

1 Energy-based Model

Definition 1. *[Energy-based Model]*

Let \mathcal{M} a measure space, and $E: \mathbb{R}^m \rightarrow (\mathcal{M} \rightarrow \mathbb{R})$. Then define probabilistic model based on E as

$$p(x; \theta) = \frac{\exp(-E(x; \theta))}{\int_{\mathcal{M}} dx' \exp(-E(x'; \theta))},$$

where $\theta \in \mathbb{R}^m$ and $x \in \mathcal{M}$.

We call this an energy-based model, where $E(\cdot; \theta)$ is called a energy function parameterized by θ .

Theorem 2. *[Universality]*

For any probability density $q: \mathcal{M} \rightarrow \mathbb{R}$ and for $\forall C \in \mathbb{R}$, define, for $\forall x \in \text{supp}(q)$,

$$E_q(x) := -\ln q(x) + C,$$

then, for $\forall x \in \text{supp}(q)$,

$$q(x) = \frac{\exp(-E_q(x))}{\int_{\text{supp}(q)} dx' \exp(-E_q(x'))}.$$

That is, for any probability density, there exists an energy function (up to constant) that can describe the probability density.

Theorem 3. *[Activity Rule]*

The local maximum of $p(\cdot; \theta)$ is the local minimum of $E(\cdot; \theta)$, and vice versa.

Theorem 4. *[Learning Rule]*

For any probability density $p_D: \mathcal{M} \rightarrow \mathbb{R}$, define Lagrangian $L(\theta; p_D) := -\int_{\mathcal{M}} dx p_D(x) \ln p(x; \theta)$. Then, the gradient of Lagrangian w.r.t. component θ^α is

$$\frac{\partial L}{\partial \theta^\alpha}(\theta; p_D) = \int_{\mathcal{M}} dx p_D(x) \frac{\partial E}{\partial \theta^\alpha}(x; \theta) - \int_{\mathcal{M}} dx p(x; \theta) \frac{\partial E}{\partial \theta^\alpha}(x; \theta),$$

or in more compact format,

$$\frac{\partial L}{\partial \theta^\alpha}(\theta; p_D) = \mathbb{E}_{x \sim p_D} \left[\frac{\partial E}{\partial \theta^\alpha}(x; \theta) \right] - \mathbb{E}_{x \sim p(x; \theta)} \left[\frac{\partial E}{\partial \theta^\alpha}(x; \theta) \right].$$

2 Effective Theory

Definition 5. *[Effective Energy]*

Suppose exists $(\mathcal{V}, \mathcal{H})$, s.t. $\mathcal{M} = \mathcal{V} \oplus \mathcal{H}$. Re-denote $E(x; \theta) \rightarrow E(v, h; \theta)$ and $p(x; \theta) \rightarrow p(v, h; \theta)$. Then, define effective energy $E_{\text{eff}}: \mathcal{V} \rightarrow \mathbb{R}$ as

$$E_{\text{eff}}(v; \theta) := -\ln \int_{\mathcal{H}} dh \exp(-E(v, h; \theta)).$$

Theorem 6. *[Effective Theory]*

Recall that $p(v; \theta) := \int_{\mathcal{H}} dh p(v, h; \theta)$. Then,

$$p(v; \theta) = \frac{\exp(-E_{\text{eff}}(v; \theta))}{\int_{\mathcal{V}} dv' \exp(-E_{\text{eff}}(v'; \theta))}.$$

Lemma 7. *[Gradient of Effective Energy]*

$$\frac{\partial E_{\text{eff}}}{\partial \theta^\alpha}(v, \theta) = \int_{\mathcal{H}} dh p(h|v; \theta) \frac{\partial E}{\partial \theta^\alpha}(v, h; \theta).$$

Theorem 8. *[Learning Rule of Effective Theory]*

For any probability density $p_D: \mathcal{V} \rightarrow \mathbb{R}$, define Lagrangian $L(\theta; p_D) := -\int_{\mathcal{V}} dv p_D(v) \ln p(v; \theta)$. Then, the gradient of Lagrangian w.r.t. component θ^α is

$$\frac{\partial L}{\partial \theta^\alpha}(\theta; p_D) = \int_{\mathcal{V}} dv \int_{\mathcal{H}} dh p_D(v) p(h|v; \theta) \frac{\partial E}{\partial \theta^\alpha}(v, h; \theta) - \int_{\mathcal{V}} dv \int_{\mathcal{H}} dh p(v, h; \theta) \frac{\partial E}{\partial \theta^\alpha}(v, h; \theta),$$

or in more compact format,

$$\frac{\partial L}{\partial \theta^\alpha}(\theta; p_D) = \mathbb{E}_{v \sim p_D, h \sim p(h|v; \theta)} \left[\frac{\partial E}{\partial \theta^\alpha}(v, h; \theta) \right] - \mathbb{E}_{v, h \sim p(v, h; \theta)} \left[\frac{\partial E}{\partial \theta^\alpha}(v, h; \theta) \right].$$

3 Examples

Example 9. [Boltzmann Machine]

- Let $\mathcal{M} = \{0, 1\}^n$, $W \in \mathbb{R}^{(n \times n)}$, $b \in \mathbb{R}^n$, $\theta := (W, b)$. Then a Boltzmann machine is defined by energy function

$$E(x; W, b) := -(1/2) \sum_{\alpha, \beta \neq \alpha} W_{\alpha\beta} x^\alpha x^\beta - \sum_{\alpha} b_{\alpha} x^\alpha.$$

- Direct calculation gives

$$p(x_\alpha = 1 | x_{\setminus \alpha}) = \sigma \left(\sum_{\beta \neq \alpha} W_{\alpha\beta} x^\beta + b_\alpha \right).$$

Example 10. [Restricted Boltzmann Machine]

- Let $\mathcal{V} = \{0, 1\}^n$ and $\mathcal{H} = \{0, 1\}^m$. Let $W \in \mathbb{R}^{(n \times m)}$, $b \in \mathbb{R}^n$, $c \in \mathbb{R}^m$, $\theta := (W, b, c)$. Then a restricted Boltzmann machine is defined by energy function

$$E(v, h; W, b, c) := -(1/2) \sum_{\alpha, \beta \neq \alpha} W_{\alpha\beta} v^\alpha h^\beta - \sum_{\alpha} b_{\alpha} v^\alpha - \sum_{\alpha} c_{\alpha} h^\alpha.$$

- Direct calculation gives

$$E_{\text{eff}}(v; W, b, c) = -\sum_{\alpha} b_{\alpha} v^\alpha - \sum_{\beta} s_+ \left(\sum_{\alpha} W_{\alpha\beta} v^\alpha + c_{\beta} \right),$$

where s_+ represents soft-plus function.