COL 819: Assignment -1

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1 Introduction

In this assignment, we are comparing performances of two peer to peer systems Pastry Rowstron (2001) and Chord Stoica (2001). Both are a type of distributed hash tables which can efficiently figure out which node contain required key. The major advantage of these systems is to provide completely decentralized, scalable and self-organizing peer to peer overlay networks. Both protocols provides algorithms of addition of nodes, deletion of nodes, addition and searching for keys.

Pastry assigns numerical id to each node and key in same space. Each pastry node maintain set of numerically as well geographically close nodes which it uses to notify of arrival/departure of nodes. Each node also maintains a routing table. Routing table consists of $log_{2^b}N$ rows and 2^b-1 columns. N is no. of nodes in network, b is size(no. of bits) of each digit of ids space. Each row i consist of node ids which have common prefix of length i with current node. Each column represent one of 2^b-1 combinations of i+1 digit. Now to route key , a node first looks into its leaf set which contains of numerically nearest nodes and see if key id within the range. Otherwise it route this key to node from routing table which has 1 more prefix match than current node. This gives a $O(log_{2^b}N)$ routing time.

Chord also assigns numerical id to each node and key in same space. But these IDs (m bit) are arranged in circle modulo 2^m where m is a parameter. Chord routes key to a node which is next in position in ID circle wrt key in clock-wise direction. To do this, Node first checks if Key id is between its own node id and its successor's (next in circle) node id. If it is then its route this Key to its successor. If not, then node figures out preceding node wrt to Key ID using its finger table and route to that preceding node. This gives a routing time of O(log N).

In this report, We show the experimental set up of both Pastry/Chord in a sequential setting. Furthermore, we show the distribution of no. of hops required to search the items after addition of nodes.

2 Experiment - Pastry

We have set-up 3 configurations of network which consist of 100, 500 and 1000 Nodes. Each configuration uses b= 4, |L| = |M| = 16. Each node contain leaf set, neighbour nodes

0	1	2		
072b030ba126b2f4b2374f342	19f3cd308f1455b3fa09a282e	20f07591c6fcb220ffe637cda		
c058f544c737782deacefa532	c16a5320fa475530d9583c34f	c203d8a151612acf12457e4d		
cf004fdc76fa1a4f25f62e0eb	None	None		
Node id - cfcd208495d565ef66e7dff9f				
Upper Leaf Set - cfecdb276f634854f3ef915e2 : cfee398643cbc3dc5eefc8933				
Lower Leaf Set - cfa0860e83a4c3a763a7e62d8 : cf004fdc76fa1a4f25f62e0eb				

Table 1: Routing table at Pastry node

and routing table. Each node is randomly assigned a 2d-geographical coordinate during creation. It is also assumed that when node is deleted, its data point gets deleted too. Now we will insert the 10000 data points and perform 1 million search queries. Further, distribution of number of hops required will be plotted.

After creation of network of 1000 nodes and adding 10000 data points and searching 1 million times, following is the pastry network summary-

Number of active nodes, 1000

Number of data add queries, 10000

Number of delete node queries, 0

Number of search queries, 1000000

Current data stored, 10000

For node with id-"cfcd208495d565ef66e7dff9f98764da", its routing table can be seen in 1. It can be seen that first row has no matching prefix with node id, 2nd row has nodes matching prefix of length 1 and 3th row has nodes with matching prefix of length 2.

After deletion of half the nodes, pastry network summary is-

Number of active nodes, 1000

Number of data add queries, 10000

Number of delete node queries, 500

Number of search queries, 1000000

Current data stored, 5125 (This no. might vary depending upon the location assigned to each pastry node but approximately 50% data points should get deleted).

Following figures(2-7) shows hops distribution for each configuration. Figure 8 is plot of mean hops vs network size.

There are two observation, first is mean number of hops increases slightly for 100 size network to 1000 size network as

$no.ofhops \propto log_{2^b}N$

where b = 4. For N=1000, this comes out approx 3.

Also, it can be seen that after random dropping of nodes, mean number of hops increases slightly in later half of plot, as network keep will try to reach to node as close numerically possible to key but that numerical close node will not have that key. So, it will further try to see in neighbourhood set or leaf set thus increasing the hops.

Distribution of hops required for 1 million queries in 100 size network

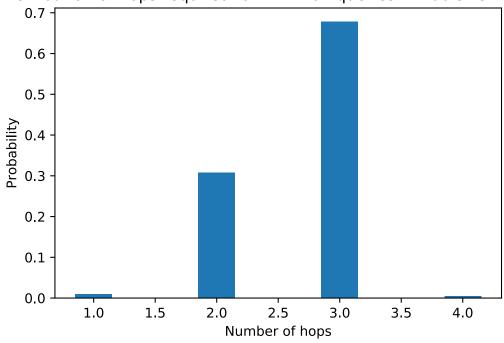


Figure 1: Hops distribution on 100 node network

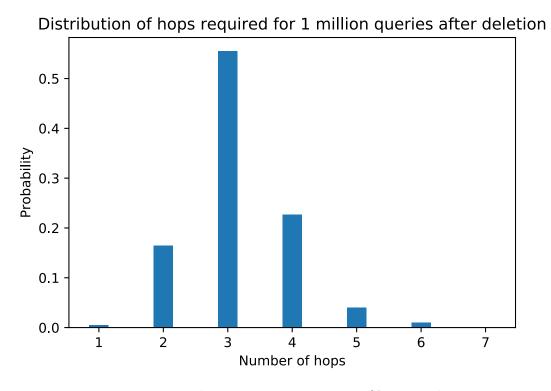


Figure 2: Hops distribution after randomly dropping 50% nodes of 100 node network

Distribution of hops required for 1 million queries in 500 size network

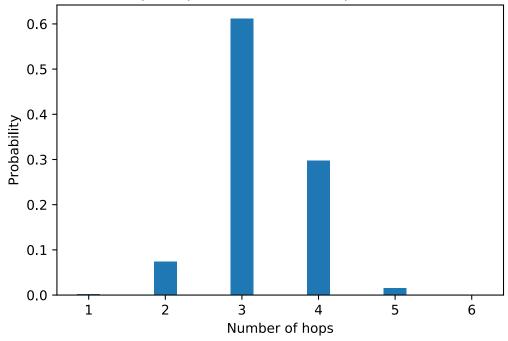


Figure 3: Hops distribution on 500 node network

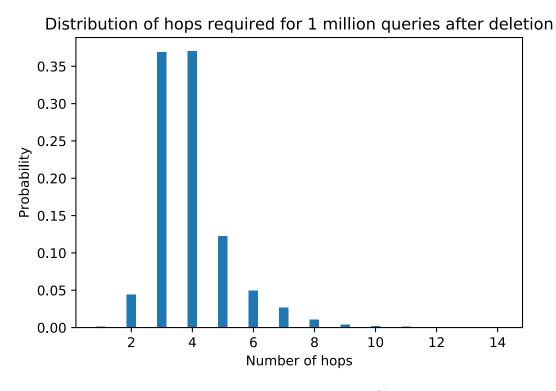


Figure 4: Hops distribution after randomly dropping 50% nodes of 500 node network

Distribution of hops required for 1 million queries in 1000 size network

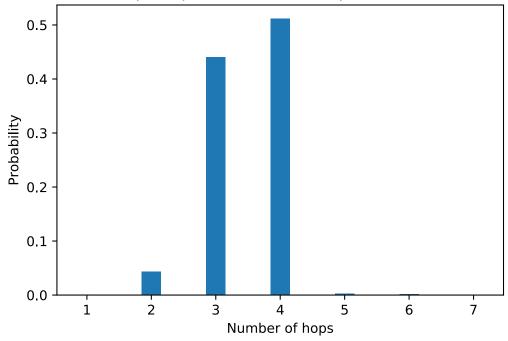


Figure 5: Hops distribution on 1000 node network

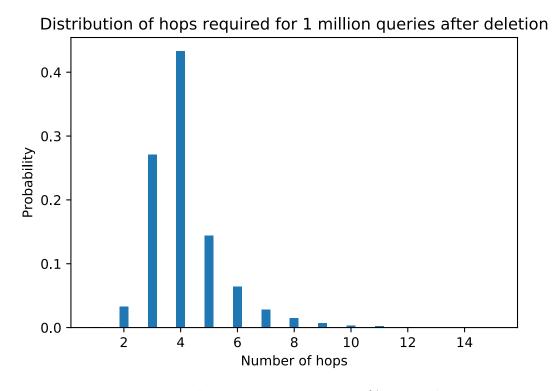


Figure 6: Hops distribution after randomly dropping 50% nodes of 1000 node network

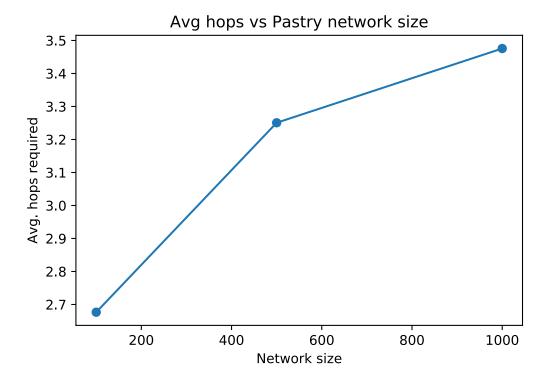


Figure 7: Means number of hops for each configuration

3 Experiment - Chord

Similar to Pastry, We have set-up 3 configurations of network which consist of 100, 500 and 1000 Nodes. It is also assumed that when node is deleted, its data point gets deleted too. For each configuration, we will insert the 10000 data points and perform 1 million search queries. Further, distribution of number of hops required will be plotted. Each node maintains a finger table to efficiently route the queries in network. Table 2 shows the format of finger table at a random node with id 243877.

Following figures (10-15) shows hops distribution for each configuration. Figure 16 is plot of mean hops vs network size.

Similar to Pastry, two observations can be made. First, mean number of hops increases slightly for 100 size network to 1000 size network as

$$no.ofhops \propto logN$$

For N=100, this comes out approx 6 and mean number of hops is approximately equal to 6.

Also, it can be seen that after random dropping of nodes, hops distribution shifts very slightly in as compared to pastry. In this case network keep will try to reach to the successor of key. But, if this successor doesn have the key, then it will know that key doesn't exist in the network and will not process further. Figure 17 shows the network route taken to find

Start	interval start	interval end	successor node	
243878	243878	243879	245001	
243879	243879	243881	245001	
243881	243881	243885	245001	
243885	243885	243893	245001	
243893	243893	243909	245001	
243909	243909	243941	245001	
243941	243941	244005	245001	
244005	244005	244133	245001	
244133	244133	244389	245001	
244389	244389	244901	245001	
244901	244901	245925	245001	
245925	245925	247973	247058	
247973	247973	252069	248237	
252069	252069	260261	252412	
260261	260261	276645	261174	
276645	276645	309413	278058	
309413	309413	374949	311010	
374949	374949	506021	375505	
506021	506021	768165	508393	
768165	768165	243877	769352	
Predecessor- 243070				
Successor- 245001				

Table 2: Finger table at Chord node

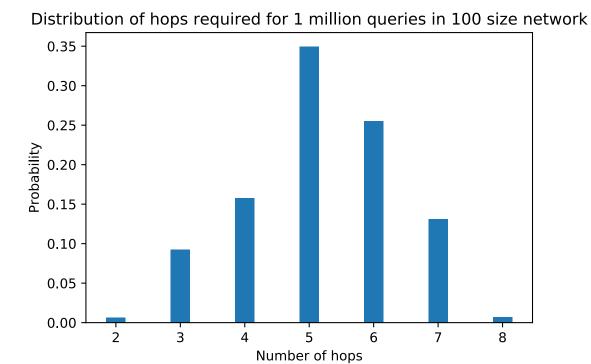


Figure 8: Hops distribution on 100 node network

Distribution of hops required for 1 million queries after deletion

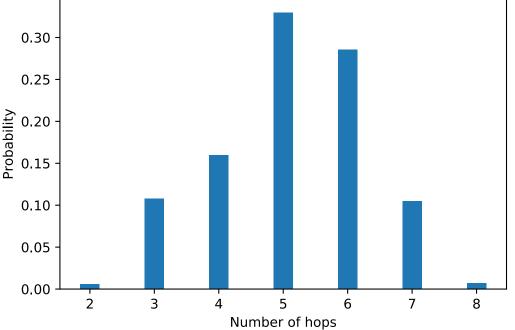


Figure 9: Hops distribution after randomly dropping 50% nodes of 100 node network

Distribution of hops required for 1 million queries in 500 size network

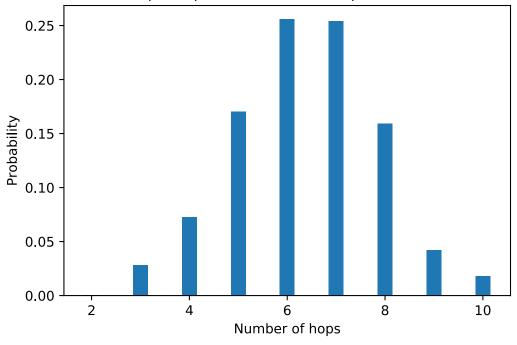


Figure 10: Hops distribution on 500 node network

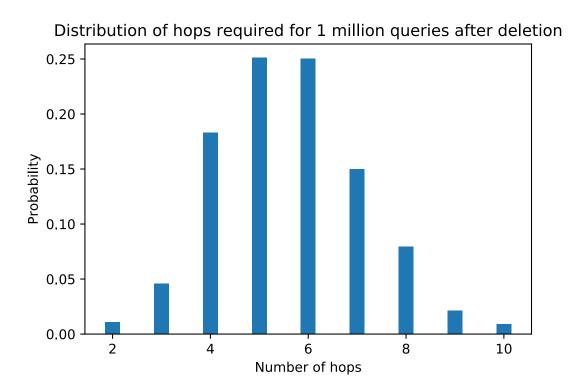


Figure 11: Hops distribution after randomly dropping 50% nodes of 500 node network

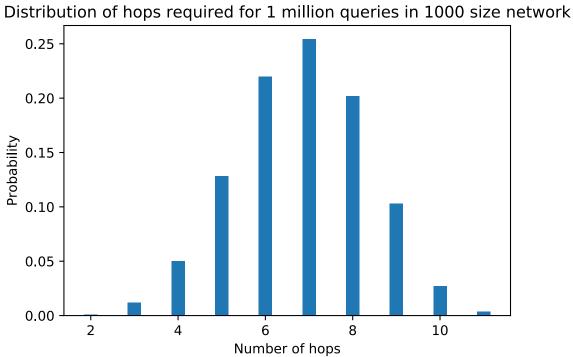


Figure 12: Hops distribution on 1000 node network

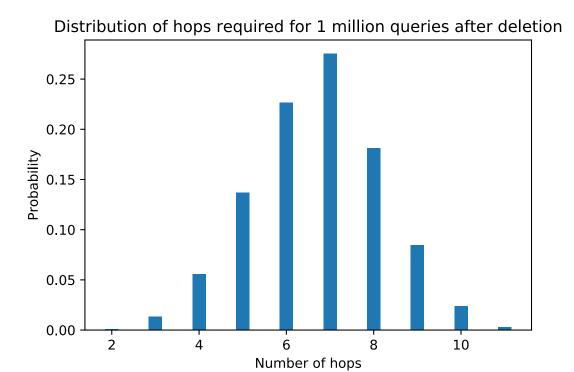


Figure 13: Hops distribution after randomly dropping 50% nodes of 1000 node network

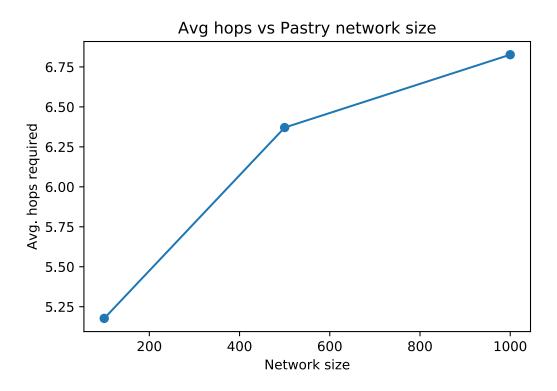


Figure 14: Means number of hops for each configuration

the key. It can be seen that at each next step, node is numerically closer to key.

```
Lookup route of key, 443636 : 339802 -> 406612 -> 439539 -> 443008 -> 443620 -> 445408

Lookup route of key, 793980 : 339802 -> 604542 -> 737729 -> 773200 -> 789882 -> 793125 -> 794210

Lookup route of key, 581388 : 339802 -> 473113 -> 541369 -> 574480 -> 579174 -> 581268 -> 581785

Lookup route of key, 677453 : 339802 -> 604542 -> 670131 -> 675207 -> 676548 -> 677094 -> 678426

Lookup route of key, 312023 : 339802 -> 864870 -> 80052 -> 211957 -> 279246 -> 297321 -> 306900 -> 311378

-> 312498

Lookup route of key, 492485 : 339802 -> 473113 -> 490930 -> 492425 -> 492964

Lookup route of key, 1001091 : 339802 -> 864870 -> 995976 -> 1000543 -> 1008914

Lookup route of key, 915454 : 339802 -> 864870 -> 897943 -> 906407 -> 910892 -> 913026 -> 913952 -> 918690

Lookup route of key, 189274 : 339802 -> 864870 -> 80052 -> 148233 -> 181162 -> 185383 -> 187565 -> 188668

-> 189191 -> 190928

Lookup route of key, 632042 : 339802 -> 604542 -> 623331 -> 632006 -> 632873
```

Figure 15: Path taken by network to route the 10 random queries

4 Performance Comparison

Chord is bit slower compared to Pastry as run time complexity of query search in Chord is $O(log_N)$ while Pastry has time complexity of $O(log_{2^b}N)$. But Chord is easy to maintain and implement compared to Pastry.

5 How to run code

For Pastry,

```
python Pastry.py
```

Similarly for Chord-

```
python Chord.py
```

Please use python3, and code will run for all 3 configurations. It will generate required plots too.

```
Shubhams-MacBook-Air:Assignment-1 shubham$ /Users/shubham/anaconda3/bin/python Pastry.py
Creating network for 100
adding data points
Searching,
Number of active nodes , 100
Number of data add queries, 10000
Number of delete node queries 0
Number of search queries, 1000000
Current data stored 10000
deleting 50% nodes
searching for queries
Creating network for 500
adding data points
Searching,
Number of active nodes , 500
Number of data add queries, 10000
Number of delete node queries 0
Number of search queries, 1000000
Current data stored 10000
```

Figure 16: Screenshot of Pastry code execution

```
[Shubhams-MacBook-Air:Assignment-1 shubham$ /Users/shubham/anaconda3/bin/python Chord.py
Creating network for 100
Adding nodes
Adding keys
Searching,
deleting 50% nodes
searching for queries
Creating network for 500
Adding nodes
Adding keys
Searching,
deleting 50% nodes
searching for queries
Creating network for 1000
Adding nodes
Adding keys
Searching,
deleting 50% nodes
searching for queries
Lookup route of key, 797292 : 909833 -> 388062 -> 650305 -> 782369 -> 791688 -> 797104 -> 7992
17
```

Figure 17: Screenshot of Chord code execution

References

Rowstron. (2001). Pastry: Scalable, decentralized object location, and routing for large-scale peer-to-peer systems. In *Middleware 2001 lecture notes in computer science* (p. 329–350).

Stoica. (2001). Chord: A scalable peer-to-peer lookup service for internet applications. In *Proceedings of the 2001 conference on applications, technologies, architectures, and protocols for computer communications* (p. 149–160). New York, NY, USA: Association for Computing Machinery. Retrieved from https://doi.org/10.1145/383059.383071 doi: 10.1145/383059.383071

6 Pastry Python code

```
import hashlib
import random
import math
import numpy as np
from matplotlib import pyplot as plt
import math
import pandas as pd
from collections import Counter
pd.set_option('display.max_rows', 500)
pd.set_option('display.max_columns', 500)
pd.set_option('display.width', 1000)
inf = math.inf
def hex_id(id):
  return hashlib.md5(str(id).encode()).hexdigest()
def random_num(a,b):
  return a + random.random() * (b-a)
def euclidean_distance(a,b):
  return np.linalg.norm(np.array(a)-np.array(b))
def node_abs_id_distance(a,b):
  return abs(int(a,16) - int(b,16))
def node_id_distance(a,b):
  return int (a, 16) - int (b, 16)
def comman_prefix_length(a,b):
  ct = 0
  for i in range(0,len(a)):
     if a[i] == b[i]:
         ct += 1
      else:
         return ct
   return ct
def compare(a,b,mode="eq"):
   if mode == "eq":
      return int(a,16) == int(b,16)
   if mode == "g":
      return int (a, 16) > int(b, 16)
   if mode == "1":
      return int(a,16) < int(b,16)
   if mode == "ge":
      return int(a,16) >= int(b,16)
```

```
if mode == "le":
      return int(a,16) \leq int(b,16)
def min_node_id(leafSet):
      return min(leafSet, key = lambda val: int(val, 16))
def max_node_id(leafSet):
      return max(leafSet,key = lambda val: int(val,16))
def get_prob_distribution(lst):
   a = Counter(lst)
   ct = sum(a.values())
   vals = list(a.keys())
  probs = [item*1.0/ct for item in a.values()]
   idx = np.argsort(vals)
  vals = np.array(vals)[idx]
  probs = np.array(probs)[idx]
   return vals, probs
class Key():
   def __init__(self,key):
      self.name = key
      self.id = hex_id(self.name)
class Node():
   def __init__(self,node_name,b=4):
      self.name = node_name
      self.id = hex_id(self.name)
      self.data = {}
      self.b = b
      self.L = self.M = int(math.pow(2,b))
      self.location = (random_num(0,90), random_num(0,180)) ##
         \hookrightarrow latitude and longitude
      self.routingTable = [[ None for item in range(0,int(math.pow
         \hookrightarrow (2,self.b)))] for i in range(0,int(128/self.b))] ## b
         \hookrightarrow = 4 configuration
      self.leafUSet = [] ### Upper leaf set
      self.leafLSet = [] ### Lower leaf set
      self.nbrSet = []
```

```
self.isOnRoute = False
def findNearestLeafNode(self, key): ### Accepts id
  nearest_node = None
  nearest_node_dist = inf
   for nbr in self.leafUSet + self.leafLSet:
      distance = node_abs_id_distance(nbr, key)
      if nearest_node_dist > distance:
         nearest_node_dist = distance
         nearest node = nbr
   return nearest node
def check_if_key_lies_in_leaf_range(self,key):
   if len(self.leafUSet) == 0 and len(self.leafLSet) == 0:
      return False
   if len(self.leafUSet) == 0:
      return compare(key,min_node_id(self.leafLSet), "ge") and
         → compare(key, self.id, 'le')
   if len(self.leafLSet) == 0:
      return compare(key, max_node_id(self.leafUSet),'le') and

    compare(key, self.id, 'ge')

   return compare(key, min_node_id(self.leafLSet), 'ge') and

    compare(key, max_node_id(self.leafUSet),'le')
def find_closest_node_in_routing_table(self, key,
   → node_id_to_object): ## This is tough
   shl = comman_prefix_length(self.id, key.id)
   node = self.routingTable[shl][int(key.id[shl],16)]
   if node is not None and node in node_id_to_object:
      return node
   else:
      for node in self.leafUSet + self.leafLSet:
         if node in node id to object:
            shl_node = comman_prefix_length(node, key.id)
            if node_abs_id_distance(node, key.id) <</pre>
               → node_abs_id_distance(node, self.id) and
               \hookrightarrow shl node >= shl:
               return node
      for row in self.routingTable:
         for node in row:
            if node is not None and node in node_id_to_object:
```

```
shl_node = comman_prefix_length(node,key.id)
                if node_abs_id_distance(node, key.id) <</pre>
                   → node_abs_id_distance(node, self.id) and
                   \hookrightarrow shl_node >= shl:
                   return node
      return None
def add_key(self,key,value,node_id_to_object,mode,ct=0): ##
   \hookrightarrow mode can be of deletion
   #if self.isOnRoute:
   #print("Come to, ", self.name," ", self.id)
   #if
   ct += 1
   if ct > 100:
      return (None, None, None)
   if mode == "find":
      if key.name in self.data:
         return (self.data[key.name], 0, [self.id])
   if_lies_in_node_range = self.check_if_key_lies_in_leaf_range
      \hookrightarrow (key.id)
   leaf_node_id = self.findNearestLeafNode(key.id)
   if if_lies_in_node_range and leaf_node_id is not None and
      → leaf_node_id in node_id_to_object:
      leaf_node = node_id_to_object[leaf_node_id]
      if node_abs_id_distance(leaf_node.id,key.id) <=</pre>
         → node_abs_id_distance(self.id, key.id):
         val, hops, route = leaf_node.add_key(key, value,
             → node_id_to_object, mode)
         if val is None and hops is None and route is None:
             return (None, None, None)
         return (val,hops+1,[self.id]+route)
      else:
         if mode == "find":
             if key.name in self.data:
                return (self.data[key.name], 0, [self.id])
            return (None, 0, [self.id])
         else:
             if mode == "find_closest_node":
```

```
return (self.id, 0, [self.id])
            self.data[key.name] = value
            return (value, 0, [self.id])
   routing_node_id = self.find_closest_node_in_routing_table(
      → key, node_id_to_object)
   if routing_node_id is not None and routing_node_id in
      → node_id_to_object:
      routing_table_node = node_id_to_object[routing_node_id]
      #print(routing_table_node.name, routing_table_node.id)
      val, hops, route = routing_table_node.add_key(key, value,
         → node_id_to_object, mode, ct)
      if val is None and hops is None and route is None:
         return (None, None, None)
      return (val,hops+1,[self.id]+route)
   if mode== "addition":
      self.data[key.name] = value
      return (value, 0, [self.id])
   if mode == "find closest node":
      return (self.id, 0, [self.id])
   return (None, 0, [self.id])
def updateLeafNodes(self, node):
   leaf_nodes = node.leafUSet + [node.id] + node.leafLSet
   distances_high = []
   distances_low = []
   for nbr in leaf_nodes:
      if nbr != self.id:
         distance = node_id_distance(nbr, self.id)
         if distance > 0:
            distances_high.append((nbr,distance))
         else:
            distances_low.append((nbr, abs(distance)))
   distances_high.sort(key=lambda val: val[1],reverse=False)
   distances_low.sort(key=lambda val: val[1], reverse= False)
   self.leafUSet = [item[0] for item in distances_high[:int(
      \hookrightarrow self.L/2)]]
```

```
self.leafLSet = [item[0] for item in distances_low[:int(self
      \hookrightarrow .L/2)]]
   return
def updateMembershipNodes(self, node, id_to_node):
   local_nodes = node.nbrSet + [node.id]
   distances = []
   for nbr in local_nodes:
      if nbr != self.id:
         distance = euclidean_distance(id_to_node[nbr].location
            → , self.location)
         distances.append((nbr, distance))
   distances.sort(key=lambda val: val[1],reverse=False)
   self.nbrSet =[item[0] for item in distances[0:self.M]]
   return
def updateRoutingTable(self,route):
   for node in route:
      shl = comman_prefix_length(self.id, node.id)
      if ct == 0:
         for i in range (0, shl+1):
            self.routingTable[i] = node.routingTable[i]
      else:
         if self.routingTable[shl][0] is None:
            self.routingTable[shl] = node.routingTable[i]
   return
def stabilize(self, node_id_to_object):
   #print("self id ,",self.id)
  newleafSet = []
   lost = False
  lost index upper = -1
  lost_index_lower = -1
  ct = 0
  removed_node_id = None
   for nodeid in self.leafUSet:
      if nodeid not in node_id_to_object:
         lost = True
         lost_index_upper = ct
         removed_node_id = nodeid
```

```
break
   ct += 1
ct = 0
if lost_index_upper == -1:
   for nodeid in self.leafLSet:
      if nodeid not in node_id_to_object:
         lost = True
         lost_index_lower = ct
         removed_node_id = nodeid
         break
      ct += 1
len_lset = len(self.leafLSet)
len_uset = len(self.leafUSet)
if lost and (len_lset > 0 or len_uset >0):
   ask_leaf_node_from = None
   if lost_index_upper != -1:
      if len_uset > 1:
         if lost_index_upper == len_uset - 1:
            ask_leaf_node_from = self.leafUSet[len_uset-2]
         else:
            ask_leaf_node_from = self.leafUSet[len_uset-1]
      else:
         self.leafUSet = []
   else:
      if lost_index_lower != -1:
         if len_lset > 1:
            #print("index, ", lost_index_lower,len_lset, )
            if lost_index_lower == len_lset - 1:
               ask_leaf_node_from = self.leafLSet[len_lset
                  \hookrightarrow -2]
            else:
               ask_leaf_node_from = self.leafLSet[len_lset
                  \hookrightarrow -1]
         else:
            self.leafLSet = []
   if ask_leaf_node_from is not None:
      ask_leaf_node_from = node_id_to_object[
         → ask_leaf_node_from]
```

```
newLeafSet = list(set(self.leafLSet + self.leafUSet +
         → ask_leaf_node_from.leafLSet + ask_leaf_node_from
         → .leafUSet))
      newLeafSet.remove(removed_node_id)
      distances_high = []
      distances_low = []
      for nbr in newLeafSet:
         if nbr != self.id:
            distance = node_id_distance(nbr,self.id)
            #print(distance)
            if distance > 0:
                distances_high.append((nbr,distance))
            else:
                distances_low.append((nbr,abs(distance)))
      distances_high.sort(key=lambda val: val[1], reverse=
         \hookrightarrow False)
      distances_low.sort(key=lambda val: val[1], reverse=
         \hookrightarrow False)
      self.leafUSet = [item[0] for item in distances_high[:
         \hookrightarrow int(self.L/2)]]
      self.leafLSet = [item[0] for item in distances_low[:
         \hookrightarrow int(self.L/2)]]
      #print(len(self.leafUSet),len(self.leafLSet))
else:
   if lost:
      self.leafUSet = []
      self.leafLSet = []
#if not lost:
   #### repair routing table
row_index = 0
import copy
dup = copy.deepcopy(self.routingTable.copy())
dup1 = copy.deepcopy(self.routingTable.copy())
for row in dup:
   for node in row:
```

```
col\_index = 0
         if node is not None and node not in node_id_to_object:
            found = False
            #print("Found, ", self.id, row_index,col_index,
               → node)
            # node is dropped###
            self.routingTable[row_index][col_index] = None
            for new_row in dup1:
               for new_node in new_row:
                  if not found:
                     if new_node is not None and new_node in
                        → node_id_to_object and new_node !=
                        → node and node_id_to_object[new_node
                        → ].routingTable[row_index][col_index]
                        → is not None and node_id_to_object[
                        → new_node].routingTable[row_index][
                        → col_index] in node_id_to_object:
                        #print(row index,col index)
                        self.routingTable[row_index][col_index]
                           → = node_id_to_object[new_node].
                           → routingTable[row_index][col_index
                           \hookrightarrow ]
                        found = True
                        #print(self.routingTable[row_index][
                           → col_index])
         col_index +=1
      row_index += 1
   return
def updateState(self,new_node,node_id_to_object):
   self.updateLeafNodes(new node)
   self.updateMembershipNodes(new_node, node_id_to_object)
   shl = comman_prefix_length(self.id, new_node.id)
   location = int(new_node.id[shl],16)
  existing_node_id = self.routingTable[shl][location]
   if existing_node_id is None:
      self.routingTable[shl][location] = new_node.id
   else:
```

```
existing_node = node_id_to_object[existing_node_id]
         if euclidean_distance(new_node.location, self.location) <</pre>

→ euclidean_distance(existing_node.location, self.
            \hookrightarrow location):
            self.routingTable[shl][location] = new_node.id
      return
   def print_node_properties(self):
      print("Name," , self.name)
      print("Id,", self.id)
      print("location, ", self.location)
      print("leaf Upper set", self.leafUSet)
      print("leaf Lower set", self.leafLSet)
      print("nbr set", self.nbrSet)
      print("Routing Table")
      df = pd.DataFrame.from_records(self.routingTable)
      display(df)
class Pastry():
   def __init__(self,num_of_nodes):
      self.N = num of nodes
      self.nodes = []
      self.node_id_to_object = {}
      for i in range(0, num_of_nodes): ### Creating nodes
         node = Node(i)
         self.nodes.append(node)
         self.node_id_to_object[node.id] = node
      for i in range(0, num_of_nodes):
         self.updateLeafNodes(self.nodes[i])
         self.updateLocalNode(self.nodes[i])
         self.updateRoutingTable(self.nodes[i])
      self.add\_queries = 0
      self.delete_queries = 0
      self.search_queries = 0
      self.data_add_queries = 0
   def findNearestNode(self, node):
      nearest_node = None
```

```
nearest_node_dist = inf
   for nbr in self.nodes:
      distance = node_abs_id_distance(nbr.id, node.id)
      if nearest_node_dist > distance:
         nearest_node_dist = distance
         nearest_node = nbr
   return nearest_node
def updateRoutingTable(self, node):
   routingTable = [[ [] for item in range(0,int(math.pow(2,node
      \hookrightarrow .b)))] for i in range(0,int(128/node.b))] ## b = 4
      → configuration
   for nbr in self.nodes:
      if nbr.id != node.id:
         shl = comman_prefix_length(node.id,nbr.id)
         routingTable[shl][int(nbr.id[shl],16)].append(nbr.id)
   for i in range(0,len(routingTable)):
      for j in range(0,len(routingTable[i])):
         if len(routingTable[i][j]) == 0:
            node.routingTable[i][j] = None
         else:
            distances = []
            for nbr in routingTable[i][j]:
               distances.append((nbr,euclidean_distance(self.
                  → node_id_to_object[nbr].location, node.
                  → location)))
            distances.sort(key=lambda val:val[1], reverse= False
            node.routingTable[i][j] = distances[0][0] ## stored

→ the closest nbr node

   return
def updateLocalNode(self, node):
  distances = []
   for nbr in self.nodes:
      if nbr.id != node.id:
         distance = euclidean_distance(nbr.location, node.
            → location)
         distances.append((nbr.id, distance))
   distances.sort(key=lambda val: val[1],reverse=False)
```

```
node.nbrSet =[item[0] for item in distances[0:node.M]]
   return
def updateLeafNodes(self, node):
   distances_high = []
   distances_low = []
   for nbr in self.nodes:
      if nbr.id != node.id:
         distance = node id distance(nbr.id, node.id)
         if distance > 0:
            distances_high.append((nbr.id, distance))
         else:
            distances_low.append((nbr.id, abs(distance)))
   distances_high.sort(key=lambda val: val[1],reverse=False)
   distances_low.sort(key=lambda val: val[1], reverse= False)
   node.leafUSet = [item[0] for item in distances_high[:int(
      \hookrightarrow node.L/2)]]
   node.leafLSet = [item[0] for item in distances_low[:int(node
      \hookrightarrow .L/2)]]
   return
def add_key(self,key,value,mode="addition",ct=0):
   if mode == "addition":
      self.add_queries += 1
   if mode == "find":
      self.search_queries += 1
   node_index= random.choice(range(0, self.N))
   return self.nodes[node_index].add_key(key,value,self.
      → node_id_to_object, mode, ct)
def add_node(self):
   node = Node(self.N+1)
   self.node_id_to_object[node.id] = node
   self.nodes.append(node)
   random_node= self.nodes[random.choice(range(0, self.N))]
   self.N += 1
```

```
nearest_node, hops, route = random_node.add_key(node,'', self.
         → node_id_to_object, "find_closest_node")
      node.updateLeafNodes(self.node_id_to_object[nearest_node])
      node.updateMembershipNodes(self.node_id_to_object[
         → nearest_node], self.node_id_to_object)
      node.updateRoutingTable([self.node_id_to_object[id] for id
         → in route])
      for nbr in node.leafLSet + node.leafUSet + node.nbrSet + [
         → item for row in node.routingTable for item in row ]:
         if nbr is not None:
            nbr_node = self.node_id_to_object[nbr]
            nbr_node.updateState(node, self.node_id_to_object)
      return "success"
   def delete_node(self):
      self.delete queries += 1
      index= random.choice(range(0, self.N))
      del self.node_id_to_object[self.nodes[index].id]
      del self.nodes[index]
      self.N = self.N-1
      for node in self.nodes:
         node.stabilize(self.node_id_to_object)
      return
   def print_network_information(self):
      print("Number of active nodes , " , len(self.nodes))
     print("Number of data add queries, ", self.add_queries)
     print("Number of delete node queries" , self.delete_queries)
     print("Number of search queries, ", self.search_queries)
     data len= 0
      for node in self.nodes:
         data_len += len(node.data)
     print("Current data stored ", data_len)
num_of_nodes = [100, 500, 1000]
hops_per_nodes = []
for nodes in num_of_nodes:
  print("Creating network for ", nodes)
  pastry = Pastry(nodes)
  print("adding data points")
```

```
keys = []
for i in range (0, 10000):
   key = Key(i)
  keys.append(key)
   pastry.add_key(key, "val_"+str(key.name), "addition")
hops_needed = []
print("Searching,")
for i in range (0, 1000000):
   key = random.choice(keys)
   hops = pastry.add_key(key,"", "find", 0) [-1]
   if hops is not None:
      hops_needed.append(len(hops))
hops_per_nodes.append(np.mean(hops_needed))
vals,probs = get_prob_distribution(hops_needed)
pastry.print_network_information()
plt.clf()
plt.bar(vals, probs, width=0.3)
#plt.hist(hops_needed) # density
plt.ylabel('Probability')
plt.xlabel('Number of hops')
plt.title("Distribution of hops required for 1 million queries
   → in "+str(nodes) +" size network")
plt.savefig(str(nodes)+"_search_queries.svg")
print("deleting 50% nodes")
for i in range(0, int(nodes*.5)):
#print("deleting , i ", i)
   pastry.delete_node()
print("searching for queries")
for i in range (0, 1000000):
   key = random.choice(keys)
   hops = pastry.add_key(key,"","find",0)[-1]
   if hops is not None:
      hops needed.append(len(hops)+1)
vals,probs = get_prob_distribution(hops_needed)
plt.clf()
plt.bar(vals, probs, width=0.3)
#plt.hist(hops_needed) # density
plt.ylabel('Probability')
plt.xlabel('Number of hops')
plt.title("Distribution of hops required for 1 million queries
   → after deletion")
```

```
plt.savefig(str(nodes)+"_delete_search_queries.svg")

plt.clf()
plt.plot(num_of_nodes, hops_per_nodes,'o-')
#plt.hist(hops_needed) # density
plt.ylabel('Avg. hops required')
plt.xlabel('Network size')
plt.title("Avg hops vs Pastry network size")
plt.savefig("pastry_avg_hops_needed.svg")
```

7 Chord Python code

```
import hashlib
import random
import math
import numpy as np
import math
import pandas as pd
from collections import Counter
inf = math.inf
def hex id(id):
   return hashlib.md5(str(id).encode()).hexdigest()
def random_num(a,b):
  return a + random.random() * (b-a)
def power_m(M):
  return int(math.pow(2,M))
def in_range(item,id1,id2,M):
   #print("in range, ", item, id1, id2 )
   if id1 is None or id2 is None or item is None:
      return False
   item = item%int(power_m(M))
   id1 = id1%int(power_m(M))
   id2 = id2\%int(power_m(M))
   if id1 == id2:
     return id1 == item
   if id1 < id2:
      return item >= id1 and item<= id2
   else:
```

```
return item >= id1 or item <= id2</pre>
def get_prob_distribution(lst):
  a = Counter(lst)
  ct = sum(a.values())
  vals = list(a.keys())
  probs = [item*1.0/ct for item in a.values()]
  idx = np.argsort(vals)
  vals = np.array(vals)[idx]
  probs = np.array(probs)[idx]
  return vals, probs
global id_to_node
id_to_node = {}
class Finger():
   def ___init___(self, start=None, interval=None, node_id=None):
      self.start = start
      self.interval = interval
      self.node = node_id
      return
class Node():
   def __init__(self,id,M):
     self.id = id
      self.M = M
     self.finger = []
      self.data= {}
      for i in range (0, self.M):
         start = (id + int(math.pow(2,i)))%int(math.pow(2,self.M))
         end = (id + int(math.pow(2,i+1)))%int(math.pow(2,self.M))
         self.finger.append(Finger(start,(start,end)))
      self.successor = None
      self.predecessor = None
```

```
def print_finger_table(self):
  print("Node id,", self.id)
  print("start interval successor")
  for i in range (0, self.M):
      print(self.finger[i].start, " " ,self.finger[i].interval,
         → " ", self.finger[i].node)
  print("Predecesssor, ", self.predecessor)
   print("Successor, ", self.successor)
  print("##################")
   return
def find_successor(self,id,route=False):
   #if id == self.id:
      #return self.id
   if route:
      n_, route_ = self.find_predecessor(id, route)
      return id_to_node[n_].successor,route_ + [id_to_node[n_].

    successorl

   else:
      n_ = self.find_predecessor(id, route)
      return id to node[n ].successor
   #print("predecessor,", n_)
def find_predecessor(self,id,route=False):
  n_{-} = self.id
   route_{-} = [n_{-}]
   #print("find predecessor key, current node , successor ", id
      → ,n_,id_to_node[n_].successor)
  while not in_range(id,n_+1,id_to_node[n_].successor,self.M):
      #print("loop")
      n_ = id_to_node[n_].closest_preceding_finger(id)
      #print("closest preceding finger, ",n )
      route_.append(n_)
   if route:
      return n_, route_
   else:
      return n_
def closest_preceding_finger(self,id):
   for i in range (self.M-1,-1,-1):
```

```
#print("in closest precedding, ", self.finger[i].node,
          \hookrightarrow self.id,id)
      if in_range(self.finger[i].node, self.id+1, id-1, self.M):
      #if in_range(id,self.finger[i].interval[0],self.finger[i
         \hookrightarrow ].interval[1]-1, self.M):
         return self.finger[i].node
def join(self, n_):
   if n_ not in id_to_node: ### that means it is first node to
      → join###
      for i in range (0, self.M):
          self.finger[i].node = self.id
      self.predecessor = self.id
      self.successor = self.id
   else: ### n_ exists
      #print("initializing")
      self.initialize_finger(n_)
      #print(id_to_node[n_].print_finger_table())
      #print("updating other nodes")
      self.update_other_nodes()
def initialize_finger(self,n_):
   n_{-} = id_{-}to_{-}node[n_{-}]
   #print(self.finger[0].interval)
   self.finger[0].node = n_.find_successor(self.finger[0].start
   self.successor = self.finger[0].node
   self.predecessor = id_to_node[self.successor].predecessor
   id_to_node[self.successor].predecessor = self.id
   for i in range(1, self.M):
      self.finger[i].node = n_.find_successor(self.finger[i].
         \hookrightarrow start)
def update_other_nodes(self):
   for i in range (0, self.M):
      if self.id-int(math.pow(2,i)) == self.predecessor:
         id_to_node[self.predecessor].update_finger_table(self.
             \hookrightarrow id, i)
      else:
          #print("key to find predecessor", self.id-int(math.pow
             \hookrightarrow (2,i)))
```

```
p= self.find_predecessor(self.id-int(math.pow(2,i)))
         #print("in update other, ",p)
         id_to_node[p].update_finger_table(self.id,i)
def update_finger_table(self, node, i):
   #print("here i , self, self.finger[i] node, self predec",i ,
      → self.id, self.finger[i].node, self.predecessor)
   if self.id == node:
      return
   if in_range(node, self.id, self.finger[i].node-1, self.M):
      self.finger[i].node = node
      if i == 0:
         self.successor = node
      id_to_node[self.predecessor].update_finger_table(node,i)
def add_key(self,key,value):
  n_ = self.find_successor(key)
  id_to_node[n_].add_key_to_itself(key,value)
   return
def add_key_to_itself(self, key, value):
   self.data[key] = value
   return
def return_val_for_key(self,key):
   if key in self.data:
      return self.data[key]
   return None
def find_key(self,key):
  n_,route = self.find_successor(key,route = True)
   return (id_to_node[n_].return_val_for_key(key), route)
   #print(len(route))
def update(self,delete_node,successor,predecessor):
   if self.successor == delete node:
      self.successor = successor
   if self.predecessor == delete_node:
      self.predecessor = predecessor
   for finger in self.finger:
      if finger.node == delete_node:
         finger.node = successor
```

```
def delete(self):
      successor = self.successor
      predecessor = self.predecessor
      for node in id_to_node:
         if node != self.id:
            id_to_node[node].update(self.id, successor, predecessor)
      return
class Chord():
  def __init__(self,N):
     print("Adding nodes")
      self.seed = False
      M = 20
      for i in range (0, N):
         id = random.choice(range(0,int(pow(2,M))))
         if i ==0:
            self.seed = id
         node = Node(id, M)
         id_to_node[id] = node
         if i == 0:
            node.join(0)
         else:
            node.join(self.seed)
      self.keys = []
      print("Adding keys")
      for i in range (0, 10000):
         key = random.choice(range(0, int(pow(2, 20))))
         self.keys.append(key)
         id_to_node[self.seed].add_key(key,str(key)+"_val")
   def find_key(self,key=None):
      if key is None:
         key = random.choice(self.keys)
      if self.seed in id_to_node:
         val, route = id_to_node[self.seed].find_key(key)
      else:
```

```
val, route = id_to_node[list(id_to_node.keys())[0]].
            → find_key(key)
      if route is not None:
         return len(route)
      else:
         return None
   def find_key_and_route(self):
      key = random.choice(self.keys)
      if self.seed in id_to_node:
         val, route = id_to_node[self.seed].find_key(key)
      else:
         val, route = id_to_node[list(id_to_node.keys())[0]].
            → find_key(key)
      route = " -> ".join([str(item) for item in route])
      print("Lookup route of key,", str(key)," :",route)
   def delete_nodes(self, N):
      import random
      for i in range (0, N):
         node id = random.choice(list(id to node.keys()))
         id_to_node[node_id].delete()
         del id to node[node id]
if __name__ == "__main__":
   num\_of\_nodes = [100, 500, 1000]
  hops_per_nodes = []
   for nodes in num_of_nodes:
      print("Creating network for ", nodes)
      chord = Chord(nodes)
      hops_needed = []
      print("Searching,")
      for i in range (0, 1000000):
         key = random.choice(chord.keys)
         hops = chord.find_key(key)
         if hops is not None:
            hops_needed.append(hops)
      hops_per_nodes.append(np.mean(hops_needed))
```

```
vals,probs = get_prob_distribution(hops_needed)
   plt.clf()
   plt.bar(vals, probs, width=0.3)
   #plt.hist(hops_needed) # density
   plt.ylabel('Probability')
   plt.xlabel('Number of hops')
   plt.title("Distribution of hops required for 1 million
      → queries in "+str(nodes) +" size network")
   plt.savefig(str(nodes) + "_chord_search_queries.svg")
   print("deleting 50% nodes")
   chord.delete nodes(int(nodes*.5))
   print("searching for queries")
   for i in range (0, 1000000):
      key = random.choice(chord.keys)
      hops = chord.find_key(key)
      if hops is not None:
         hops_needed.append(hops)
   vals,probs = get_prob_distribution(hops_needed)
   plt.clf()
   plt.bar(vals, probs, width=0.3)
   #plt.hist(hops needed) # density
   plt.ylabel('Probability')
   plt.xlabel('Number of hops')
   plt.title("Distribution of hops required for 1 million
      → queries after deletion")
   plt.savefig(str(nodes)+"_chord_delete_search_queries.svg")
plt.clf()
plt.plot(num_of_nodes, hops_per_nodes,'o-')
#plt.hist(hops_needed) # density
plt.ylabel('Avg. hops required')
plt.xlabel('Network size')
plt.title("Avg hops vs Pastry network size")
plt.savefig("chord_avg_hops_needed.svg")
for i in range (0,10):
   chord.find_key_and_route()
   print()
```

id_to_node[list(id_to_node.keys())[0]].print_finger_table()