

CS 663
Assignment 5
Qs 5 - Report

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Verifying the results

The spike for the Image J restoration plot occurs at (31, 231). This is interpreted as (31, -71) by applying a wrap-around on the image of size 300 * 300 for translation. The initial translation applied was (-30, 70).

Hence this new translation will restore Image I from Image J

Similarly, in case of noisy images, we see a spike at (31, 231). This again is interpreted as (31, -71) by applying a wrap-around on the image of size 300 * 300 for translation. But since the original images were noisy, the spike is not clear but surrounded by other non-zero frequencies.

The logarithm plots of the Fourier magnitudes is a constant of value $=\log(2)$ because the result of the cross-power spectrum is a complex number of unit magnitude always.

Analysis of time complexities

For an Image of size $N * N$, this method involves first step, the calculation of Fourier transforms using FFT [time complexity of each being of $O(N \log(N))$] followed by a conjugation [$O(N)$] & vectorized pointwise multiplication & division [$O(1)$]. Thus, the overall time complexity is **$O(N \log N)$** .

If we use pixel-wise image comparison for an $N * N$ image, the time complexity of predicting the translation would be $O(N^2)$.

Rotation Correction mentioned in the paper

If $f_2(x,y)$ is a rotated version of $f_1(x, y)$ [with a rotation of θ], doing a Fourier Transform in the cartesian coordinates would yield

$$F_2(u, v) = F_1(u \cos(\theta) + v \sin(\theta), -u \sin(\theta) + v \cos(\theta)).$$

The magnitudes for both are same. So, we can use the same concept of cross-power spectrum as before by converting the rotation by θ into a translation. In the polar

coordinates, the rotation would become a translation. So we convert the images into polar coordinates & take their Fourier Transform.

$$f_2(r, \theta) = f_1(r, \theta - \theta_0)$$
$$F_2(m, n) = \exp(-2 \pi j(n \cdot \theta_0)) * F_1(m, n)$$

Thus, cross-power spectrum of $F_1(m, n)$ & $F_2(m, n)$ would yield $\exp(2 \pi j(n \cdot \theta_0))$, using which we can calculate the rotation.

Any translation in x & y would lead to a change in r by r_0 , such that the cross power spectrum would yield $\exp(2 \pi j(m \cdot r_0 + n \cdot \theta_0))$. Hence, displacement & rotation can be figured out. The exact (x, y) translations can be figured out using the original cross-power spectrum in the cartesian coordinates.

* All the Images and plots are included in the MATLAB publish myMainScript.html file