

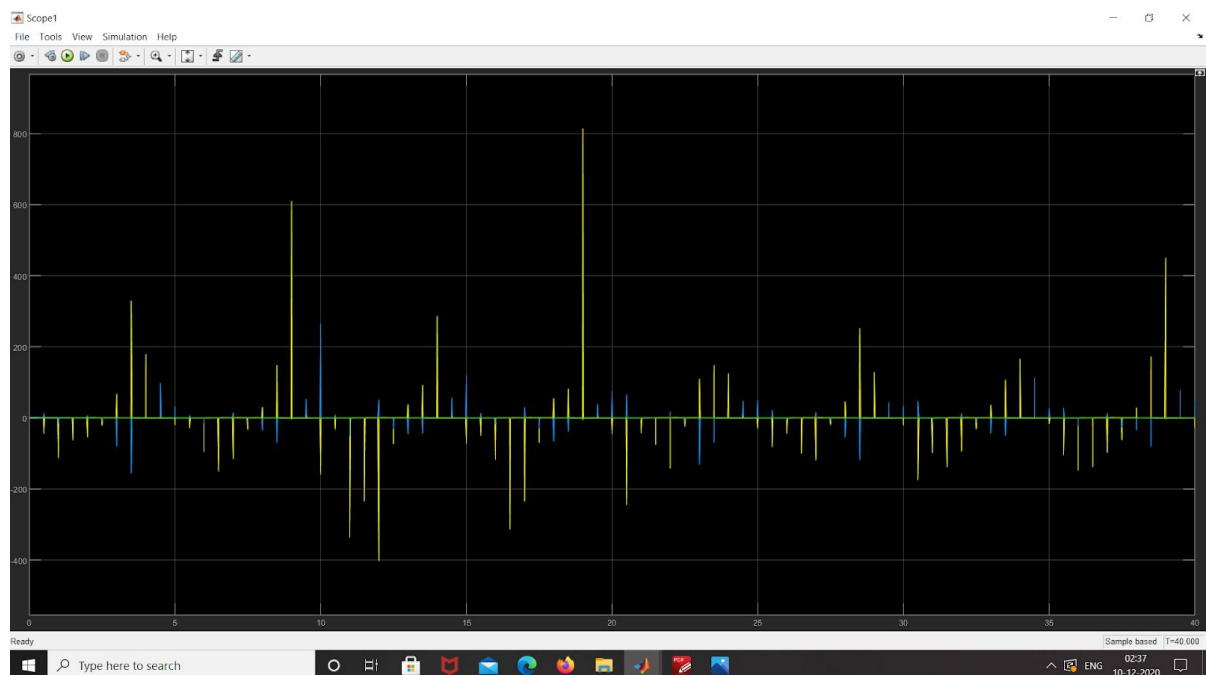
ROBOTICS

Graphs

1) t_{ou} vs t



2) \dot{e} vs t

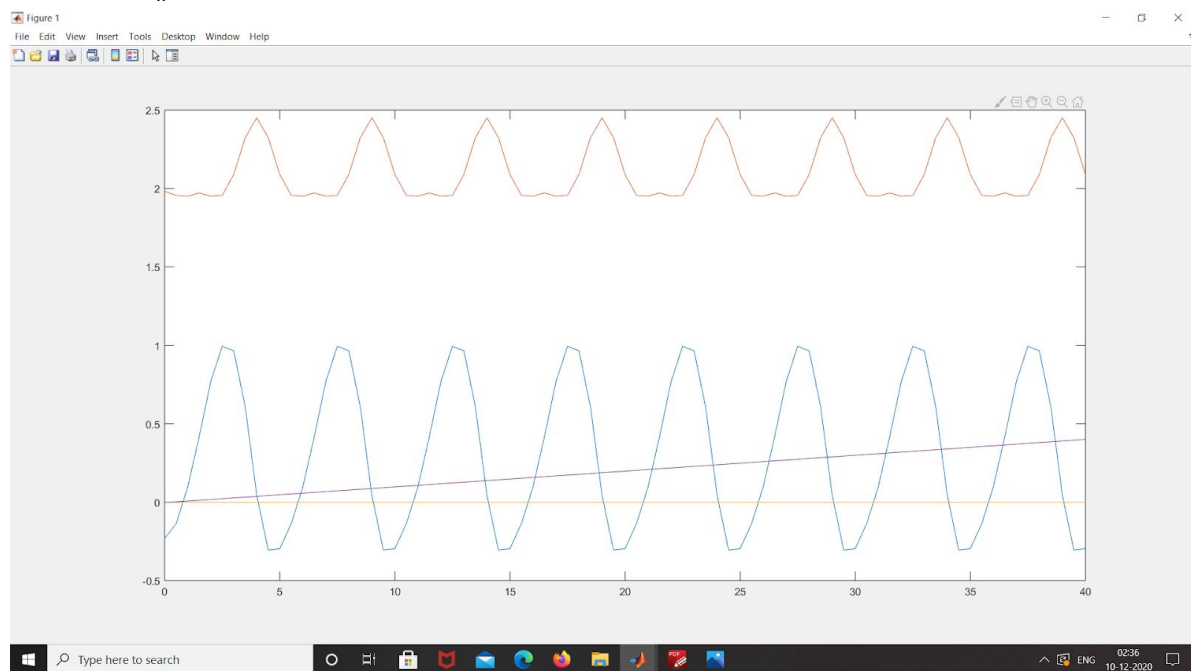


3) e vs t

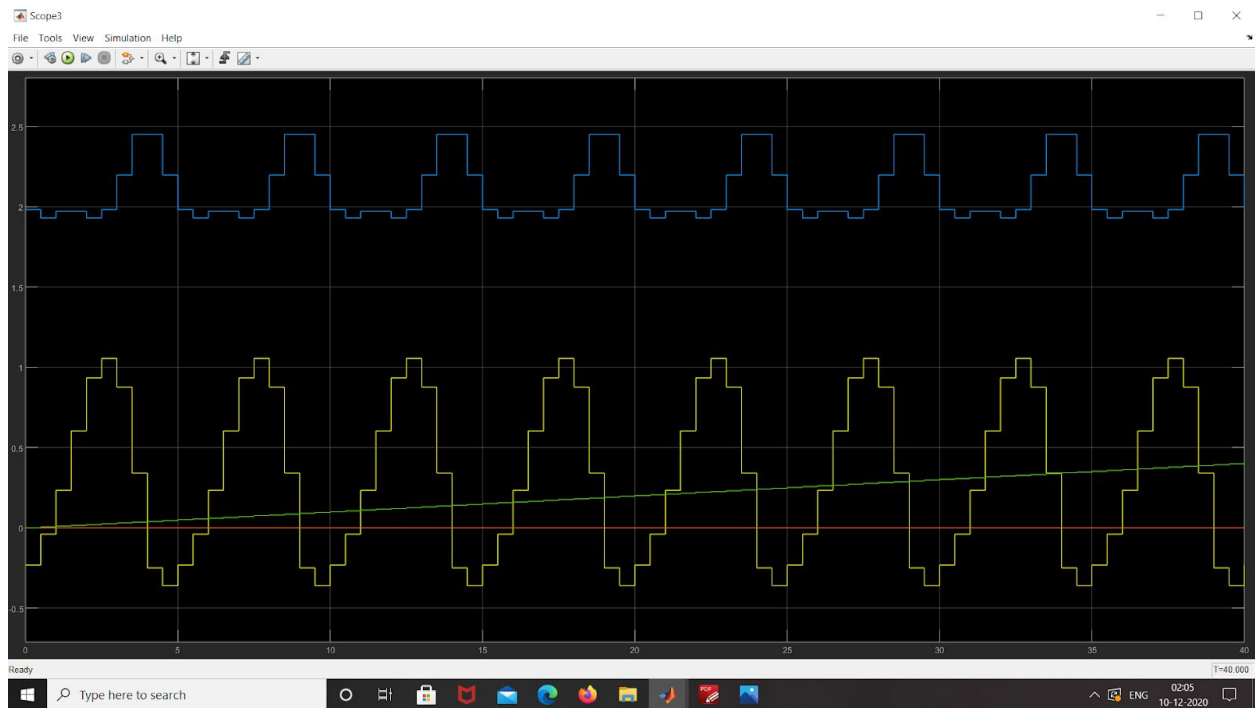


4) qd vs t

I used matlab command:
`smoothdata()`



Without smooth:



5) x y z

