





oneERNI
Global Hackathon
September 22-25 2023

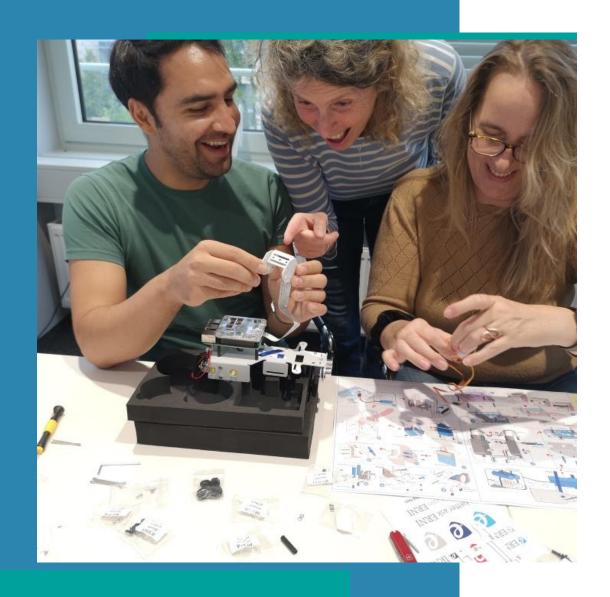




Happy when we finished creating and assembling all the parts, ...

... but that's when the real work began – late afternoon 22.09.





Challenge accepted – to earn the most points in:

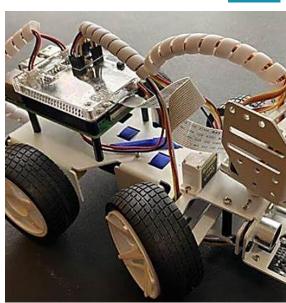






Our Vison: build a self-driving PiCar

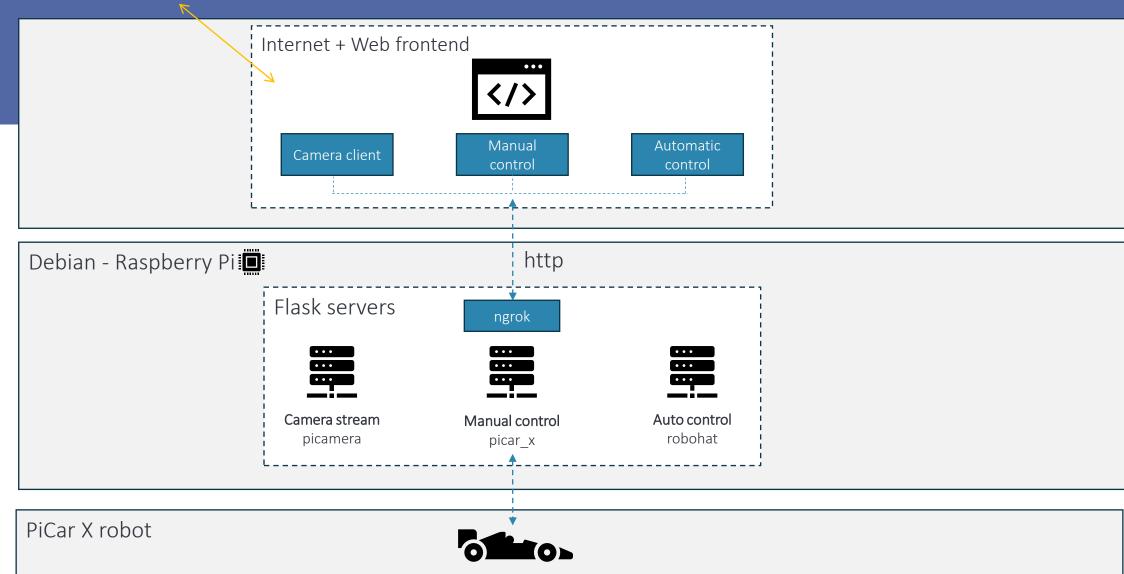








Architecture



Our Approaches to solve the challenge

- ☐ Do a line follower
- ☐ Do a camera-based navigation

Our Proposed Solution?

- ☐ We control the robot with the controller dashboard
- ☐ We write the values in a log file
- ☐ We program a script to parse those log files and create an algorithm to repeat the track in log file

Results from these two approaches

| Approach | Difficulty level | Time to complete |
|-------------------------|------------------|-------------------|
| Camera based navigation | Medium | 1 min, 10 seconds |
| Line Follower | Easy | 1 min 20 seconds |

Some Insights

```
list of commands , steer angle = -45 to - 48 degree with respect to gate 1
['FORWARD', 200, 4, 0],

['RIGHT', 200, 9, 1.638500576],

['RIGHT', 200, 14, 2.0725836753845215],

['RIGHT', 200, 19, 2.350529909133911],

['FORWARD', 200, 4, 3.5228655338287354],
```

| Approach | Difficulty level | Time to complete |
|------------------------|------------------|------------------|
| Memorization Technique | Extreme | 17.35 seconds |
| | | |

Make it Lightweight, remove IR, Ultrasonic sensors etc

Some Insights

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```

| Approach | Difficulty level | Time to complete |
|------------------------|------------------|------------------|
| Memorization Technique | Extreme | 16.55 seconds |
| | | |

Make it Lightweight, remove IR, Ultrasonic sensors etc

Results from the late afternoon 23.09.2023:

Autonomous run ("level 1")

- First steps along the line
- The little car had a lot to learn

Video Link is in video_link.txt file in repo root folder

Autonomous run ("level 5")

- Fastest run: 17:35 seconds
- Based on data collected during manual runs it is the foundation for our fastest autonomous run

Learnings:

- ✓ We can get really hungry during late nights too
- ✓ The office main entrance locks after 8pm , so use keys and backdoor entrance
- ✓ Collecting used bottles can be useful to create gates for Hackathons