Task: Speed Control of DC Motor using PIC18F4550

Objective: The objective of this task is to interface a DC motor with the PIC18F4550 microcontroller and implement speed control functionality.

Requirements:

- 1. PIC18F4550 microcontroller board
- 2. DC motor
- 3. Motor driver circuit (e.g., L293D)
- 4. Power supply for the motor (e.g., battery or external power source)
- 5. Breadboard and jumper wires
- 6. PIC programming software (e.g., MPLAB IDE)
- 7. C programming knowledge

Task Steps:

- 1. Set up the hardware:
 - a. Connect the PIC18F4550 microcontroller board to the computer using a USB cable.
- b. Connect the motor driver circuit (e.g., L293D) to the PIC18F4550 board according to the datasheet of the motor driver.
 - c. Connect the DC motor to the motor driver circuit.
 - d. Connect the power supply for the motor to the motor driver circuit.
 - e. Make sure all the connections are secure and properly wired.

2. Write the C code:

- a. Open the PIC programming software (e.g., MPLAB IDE) and create a new project.
- b. Write the necessary code to initialize the PIC18F4550 microcontroller and configure the required pins for motor control.
 - c. Implement a speed control algorithm using pulse width modulation (PWM) technique.
 - d. Define suitable variables and constants for controlling the motor speed.
 - e. Write code to vary the duty cycle of the PWM signal to control the motor speed.
 - f. Add any necessary delay or loop to maintain the desired speed.
- 3. Compile and program the microcontroller:
 - a. Compile the code in the PIC programming software to check for any errors.
- b. Once the code is error-free, program the PIC18F4550 microcontroller using the programming software and appropriate programming hardware (e.g., PIC programmer or USB bootloader).
- 4. Test and verify:

- a. Connect the power supply to the motor circuit and power on the system.
- b. Observe the motor behavior and check if the speed control is functioning as desired.
- c. Adjust the speed control variables in the code to experiment with different motor speeds.
- d. Make sure the motor responds accurately to the speed control inputs.

5. Documentation:

- a. Prepare a detailed report documenting the task, including the hardware setup, code explanation, and test results.
 - b. Include relevant circuit diagrams, code snippets, and screenshots if necessary.
- c. Provide a step-by-step explanation of the process followed to achieve the speed control of the DC motor.