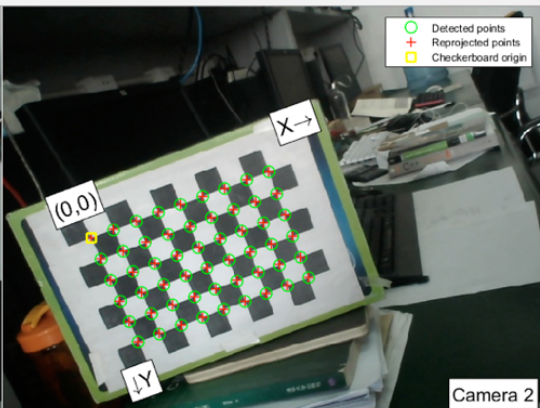


Show Rectified

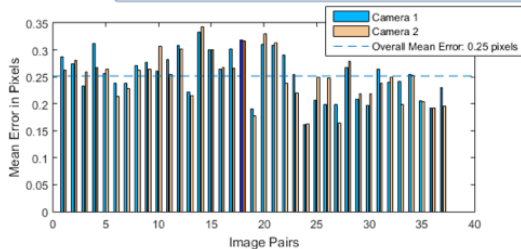
Camera 1



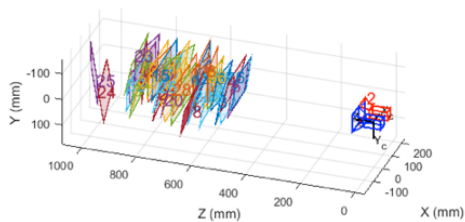
- Detected points
- + Reprojected points
- Checkerboard origin

Camera 2

Reprojection Errors



Extrinsics



Show pattern-centric view