

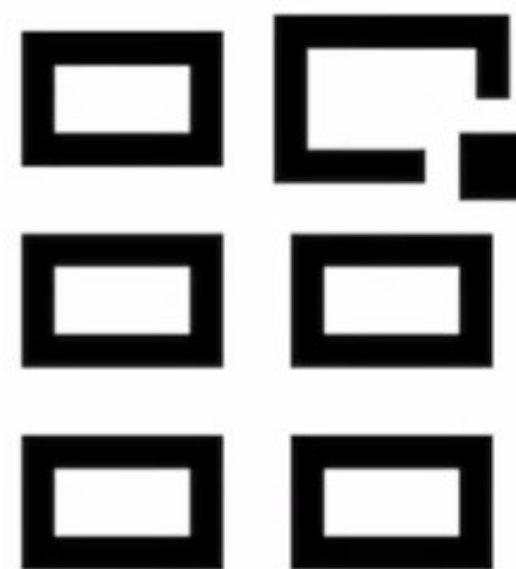


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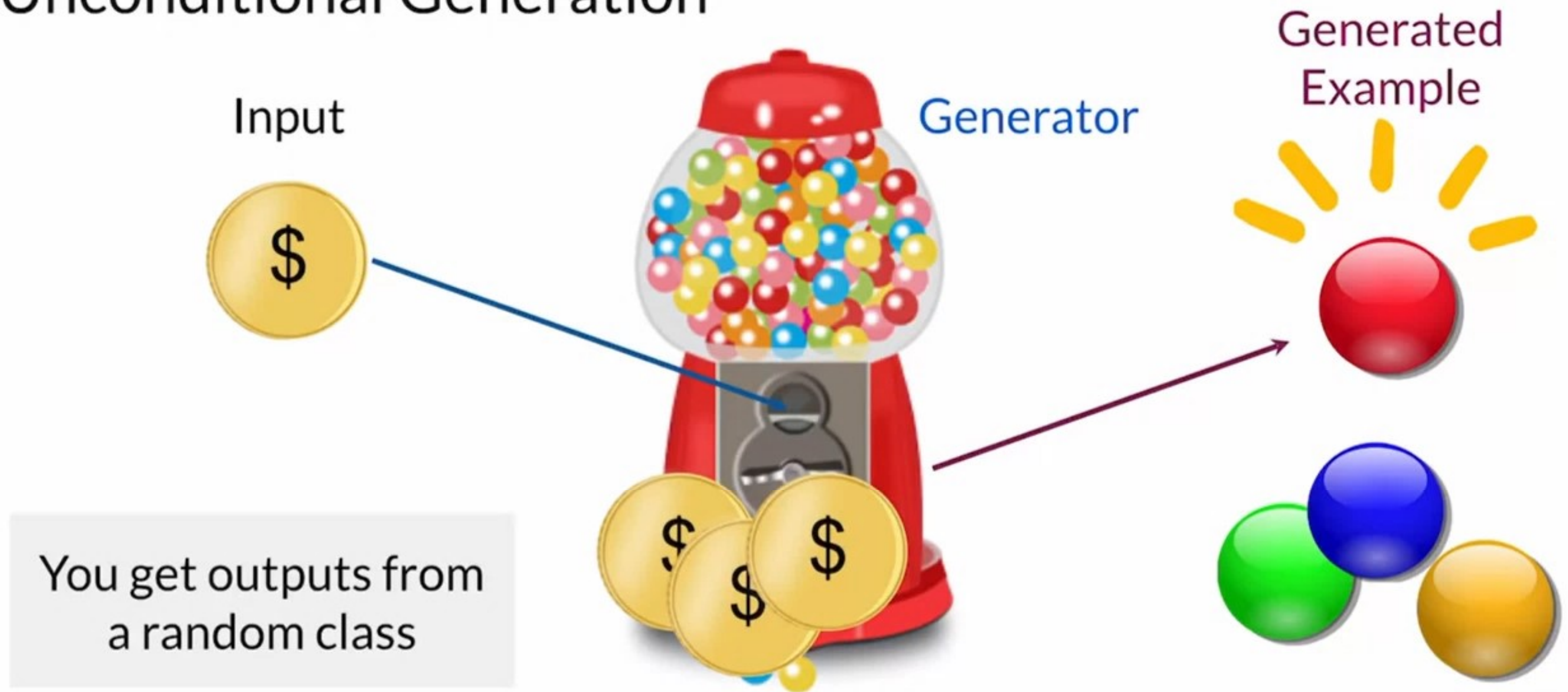
# Conditional Generation: Intuition

# Outline

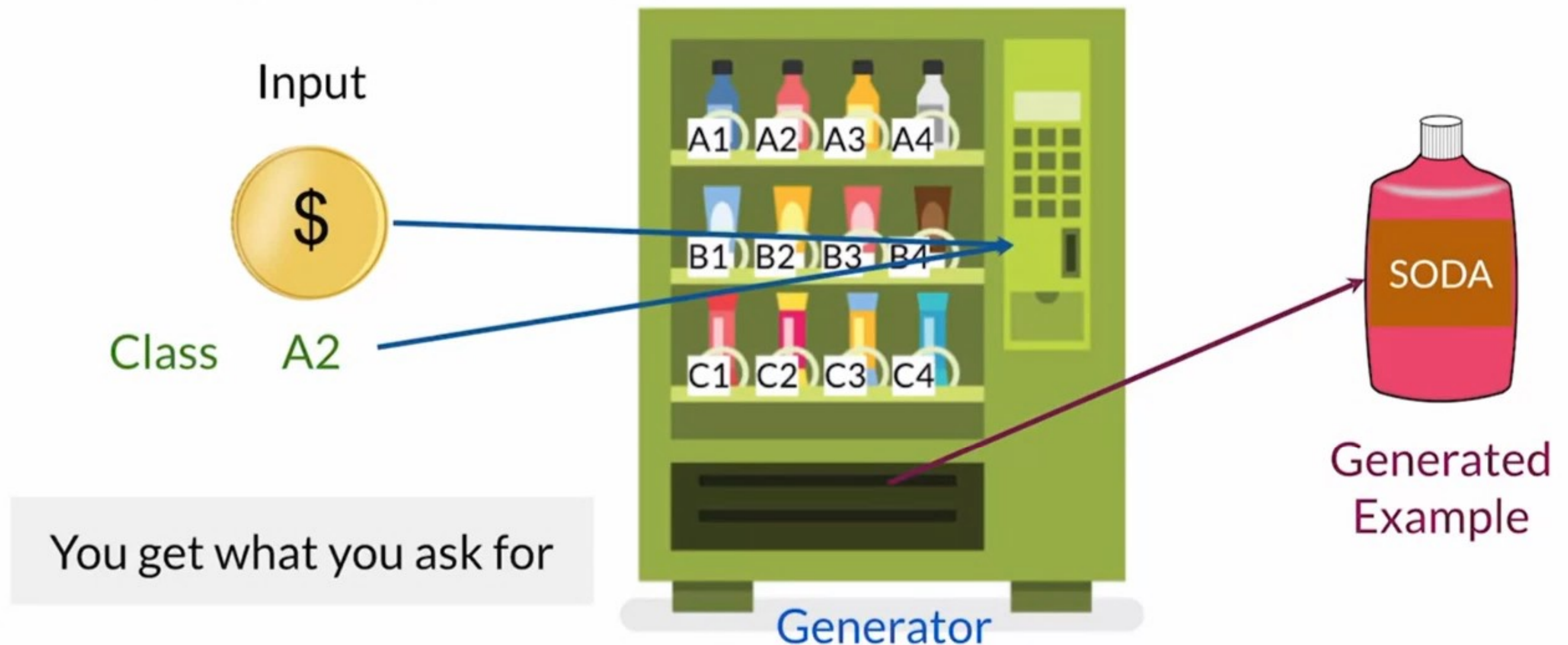
- Unconditional generation
- Conditional vs. unconditional generation



# Unconditional Generation



# Conditional Generation



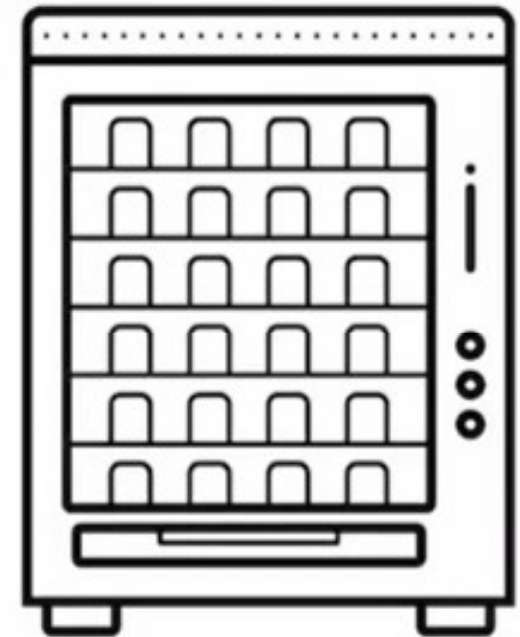


# Conditional vs. Unconditional Generation

Conditional	Unconditional
Examples from <b>the classes you want</b>	Examples from <i>random classes</i>
Training dataset needs to be <b>labeled</b>	Training dataset <i>doesn't need to be labeled</i>

# Summary

- Conditional generation requires labeled datasets
- Examples can be generated for the selected class



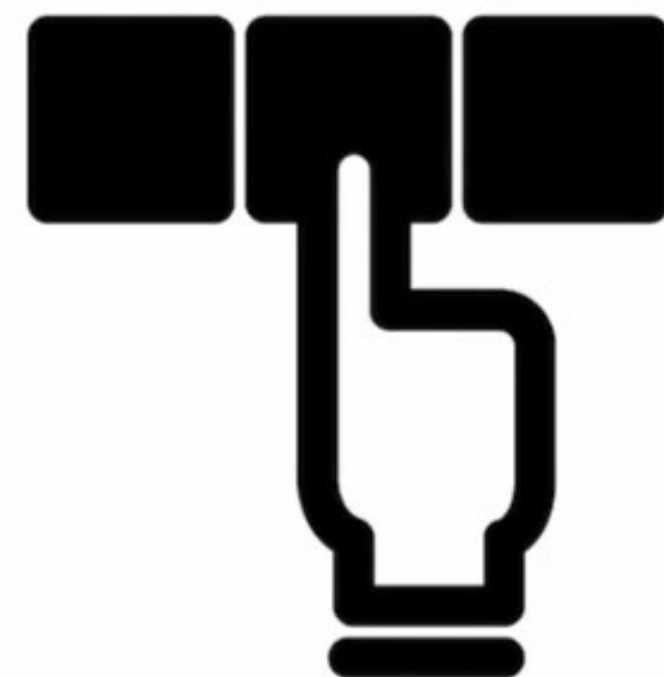


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# Conditional Generation: Inputs

# Outline

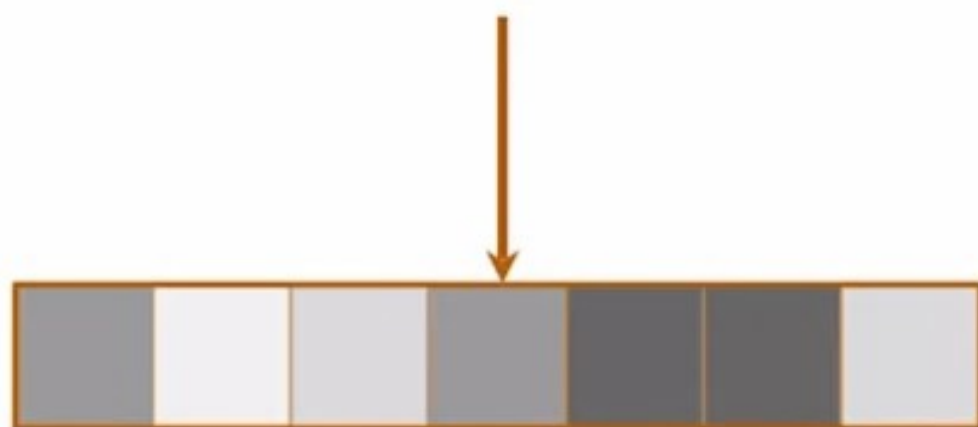
- How to tell the generator what type of example to produce
- Input representation for the discriminator





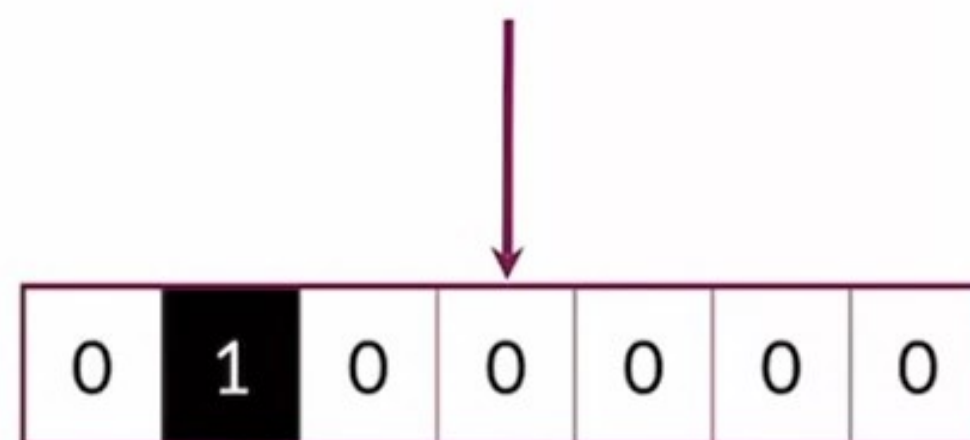
# Generator Input

Noise vector



Randomness in the generation

Class (one-hot) vector



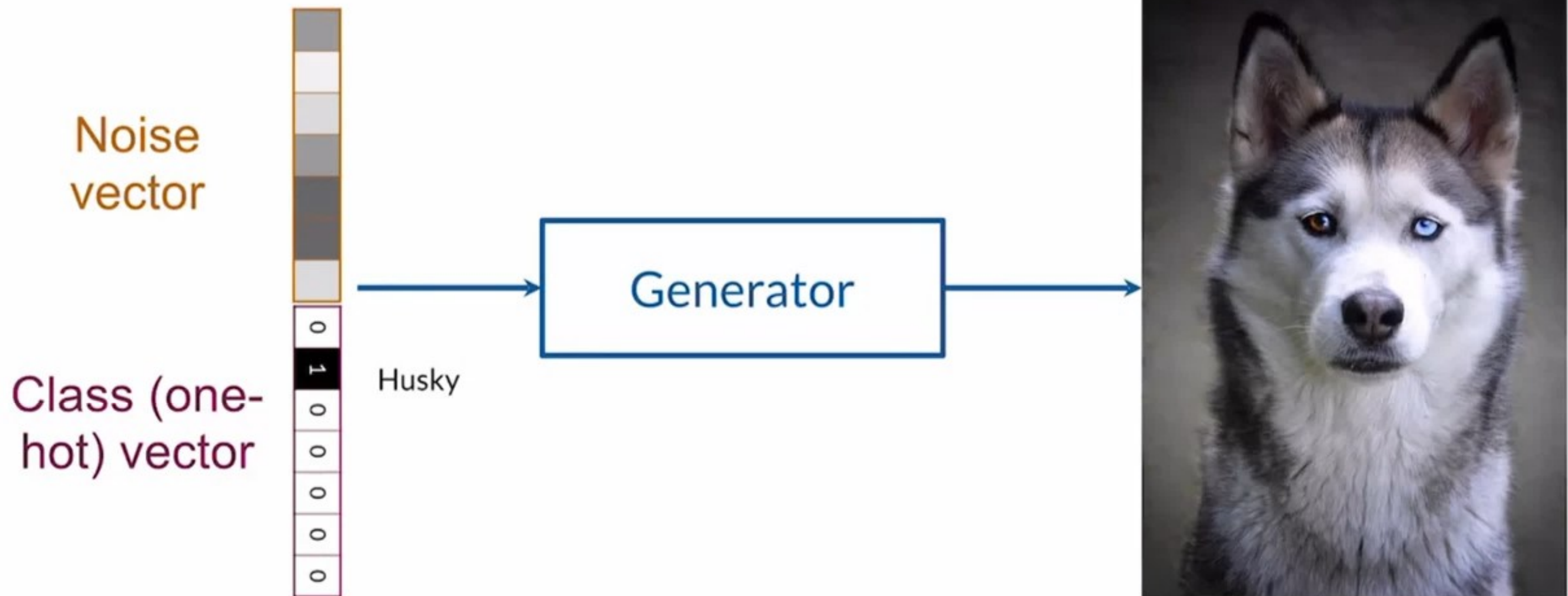
Control in the generation

Husky

dog breed

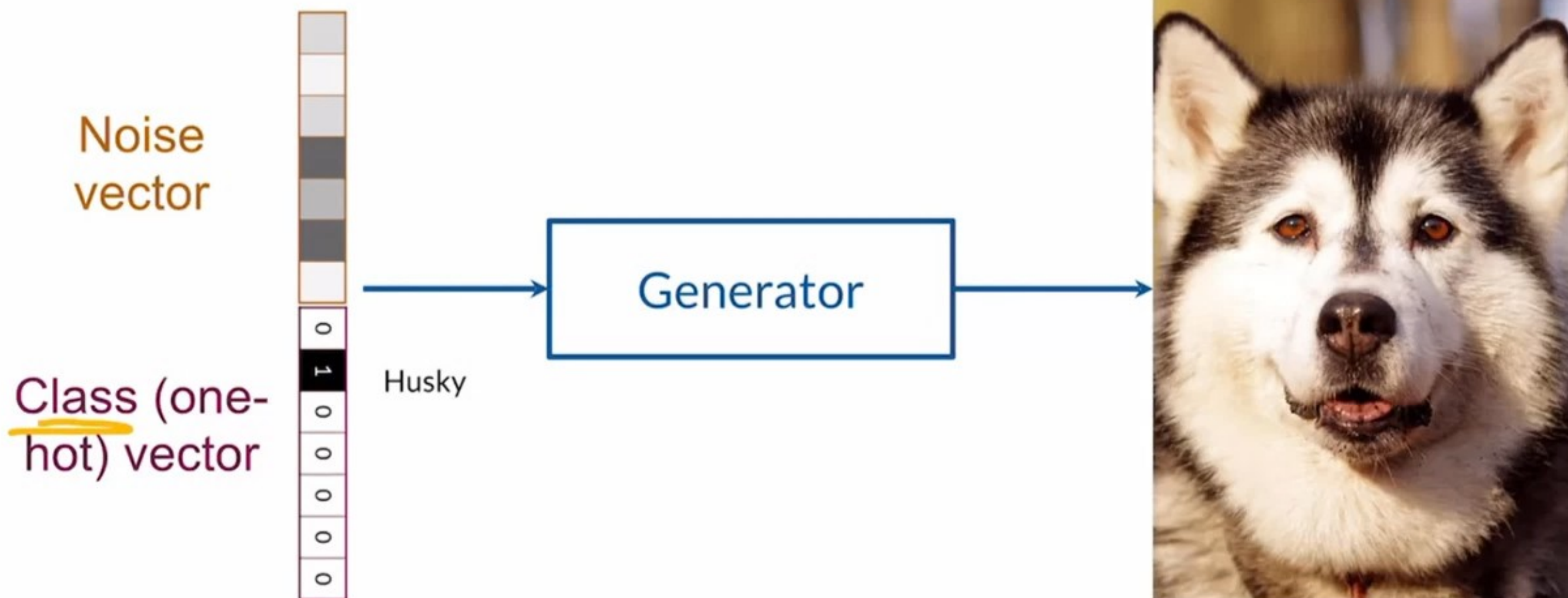
# Generator Input

Output



# Generator Input

Output



## Discriminator Input

Real image of some breed  
other than Golden Retriever



Discriminator

Output

5%  
Real

Golden Retriever

class

Real image of different class is  
considered as a fake image by the  
discriminator.



# Discriminator Input



Golden Retriever

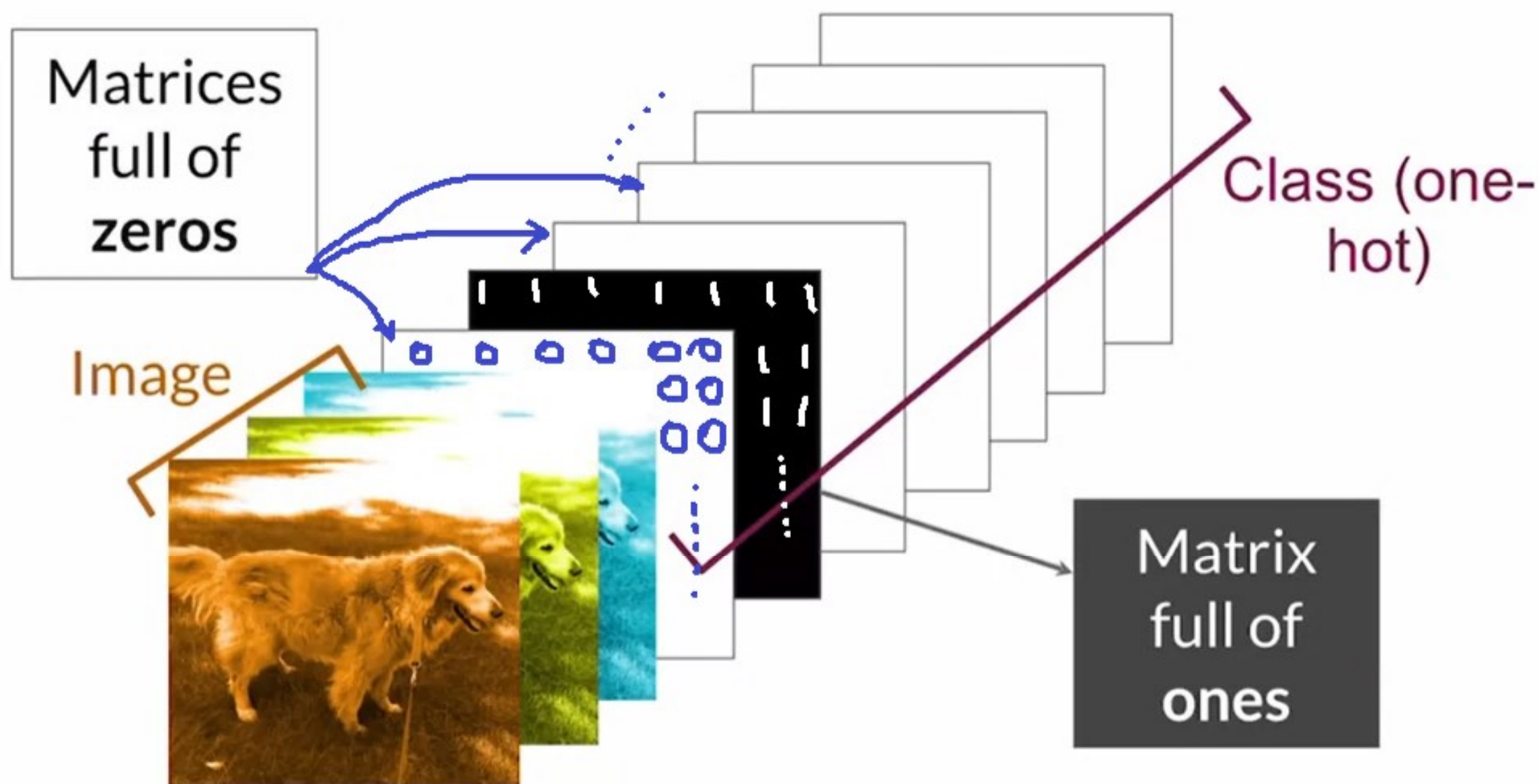
Discriminator

Output

98%  
Real

# Discriminator Input

We can feed the one hot vector (class) as channels. Other space efficient methods may also be used especially if there are lots of





# Summary

- The class is passed to the generator as one-hot vectors
- The class is passed to the discriminator as one-hot matrices
- The size of the vector and the number of matrices represent the number of classes



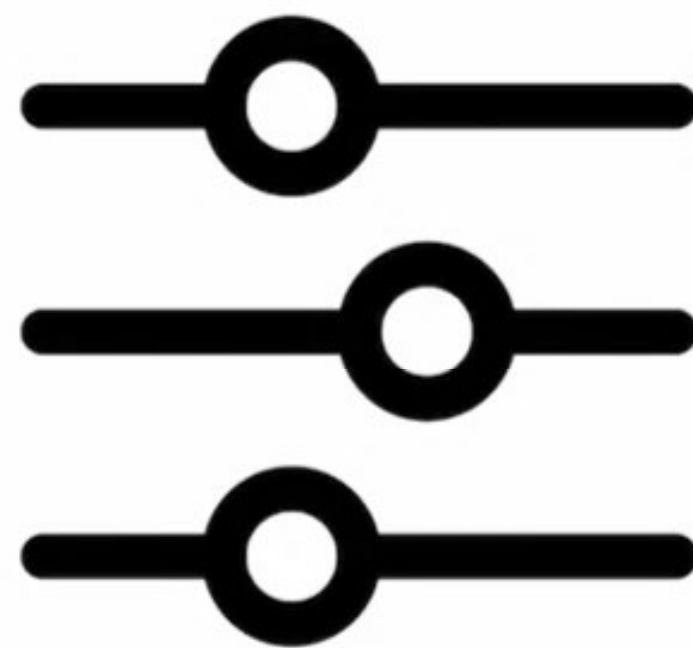


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# Controllable Generation

# Outline

- What is controllable generation
- How it compares to conditional generation



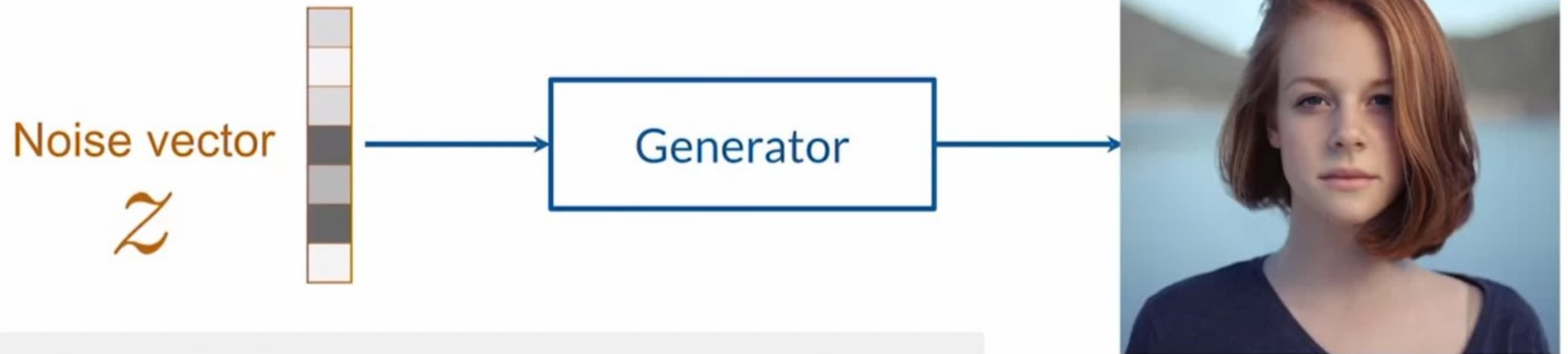
# Controllable Generation



Change specific features of the output

Available from: <https://arxiv.org/abs/1907.10786>

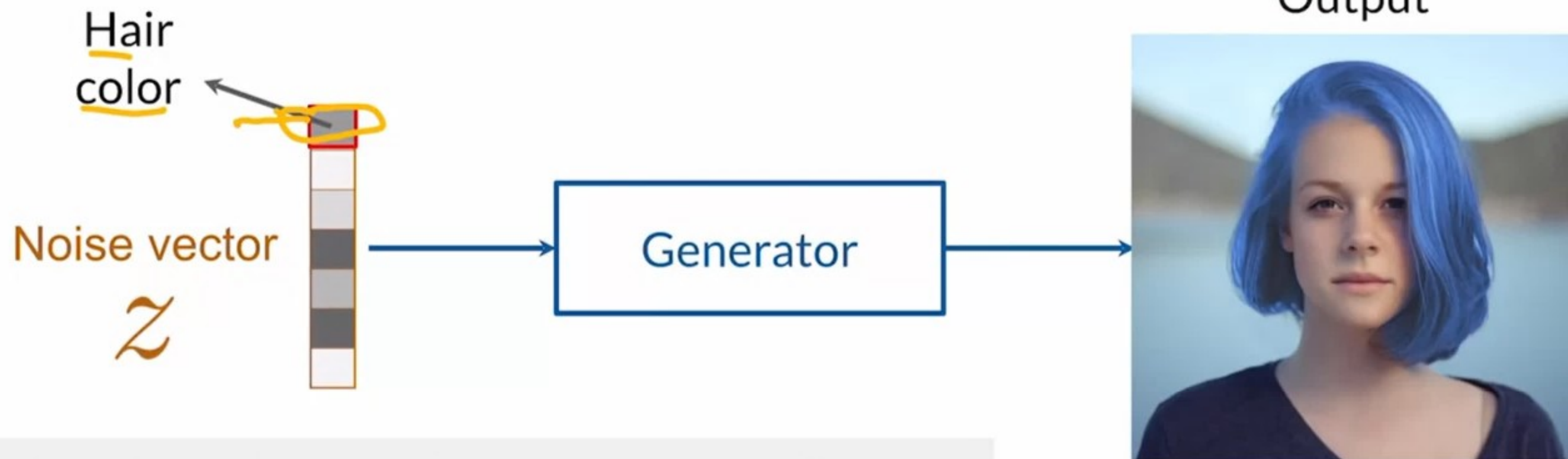
# Controllable Generation



Tweak the input noise vector to get different features on the output



# Controllable Generation



Tweak the input noise vector to get different features on the output

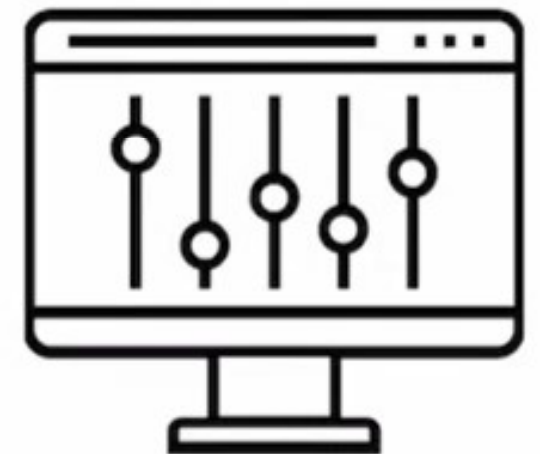


# Controllable Generation vs. Conditional Generation

Controllable	Conditional
Examples with the <b>features that you want</b>	Examples from <i>the classes you want</i>
Training dataset <b>doesn't need to be labeled</b>	Training dataset <i>needs to be labeled</i>
<b>Manipulate the z vector</b> input	<i>Append a class vector</i> to the input

# Summary

- Controllable generation lets you control the features of the generated outputs
- It does not need a labeled training dataset
- The input vector is tweaked to get different features on the output



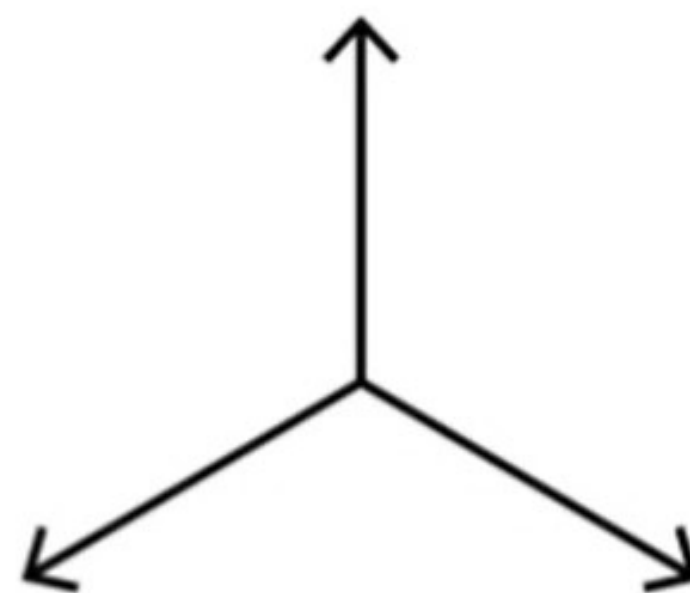


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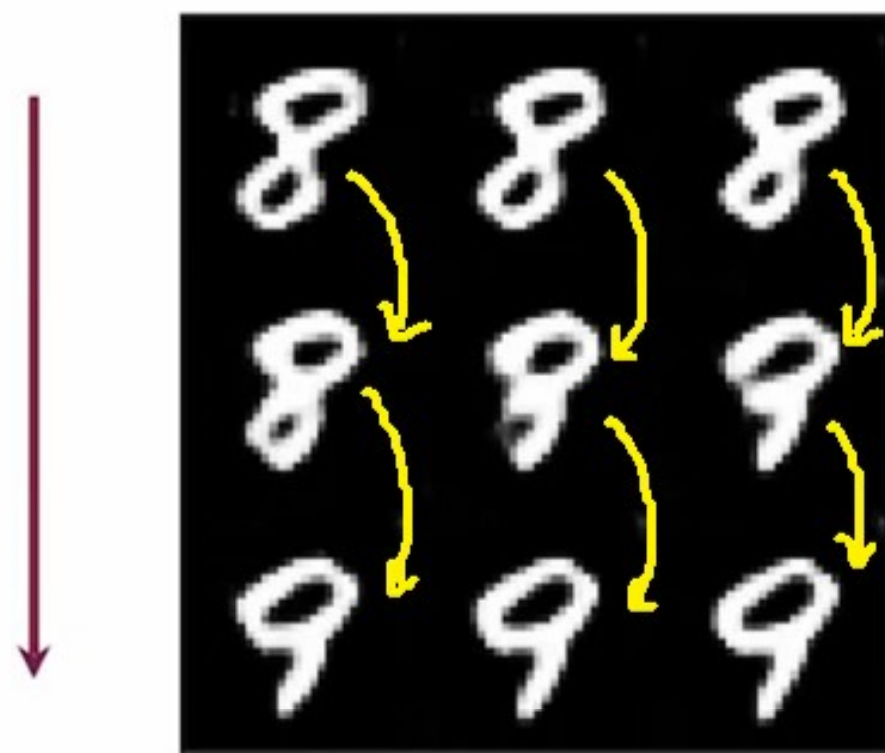
# Vector Algebra in the $Z$ -Space

# Outline

- Interpolation in the  $Z$ -space
- Modifying the noise vector  $z$  to control desired features



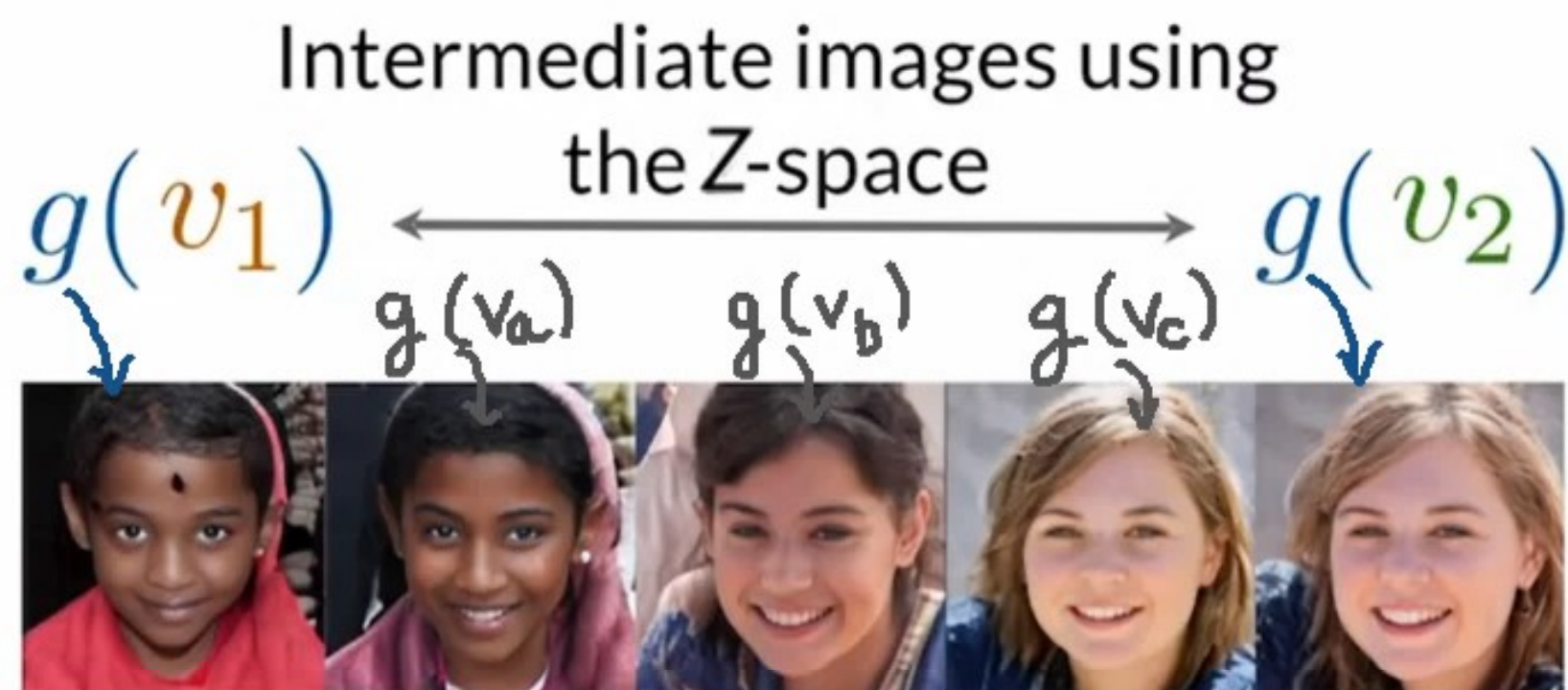
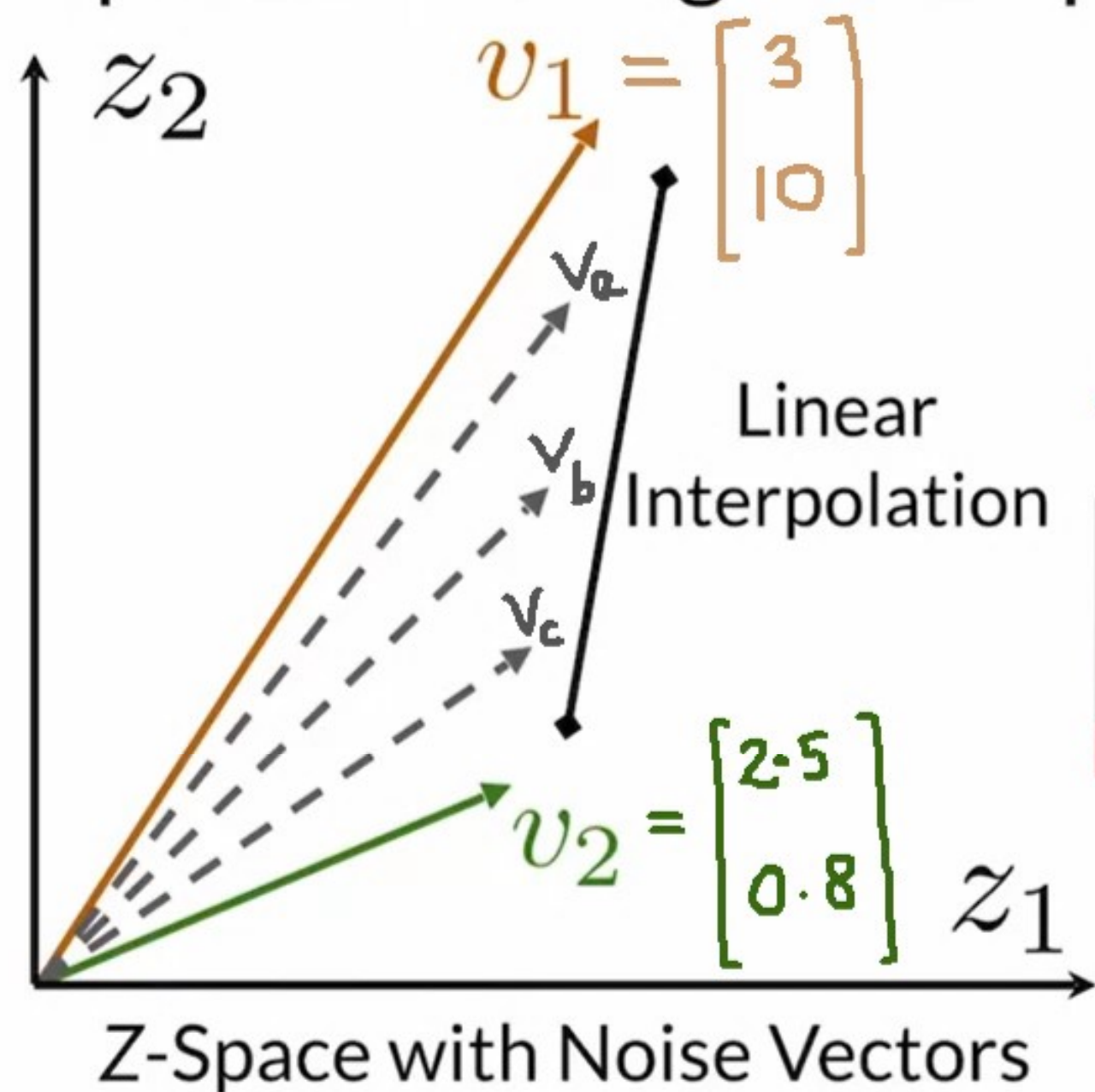
## Interpolation Using the Z-Space



How an image morphs into  
another



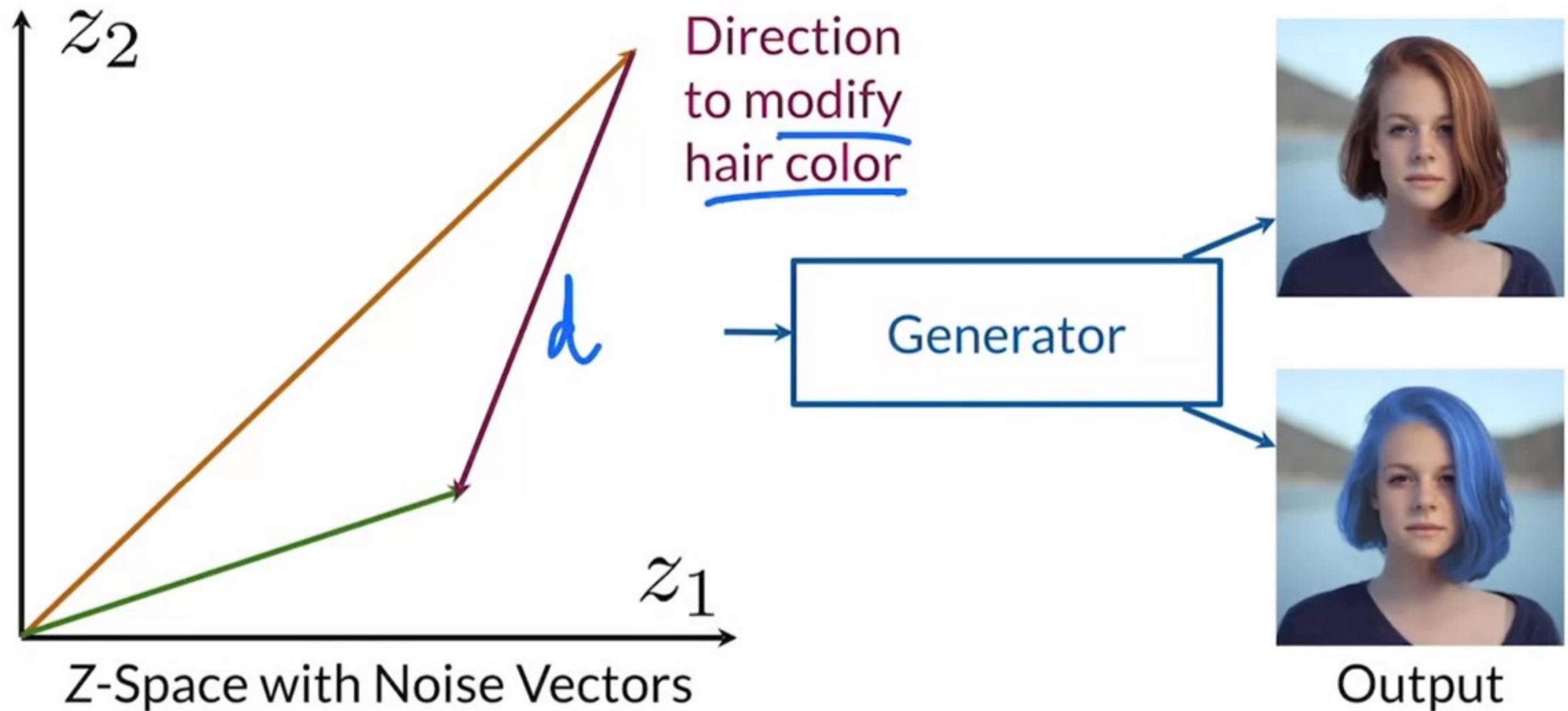
# Interpolation Using the Z-Space



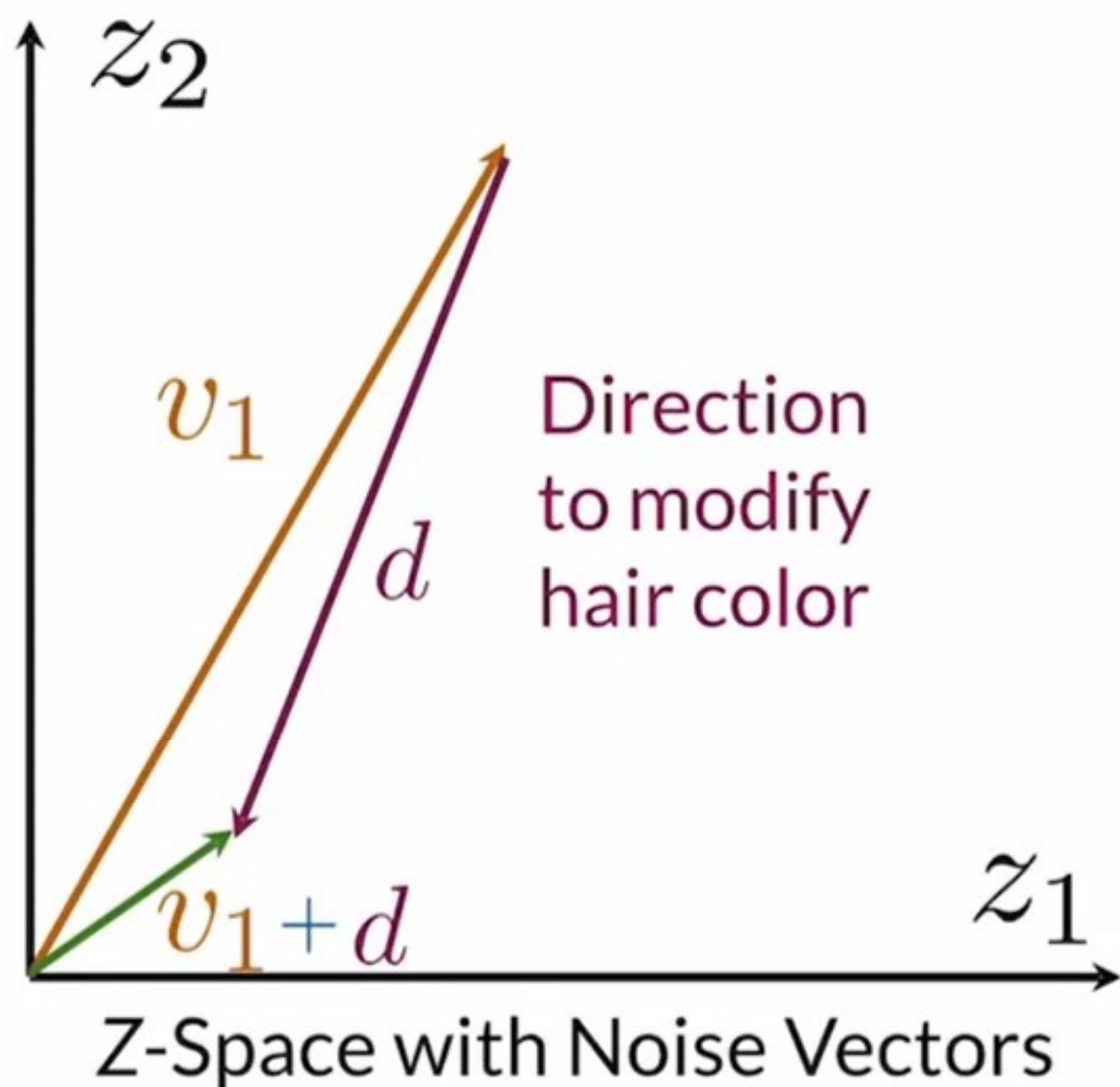


Identify the direction to control generation by hair color.

## Z-Space and Controllable Generation

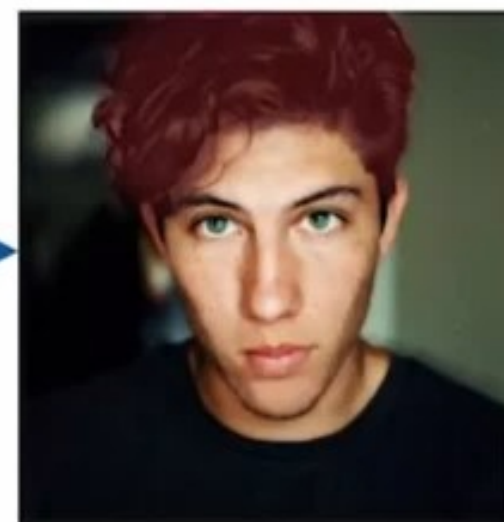


# Z-Space and Controllable Generation



Original output

$$g(v_1)$$



Controlled output

$$g(v_1 + d)$$



# Summary

- To control output features, you need to find directions in the Z-space
- To modify your output, you move around in the Z-space





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# Challenges with Controllable Generation

# Outline

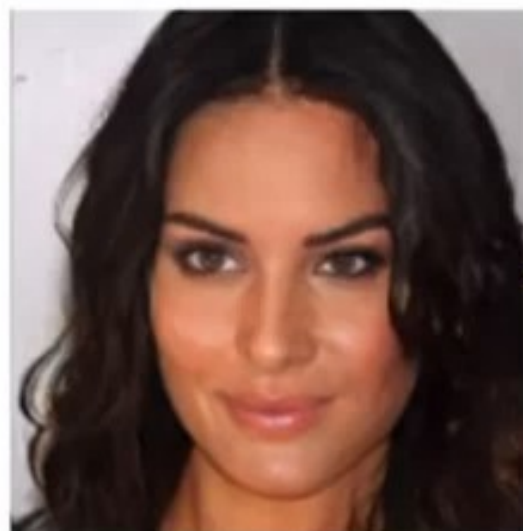
- Output feature correlation
- Z-space entanglement





# Feature Correlation

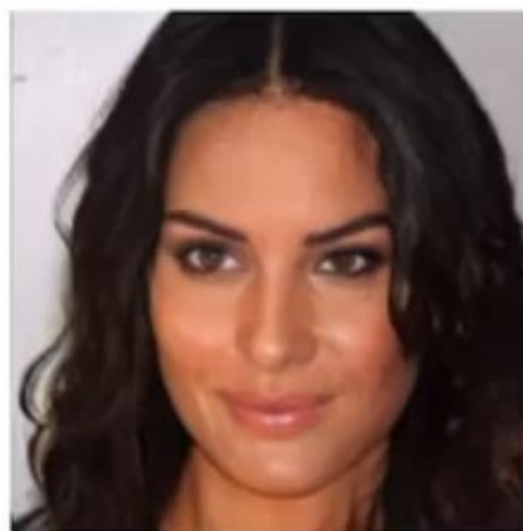
Uncorrelated  
Features



Add beard



Correlated  
Features



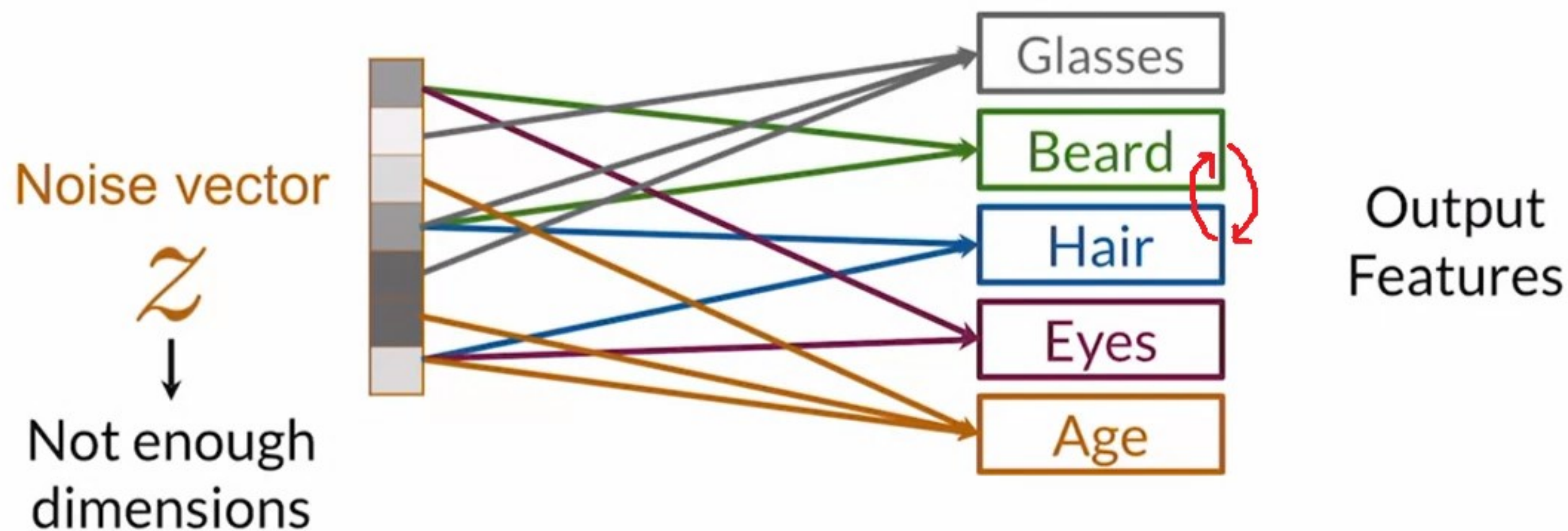
Add beard

Make more  
masculine





# Z-Space Entanglement



Changing beard will end up changing other features.  
It is not possible to control single output features

# Summary

- When trying to control one feature, others that are correlated change
- Z-space entanglement makes controllability difficult, if not impossible
- Entanglement happens when  $z$  does not have enough dimensions



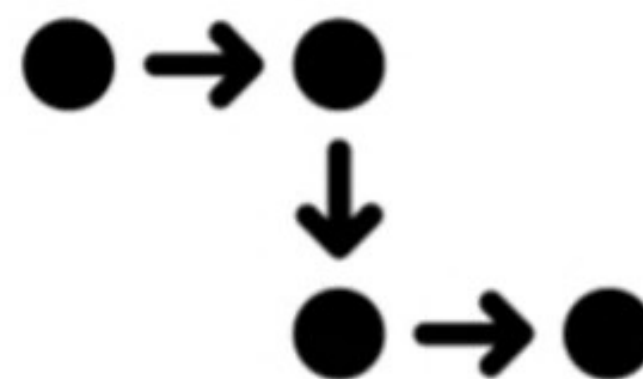


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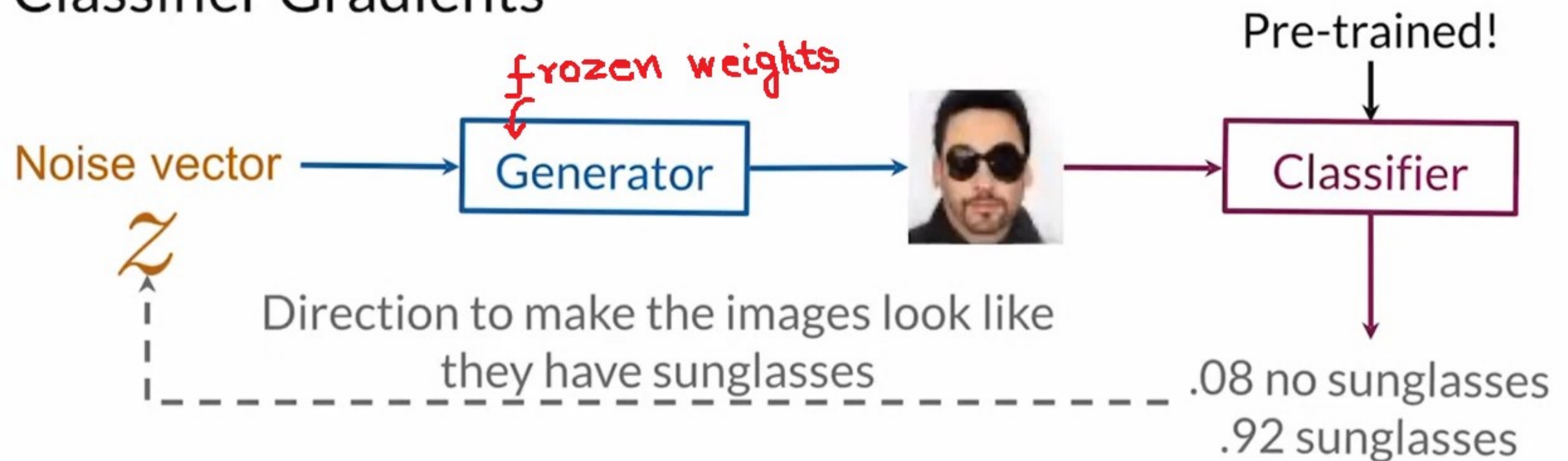
# Classifier Gradients

# Outline

- How to use classifiers to find directions in the Z-space
- Requirements to use this method



# Classifier Gradients



Modify **just** the **noise vector** until the feature emerges



# Summary

- Classifiers can be used to find directions in the Z-space
- To find directions, the updates are done just to the noise vector





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# Disentanglement

# Outline

- What a disentangled Z-space means
- Ways to encourage disentangled Z-spaces



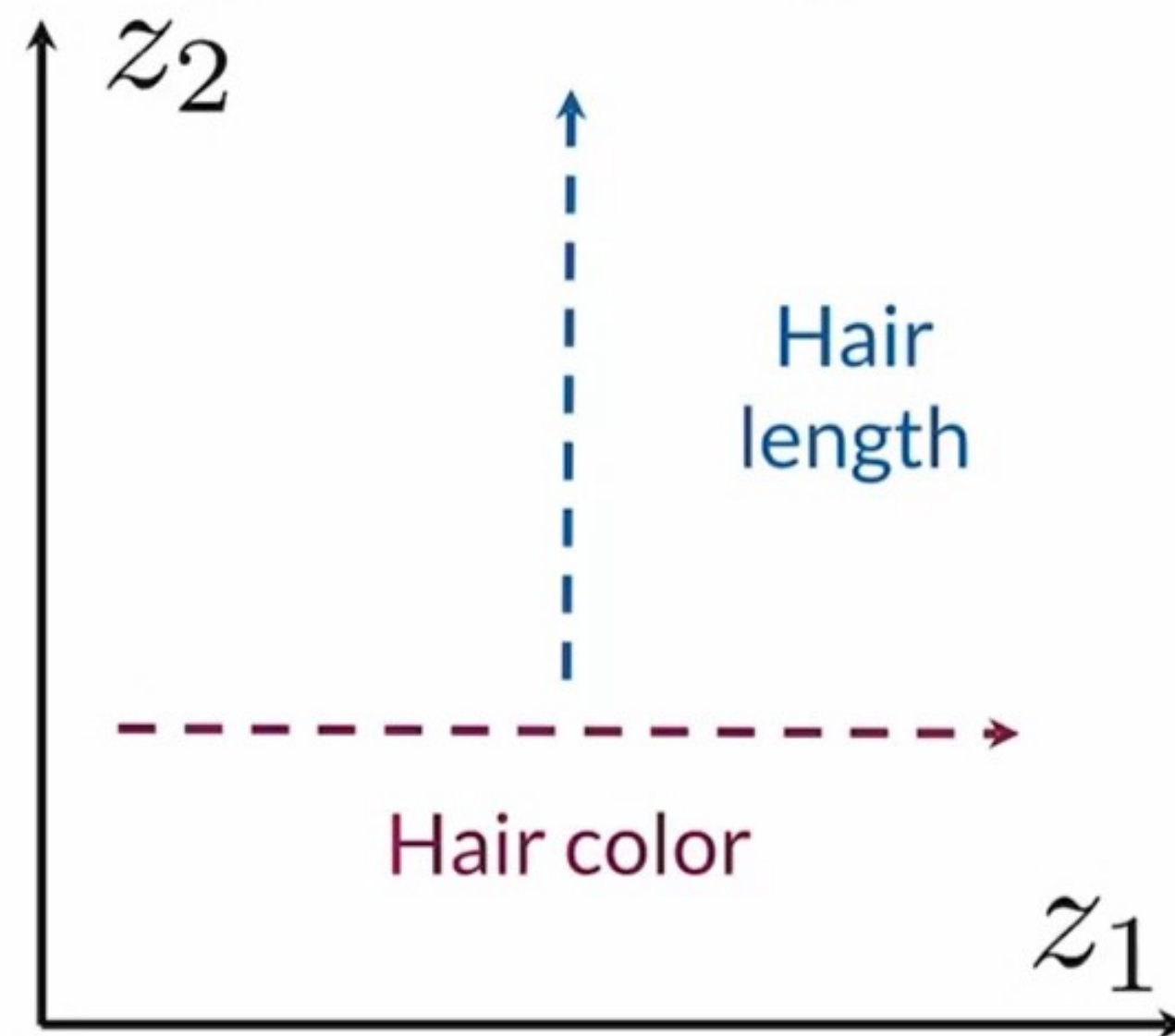
## Disentangled Z-Space

$$\begin{array}{c} z_1 \quad z_2 \\ v_1 = [ \text{1}, \text{2}, \text{3}, \dots ] \\ v_2 = [ \text{5}, \text{6}, \text{7}, \dots ] \end{array}$$

Hair color      Hair length

Latent factors of variation

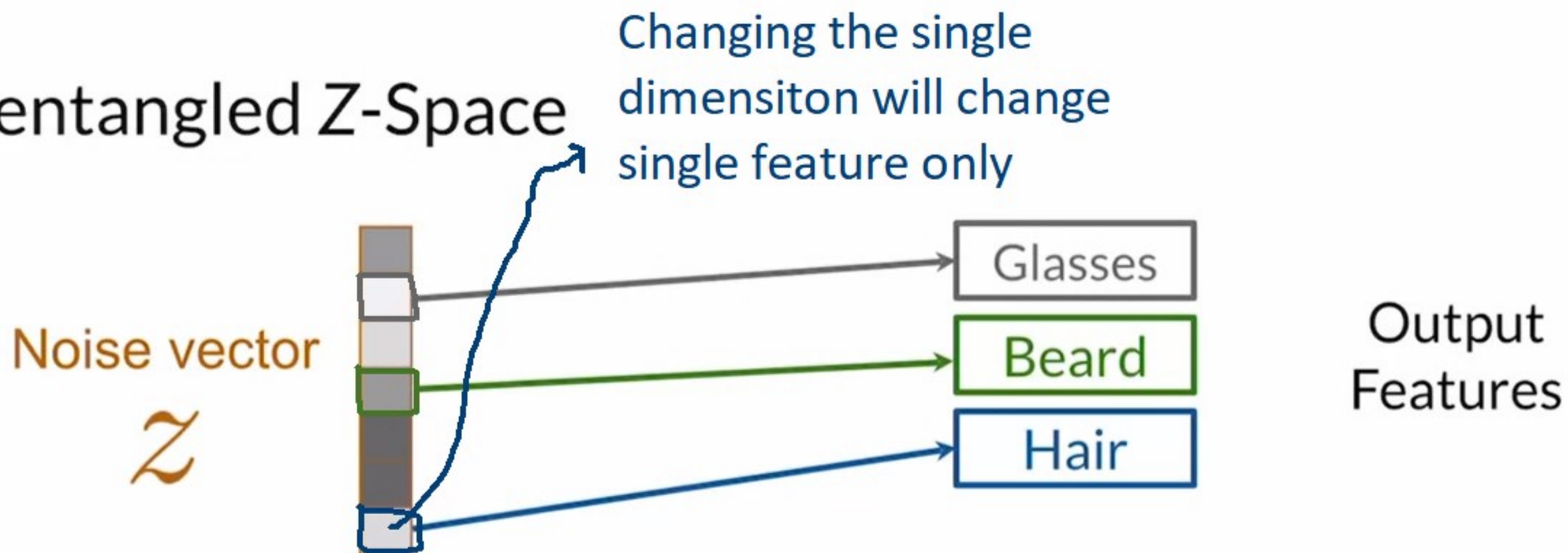
The noise vectors are of higher dimensions. For simplicity we are using 2 dimensional Z-space here.



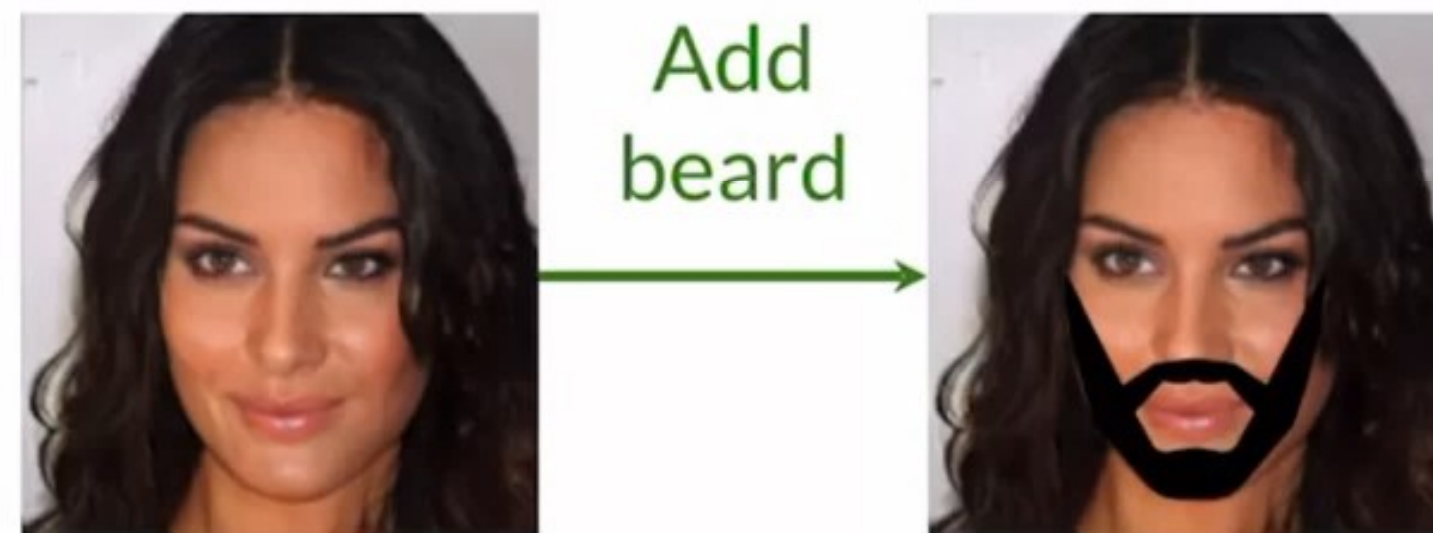
Z-Space with Noise Vectors

To control 2 features, we need a noise vector with more than 2 dimensions. Hair color and hair length are disentangled but others might not be...

# Disentangled Z-Space

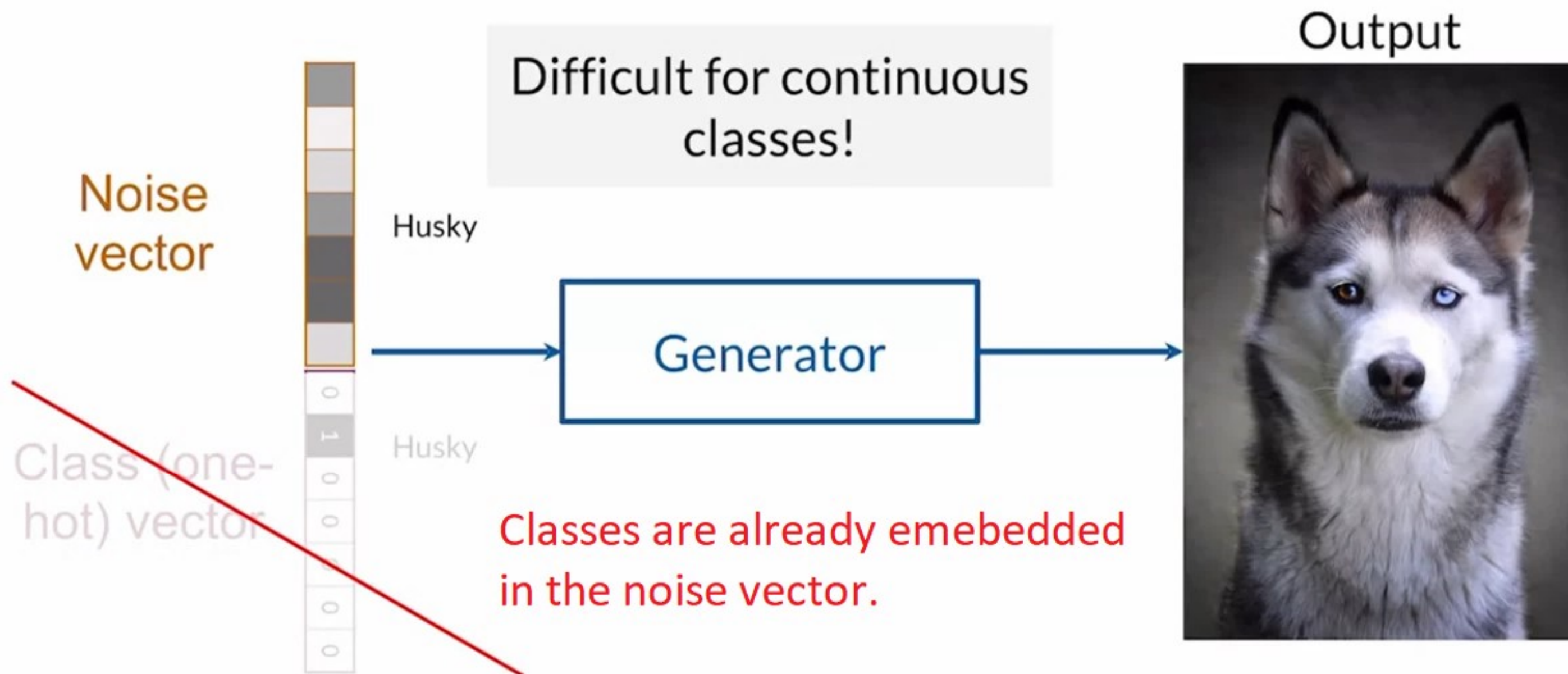


Changes to one feature don't affect the others

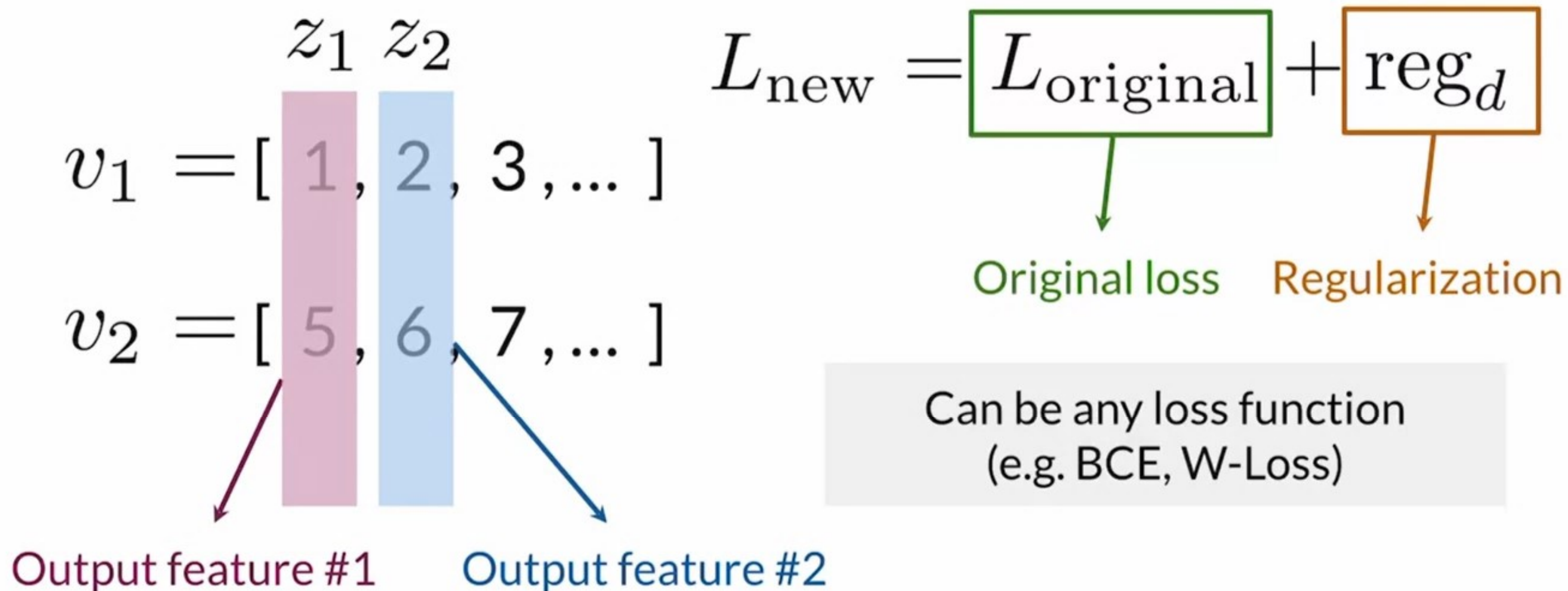




# Encourage Disentanglement: Supervision



## Encourage Disentanglement: Loss Function



# Summary

- Disentangled Z-spaces let you control individual features by corresponding  $z$  values directly to them
- There are supervised and unsupervised methods to achieve disentanglement

