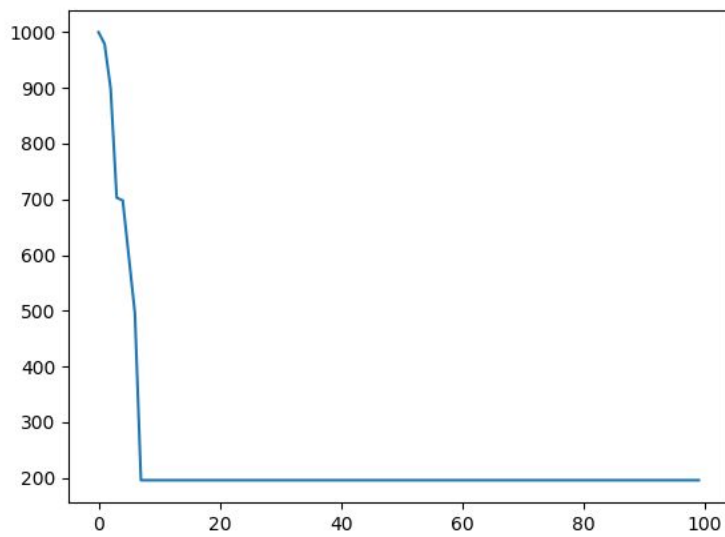
W/O K MEANS



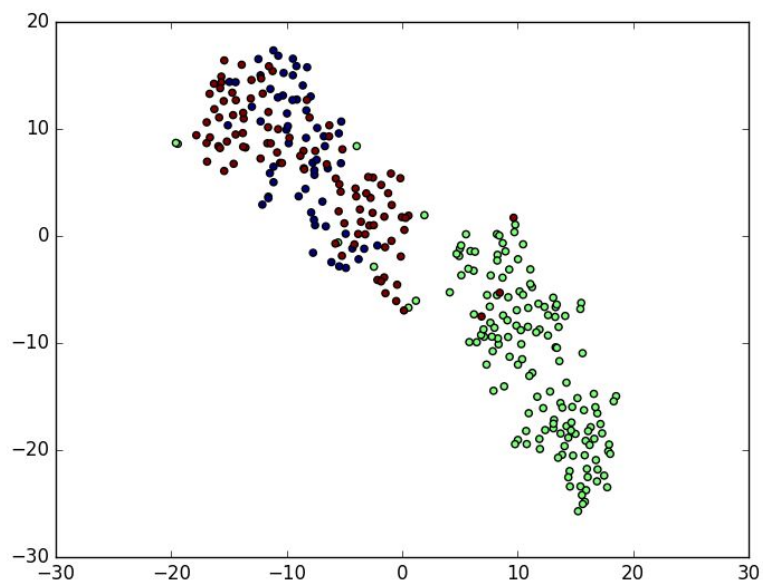
WITH K MEANS



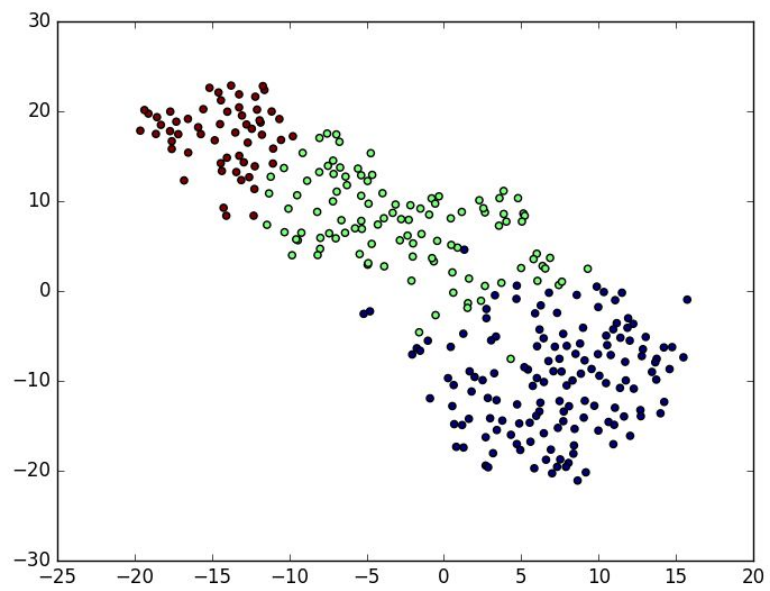
## OBJECTIVE FUNCTION - ITERATIONS



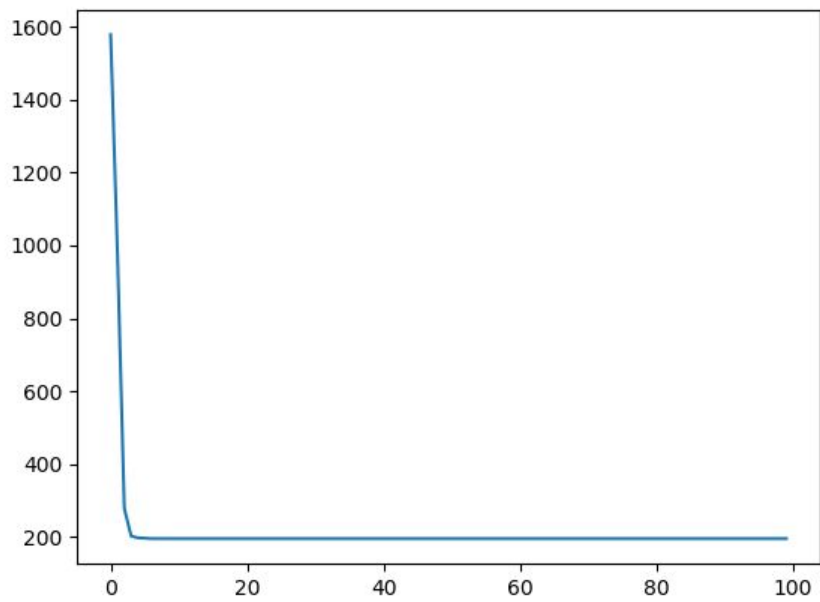
## **VERTEBRAL** W/O K MEANS



WITH K MEANS

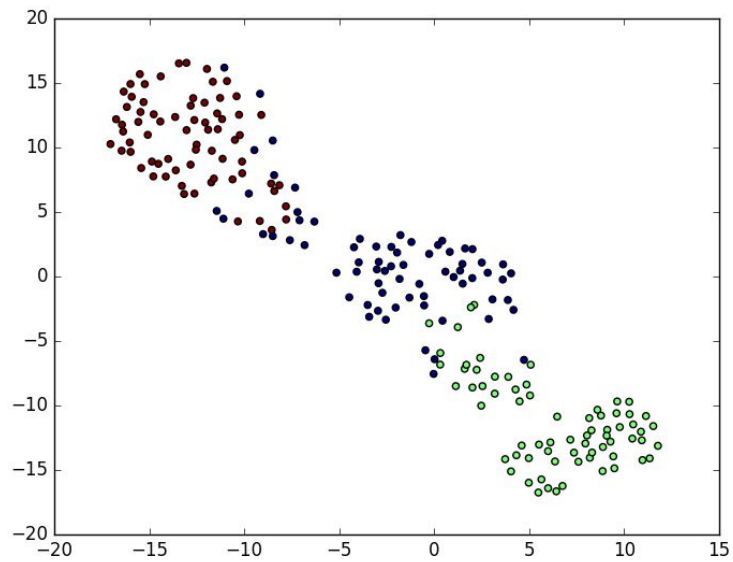


OBJECTIVE FUNCTION - ITERATIONS

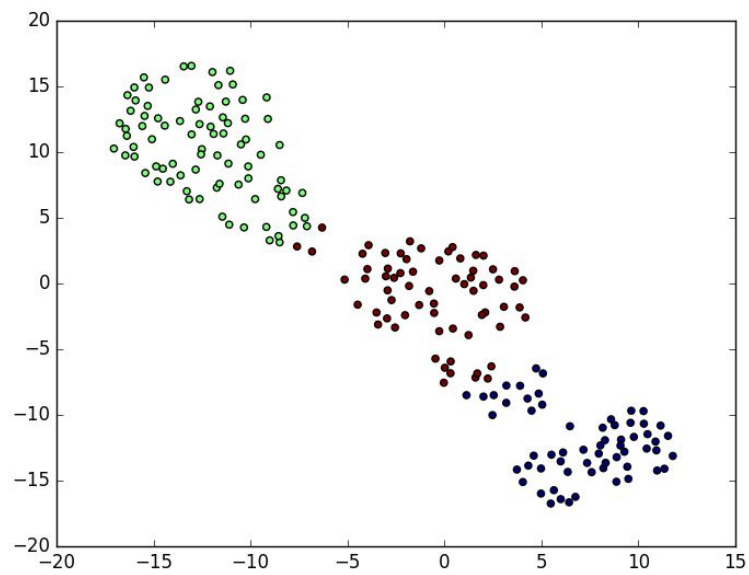


## ***SEEDS DATASET***

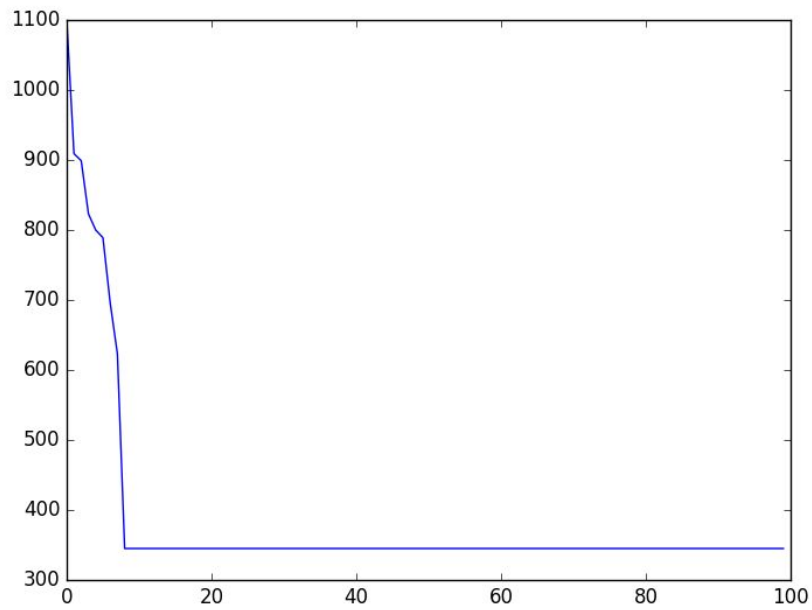
W/O K MEANS



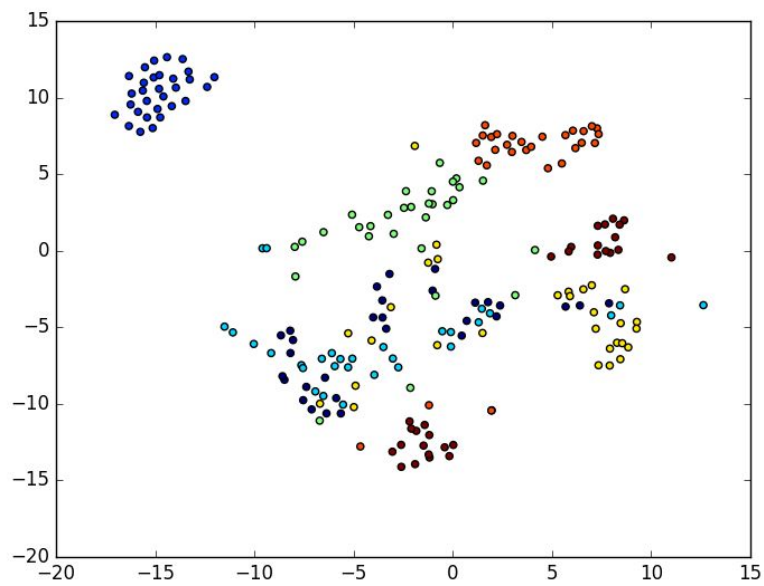
WITH K MEANS



## OBJECTIVE FUNCTION - ITERATIONS

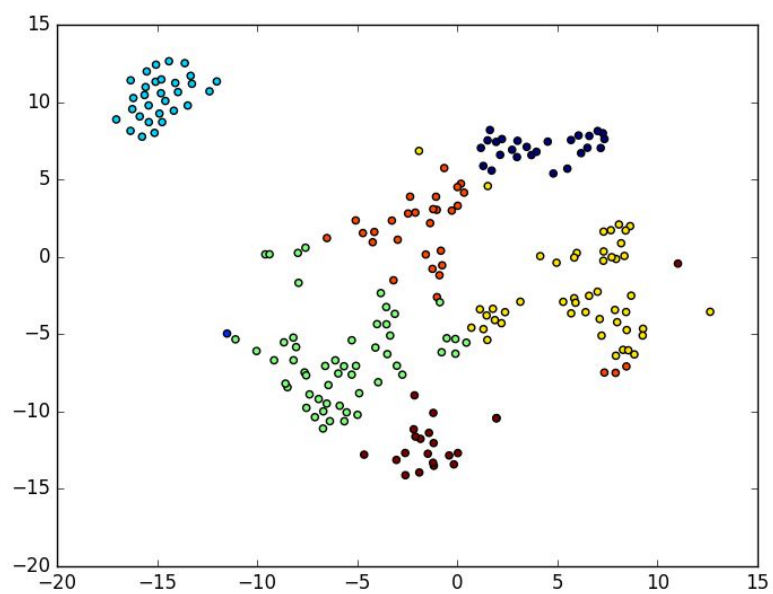


## **SEGMENTATION** W/O K MEANS

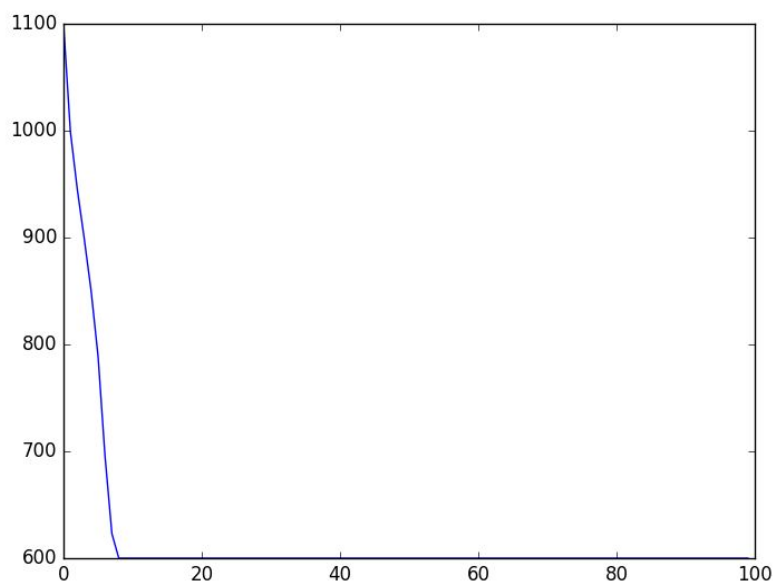


## WITH K MEANS





## OBJECTIVE FUNCTION - ITERATIONS



**INFERENCE:**

The division was pretty much same as the one obtained in the original graphs and the best division was when  $k = \text{truth value}$ . The outliers were removed, which provided such a clear division.

TABLE:

DATA	K=2			K= True			K=12		
	ARI	NMI	AMI	ARI	NMI	AMI	ARI	NMI	AMI
IRIS	0.5283712	0.629048024	0.49721491	0.73071892874	0.73768173981	0.729183278	0.5321638716	0.66351263921	0.513129379712
SEGM ENTAT ION	0.0938196	0.3818291873	0.179028398	0.1098278311`	0.48920390230	0.215278367	0.0419231231123	0.04272692712	0.1017836876764
SEEDS	0.4523921	0.5429738493	0.422731231`	0.69297133428	0.702981131227	0.692889171	0.3234713242178	0.572368124236	0.398374891469
VERTE BRAL	0.0638712	0.2187837981	0.181739871	0.281732891318	0.37248246745	0.328317811	0.138783979873	0.21287e38921	0.237863786987

The results were the best for  $k = \text{truth value}$ . The values were closer to 1, when we had the correct value of  $k$ .

***Consistency between qualitative and quantitative analysis:***

As in the graphs, best results were obtained when  $k = \text{truth value}$  was chosen and also, the qualitative and qualitative analysis were consistent.