

# Conditional GAN (C-GAN)

Originally proposed by [Mirza et al.](#) is their work titled Conditional Generative Adversarial Nets. This network uses a basic implementation where generator and discriminator models are MLPs with additional inputs for conditioning with class labels. This notebook trains both networks using ADAM optimizer to play the minimax game. We showcase the effectiveness using MNIST digit generation

# Conditional GAN (C-GAN)

Originally proposed by [Mirza et al.](#) is their work titled Conditional Generative Adversarial Nets. This network uses a basic implementation where generator and discriminator models are MLPs with additional inputs for conditioning with class labels. This notebook trains both networks using ADAM optimizer to play the minimax game. We showcase the effectiveness using MNIST digit generation

```
In [1]: import torch
import torch.nn as nn
import torch.optim as optim
import torchvision.datasets as datasets
import torchvision.transforms as transforms
from torch.utils.data import DataLoader
import matplotlib.pyplot as plt
import numpy as np

In [2]: # Define the generator
class Generator(nn.Module):
    def __init__(self, z_dim, num_classes):
        super(Generator, self).__init__()
        self.label_emb = nn.Embedding(num_classes, z_dim)
        self.model = nn.Sequential(
            nn.Linear(z_dim * 2, 128),
            nn.ReLU(),
            nn.Linear(128, 256),
            nn.ReLU(),
            nn.Linear(256, 512),
            nn.ReLU(),
            nn.Linear(512, 28 * 28),
            nn.Tanh()
        )

    def forward(self, z, labels):
        z = torch.cat([z, self.label_emb(labels)], dim=1)
        return self.model(z).view(-1, 1, 28, 28)

In [3]: # Define the discriminator
class Discriminator(nn.Module):
    def __init__(self, num_classes):
        super(Discriminator, self).__init__()
        self.label_emb = nn.Embedding(num_classes, 28 * 28)
```



```
In [8]: def generate_and_show_images(epoch):
    generator.eval()
    z = torch.randn(10, z_dim, device=device)
    labels = torch.arange(10, device=device)
    with torch.no_grad():
        fake_imgs = generator(z, labels).cpu().numpy()
    generator.train()

    fig, axes = plt.subplots(1, 10, figsize=(10, 2))
    for i, img in enumerate(fake_imgs):
        axes[i].imshow(img[0], cmap='gray')
        axes[i].set_title(f"Label: {i}")
        axes[i].axis('off')
    plt.show()
```

```
In [ ]: # Training Loop
for epoch in range(epochs):
    for i, (imgs, labels) in enumerate(dataloader):
        imgs, labels = imgs.to(device), labels.to(device)
        batch_size = imgs.shape[0]

        # Prepare Labels
        real_labels = torch.ones(batch_size, 1, device=device)
        fake_labels = torch.zeros(batch_size, 1, device=device)

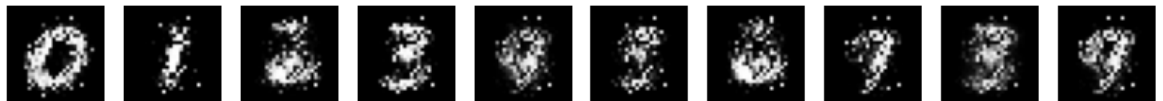
        # Train discriminator
        optimizer_D.zero_grad()
        z = torch.randn(batch_size, z_dim, device=device)
        fake_imgs = generator(z, labels)
        real_loss = criterion(discriminator(imgs, labels), real_labels)
        fake_loss = criterion(discriminator(fake_imgs.detach(), labels), fake_labels)
        d_loss = real_loss + fake_loss
        d_loss.backward()
        optimizer_D.step()

        # Train generator
        optimizer_G.zero_grad()
        g_loss = criterion(discriminator(fake_imgs, labels), real_labels)
        g_loss.backward()
        optimizer_G.step()

    print(f"Epoch [{epoch+1}/{epochs}] | D Loss: {d_loss.item():.4f} | G Loss: {g_loss.item():.4f}")
    if (epoch + 1) % 1 == 0:
        generate_and_show_images(epoch)
```

Epoch [1/1000] | D Loss: 1.1261 | G Loss: 2.5655

Label: 0 Label: 1 Label: 2 Label: 3 Label: 4 Label: 5 Label: 6 Label: 7 Label: 8 Label: 9

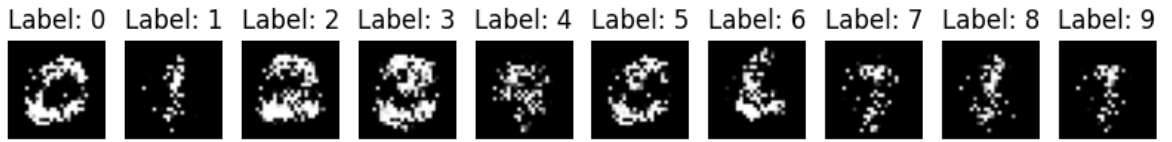


Epoch [2/1000] | D Loss: 0.4935 | G Loss: 3.3080

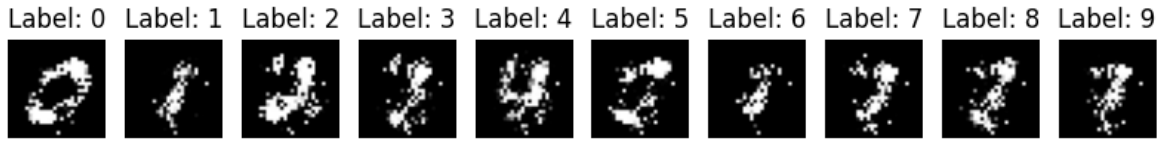
Label: 0 Label: 1 Label: 2 Label: 3 Label: 4 Label: 5 Label: 6 Label: 7 Label: 8 Label: 9



Epoch [3/1000] | D Loss: 0.4222 | G Loss: 2.9534



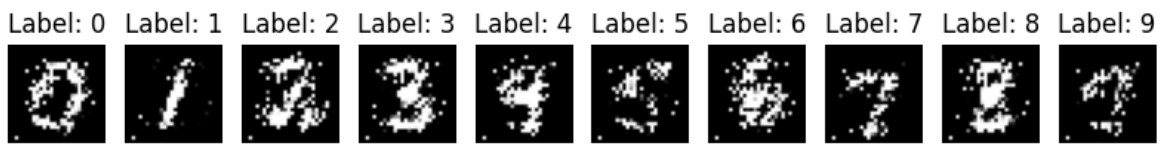
Epoch [4/1000] | D Loss: 0.3580 | G Loss: 3.3466



Epoch [5/1000] | D Loss: 0.2639 | G Loss: 2.4299



Epoch [6/1000] | D Loss: 0.3716 | G Loss: 3.4267



Epoch [7/1000] | D Loss: 0.1991 | G Loss: 3.7193



Epoch [8/1000] | D Loss: 0.0071 | G Loss: 6.4297



Epoch [9/1000] | D Loss: 0.0154 | G Loss: 5.7319



Epoch [10/1000] | D Loss: 0.0008 | G Loss: 7.7892



Epoch [11/1000] | D Loss: 0.0165 | G Loss: 6.9286



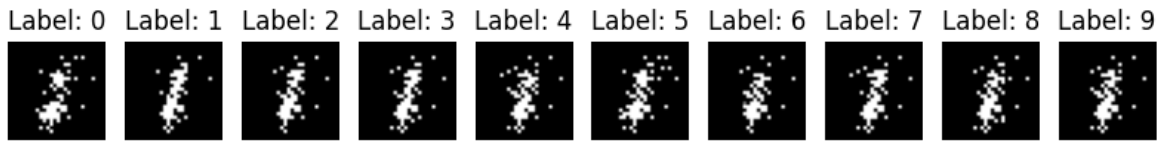
Epoch [12/1000] | D Loss: 0.0557 | G Loss: 5.7088



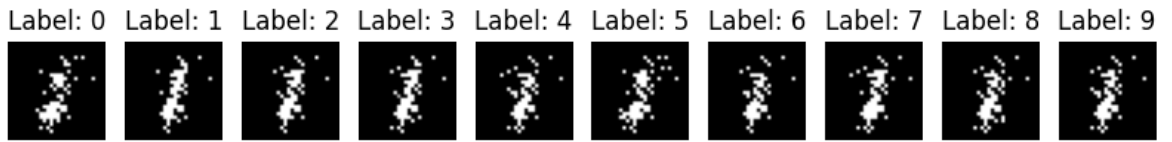
Epoch [13/1000] | D Loss: 0.0012 | G Loss: 7.6813



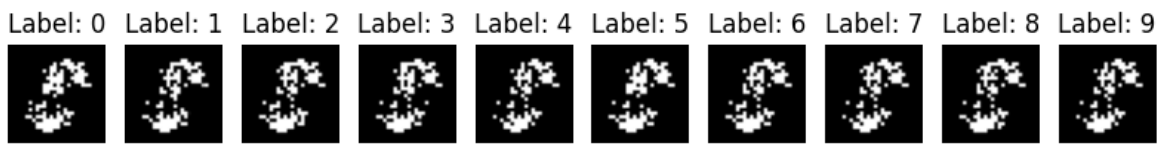
Epoch [14/1000] | D Loss: 0.0002 | G Loss: 8.9261



Epoch [15/1000] | D Loss: 0.0003 | G Loss: 9.1910



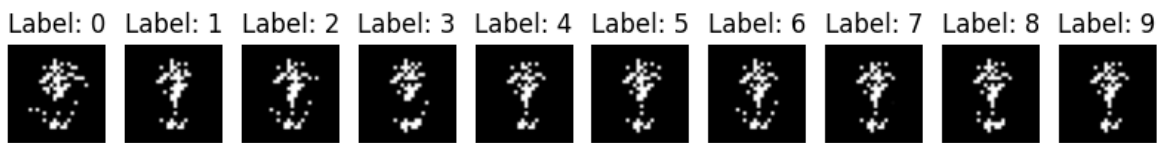
Epoch [16/1000] | D Loss: 0.0003 | G Loss: 8.6102



Epoch [17/1000] | D Loss: 0.0211 | G Loss: 5.8722



Epoch [18/1000] | D Loss: 0.0001 | G Loss: 10.3863



Epoch [19/1000] | D Loss: 0.0042 | G Loss: 7.3401



Epoch [20/1000] | D Loss: 0.0001 | G Loss: 10.0092



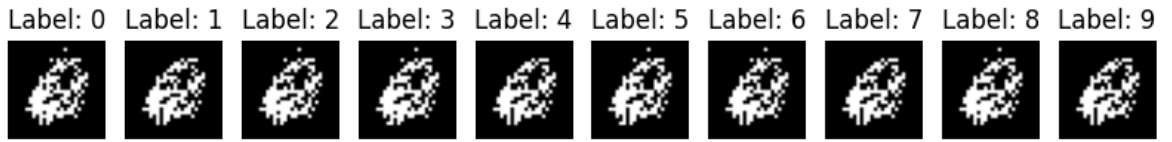
Epoch [21/1000] | D Loss: 0.0000 | G Loss: 10.9068



Epoch [22/1000] | D Loss: 0.0000 | G Loss: 11.8375



Epoch [23/1000] | D Loss: 0.0000 | G Loss: 11.9878



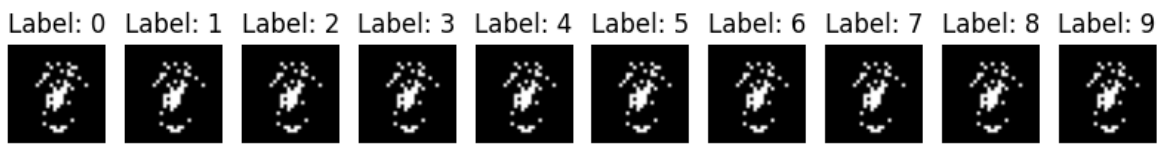
Epoch [24/1000] | D Loss: 0.0003 | G Loss: 8.7661



Epoch [25/1000] | D Loss: 0.0000 | G Loss: 11.2474



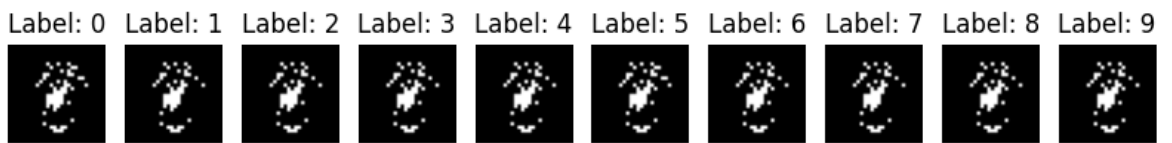
Epoch [26/1000] | D Loss: 0.0000 | G Loss: 11.7373



Epoch [27/1000] | D Loss: 0.0000 | G Loss: 12.4325



Epoch [28/1000] | D Loss: 0.0000 | G Loss: 12.0832



Epoch [29/1000] | D Loss: 0.0000 | G Loss: 12.5280



Epoch [30/1000] | D Loss: 0.0000 | G Loss: 12.6174



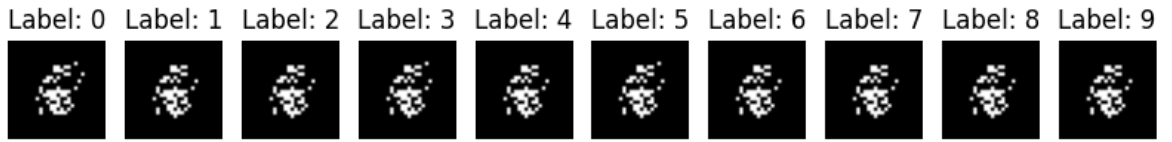
Epoch [31/1000] | D Loss: 0.0000 | G Loss: 12.7858



Epoch [32/1000] | D Loss: 0.0000 | G Loss: 13.0825



Epoch [33/1000] | D Loss: 0.0001 | G Loss: 9.8179



Epoch [34/1000] | D Loss: 0.0001 | G Loss: 10.3254



Epoch [35/1000] | D Loss: 0.0052 | G Loss: 8.6352



Epoch [36/1000] | D Loss: 0.0001 | G Loss: 11.0021



Epoch [37/1000] | D Loss: 0.0000 | G Loss: 11.6431



Epoch [38/1000] | D Loss: 0.0002 | G Loss: 12.1269



Epoch [39/1000] | D Loss: 0.0000 | G Loss: 12.9875



Epoch [40/1000] | D Loss: 0.0000 | G Loss: 12.8319



Epoch [41/1000] | D Loss: 0.0000 | G Loss: 13.2082



Epoch [42/1000] | D Loss: 0.0000 | G Loss: 13.4357



Epoch [43/1000] | D Loss: 0.0000 | G Loss: 13.7428



Epoch [44/1000] | D Loss: 0.0000 | G Loss: 13.3872



Epoch [45/1000] | D Loss: 0.0000 | G Loss: 13.8519



Epoch [46/1000] | D Loss: 0.0000 | G Loss: 13.9370



Epoch [47/1000] | D Loss: 0.0000 | G Loss: 14.3679



Epoch [48/1000] | D Loss: 0.0000 | G Loss: 15.1022



Epoch [49/1000] | D Loss: 0.0000 | G Loss: 15.0676



Epoch [50/1000] | D Loss: 0.0000 | G Loss: 15.3978



Epoch [51/1000] | D Loss: 0.0000 | G Loss: 15.5206

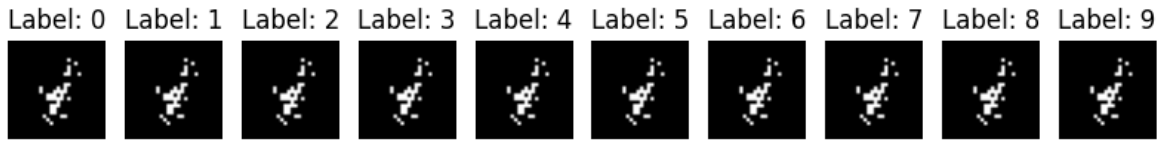


Epoch [52/1000] | D Loss: 0.0000 | G Loss: 15.7414

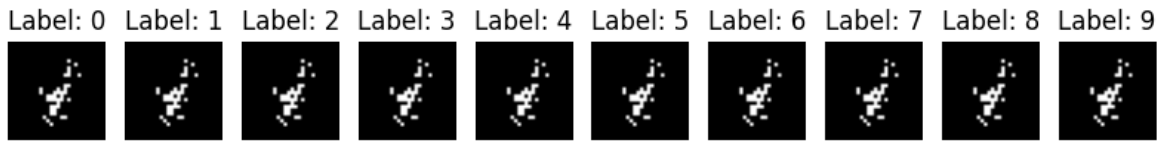


Epoch [53/1000] | D Loss: 0.0026 | G Loss: 7.7218





Epoch [54/1000] | D Loss: 0.0001 | G Loss: 10.0251



Epoch [55/1000] | D Loss: 0.0001 | G Loss: 10.4928



Epoch [56/1000] | D Loss: 0.0000 | G Loss: 11.2056



Epoch [57/1000] | D Loss: 0.0000 | G Loss: 11.6141



Epoch [58/1000] | D Loss: 0.0000 | G Loss: 12.0458



Epoch [59/1000] | D Loss: 0.0000 | G Loss: 12.4808



Epoch [60/1000] | D Loss: 0.0000 | G Loss: 13.0851



Epoch [61/1000] | D Loss: 0.0000 | G Loss: 13.3643



Epoch [62/1000] | D Loss: 0.0000 | G Loss: 13.7085



Epoch [63/1000] | D Loss: 0.0000 | G Loss: 13.9850



Epoch [64/1000] | D Loss: 0.0000 | G Loss: 14.1755



Epoch [65/1000] | D Loss: 0.0000 | G Loss: 14.3996



Epoch [66/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [67/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [68/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [69/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [70/1000] | D Loss: 100.0000 | G Loss: 0.0000



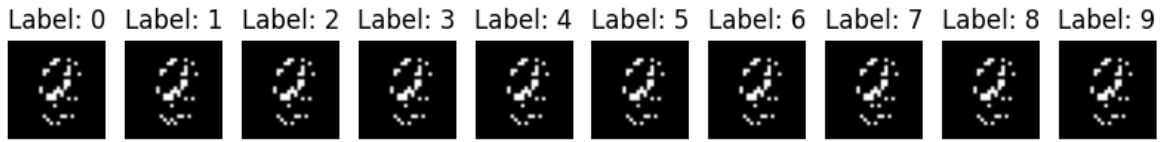
Epoch [71/1000] | D Loss: 100.0000 | G Loss: 0.0000



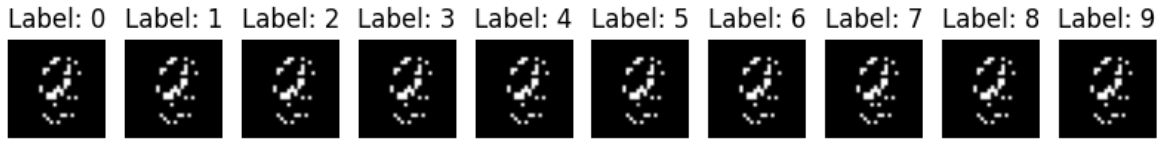
Epoch [72/1000] | D Loss: 100.0000 | G Loss: 0.0000



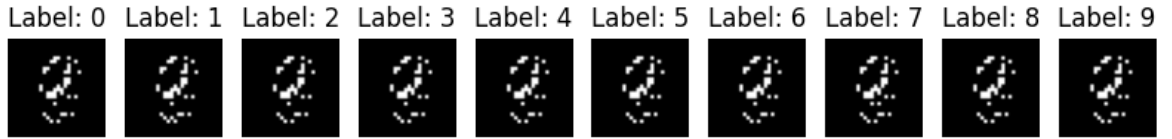
Epoch [73/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [74/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [75/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [76/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [77/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [78/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [79/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [80/1000] | D Loss: 100.0000 | G Loss: 0.0000



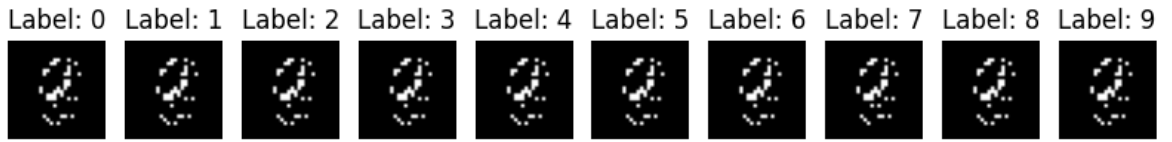
Epoch [81/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [82/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [83/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [84/1000] | D Loss: 100.0000 | G Loss: 0.0000



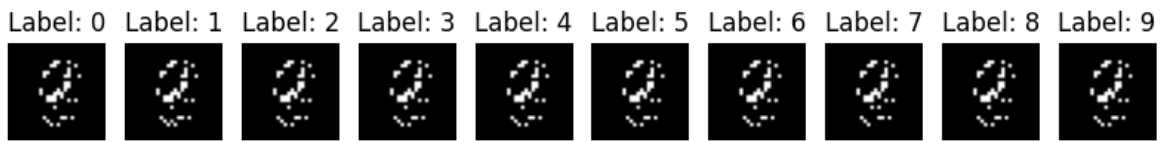
Epoch [85/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [86/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [87/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [88/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [89/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [90/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [91/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [92/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [93/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [94/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [95/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [96/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [97/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [98/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [99/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [100/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [101/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [102/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [103/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [104/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [105/1000] | D Loss: 100.0000 | G Loss: 0.0000



Epoch [106/1000] | D Loss: 100.0000 | G Loss: 0.0000



In [ ]: