

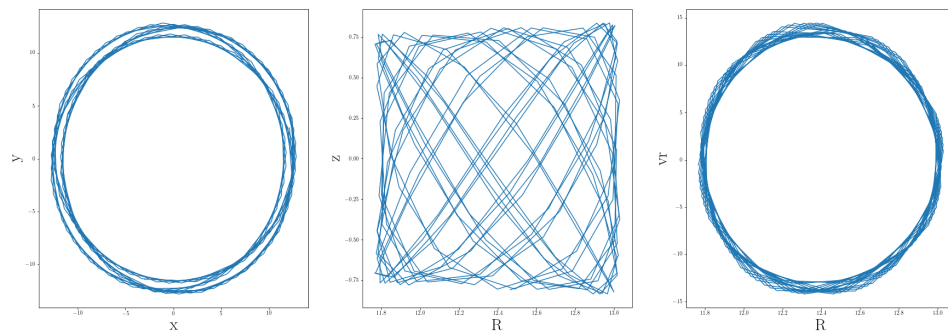
3D simulation using Quasiisothermal distribution function

initilize qusiisothermal df, sample 500,000 particles, and use their postions and velcoity as the initial condition, integrate over 10Gyr

```
df = agama.DistributionFunction(type='QuasiIsothermal',Sigma0=1e3,Rdisk=3.7,
                                Hdisk=0.8,Sigmar0=50,Rsigmar=7.4,potential=pot)
```

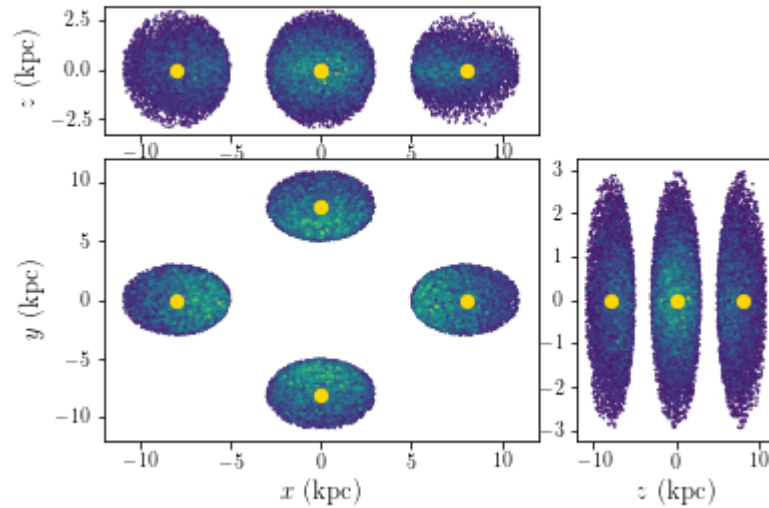
What scales of Hdsik, Simgar0 (radial velocity dispersion), Rsigmar (radial scale) are good?

- Rdisk = scale length of the disk, why set Rdisk = 3.7
- Sigmar0 and Rsigmar controls the dispersion profile: exponetal with central value sigmar0 and radial scale Rsigmar. ??? Suggested Rsigmar ~ 2Rdisk
Here is an example of the orbit over 10Gyr. They look like thos plots in galpy documnetation for orbit integration



integrate over 10Gyr wit Agama, then transfer velcoity to Galactocentric coordinate, find pm and vlos

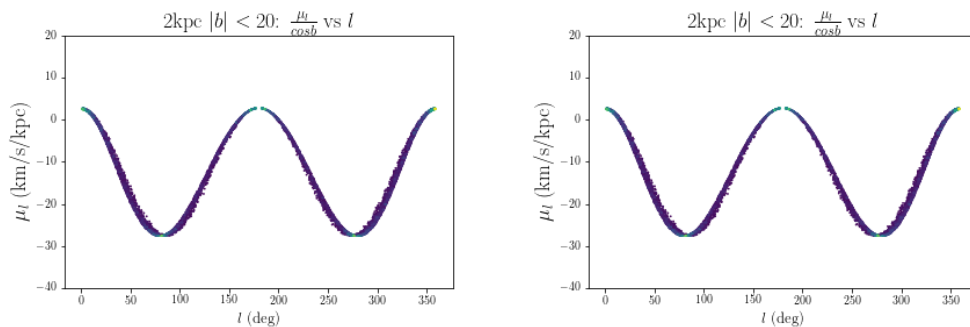
Agama returns $[x, y, z, vx, vy, vz]$. I used `bovy_coords` in `galpy` to make coordinate transformatio. Then define Orbit objects using (r, vR, vT, z, vz, Φ) where I have set vR to 0, and find pm and vlos fro its attributes. To increase the number of effective test particl within the range of appropriate Taylor approximation, I created 4 imaginary suns. The position and velcoity $[x, y, z, vx, vy, vz]$ of each is:
 $[8, 0, 0, 0, 220, 0]$, $[0, 8, 0, 0, -220, 0]$, $[-8, 0, 0, 0, -220, 0]$, $[0, -8, 0, 220, 0, 0]$ (The sun rotates in counter clockwise direction sinc the Galacto-centric coordinate is right-handed)
 Here shows the test particles falls within 4kpc from the Sun ($\sim 55,000$) // $[<2pc, \sim 18,000]$



Now we are ready to look at how d range and b range affects the functions of $\Delta_{\mu_l}, \Delta_{\mu_b}, \Delta_{v_{los}}$ vs l . The dispersions in μ_b and v_{los} are much smaller than μ_l . The dispersion in μ_b is so big that the expected double peak pattern is barely visible after taking binned median.

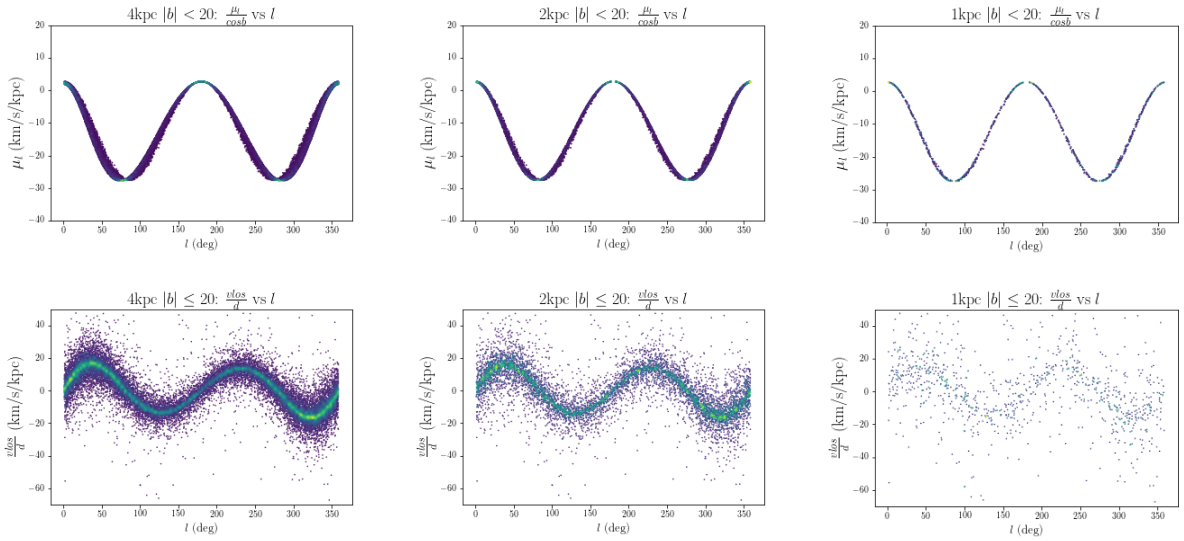
μ_l gives the most consistent double sin functions. As d goes down from 4 kpc to 1 kpc, the points on the scatter plot fall down to a narrower line. This implies we get smaller deviations from the model predicted by the Oort constants in the region closer to the Sun. I would not choose to restrict d to 1 kpc because of the costs of simulations programming. On the other hand, this simulation does not show significant effect of b compared to d on the results. I think the effect of d is expected because of the limit of Taylor approximation. Compared to Gaia data, which Li and Bovy both restrict to $|b| < 20$, in this simulation (under a relatively ideal set-up of the MW disk), dividing $\cos b$ is enough.

dividing $\cos b$ vs not:



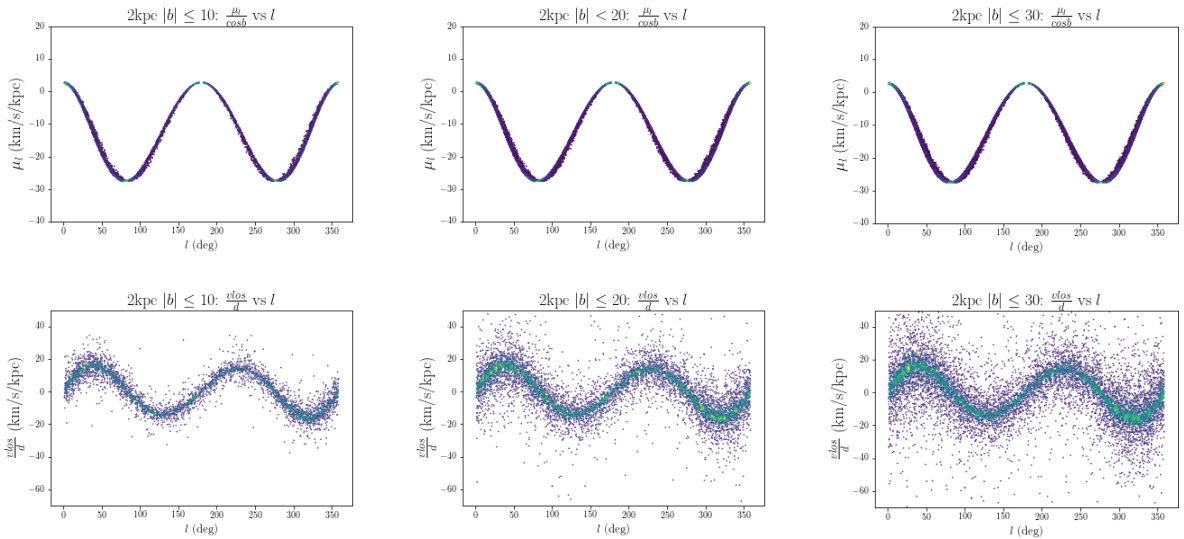
Varying d range

$d < 4kpc, |b| < 20$ V.S. $d < 2kpc, |b| < 20$ V.S. $d < 1kpc, |b| < 20$ (# of test particles: 25560->7818->989)



Varying b range at 2kpc

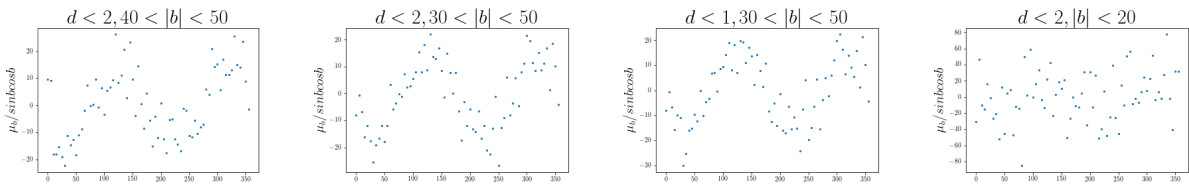
$d < 2kpc, |b| < 20$ vs $d < 2kpc, |b| < 30$ vs $d < 1kpc, |b| < 40$



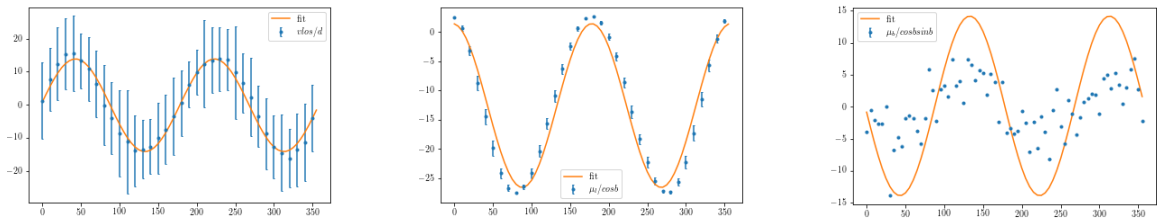
As to v_{los} , from the plots above, visually, the effect of b range is more significant than d . For the three plots with varying d cut-off, the spread of scatter points around the central double sinusoidal function seems to stay roughly the same. On the contrary, this spread around the central line is smallest for $|b| < 10$, and larger as for wider b range I would expect that, from $v_{los} = d(A \sin 2l + C \cos 2l + K)$, the d would have a larger influence than b . However, the results above imply dividing v_{los} by d will eliminate the effect of d , but the effect of b is implicit in the equation of v_{los} . Is there any explanation for this?

on μ_b :

Number of test particles fall under each criteria: 2pc&|b|~40-50:3326; 2pc&|b|~30-50:8019; 1pc&|b|~30-50:6216; 2pc&|b|<20:7818



I should be using uncertainty as a measure of which range is good. After taking away outliers, I used binned median vs l and MCMC to find their uncertainties for comparison. However, I am unsure about if the likelihood function in MCMC should include all three quantities or do each one individually? Visually, I think μ_l and v_{los} are good within 2kpc and $|b| < 20$, and for μ_b , $d < 2kpc$ and $30 \leq |b| \leq 50$ seems the best one among the four examples above.



(I corrected the rightmost panel after our meeting)

$$A = 13.98 \pm 1.32, B = -12.59 \pm 1.27, C = 0.99 \pm 1.30, K = -0.14 \pm 1.75$$

What we have learned from this simulation?

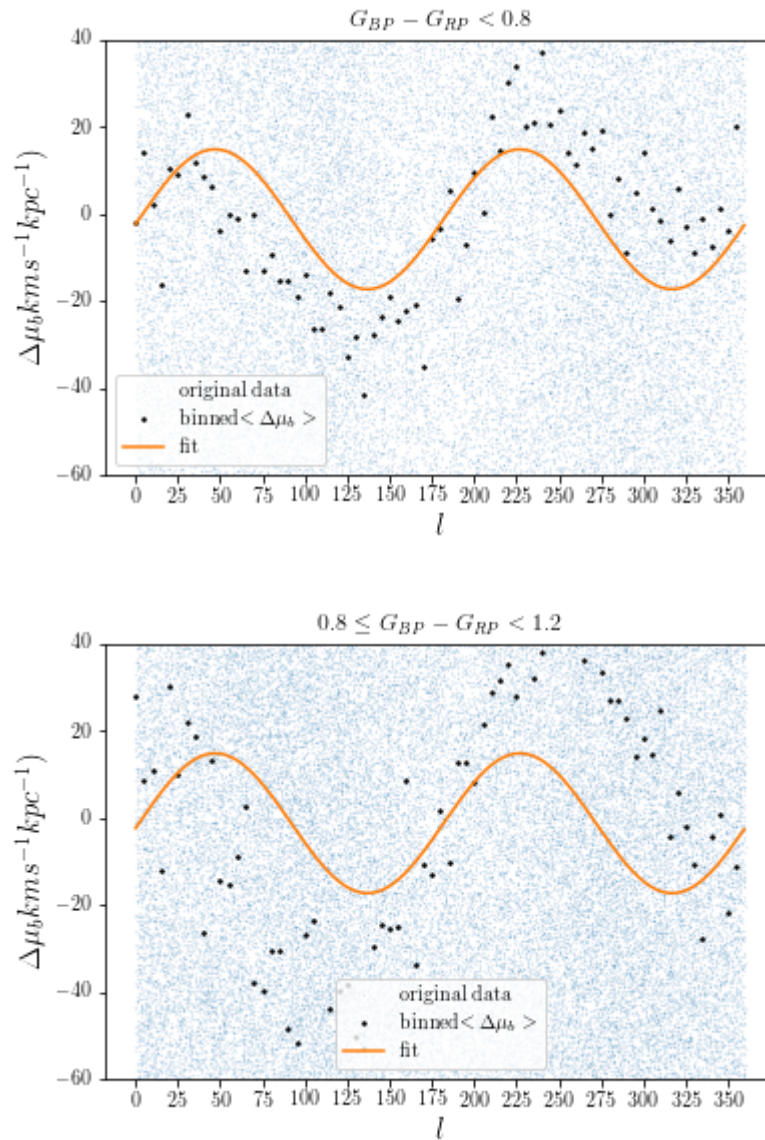
μ_l : we can choose 2kpc cut-off. $|b|$ range has lesser effect than d . v_{los} : we can choose 2kpc cut-off. d range has lesser effect than $|b|$. (I will need to set $\sigma_0 = 15$ (or smaller) and re-run the program)

DR2 correction

Last week, I first found A, B, C, K and u_0, v_0, w_0 by MLE estimation on the value of v_{los} and μ_l before correction. Then I tried to determine A, C, K, u_0, v_0, w_0 from μ_b with same method, but the binned median of μ_b before peculiar motion correction did not yield the predicted sinusoidal dependency.

The week, I used the u_0, v_0, w_0 estimated from μ_l and v_{los} to correct μ_b :

$$\Delta_{\mu_l} = \frac{1}{\sin b \cos b} (\mu_b - \varpi[(u_0 \cos l + v_0 \sin l) \sin b - w_0 \cos b])$$
 It seems Δ_{μ_l} do not provide good data to fit Oort constants.



I am planning to take MCMC on μ_l and v_{los} together to find A,B,C,K,u0,v0,w0 and their uncertainties, then, with the value of u0,v0,w0 aforesaid, correct $\Delta\mu_l$, $\Delta\mu_b$ and Δv_{los} , and finally use MCMC on the three corrected pm and vlos to find the uncertainty in A,B,C and K

What I need to fix is error propagation from using the partial derivative rules to find the error in μ_l , μ_b and l and b . I calculated the partial derivative wrong because I forgot about the errors in declination and ascension angle. So the actual error propagation equation is much longer than the one I used. I also would have to do the same for $\Delta\mu_l$, $\Delta\mu_b$ and Δv_{los} . Is there any easy way to calculate these errors?

$$\mu_l = \frac{1}{\cos b} (C_1 \mu_\alpha + C_2 \mu_\delta),$$

$$\mu_b = \frac{1}{\cos b} (-C_2 \mu_\alpha + C_1 \mu_\delta)$$

$$\sigma_{\mu_l}^2 = \sigma_b^2 \left(\frac{\partial \mu_l}{\partial b} \right)^2 + \sigma_\alpha^2 \left(\frac{\partial \mu_l}{\partial \alpha} \right)^2 + \sigma_\delta^2 \left(\frac{\partial \mu_l}{\partial \delta} \right)^2 + \sigma_{\mu_\alpha}^2 \left(\frac{\partial \mu_l}{\partial \mu_\alpha} \right)^2 + \sigma_{\mu_\delta}^2 \left(\frac{\partial \mu_l}{\partial \mu_\delta} \right)^2$$

where

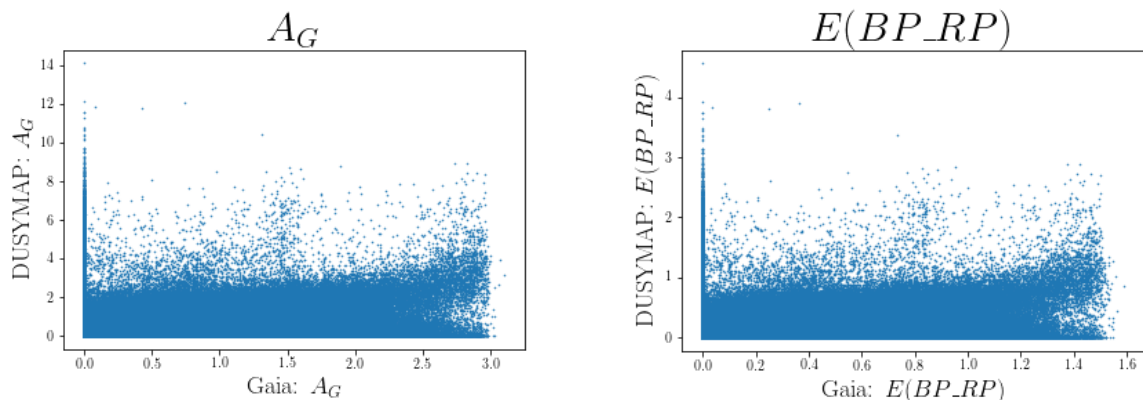
$$C_1 = \sin \delta_G \cos \delta - \cos \delta_G \sin \delta \cos(\alpha - \alpha_G),$$

$$C_2 = \cos \delta_G \sin(\alpha - \alpha_G)$$

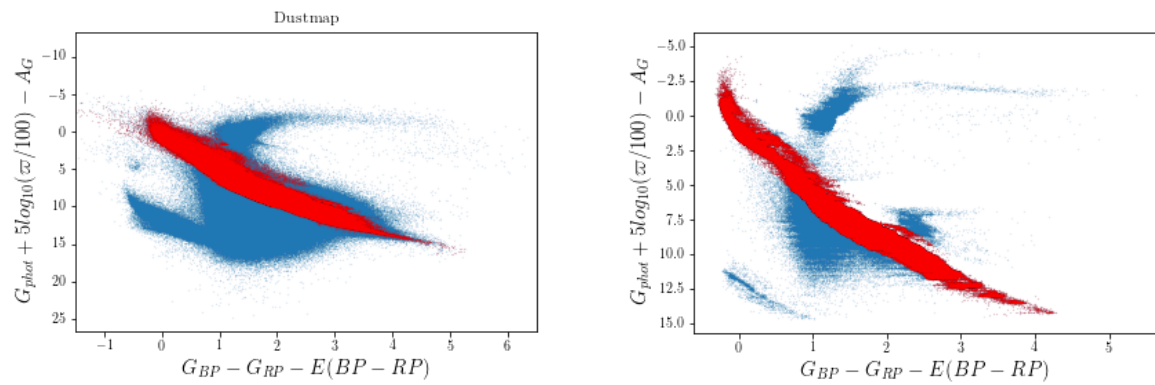
$$\cos b = \sqrt{C_1^2 + C_2^2} \text{ and } \alpha_G = 192^\circ.86, \delta_G = 27^\circ.13.$$

Dustmap

Dustmap takes a coordinate as input and gives the extinction at that point. We use Dustmap because we need correct color excess and extinction to divid EDR3 samples to different color groups. I am just using DR2 because we have observational data of $E(BP-RP)$ and A_G in DR2, and we can compare it with the result from Dustmap so I know if Dustmap achieve desired functions. Here I plotted the extinction and color excess from Gaia on the x-axis, and the corresponding value from Dustmap on the y-axis. For both color excess and extinction, Dustmap have exteremely high values compared when the actual Gaia value around 0. The ranges of extinction and color excess value from Dustamp are larger. (For all the NaN entries I filled in with 0)



Because both A_G and $E(BP_RP)$ from Dustmap can take largers value, we see that on the H-R diagram below, $G_{BP}-G_{RP}-E(BP_RP)$ and $G+5\log_{10}(\varpi/100)-A_G$ cover different ranges. If I use Dustmap for color and extinction correction, I can't divid Gaia's main sequence star samples to different color subgroups using the criteria of Li.



2D histogram comparison: Again, the ranges of A_G and $E(BP - RP)$ are larger for result calculated from Dustmap. We see a higher density at (0,0) because I made all NaN entries to 0

