

Practical = 7

Name: shubham shivraj Suryawanshi

Reg. No: 2020BIT004

Write a code with complete simulation of the following

AVL tree

Binary Heap

Max Heap

Min Heap

Heapyfy

1) AVL tree

AVL tree implementation in C++

```
#include <iostream>
using namespace std;

class Node {
public:
    int key;
    Node *left;
    Node *right;
    int height;
};

int max(int a, int b);

// Calculate height
int height(Node *N) {
    if (N == NULL)
        return 0;
    return N->height;
}

int max(int a, int b) {
    return (a > b) ? a : b;
}

// New node creation
Node *newNode(int key) {
    Node *node = new Node();
    node->key = key;
    node->left = NULL;
    node->right = NULL;
    node->height = 1;
    return (node);
}

// Rotate right
Node *rightRotate(Node *y) {
    Node *x = y->left;
    Node *T2 = x->right;
    x->right = y;
    y->left = T2;
    y->height = max(height(y->left),
        height(y->right)) +
        1;
    x->height = max(height(x->left),
        height(x->right)) +
        1;
    return x;
}
```

```

}

// Rotate left
Node *leftRotate(Node *x) {
    Node *y = x->right;
    Node *T2 = y->left;
    y->left = x;
    x->right = T2;
    x->height = max(height(x->left),
        height(x->right)) +
        1;
    y->height = max(height(y->left),
        height(y->right)) +
        1;
    return y;
}

// Get the balance factor of each node
int getBalanceFactor(Node *N) {
    if (N == NULL)
        return 0;
    return height(N->left) -
        height(N->right);
}

// Insert a node
Node *insertNode(Node *node, int key) {
    // Find the correct position and insert the node
    if (node == NULL)
        return (newNode(key));
    if (key < node->key)
        node->left = insertNode(node->left, key);
    else if (key > node->key)
        node->right = insertNode(node->right, key);
    else
        return node;

    // Update the balance factor of each node and
    // balance the tree
    node->height = 1 + max(height(node->left),
        height(node->right));
    int balanceFactor = getBalanceFactor(node);
    if (balanceFactor > 1) {
        if (key < node->left->key) {
            return rightRotate(node);
        } else if (key > node->left->key) {
            node->left = leftRotate(node->left);
            return rightRotate(node);
        }
    }
    if (balanceFactor < -1) {
        if (key > node->right->key) {
            return leftRotate(node);
        } else if (key < node->right->key) {
            node->right = rightRotate(node->right);
            return leftRotate(node);
        }
    }
    return node;
}

// Node with minimum value
Node *nodeWithMimumValue(Node *node) {
    Node *current = node;
    while (current->left != NULL)
        current = current->left;
    return current;
}

```

```

// Delete a node
Node *deleteNode(Node *root, int key) {
    // Find the node and delete it
    if (root == NULL)
        return root;
    if (key < root->key)
        root->left = deleteNode(root->left, key);
    else if (key > root->key)
        root->right = deleteNode(root->right, key);
    else {
        if ((root->left == NULL) ||
            (root->right == NULL)) {
            Node *temp = root->left ? root->left : root->right;
            if (temp == NULL) {
                temp = root;
                root = NULL;
            } else
                *root = *temp;
            free(temp);
        } else {
            Node *temp = nodeWithMimumValue(root->right);
            root->key = temp->key;
            root->right = deleteNode(root->right,
                                    temp->key);
        }
    }

    if (root == NULL)
        return root;

    // Update the balance factor of each node and
    // balance the tree
    root->height = 1 + max(height(root->left),
                          height(root->right));
    int balanceFactor = getBalanceFactor(root);
    if (balanceFactor > 1) {
        if (getBalanceFactor(root->left) >= 0) {
            return rightRotate(root);
        } else {
            root->left = leftRotate(root->left);
            return rightRotate(root);
        }
    }
    if (balanceFactor < -1) {
        if (getBalanceFactor(root->right) <= 0) {
            return leftRotate(root);
        } else {
            root->right = rightRotate(root->right);
            return leftRotate(root);
        }
    }
    return root;
}

// Print the tree
void printTree(Node *root, string indent, bool last) {
    if (root != nullptr) {
        cout << indent;
        if (last) {
            cout << "R----";
            indent += " ";
        } else {
            cout << "L----";
            indent += "| ";
        }
        cout << root->key << endl;
        printTree(root->left, indent, false);
    }
}

```

```

    printTree(root->right, indent, true);
}
}

```

```

int main() {
    Node *root = NULL;
    root = insertNode(root, 33);
    root = insertNode(root, 13);
    root = insertNode(root, 53);
    root = insertNode(root, 9);
    root = insertNode(root, 21);
    root = insertNode(root, 61);
    root = insertNode(root, 8);
    root = insertNode(root, 11);
    printTree(root, "", true);
    root = deleteNode(root, 13);
    cout << "After deleting " << endl;
    printTree(root, "", true);
}
Output:

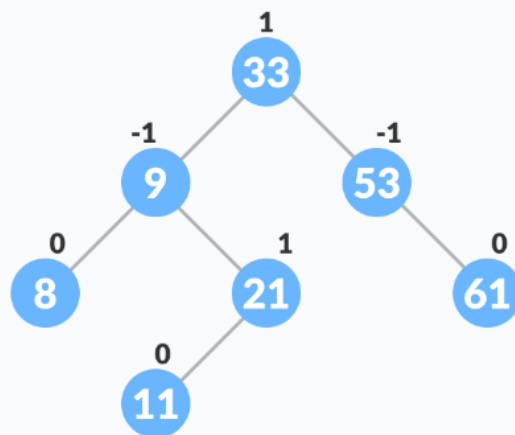
```

```

R----33
|
L----9
|   L----8
|   |   R----21
|   |   |   L----11
|   R----53
|   |   R----61
PS D:\Assignments TY\DAA\Codes\output> 

```

Simulation:



2) Binary Heap

// A C++ program to demonstrate common Binary Heap Operations

```
#include<iostream>
```

```
#include<climits>
```

```
using namespace std;
```

// Prototype of a utility function to swap two integers

```
void swap(int *x, int *y);
```

// A class for Min Heap

```

class MinHeap
{
    int *harr; // pointer to array of elements in heap
    int capacity; // maximum possible size of min heap
    int heap_size; // Current number of elements in min heap
public:
    // Constructor
    MinHeap(int capacity);

    // to heapify a subtree with the root at given index
    void MinHeapify(int );

    int parent(int i) { return (i-1)/2; }

    // to get index of left child of node at index i
    int left(int i) { return (2*i + 1); }

    // to get index of right child of node at index i
    int right(int i) { return (2*i + 2); }

    // to extract the root which is the minimum element
    int extractMin();

    // Decreases key value of key at index i to new_val
    void decreaseKey(int i, int new_val);

    // Returns the minimum key (key at root) from min heap
    int getMin() { return harr[0]; }

    // Deletes a key stored at index i
    void deleteKey(int i);

    // Inserts a new key 'k'
    void insertKey(int k);
};

// Constructor: Builds a heap from a given array a[] of given size
MinHeap::MinHeap(int cap)
{
    heap_size = 0;
    capacity = cap;
    harr = new int[cap];

```

```
}
```

```
// Inserts a new key 'k'
```

```
void MinHeap::insertKey(int k)
```

```
{
```

```
    if (heap_size == capacity)
```

```
    {
```

```
        cout << "\nOverflow: Could not insertKey\n";
```

```
        return;
```

```
    }
```

```
    // First insert the new key at the end
```

```
    heap_size++;
```

```
    int i = heap_size - 1;
```

```
    harr[i] = k;
```

```
    // Fix the min heap property if it is violated
```

```
    while (i != 0 && harr[parent(i)] > harr[i])
```

```
    {
```

```
        swap(&harr[i], &harr[parent(i)]);
```

```
        i = parent(i);
```

```
    }
```

```
}
```

```
// Decreases value of key at index 'i' to new_val. It is assumed that
```

```
// new_val is smaller than harr[i].
```

```
void MinHeap::decreaseKey(int i, int new_val)
```

```
{
```

```
    harr[i] = new_val;
```

```
    while (i != 0 && harr[parent(i)] > harr[i])
```

```
    {
```

```
        swap(&harr[i], &harr[parent(i)]);
```

```
        i = parent(i);
```

```
    }
```

```
}
```

```
// Method to remove minimum element (or root) from min heap
```

```
int MinHeap::extractMin()
```

```
{
```

```
    if (heap_size <= 0)
```

```
        return INT_MAX;
```

```
    if (heap_size == 1)
```

```

    {
        heap_size--;
        return harr[0];
    }

    // Store the minimum value, and remove it from heap
    int root = harr[0];
    harr[0] = harr[heap_size-1];
    heap_size--;
    MinHeapify(0);

    return root;
}

// This function deletes key at index i. It first reduced value to minus
// infinite, then calls extractMin()
void MinHeap::deleteKey(int i)
{
    decreaseKey(i, INT_MIN);
    extractMin();
}

// A recursive method to heapify a subtree with the root at given index
// This method assumes that the subtrees are already heapified
void MinHeap::MinHeapify(int i)
{
    int l = left(i);
    int r = right(i);
    int smallest = i;
    if (l < heap_size && harr[l] < harr[i])
        smallest = l;
    if (r < heap_size && harr[r] < harr[smallest])
        smallest = r;
    if (smallest != i)
    {
        swap(&harr[i], &harr[smallest]);
        MinHeapify(smallest);
    }
}

// A utility function to swap two elements

```

```

void swap(int *x, int *y)
{
    int temp = *x;
    *x = *y;
    *y = temp;
}

// Driver program to test above functions
int main()
{
    MinHeap h(11);
    h.insertKey(3);
    h.insertKey(2);
    h.deleteKey(1);
    h.insertKey(15);
    h.insertKey(5);
    h.insertKey(4);
    h.insertKey(45);
    cout << h.extractMin() << " ";
    cout << h.getMin() << " ";
    h.decreaseKey(2, 1);
    cout << h.getMin();
    return 0;
}

```

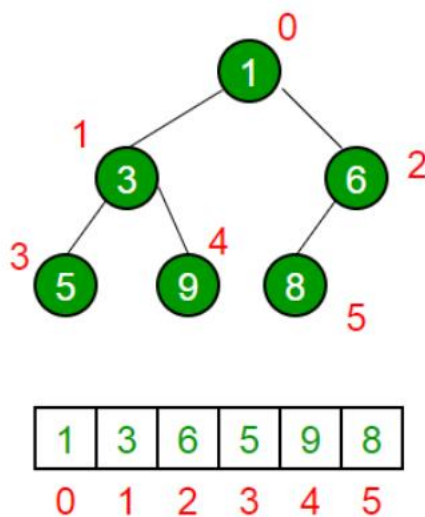
}}Output:

```

PS D:\Assignments TY\DAA\Codes\output
● PS D:\Assignments TY\DAA\Codes\output
○ 2 4 1
PS D:\Assignments TY\DAA\Codes\output

```

Simulation:



3) Max Heap

```
#include <iostream>
```



```

using namespace std;

void heapify(int arr[], int n, int i) {
    // Find largest among root, left child and right child
    int largest = i;
    int left = 2 * i + 1;
    int right = 2 * i + 2;

    if (left < n && arr[left] > arr[largest])
        largest = left;

    if (right < n && arr[right] > arr[largest])
        largest = right;

    // Swap and continue heapifying if root is not largest
    if (largest != i) {
        swap(arr[i], arr[largest]);
        heapify(arr, n, largest);
    }
}

// main function to do heap sort
void heapSort(int arr[], int n) {
    // Build max heap
    for (int i = n / 2 - 1; i >= 0; i--)
        heapify(arr, n, i);

    // Heap sort
    for (int i = n - 1; i >= 0; i--) {
        swap(arr[0], arr[i]);

        // Heapify root element to get highest element at root again
        heapify(arr, i, 0);
    }
}

// Print an array
void printArray(int arr[], int n) {
    for (int i = 0; i < n; ++i)
        cout << arr[i] << " ";
    cout << "\n";
}

// Driver code
int main() {
    int arr[] = {1, 12, 9, 5, 6, 10};

```

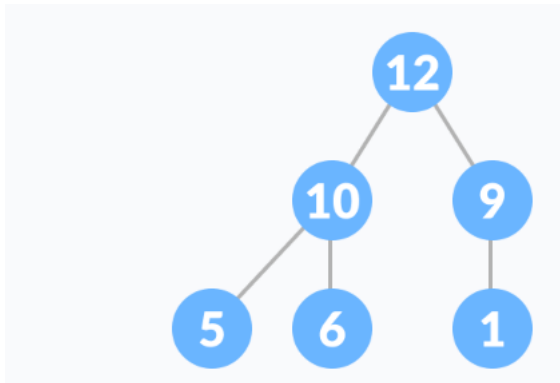
```
int n = sizeof(arr) / sizeof(arr[0]);
heapSort(arr, n);
```

```
cout << "Sorted array is \n";
printArray(arr, n);
```

} **Output:-**

```
Sorted array is
1 5 6 9 10 12
```

Simulation:



4) Min Heap

```
#include <bits/stdc++.h>
using namespace std;
```

```
// Driver code
```

```
int main ()
```

```
{
```

```
// Creates a max heap
```

```
priority_queue <int> pq;
```

```
pq.push(5);
```

```
pq.push(1);
```

```
pq.push(10);
```

```
pq.push(30);
```

```
pq.push(20);
```

```
// One by one extract items from max heap
```

```
while (pq.empty() == false)
```

```
{
```

```
    cout << pq.top() << " ";
```

```
    pq.pop();
```

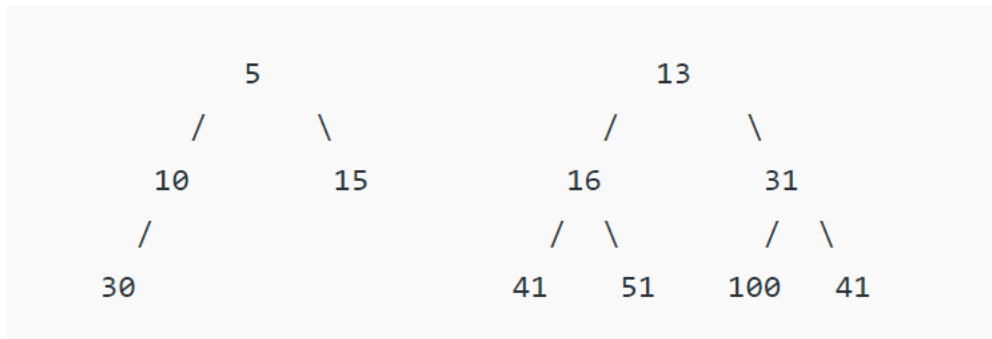
```
}
```

```
return 0;
```

} **Output:-**

```
30 20 10 5 1
```

Simulation:



5)Heapify

```

#include <iostream>
using namespace std;

// To heapify a subtree rooted with node i
// which is an index in arr[].
// n is size of heap
void heapify(int arr[], int N, int i)
{
    // Initialize largest as root
    int largest = i;

    // left = 2*i + 1
    int l = 2 * i + 1;

    // right = 2*i + 2
    int r = 2 * i + 2;

    // If left child is larger than root
    if (l < N && arr[l] > arr[largest])
        largest = l;

    // If right child is larger than largest
    // so far
    if (r < N && arr[r] > arr[largest])
        largest = r;

    // If largest is not root
    if (largest != i) {
        swap(arr[i], arr[largest]);

        // Recursively heapify the affected
        // sub-tree
        heapify(arr, N, largest);
    }
}

```

```

}
}

// Main function to do heap sort
void heapSort(int arr[], int N)
{

    // Build heap (rearrange array)
    for (int i = N / 2 - 1; i >= 0; i--)
        heapify(arr, N, i);

    // One by one extract an element
    // from heap
    for (int i = N - 1; i > 0; i--) {

        // Move current root to end
        swap(arr[0], arr[i]);

        // call max heapify on the reduced heap
        heapify(arr, i, 0);
    }
}

// A utility function to print array of size n
void printArray(int arr[], int N)
{
    for (int i = 0; i < N; ++i)
        cout << arr[i] << " ";
    cout << "\n";
}

// Driver's code
int main()
{
    int arr[] = { 12, 11, 13, 5, 6, 7 };
    int N = sizeof(arr) / sizeof(arr[0]);

    // Function call
    heapSort(arr, N);

    cout << "Sorted array is \n";
    printArray(arr, N);
} Output:-

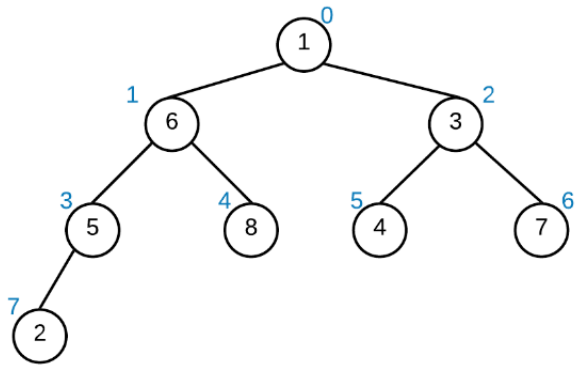
```

```

Sorted array is
5 6 7 11 12 13

```

Simulation:



1	6	3	5	8	4	7	2
0	1	2	3	4	5	6	7