

Shubh Goel

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EDUCATION

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| • ETH Zurich [5.835/6] | 2024 - 2026 |
| <i>MSc. in Computer Science, Major: Machine Intelligence, Minor: Data Management Systems</i> | Zurich, Switzerland |
| • Indian Institute of Technology Delhi [9.154/10] | 2020 - 2024 |
| <i>B.Tech. in Electrical Engineering, Minor: Computer Science</i> | Delhi, India |
| • Mount Carmel School Dwarka [97.8 %] | 2020 |
| <i>Central Board of Secondary Education (CBSE) (Grade XII);</i> | Delhi, India |
| • Mount Carmel School Dwarka [95.4 %] | 2018 |
| <i>Central Board of Secondary Education (CBSE) (Grade X)</i> | Delhi, India |

SCHOLASTIC ACHIEVEMENTS

- **IIT Delhi Semester Merit Award:** Made it to the **top 7% (among 1200+ students)** in **6 out of 8 semesters**
- **Department Rank:** Made it to the **top 3 out of 128** students in the Electrical Engineering undergraduate program at IIT Delhi
- **Joint Entrance Exam (JEE):** Secured an All India Rank (General) of **2209** (JEE Mains) & **1323** (JEE Advanced) among 1.1 M candidates
- Awarded **CBSE Merit Certificate** in grade X for standing in the **top 0.1%** students nationally in Science
- Awarded **CBSE Merit Certificate** in grade XII for standing in the **top 0.1%** students nationally in Math, Physics, and CS
- **National Science Olympiad 2018:** Won the **silver medal** for securing a **Zonal Rank 2** and an **International Rank 27**

INTERNSHIPS

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| • JP Morgan Chase and Co., Mumbai/QR-Counterparty Credit Risk | <i>May, 2023 - Jun, 2023</i> |
| <i>IMM Back-testing Failure Analysis and Remediation</i> | |
| – Improved equity market factor back-testing failures by 40% by proposing a new outlier removal algorithm for historical vol calibration | |
| – Worked on the analysis of MtM differences between Commodity Swap/Index Swap pricing models and FO models | |
| – Automated the process of Onboarding and Off-boarding of counterparties to/from exposure back-testing portfolio | |
| • Implementation of Contour Tracing Algorithms on an FPGA board Prof. Subrat Kar | <i>Jun 2022-Nov 2023</i> |
| <i>Global Internship Program in Engineering Design and Innovation, IIT Delhi</i> | |
| – Implemented Adapted and Segmented(AnS) Pixel-Following, Vertex-Following and Run-Data-Base-Following algorithms in Verilog | |
| – Implemented a novel hardware accelerator for contour tracing in image analysis and CV using the AnS algorithms on Xilinx-7 FPGA platform | |
| – Achieved a speedup of 55x compared to existing methods, making it ideal for parallel processing arrays and mesh-connected networks | |

PUBLICATIONS

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| • MMA-Net: Multi-Modal Attention Network for 2-D Object Detection in Autonomous Driving [DOI] | <i>Sep 2024</i> |
| <i>Abhilash Gaur*, Shubh Goel*, Kanishk Goel*, Seshan Srirangarajan, Po-Hsuan Tseng, Kai-Ten Feng</i> | ICASSP 2025 |
| • A Hardware Accelerator for Contour Tracing in Real-Time Imaging [DOI] | <i>Nov 2023</i> |
| <i>Sonal Gupta, Shubh Goel, Ayush Kumar, and Subrat Kar, Senior Member, IEEE</i> | IEEE Sensors journal 2024 |

ACADEMIC SERVICE

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| • Graduate Teaching Assistant | <i>Sep 2025 - Jan 2026</i> |
| <i>263-5902-00 S: Computer Vision</i> | |
| • Undergraduate Teaching Assistant | <i>Jan 2024 - May 2024</i> |
| <i>COL100: Introduction to Computer Science</i> | |
| • Undergraduate Teaching Assistant | <i>Aug 2023 - Nov 2023</i> |
| <i>ELL101: Introduction to Electrical Engineering</i> | |

RESEARCH EXPERIENCE

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| • Safe Guaranteed Domain Exploration with Autonomous Robots | <i>Mar 2025 - Sep 2025</i> |
| <i>Prof. Andreas Krause</i> | LAS, ETH Zurich |
| – Helped in extending a theoretical safe exploration framework to real-world autonomous navigation applications in Isaac Sim | |
| – Improved robot trajectory smoothness and time taken by it to reach the goal, and implemented baselines for comparison | |
| – Built a scalable experimentation pipeline using Docker and Weights & Biases; conducted detailed timing analysis across distributed ROS 2 nodes | |
| • Evaluation of Visual Encoders on Dexterous Manipulation Tasks in Simulation [Preprint] | <i>Sep 2024 - Nov 2024</i> |
| <i>Prof. Marc Pollefeys</i> | CVG, ETH Zurich |
| – Benchmarked SOTA visual encoders (DINO, R3M, HRP, etc.) on robotic manipulation evaluation suites like Franka Kitchen, Metaworld, etc | |
| – Recorded expert demonstrations using Rokoko Smartgloves for behaviour cloning on a novel benchmark with four dexterous manipulation tasks | |
| • Multi-Modal Sensor Fusion Model for Autonomous Driving[Bachelor's Thesis] | <i>Aug 2023 - May 2024</i> |
| <i>Prof. Seshan Srirangarajan</i> | IIT Delhi |
| – Designed an attention-based cross-modal feature learning model having robustness to sensor failure, to fuse multi-modal sensor data | |
| – Utilized CARLA , an open-source simulator tailored for autonomous driving research, to create realistic urban environments | |
| – Tested the fusion model on object detection task, achieving a high Mean Average Precision of 80.09% on the generated data | |

COURSE PROJECTS

- **Table Cell Classification for Question Answering** Mar 2024
IIT Delhi
Prof. Mausam
 - Built a **Bi-LSTM** based model for predicting correct column and row for the given question and the corresponding table
 - Utilized **nltk** library for tokenization and initialized the token embeddings with pre-trained **Fasttext embeddings**
 - Achieved a high column accuracy of **89 %**, indicating the effectiveness of the developed model in correct column prediction
- **Planning in Markov Decision Process and Deep Q-Learning** Mar 2024
Prof. Rohan Paul
 - Implemented **value iteration**, **policy iteration**, and their respective variants to find an optimal policy for a given MDP
 - Implemented Q-learning using **OpenAI Gym** and **PyTorch** to learn a state-action value function for a **model-free** setting
- **Imitation Learning and Policy Gradients** Apr 2024
Prof. Rohan Paul
 - Implemented **DAGGER** and **Reinforce** to learn an optimal policy in **Hopper-v4** and **Ant-v4** environments from OpenAI Gym
 - Utilized **SAC algorithm** with **Hindsight Experience Replay** to train a goal-conditioned policy for the **PandaPush-v3** environment
- **Rollerball: A Chess variant** Nov 2023
Prof. Mausam
 - Engineered a Rollerball playing AI agent using **minimax** algorithm with **alpha-beta** pruning and early cut-off
 - Improved the agent's performance using **quiescence search**, **heatmaps**, **transposition tables** and **opening book**
- **Graph Neural Networks** Nov 2023
Prof. Sayan Ranu
 - Designed a **GIN** based architecture using **Pytorch Geometric** to predict whether a molecule inhibits HIV virus replication or not
 - Achieved a high ROC-AUC of **0.76** on the test data by introducing skip connections, dropout layers and weight decay

TECHNICAL SKILLS

Programming Languages(Proficiency Level)	JAVA/C/C++/Python(Advanced), MATLAB(Basic)
Software/Libraries/Frameworks	IsaacSim, ROS 2, Pandas, Numpy, Scikit-Learn, TensorFlow, PyTorch, Gensim, NLTK, HuggingFace, OpenAI Gym, Vivado, L<small>A</small>T<small>E</small>X

KEY COURSES TAKEN

Computer Science	Data Structure & Algorithms, Discrete Math, Analysis & Design of Algorithms, Computer Architecture, Machine Intelligence & Learning, Data Mining, Principles of Autonomous Systems, NLP, Deep Learning, Probabilistic AI, Computer Vision, Advanced OS, Foundations of Reinforcement Learning, Design of Parallel and High-Performance Computing (Ongoing)
Mathematics and Statistics	Probability & Stochastic Processes, Linear Algebra & Differential Equations, Calculus

POSITIONS OF RESPONSIBILITY

- **Core Team Member** March 2021 - May 2024
Algorithms and Coding Club(ANCC) IIT Delhi
 - Assisted my team in launching the **Summer of Competitive Programming(SoCP)** program for the first time in July 2021
 - Led my team to **organize inter-college tournament**, a Competitive Programming knock out tournament **for the first time** in Tryst'23
 - Worked with my team in planning and organizing activities that helped the club to attain official status in 2023