```
Inst) while (log <= high)

{
mid = log wo high) /2;

ub (avor [mid] = key)

veturn trul;

else if (avor [mid] > key)

high = mid-1;

else is

low = mid+1
```

ans2) Iterative insertion sort:

return false;

```
for (int l=1; i < n; i++)

{ j=i-1;
    x = A [i];
    while (j>-1 & & A (j)>m)

{ A [j+1] = A [j];
    j--;
    3
    A [j+1] = n;
}
```

Recursive Insortion sout

Insertion sort is online sorting because whenever element come, insertion sort define its right place void insertion sort (int aut], int n)

it (n<=1)

veturn;

insurtion start (arr, n-1);

int last = arr (n-1);

i=n-2;

while (j>=0 & & arr cj]> last)

f arr [j+1] = arr [j);

g--;

arr [j+1] = last;

Ans3) Bubblesort - O(n2) Insurtion sort ___ o(n2) Selection sort - O(n2) Murge sort - o(n+logn) Quick sort - O(negn) Count sout (o an) Bucket sort - o(n) dns4) Online sorting - Insertion sort Stable sorting > Merge sort Inplace sorting > Bubble sort, Inscrtion sort, selection sout while (dow <= high) dres) Herative Binary Search: 2 int mid = (low + high) /2 if (aur [mid] == key) return true; O(logn) else if (avoilmid) 7 key) high = mid-1; else low=mid+1; Recursive Rinary Talle: while (dow <= high) 1 int mid = (eswothigh)/2 if (aur [mid] == key) Oclogn) suturn tout; else if (any [mid] 7 key) Birary search (avor, low, mid-1) Binary search (cor, mid+1, high); jutum folse;

```
Inst) T(m)=T(m/2)+T(m/2)+(

Anst) map < int, int > m;

for (int i=0; i < avr. size(); i++)

ib (m. find (target - avr. [i]) = m.end())

m [avor[i]] = 1;

else

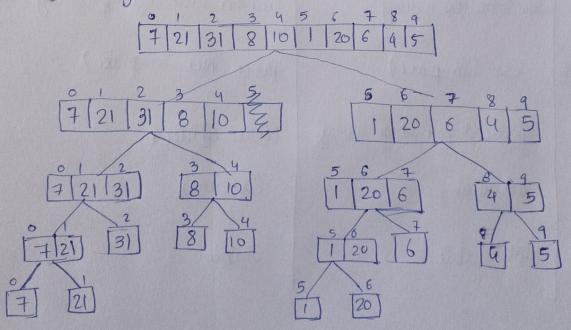
1

count < i < " " < mp[avr. ti]];

}
```

ans):) Quicksort is the fastest general purpose sout. In most practical situation, quicksort is the method of choice. If stability is best important and space is available, murgesort might be sout.

Insq) Inversion indicates — how far or close the array is from



Inversion = 3

Anslo) Worst case: The worst case occurs when the pickla pivot is always an extreme (smallest or largest) element. This happens when input away & is sorted as sewers sorted and either first or last element is picked as pivot.

Best case: Best case occurs when pivot element is the middle element as new to the middle element.

O(nlogn)

Ans II) Meuge sort: $T(n) = 2T(\frac{n}{2}) + o(n^2)$ Ouick sort: $T(n) = 2T(\frac{n}{2}) + n + 1$

Basis	Quick Sort	menge sont
• Partition	splitting is done in any	bray is parted into just 2 halves
works well on	sa smaller avray	fine on any size of array.
Addition of space	less (in-place)	More (Not in-place)
efficient	inefficient for large array	More efficient
sorting Muthual	Internal	External
· Stability	Not stable	Stable

- Ans14) We will use Morge sout because we can divide the 461B data into 4 Packets of 1 61B and sout them separately and combine them later.
- · Internal sorting: all the data to sort is stored in memory at all times while sorting is in progress.
- * External sorting: all the data is stored outside memory and only loaded into memory in small churks.