

Chapter 1

Stochastics

1.1 Ordinary Differential Equation

Let \mathcal{M} a smooth manifold, and $f: \mathbb{R} \rightarrow \mathcal{M} \rightarrow T\mathcal{M}$ ^{1.1}, we have ordinary differential equation^{1.2}

$$\frac{dx^a}{dt}(t) = f^a(t, x). \quad (1.1)$$

This ordinary differential equation induces a push-forward operator, $\hat{T}_{t \rightarrow t'}: \mathbb{R} \rightarrow \mathbb{R} \rightarrow \mathcal{M} \rightarrow \mathcal{M}$, which pushes the particle on position on \mathcal{M} at time t to another position on \mathcal{M} at time t' .

Let $\Omega^k(\mathcal{M})$ the space of k -forms on \mathcal{M} , where $k \leq \dim(\mathcal{M})$. This ordinary differential equation also induces a pull-back operator on k -forms^{1.3}, $\hat{T}_{t \rightarrow t'}^*: \mathbb{R} \rightarrow \mathbb{R} \rightarrow \Omega^k(\mathcal{M}) \rightarrow \Omega^k(\mathcal{M})$, which describes the transition of k -form from time t to t' .

Precisely, consider $\forall \psi^{(k)} \in \Omega^k(\mathcal{M})$, we can write it explicitly by indices, as

$$\psi^{(k)}(x) = (1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x) dx^{\alpha_1} \wedge \dots \wedge dx^{\alpha_k}, \quad (1.2)$$

where the indices in $\psi_{\alpha_1 \dots \alpha_k}^{(k)}(x)$ is anti-symmetric. Regardless of the $1/k!$ factor, the $\psi_{\alpha_1 \dots \alpha_k}^{(k)}(x)$ can be viewed as the local density at x and the $dx^{\alpha_1} \wedge \dots \wedge dx^{\alpha_k}$ as area or volume unit. Thus, $\psi^{(k)}(x)$, as a whole, is the mass unit. \hat{T}^* is thus is a forward pushing transition of mass unit.

Lemma 1.1. *Explicitly, we have*

$$(\hat{T}_{t \rightarrow t'}^* \psi^{(k)})(x') = (1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(\hat{T}_{t' \rightarrow t} x') \bigwedge_{i=1}^k (\mathcal{D}\hat{T}_{t' \rightarrow t})_{\beta_i}^{\alpha_i}(x') dx'^{\beta_i}, \quad (1.3)$$

where $\mathcal{D}\hat{T}_{t' \rightarrow t}$ denotes the Jacobian of $\hat{T}_{t' \rightarrow t}$.

Proof. Let $x' = \hat{T}_{t \rightarrow t'} x$ and $\psi'^{(k)} = \hat{T}_{t \rightarrow t'}^* \psi^{(k)}$, by conservation of mass during the pushing, we have

$$\psi'^{(k)}_{\alpha_1 \dots \alpha_k}(x') dx'^{\alpha_1} \wedge \dots \wedge dx'^{\alpha_k} = \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x) dx^{\alpha_1} \wedge \dots \wedge dx^{\alpha_k}.$$

Replace x by $x = \hat{T}_{t' \rightarrow t} x'$, we get

$$\psi'^{(k)}_{\alpha_1 \dots \alpha_k}(x') dx'^{\alpha_1} \wedge \dots \wedge dx'^{\alpha_k} = \psi_{\alpha_1 \dots \alpha_k}^{(k)}(\hat{T}_{t' \rightarrow t} x') \bigwedge_{i=1}^k (\mathcal{D}\hat{T}_{t' \rightarrow t})_{\beta_i}^{\alpha_i}(x') dx'^{\beta_i}.$$

Inserting back the $(1/k!)$ factor, we arrive at

$$(\hat{T}_{t \rightarrow t'}^* \psi^{(k)})(x') = (1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(\hat{T}_{t' \rightarrow t} x') \bigwedge_{i=1}^k (\mathcal{D}\hat{T}_{t' \rightarrow t})_{\beta_i}^{\alpha_i}(x') dx'^{\beta_i}. \quad \square$$

1.1.1 Infinitesimal Pull-back

Now, we try to derive the explicit expression of $\hat{T}_{t \rightarrow t'}^*$ depending on f^a in the limit $t' \rightarrow t$. This infinitesimal version of pull-back can be described by Lie derivative.

Definition 1.2. [Lie Derivative] Given $f: \mathbb{R} \rightarrow \mathcal{M} \rightarrow T\mathcal{M}$, Lie derivative $\hat{L}_f: \mathbb{R} \rightarrow \Omega^k(\mathcal{M}) \rightarrow \Omega^k(\mathcal{M})$ is defined as

$$\hat{L}_f(t) := \lim_{\Delta t \rightarrow 0} \frac{1 - \hat{T}_{t \rightarrow t+\Delta t}^*}{\Delta t}, \quad (1.4)$$

where \hat{T}^* is the pull-back induced by f .

Some useful definitions in exterior algebra are recalled. Operators $\hat{d} := dx^\alpha \wedge \partial_\alpha$ ^{1.4} and, for $\forall f$, $\hat{i}_f := f^\alpha i_\alpha$, where i_α is the interior product^{1.5}. Let A and B compositions of $dx^\alpha \wedge$ and i_a , then $[A, B]$ is commutator if both A and B have balanced $dx^\alpha \wedge$ and i_a , otherwise anti-commutator.

With these definitions, we conclude the explicit relation between f and \hat{L}_f , as follow.

1.1. The notation $A \rightarrow B \rightarrow C$ in declarations always means $A \rightarrow (B \rightarrow C)$. Further, $A \rightarrow B \rightarrow \dots$ means $A \rightarrow (B \rightarrow (\dots))$. This is an useful convension from Haskell.

1.2. We employ Einstein's convension of summation thoroughly.

1.3. Even though we call it something-back, but it pushes forward the k -forms. The name comes from the fact that forward pushing of k -forms is equivalent to backward pushing the mass unit, as the following discussion shows.

1.4. Operator ∂_α is short for $\partial/\partial x^\alpha$.

1.5. Interior product $i_a: \Omega^k(\mathcal{M}) \rightarrow \Omega^{k-1}(\mathcal{M})$ is defined as, for $\forall \psi^{(k)} \in \Omega^k(\mathcal{M})$,

$$i_\alpha \psi^{(k)} := (1/k!) \sum_{i=1}^k (-1)^{i-1} \psi_{\alpha_1 \dots (\alpha_i \rightarrow \alpha) \dots \alpha_k} dx^{\alpha_1} \wedge \dots \wedge dx^{\alpha_i} \wedge \dots \wedge dx^{\alpha_k}, \quad (1.5)$$

where \overline{A} means that A is deleted, and $\overline{A} \rightarrow B$ means that the original A is replaced by B . That is, it annihilates a $dx^\alpha \wedge$. The most useful property of interior product is the anti-commutator $[dx^\alpha \wedge, i_\beta]_+ = \delta_\beta^\alpha$.

Theorem 1.3. *[Cartan's Magic Formula] We have*

$$\hat{L}_f = [\hat{d}, \hat{i}_f]. \quad (1.6)$$

Proof. As $t' = t + \Delta t$ with Δt tiny, we have $\hat{T}_{t' \rightarrow t}^* x' = x' - f(t', x') \Delta t$. Then, $\mathcal{D}\hat{T}_{t' \rightarrow t}^* = 1 - \mathcal{D}f \Delta t$, where $\mathcal{D}f$ denotes the Jacobian of f . Now, insert this two expressions into the definition of $\hat{T}_{t' \rightarrow t}^* \psi^{(k)}$, we find

$$(\hat{T}_{t' \rightarrow t}^* \psi^{(k)})(x') = (1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x' - f(t', x') \Delta t) \bigwedge_{i=1}^k (\delta_{\beta_i}^{\alpha_i} - (\partial_{\beta_i} f^{\alpha_i})(t', x') \Delta t) dx'^{\beta_i}.$$

First, consider the expansion of $(1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x) \bigwedge_{i=1}^k (\delta_{\beta_i}^{\alpha_i} - (\partial_{\beta_i} f^{\alpha_i})(t', x') \Delta t) dx'^{\beta_i}$, up to $\mathcal{O}(\Delta t)$,

$$\begin{aligned} & (1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x) \bigwedge_{i=1}^k (\delta_{\beta_i}^{\alpha_i} - (\partial_{\beta_i} f^{\alpha_i})(t', x') \Delta t) dx'^{\beta_i} \\ &= (1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x) dx^{\alpha_1} \wedge \dots \wedge dx^{\alpha_k} \\ & - \Delta t \sum_{i=1}^k (1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x) (\partial_{\beta_i} f^{\alpha_i})(t', x') dx^{\alpha_1} \wedge \dots \wedge (dx^{\alpha_i} \rightarrow dx^{\beta_i}) \wedge \dots \wedge dx^{\alpha_k}, \end{aligned}$$

where $A \rightarrow B$ means that the original A is replaced by B . Now, we show that summation in the last line equals to $\partial_{\beta} f^{\alpha}(t', x') dx^{\beta} \wedge i_{\alpha} \psi^{(k)}(x)$. Recall that

$$i_{\alpha} \psi^{(k)}(x) := (1/k!) \sum_{i=1}^k (-1)^{i-1} \psi_{\alpha_1 \dots (\alpha_i \rightarrow \alpha) \dots \alpha_k}(x) dx^{\alpha_1} \wedge \dots \wedge dx^{\alpha_i} \wedge \dots \wedge dx^{\alpha_k},$$

where A means the original A is deleted. Indeed,

$$\begin{aligned} & (\partial_{\beta} f^{\alpha})(t', x') dx^{\beta} \wedge i_{\alpha} \psi^{(k)}(x) \\ &= (\partial_{\beta} f^{\alpha})(t', x') dx^{\beta} \wedge (1/k!) \sum_{i=1}^k (-1)^{i-1} \psi_{\alpha_1 \dots (\alpha_i \rightarrow \alpha) \dots \alpha_k}(x) dx^{\alpha_1} \wedge \dots \wedge dx^{\alpha_i} \wedge \dots \wedge dx^{\alpha_k} \\ &= (\partial_{\beta} f^{\alpha})(t', x') \sum_{i=1}^k (1/k!) \psi_{\alpha_1 \dots (\alpha_i \rightarrow \alpha) \dots \alpha_k}(x) dx^{\alpha_1} \wedge \dots \wedge (dx^{\alpha_i} \rightarrow dx^{\beta}) \wedge \dots \wedge dx^{\alpha_k} \\ &= \sum_{i=1}^k (\partial_{\beta_i} f^{\alpha_i})(t', x') (1/k!) \psi_{\alpha_1 \dots \alpha_i \dots \alpha_k}(x) dx^{\alpha_1} \wedge \dots \wedge (dx^{\alpha_i} \rightarrow dx^{\beta_i}) \wedge \dots \wedge dx^{\alpha_k} \\ &= \sum_{i=1}^k (\partial_{\beta_i} f^{\alpha_i})(t', x') (1/k!) \psi_{\alpha_1 \dots \alpha_k}(x) dx^{\alpha_1} \wedge \dots \wedge (dx^{\alpha_i} \rightarrow dx^{\beta_i}) \wedge \dots \wedge dx^{\alpha_k}, \end{aligned}$$

where in the last two lines, we replaced the dummy indices $\alpha \rightarrow \alpha_i$ and $\beta \rightarrow \beta_i$, and then found that $\psi_{\alpha_1 \dots \alpha_i \dots \alpha_k}$ can be written back to $\psi_{\alpha_1 \dots \alpha_k}$. Thus,

$$(1/k!) \psi_{\alpha_1 \dots \alpha_k}^{(k)}(x) \bigwedge_{i=1}^k (\delta_{\beta_i}^{\alpha_i} - (\partial_{\beta_i} f^{\alpha_i})(t', x') \Delta t) dx'^{\beta_i} = (1 - \Delta t (\partial_{\beta} f^{\alpha})(t', x') dx^{\beta} \wedge i_{\alpha}) \psi^{(k)}(x).$$

So, we find,

$$\begin{aligned} & (\hat{T}_{t' \rightarrow t}^* \psi^{(k)})(x') = (1 - \Delta t (\partial_{\beta} f^{\alpha})(t', x') dx^{\beta} \wedge i_{\alpha}) \psi^{(k)}(x) \\ \{x = x' - f(t', x') \Delta t\} &= (1 - \Delta t (\partial_{\beta} f^{\alpha})(t', x') dx^{\beta} \wedge i_{\alpha}) \psi^{(k)}(x' - f(t', x') \Delta t) \\ &= (1 - \Delta t (\partial_{\beta} f^{\alpha})(t', x') dx^{\beta} \wedge i_{\alpha}) (1 - \Delta t f^{\alpha}(t', x') \partial_{\alpha}) \psi^{(k)}(x') \\ &= \psi^{(k)}(x') - (f^{\alpha}(t', x') \partial_{\alpha} + (\partial_{\beta} f^{\alpha})(t', x') dx^{\beta} \wedge i_{\alpha}) \psi^{(k)}(x') \Delta t + \mathcal{O}(\Delta t^2). \end{aligned}$$

Thus,

$$\begin{aligned} \hat{L}_f &:= \lim_{\Delta t \rightarrow 0} \frac{1 - \hat{T}_{t' \rightarrow t}^* \Delta t}{\Delta t} \\ &= f^{\alpha} \partial_{\alpha} + (\partial_{\beta} f^{\alpha}) dx^{\beta} \wedge i_{\alpha}. \end{aligned}$$

Since $\hat{d} := dx^{\alpha} \wedge \partial_{\alpha}$ and $\hat{i}_f := f^{\alpha} i_{\alpha}$, we have

$$\begin{aligned} [\hat{d}, \hat{i}_f] &= dx^{\alpha} \wedge \partial_{\alpha} f^{\beta} i_{\beta} + f^{\beta} i_{\beta} dx^{\alpha} \wedge \partial_{\alpha} \\ &= (\partial_{\alpha} f^{\beta}) dx^{\alpha} \wedge i_{\beta} + f^{\beta} dx^{\alpha} \wedge i_{\beta} \partial_{\alpha} \\ \{[dx^{\alpha} \wedge, i_{\beta}] = \delta_{\beta}^{\alpha}\} &+ f^{\beta} \delta_{\beta}^{\alpha} \partial_{\alpha} - f^{\beta} dx^{\alpha} \wedge i_{\beta} \partial_{\alpha} \\ &= (\partial_{\alpha} f^{\beta}) dx^{\alpha} \wedge i_{\beta} + f^{\alpha} \partial_{\alpha}, \end{aligned}$$

which is \hat{L}_f . □

1.2 Stochastic Differential Equation

A direct generalization of ordinary differential equation is adding a Gaussian noise, as stochastic differential equation

$$\frac{dx^{\alpha}}{dt}(t) = f^{\alpha}(t, x) + g_{\beta}^{\alpha}(t, x) \eta^{\beta}(t), \quad (1.7)$$

where, for $\forall t$ and α , $\eta^{\alpha}(t) \sim \mathcal{N}(0, 1/dt)$. Thus, $\eta: \mathbb{R} \rightarrow V$ with V an Euclidean space, and $g: \mathbb{R} \rightarrow \mathcal{M} \rightarrow V \rightarrow TM$.

For any functional $F[\eta]$, split the time interval $[t, t']$ by $t = t_1 < t_2 < \dots < t_N = t'$, with $t_{i+1} - t_i \equiv \Delta t$, then define the expectation as

$$\begin{aligned} \langle F \rangle &:= \int D[\eta] \exp\left(-\frac{1}{2} \int dt \delta_{\alpha\beta} \eta^{\alpha}(t) \eta^{\beta}(t)\right) F[\eta] \\ &:= \lim_{\Delta t \rightarrow 0} Z^{-1} \int d\eta(t_1) \dots d\eta(t_N) \exp\left(-\frac{1}{2} \sum_i \Delta t \delta_{\alpha\beta} \eta^{\alpha}(t_i) \eta^{\beta}(t_i)\right) F[\eta], \end{aligned}$$

where Z the normalization factor so that $\langle 1 \rangle = 1$. Notice that the dimension of η and that of f may not equal.

1.2.1 Infinitesimal Pull-back Expectation

For any configuration η given, the stochastic differential equation is reduced to an ordinary differential equation. In this case, the pull-back depends on η , that is, $\hat{T}_{t' \rightarrow t}^*[\eta]$. We care about the expectation $\langle \hat{T}_{t' \rightarrow t}^*[\eta] \rangle$ over all possible configuration of η , especially it's infinitesimal version.

As before, define the stochastic version of Lie derivative, as

$$\hat{H}_{(f,g)}(t) := \lim_{\Delta t \rightarrow 0} \frac{1 - \langle \hat{T}_{t \rightarrow t+\Delta t}^*[\cdot] \rangle}{\Delta t}, \quad (1.8)$$

where $\hat{T}_{t \rightarrow t+\Delta t}^*$ depends on the configuration η .

Theorem 1.4. *We have*

$$\hat{H}_{(f,g)} = \hat{L}_f - \frac{1}{2} \hat{L}_g^2, \quad (1.9)$$

where $\hat{L}_g^2 := \delta^{\alpha\beta} \hat{L}_{g_\alpha} \hat{L}_{g_\beta}$.

Proof. Given configuration of η , let $F_\eta^\alpha(t, x) := f^\alpha(t, x) + g_\beta^\alpha(t, x) \eta^\beta(t)$. Directly, we have

$$\hat{L}_{F_\eta} = \hat{L}_f + \hat{L}_{g_\beta} \eta^\beta.$$

Then, we have $\hat{T}_{t \rightarrow t+\Delta t}^*[\eta] = \exp(-\hat{L}_{F_\eta} \Delta t)$.^{1.6} Then,

$$\begin{aligned} \langle \hat{T}_{t \rightarrow t+\Delta t}^*[\cdot] \rangle &= \int d\eta(t) \exp\left(-\frac{1}{2} \Delta t \delta_{\alpha\beta} \eta^\alpha(t) \eta^\beta(t)\right) \exp(-\hat{L}_{F_\eta} \Delta t) \\ &= \int d\eta(t) \exp\left(-\frac{1}{2} \Delta t \delta_{\alpha\beta} \eta^\alpha(t) \eta^\beta(t)\right) \left(1 - \hat{L}_{F_\eta} \Delta t + \frac{1}{2} (\hat{L}_{F_\eta} \Delta t)^2 + \dots\right) \\ &= 1 - \langle \hat{L}_{F_\eta} \Delta t \rangle + \frac{1}{2} \langle (\hat{L}_{F_\eta} \Delta t)^2 \rangle + \dots \end{aligned}$$

Since $\langle \eta^\beta \rangle = 0$, $\langle \hat{L}_{F_\eta} \Delta t \rangle = \langle \hat{L}_f + \hat{L}_{g_\beta} \eta^\beta \rangle \Delta t = \hat{L}_f \Delta t$. And since $\langle \eta^\alpha \eta^\beta \rangle = \delta^{\alpha\beta} / \Delta t$,

$$\begin{aligned} \langle (\hat{L}_{F_\eta} \Delta t)^2 \rangle &= \langle (\hat{L}_f + \hat{L}_{g_\alpha} \eta^\alpha) (\hat{L}_f + \hat{L}_{g_\beta} \eta^\beta) \rangle \Delta t^2 \\ \{ \langle \eta^\beta \rangle = 0 \} &= \hat{L}_f^2 \Delta t^2 + \hat{L}_{g_\alpha} \hat{L}_{g_\beta} \langle \eta^\alpha \eta^\beta \rangle \Delta t^2 \\ \{ \langle \eta^\alpha \eta^\beta \rangle = \delta^{\alpha\beta} / \Delta t \} &= \hat{L}_f^2 \Delta t^2 + \hat{L}_{g_\alpha} \hat{L}_{g_\beta} \delta^{\alpha\beta} \Delta t \\ \{ \hat{L}_g^2 := \dots \} &= \hat{L}_f^2 \Delta t^2 + \hat{L}_g^2 \Delta t. \end{aligned}$$

Thus,

$$\begin{aligned} \langle \hat{T}_{t \rightarrow t+\Delta t}^*[\cdot] \rangle &= 1 - \langle \hat{L}_{F_\eta} \rangle \Delta t + \frac{1}{2} \langle (\hat{L}_{F_\eta} \Delta t)^2 \rangle + \dots \\ &= 1 - \hat{L}_f \Delta t + \frac{1}{2} (\hat{L}_g^2) \Delta t + o(\Delta t). \end{aligned}$$

So, finally,

$$\hat{H}_{(f,g)} := \lim_{\Delta t \rightarrow 0} \frac{1 - \langle \hat{T}_{t \rightarrow t+\Delta t}^*[\cdot] \rangle}{\Delta t} = \hat{L}_f - \frac{1}{2} \hat{L}_g^2. \quad \square$$

Example 1.5. [Fokker-Planck Equation] In the case $g_\beta^\alpha \equiv \sqrt{2T} \delta_\beta^\alpha$,

$$\hat{H} = (\partial_\alpha f^\beta) dx^\alpha \wedge i_\beta + f^\alpha \partial_\alpha - T \partial^2, \quad (1.10)$$

where $\partial^2 := \delta^{\alpha\beta} \partial_\alpha \partial_\beta$. Applying on $\psi^{(D)}$ with $D = \dim(\mathcal{M})$, since $dx^\alpha \wedge \psi^{(D)} = 0$, and thus $dx^\alpha \wedge i_\beta \psi^{(D)} = \delta_\beta^\alpha \psi^{(D)}$, we find

$$\hat{H} \psi^{(D)} = (\partial_\alpha f^\alpha - T \partial^2) \psi^{(D)}, \quad (1.11)$$

which is the Fokker-Planck equation.

1.2.2 Symmetry (TODO)

^{1.6}. TODO: needs some proof.

Bibliography

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