PROGRAMMING AND DATA STRUCTURES

BINARY TREES

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OUTLINE

- Characteristics of binary trees
- Binary Search Trees (BST)
- Operations on BSTs
- → Implementation of the BST class
- → Heap
- Operations on the Heap
- Implementation of the Heap class

STUDENT LEARNING OUTCOMES

At the end of this chapter, you should be able to:

- Describe the properties of binary trees/BST/ Heap
- Trace operations on binary trees/BST/Heap
- Implement BST/Heap generic data structures
- Use the BST/Heap data structures
- Evaluate the complexity of the operations on BST/Heap

What is a binary tree?

- Data organized in a binary tree structure
- Easy and efficient access and update in large collections of data
- Used for efficient search operations
- Wide range of applications: mathematical expressions, game strategies, decision trees, data compression, ...

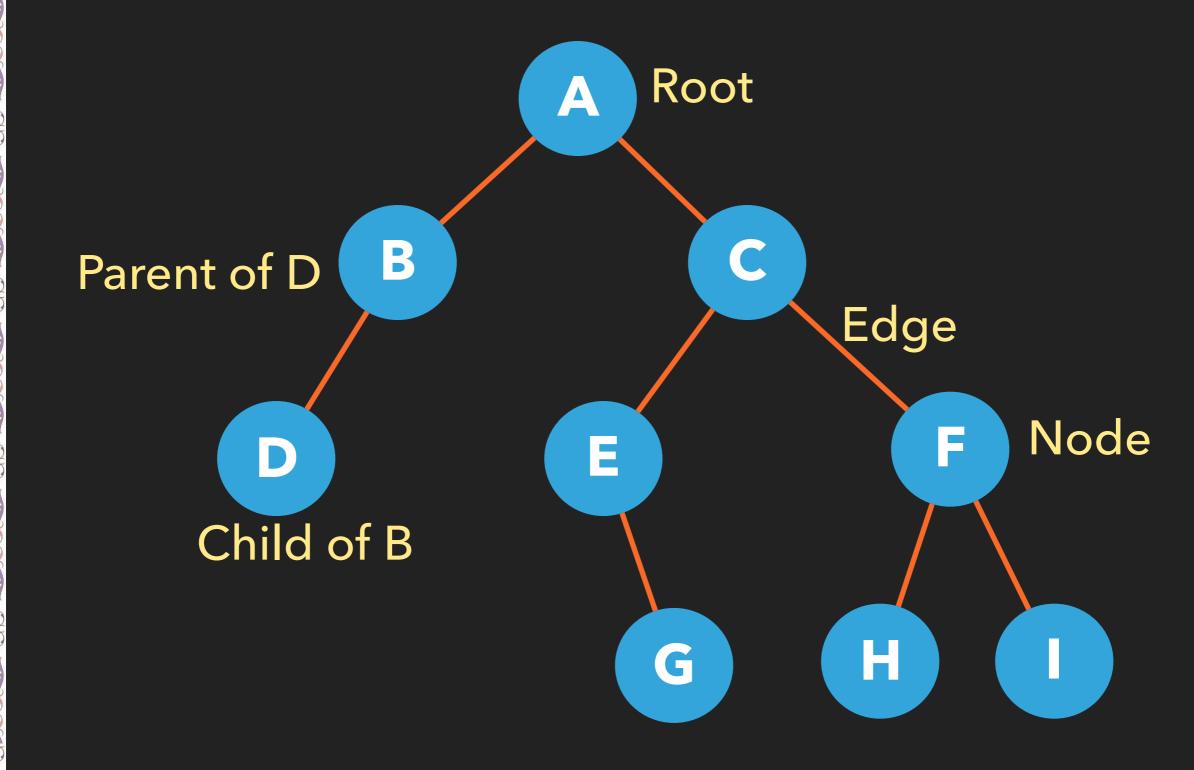
Set of elements called nodes (vertices) interconnected with edges (arcs)

◆ The first node is called the root

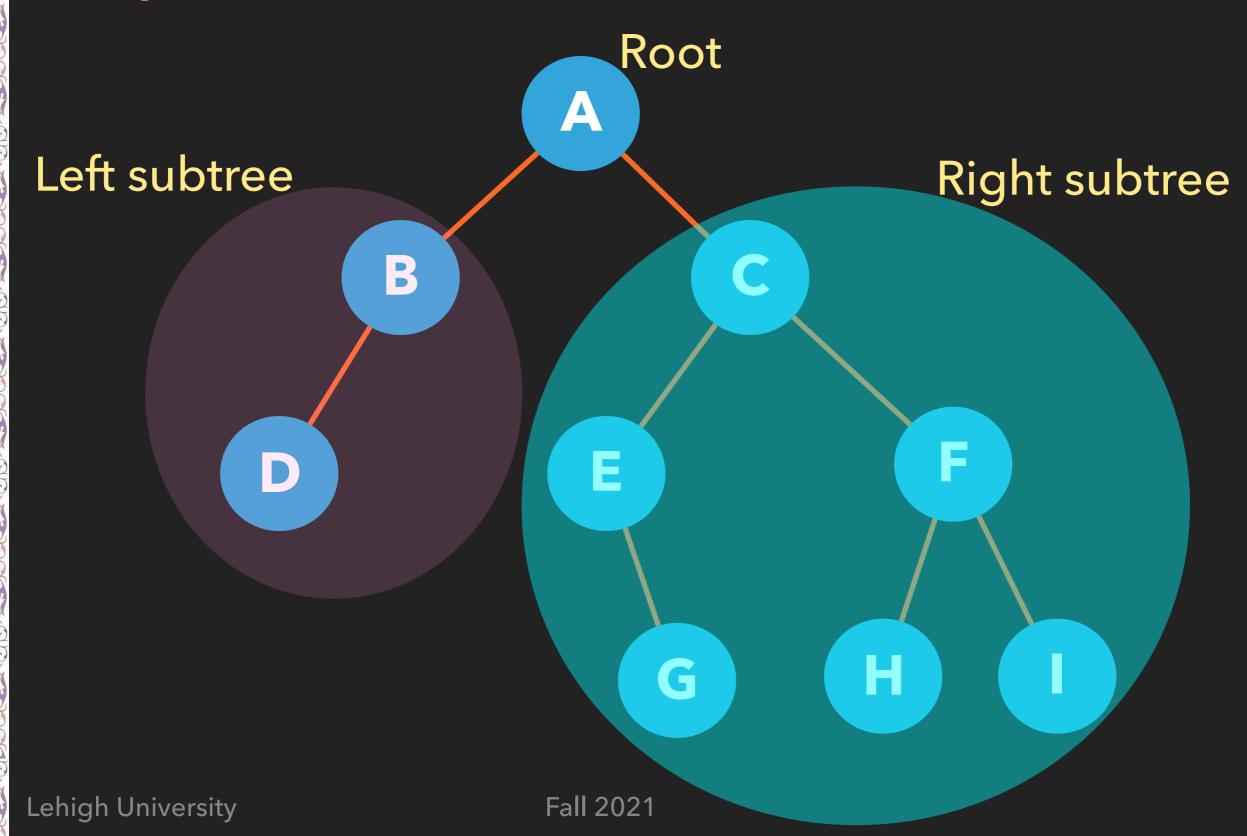
The root is connected to two binary trees (left subtree and right subtree)

Every node has a parent (except the root) and may have one child or two children at most

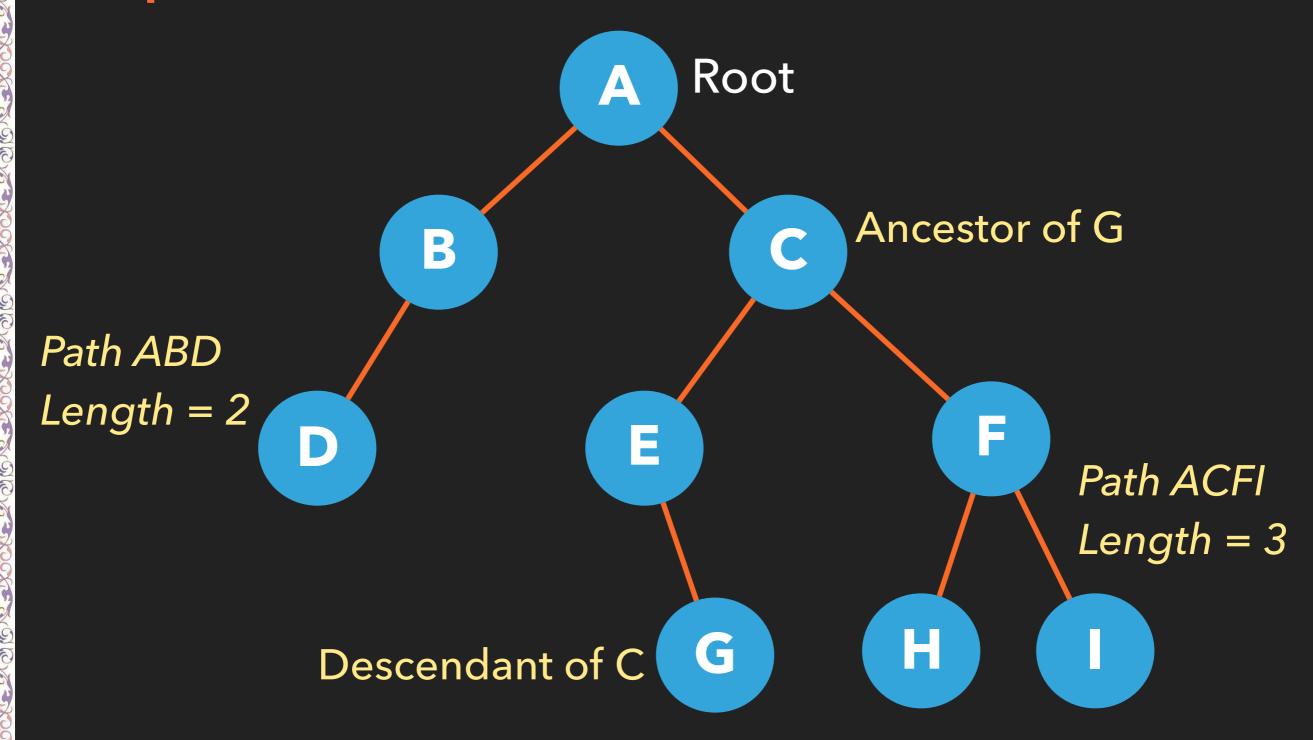
The root is the ancestor of all the nodes in the tree



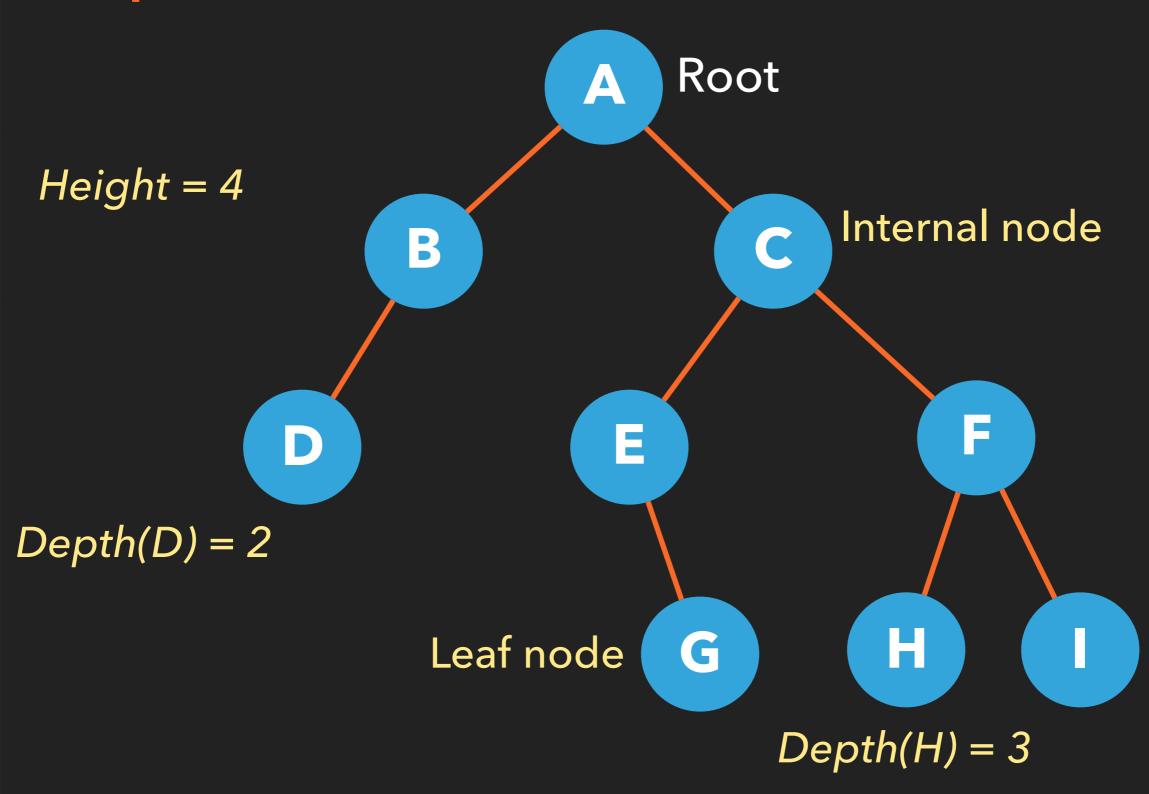
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- Path: Sequence of connected nodes starting at any level of the tree
- Length of a path: the number of nodes in the sequence - 1 (number of edges)
- ◆ If there is a path from node P to node Q, Q is the descendant of P and P is an ancestor of Q

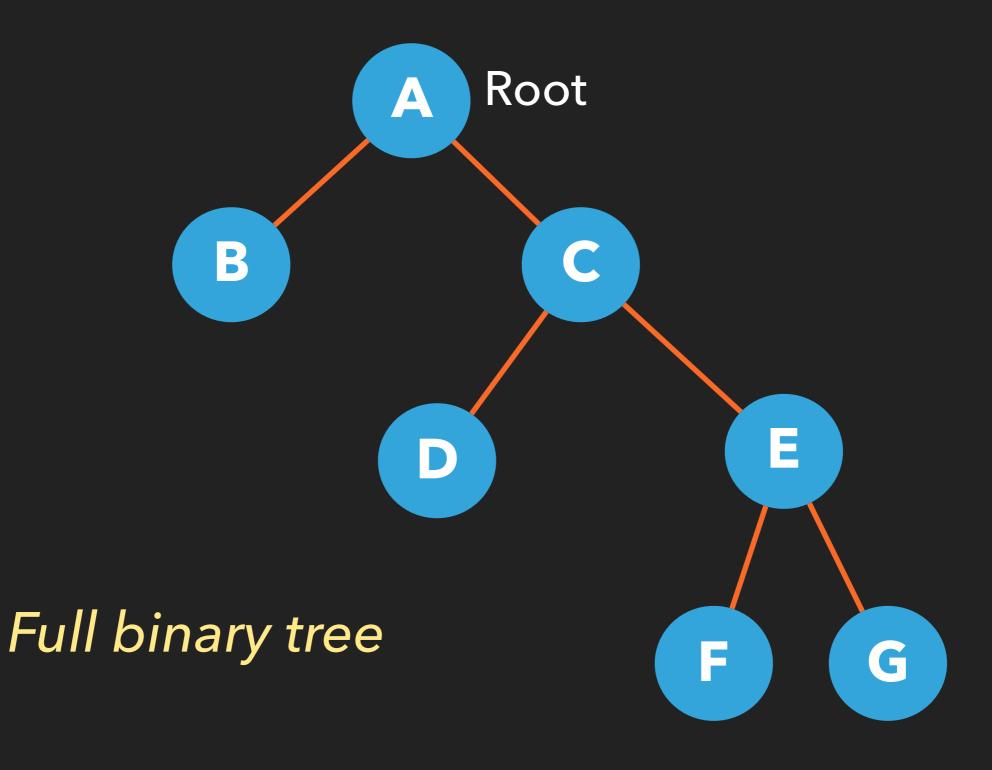


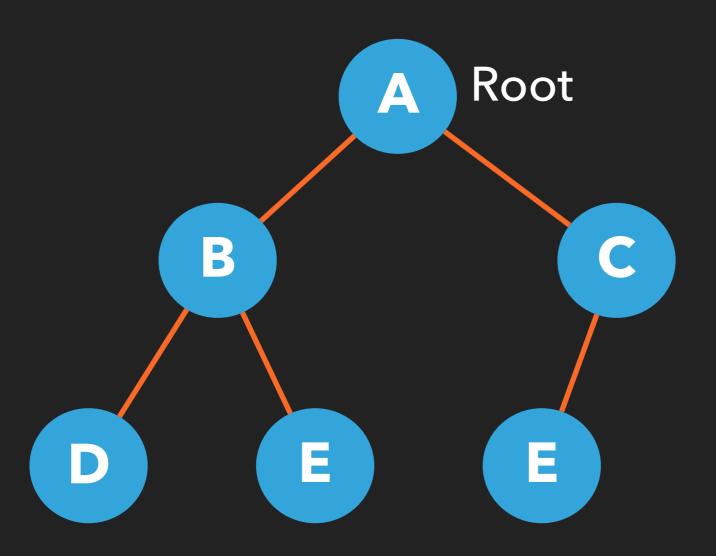
- Depth of a node: Length of the path from the root to the node
- Height of a tree: the depth of the deepest node + 1
- ◆ Leaf node: node that has no children
- ◆ Internal node: node that has at least one child



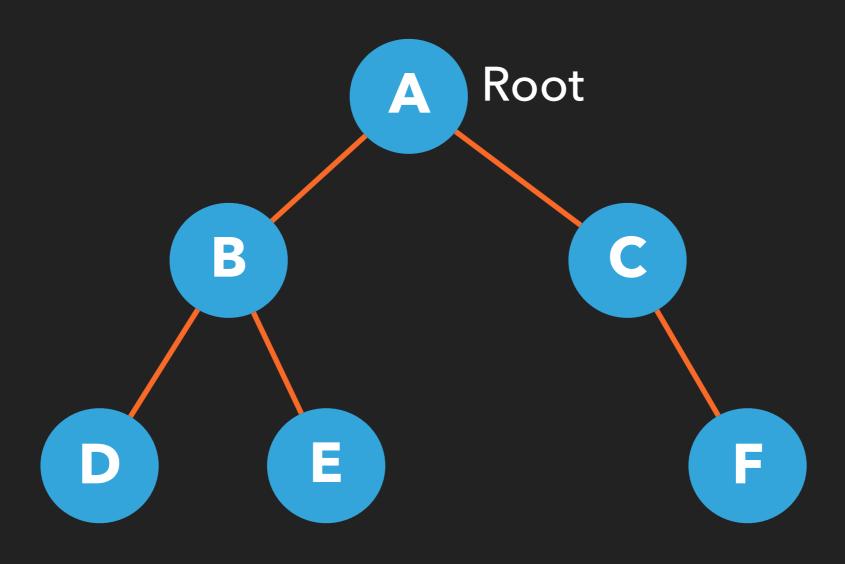
Full Binary Tree: each node is a leaf or an internal node with exactly two children

◆ Complete Binary Tree: Every level is filled except the last level, and the leaves on the last level are placed leftmost





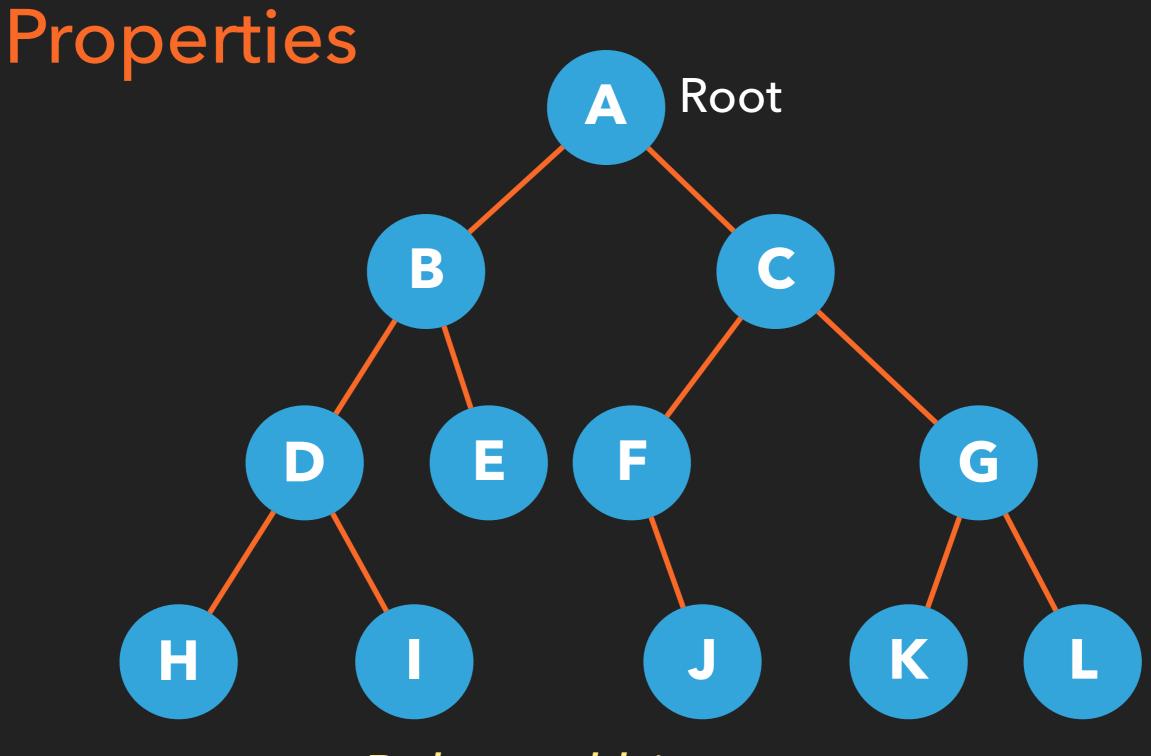
Complete binary tree but not full



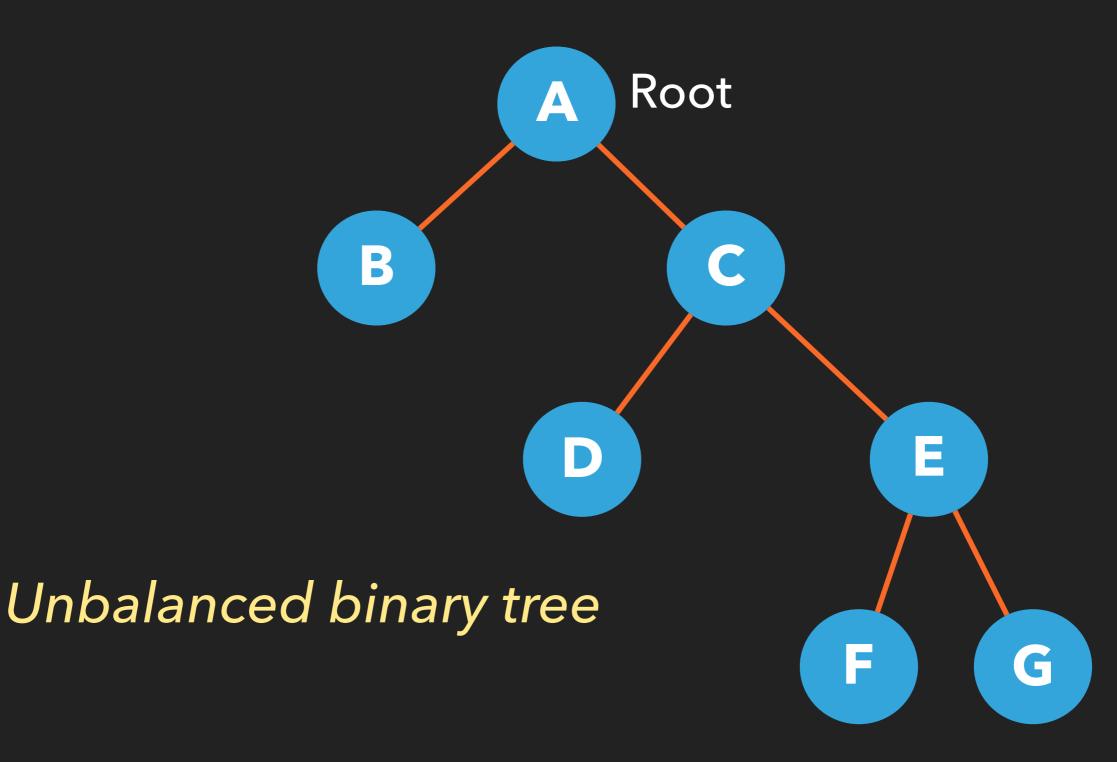
Not Complete - not full

◆ Balanced Binary Tree: for each node, the height of the left subtree and the height of the right subtree differ by at most 1

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Balanced binary tree



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Practice

Root?

Depth(35)?

Path from 70 to 72?

Height of the tree?

Leaf nodes?

Internal nodes?

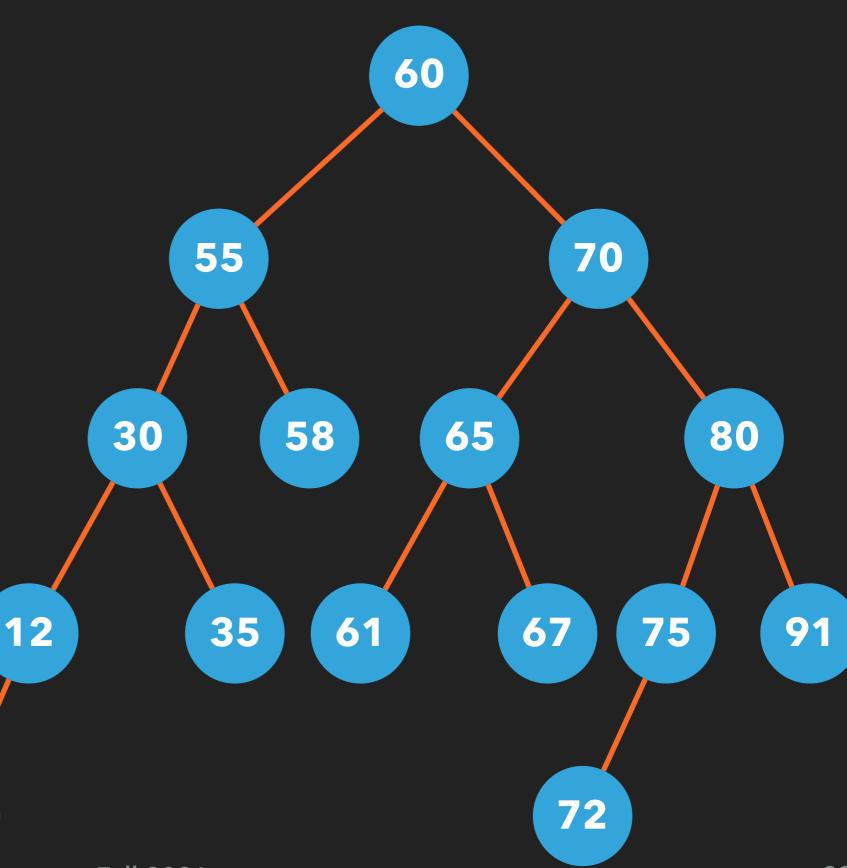
Children of 55?

Descendants of 55?

Full?

Complete?

Balanced?



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Binary Tree Traversal

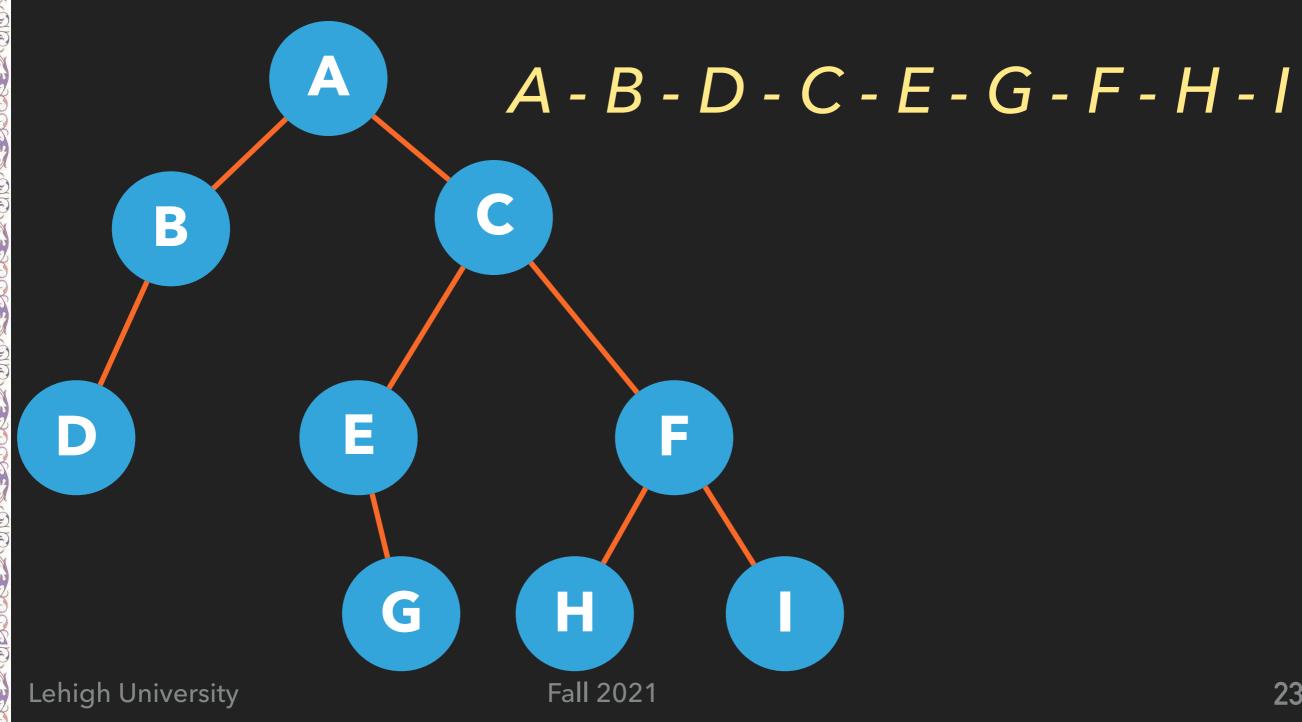
- Any process of visiting all the nodes in the tree is called traversal
- ◆ Three common traversals
 - Preorder
 - ♦ Inorder
 - Postorder

Preorder Traversal

- Any node is visited before its children
- ♦ V-L-R: Visit Node Go Left Go Right
 - ◆ Visit the node
 - → Traverse the left subtree
 - ◆ Traverse the right subtree

Preorder Traversal

♦ V-L-R: Visit Node - Go Left - Go Right

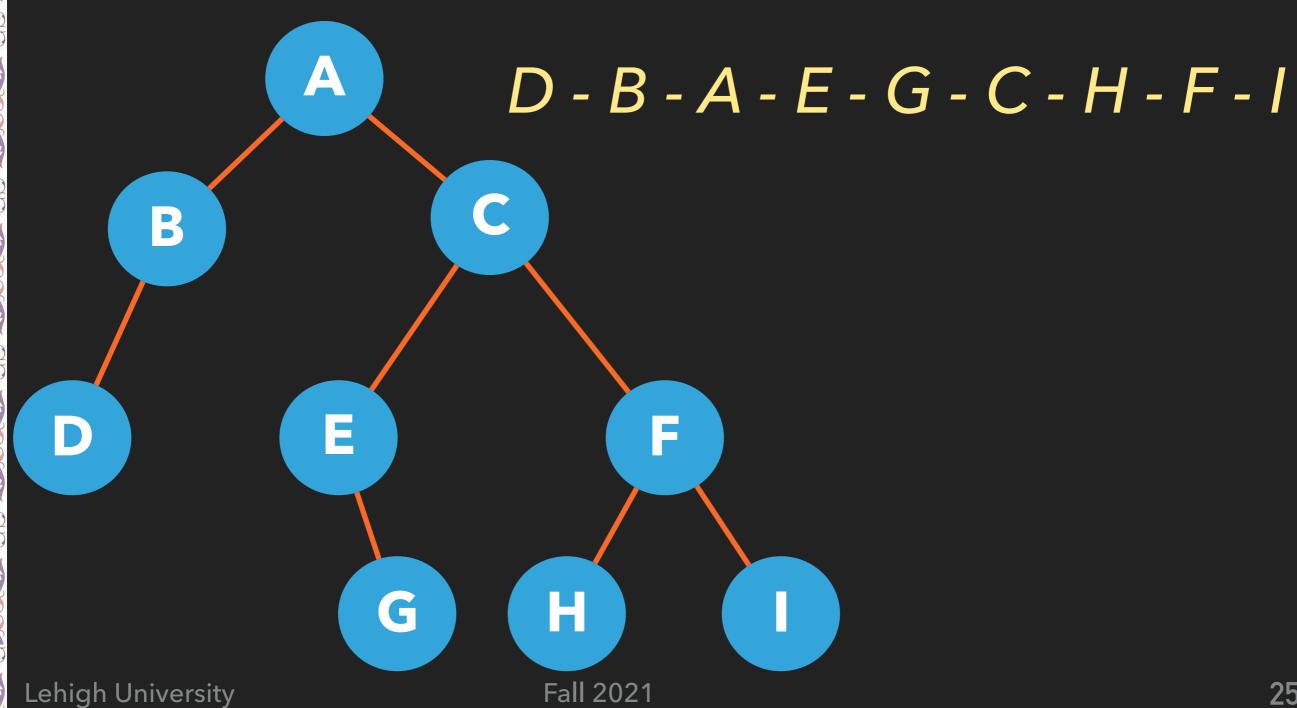


Inorder Traversal

- Any node is visited after its left subtree and before its right subtree
- ◆ L-V-R: Go Left Visit Node Go Right
 - ◆ Traverse the left subtree
 - ◆ Visit the node
 - ◆ Traverse the right subtree

In order Traversal

◆ L-V-R: Go Left - Visit Node - Go Right

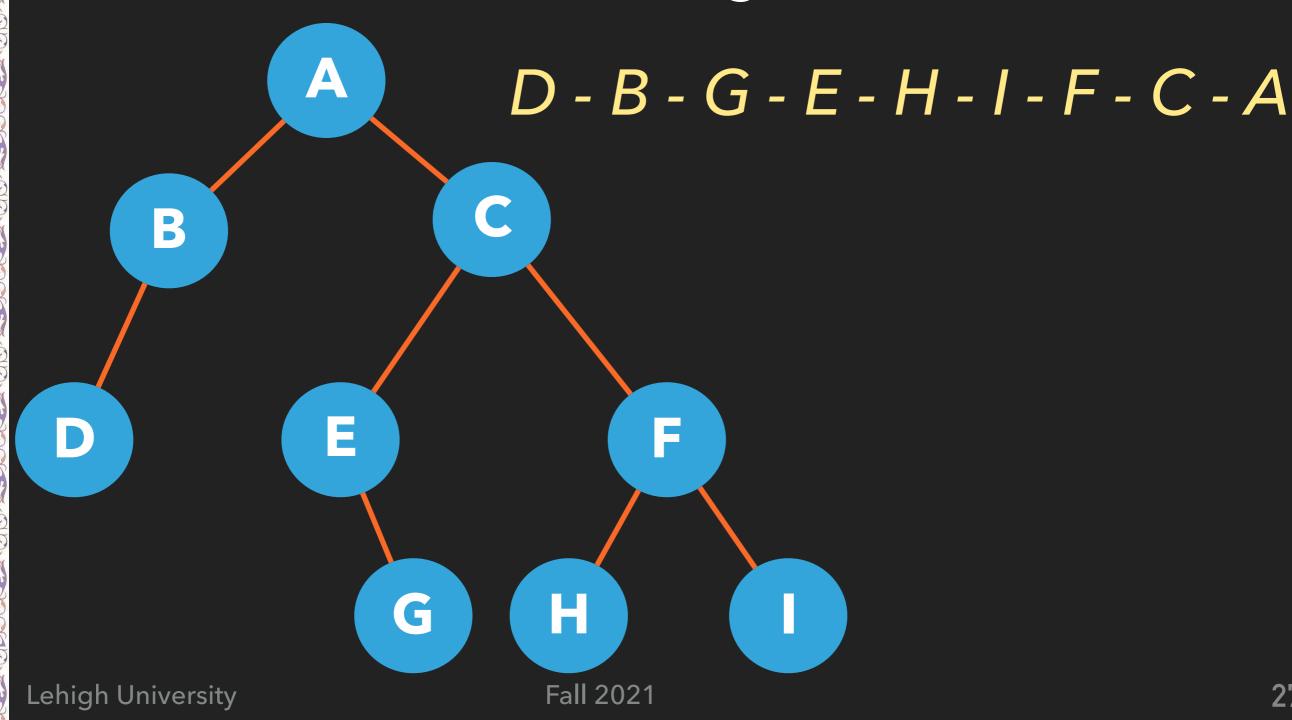


Postorder Traversal

- Any node is visited after its left subtree and right subtree
- ◆ L-R-V: Go Left Go Right Visit Node
 - ◆ Traverse the left subtree
 - ◆ Traverse the right subtree
 - ◆ Visit the node

Postorder Traversal

◆ L-R-V: Go Left - Go Right - Visit Node

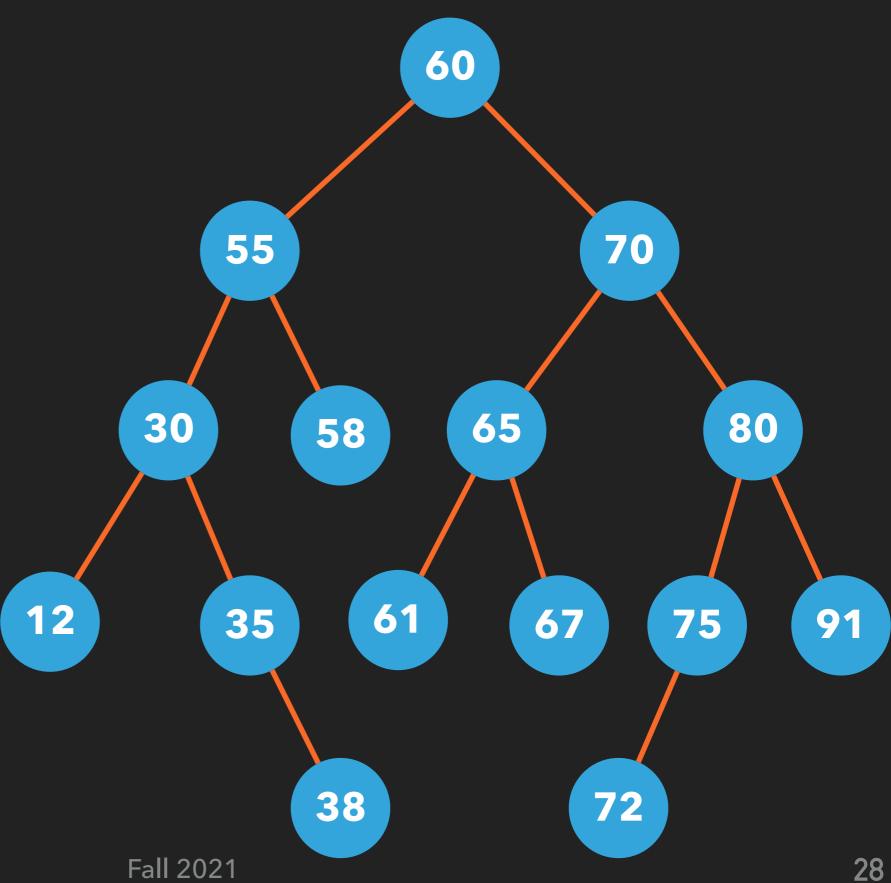


Practice

Preorder:

Inorder:

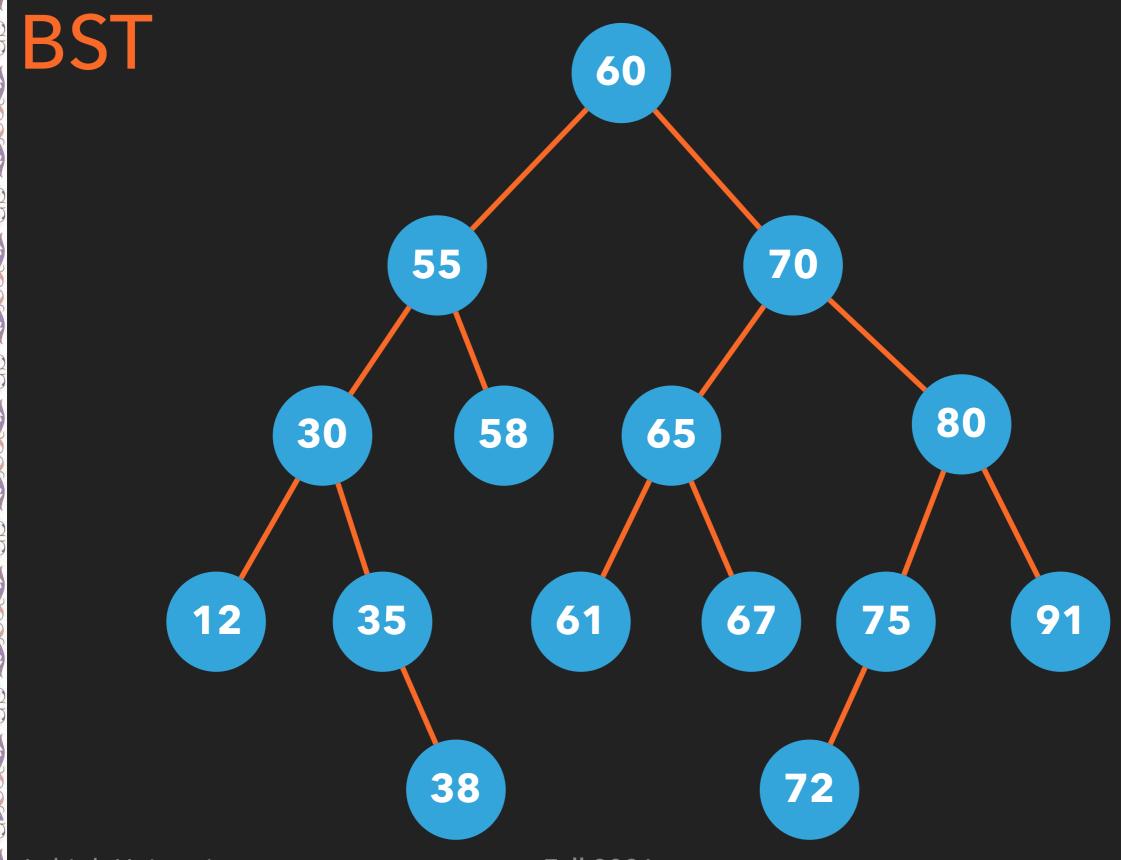
Postorder:



Binary Search Tree (BST)

- Special binary tree
 - ◆ BST has a root, a left subtree (L) and a right subtree (R)
 - The value of the root is greater than the value of every node in L
 - ◆ The value of the root is less than the value of every node in R
 - ◆ L and R are also BSTs
 - Used for efficient search in large data sets

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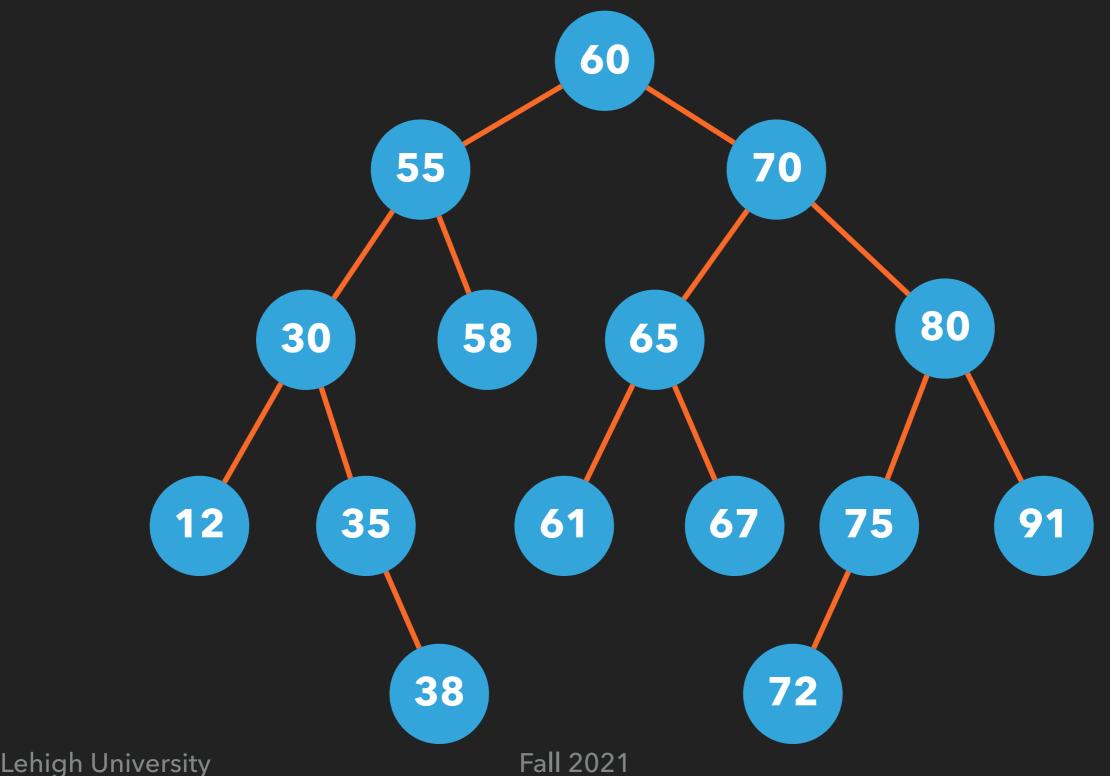


BST

- Common operations on BST
 - Search for a specific value in the BST
 - Add a node to the BST while keeping the BST properties
 - Remove a node from the BST while keeping the BST properties
 - ◆ Traverse the BST (preorder, inorder, postorder)

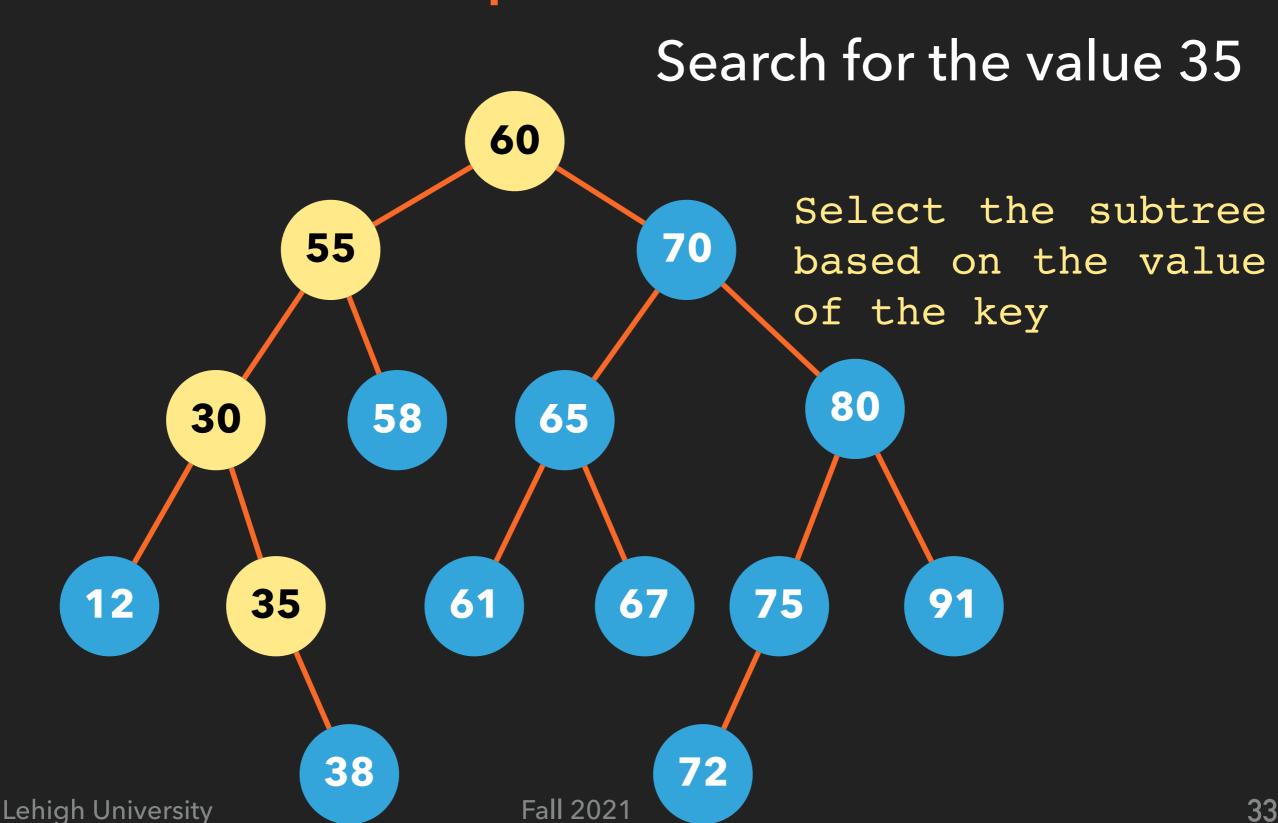
BST - Search

Search for the value 35



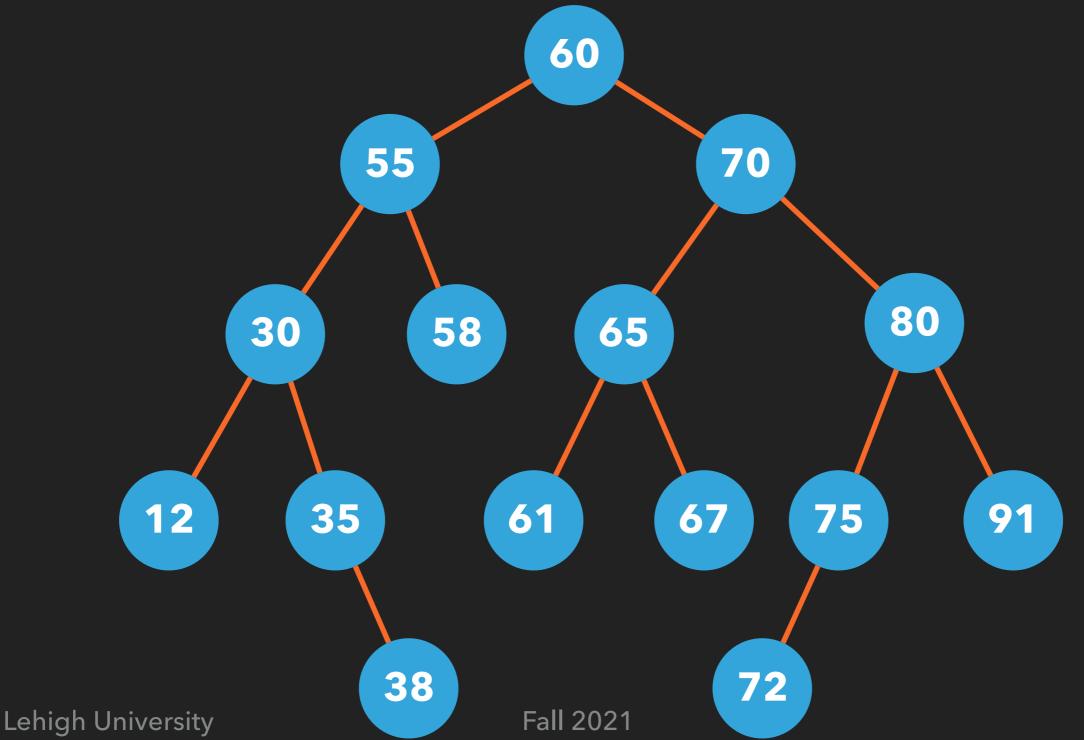
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BST - Search operation



BST - Search operation

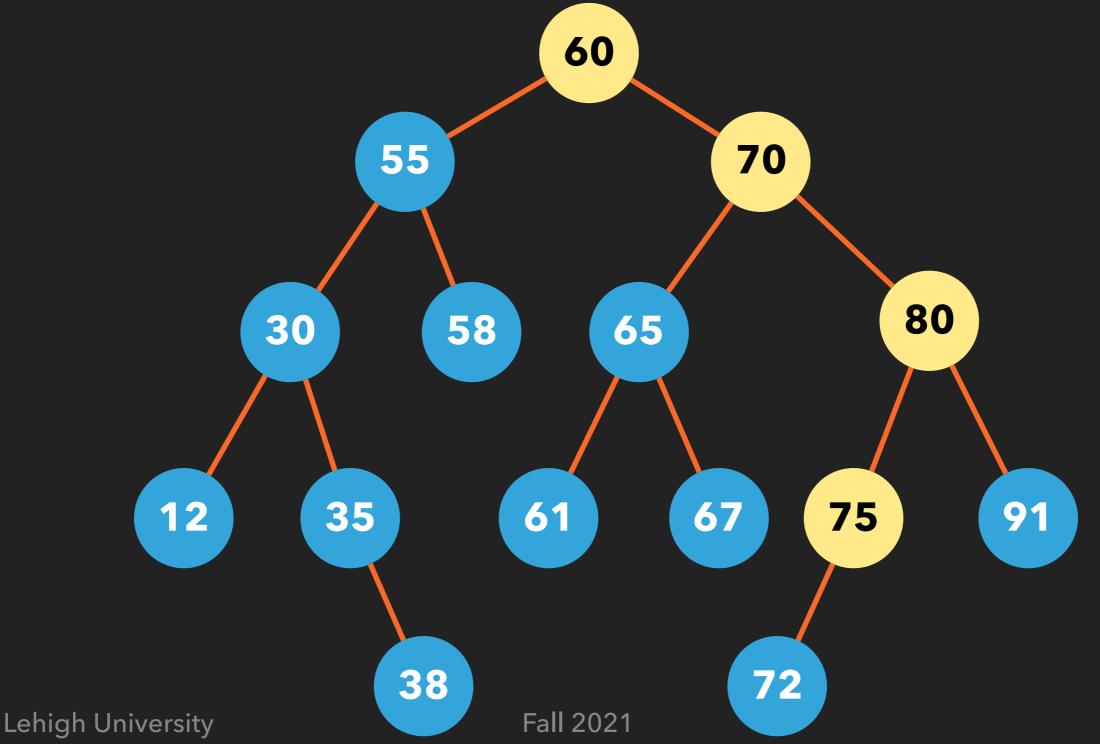
Search for the value 75



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BST - Search operation

Search for the value 75



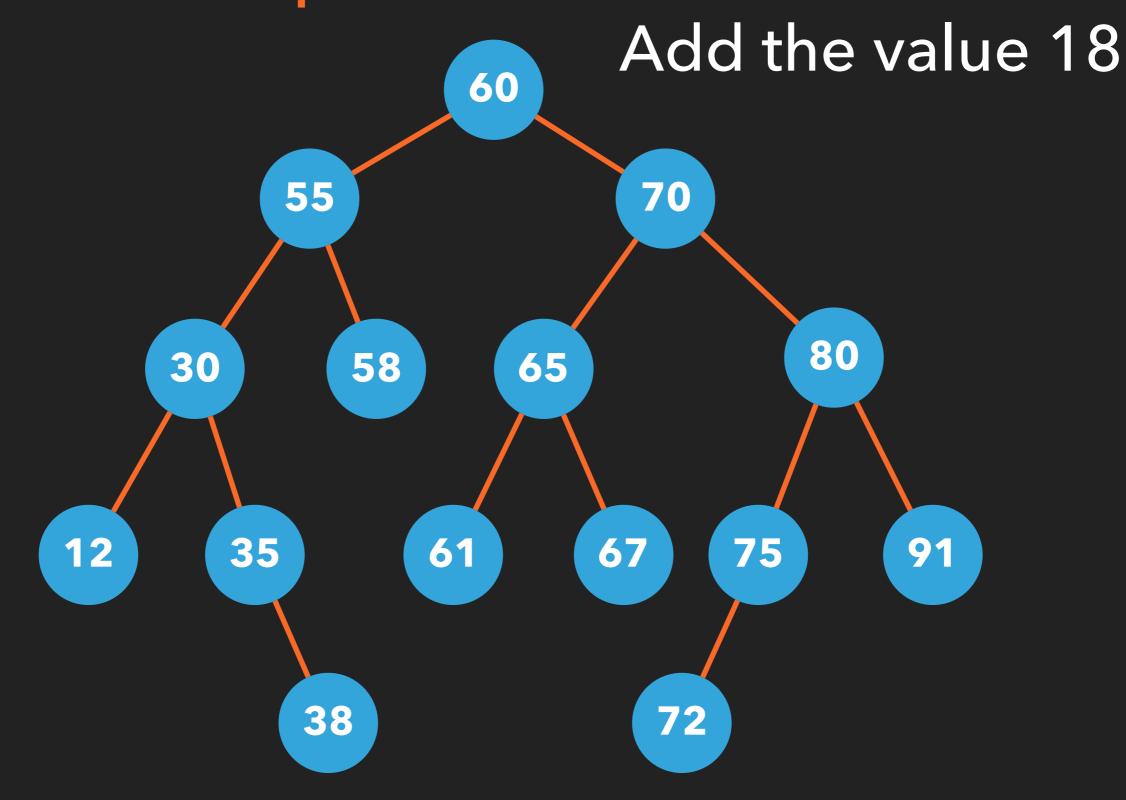
BST - Search algorithm

contains

```
boolean contains (item)
```

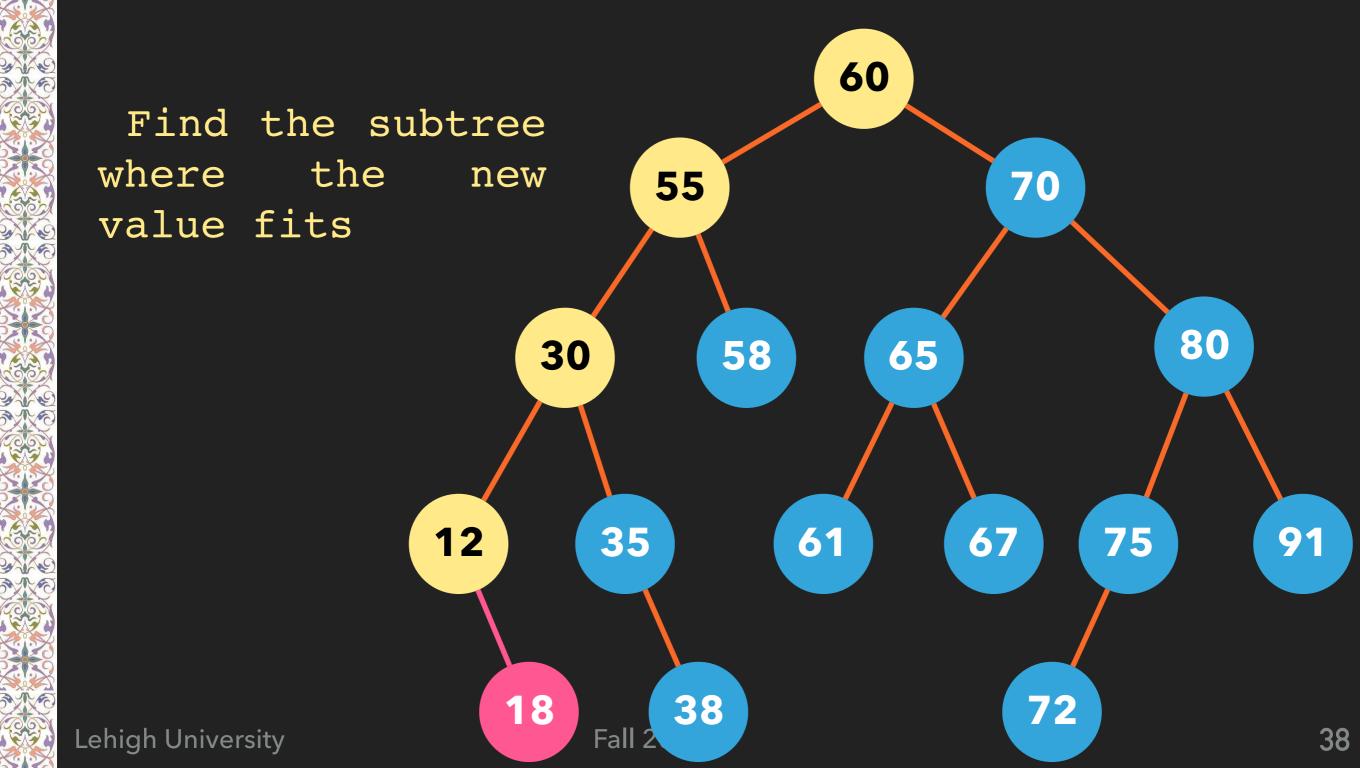
```
current node = root // start from the root
while(current node is not null){
   if(the value of the current node == item)
      return true
   else if (value of the current node > item)
      current node is set to its left child
   else
      current node is set to its right child
}
return false
```

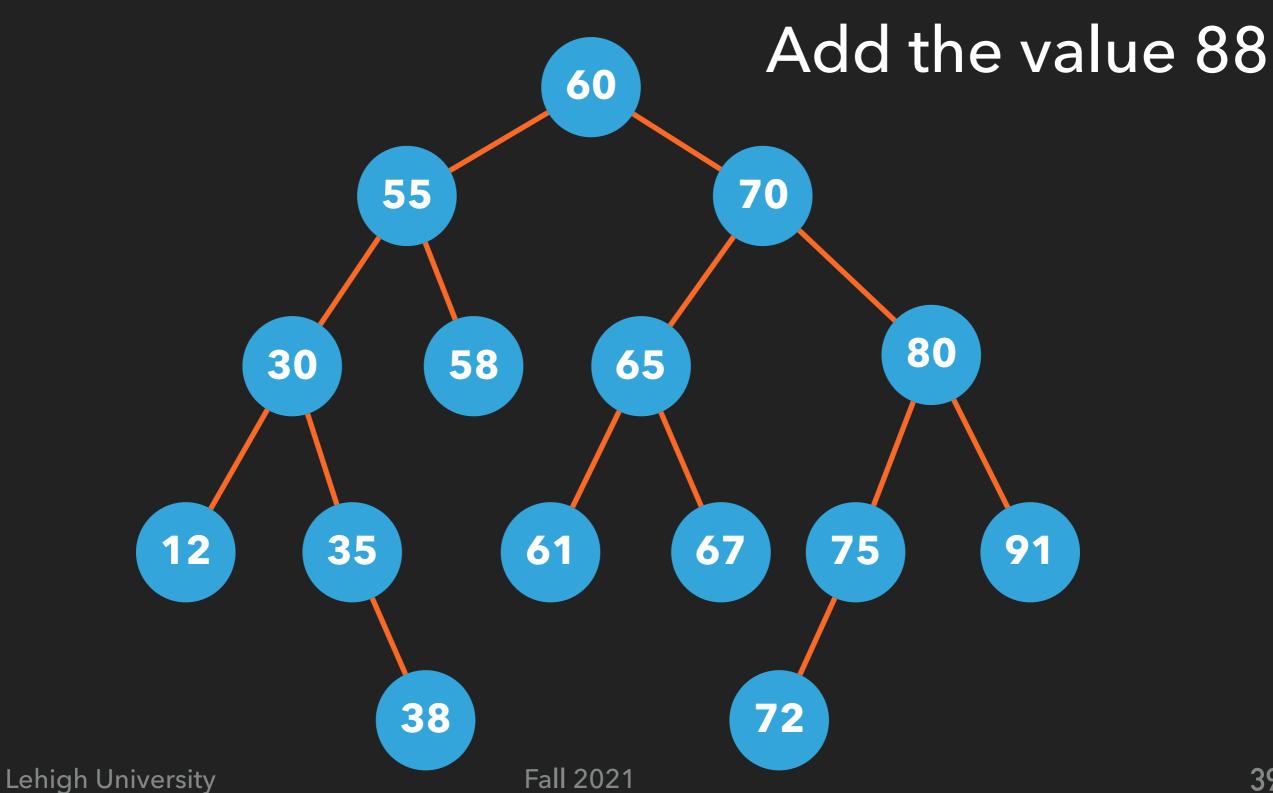
end contains

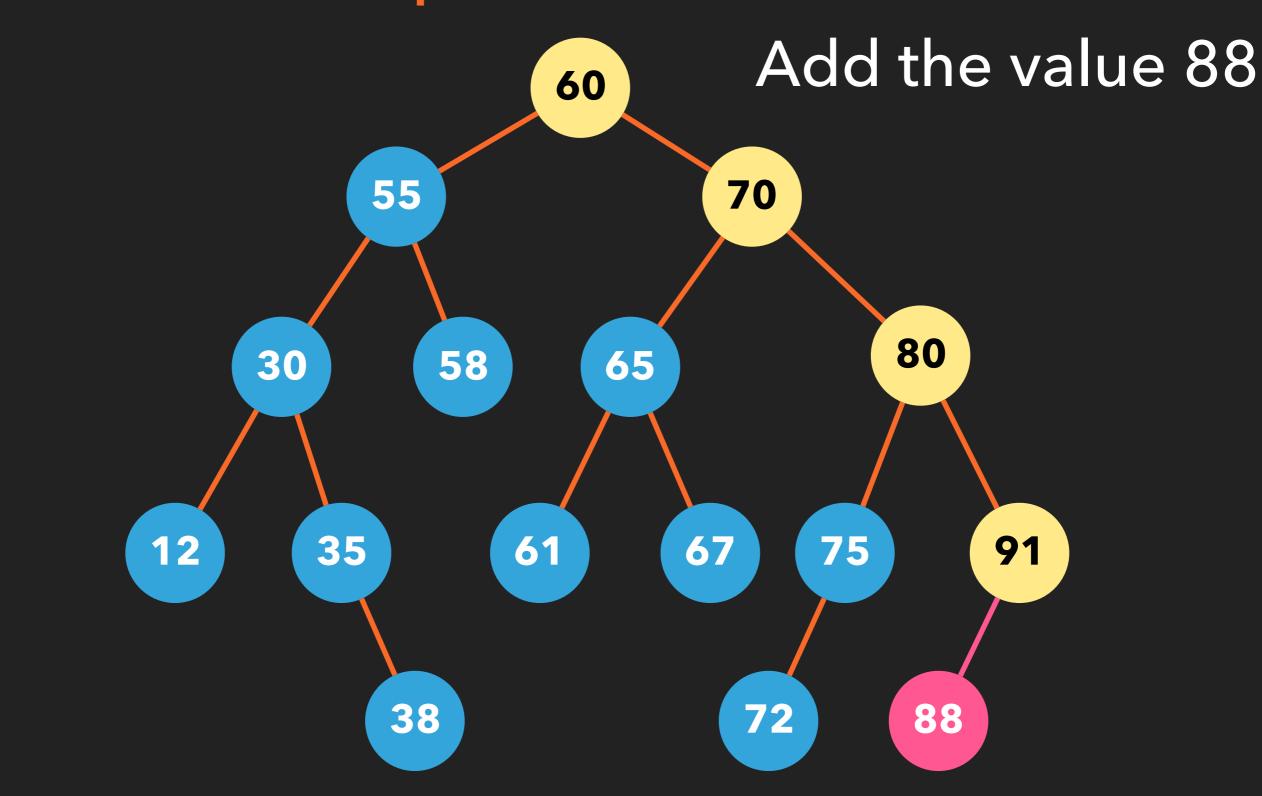


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Add the value 18



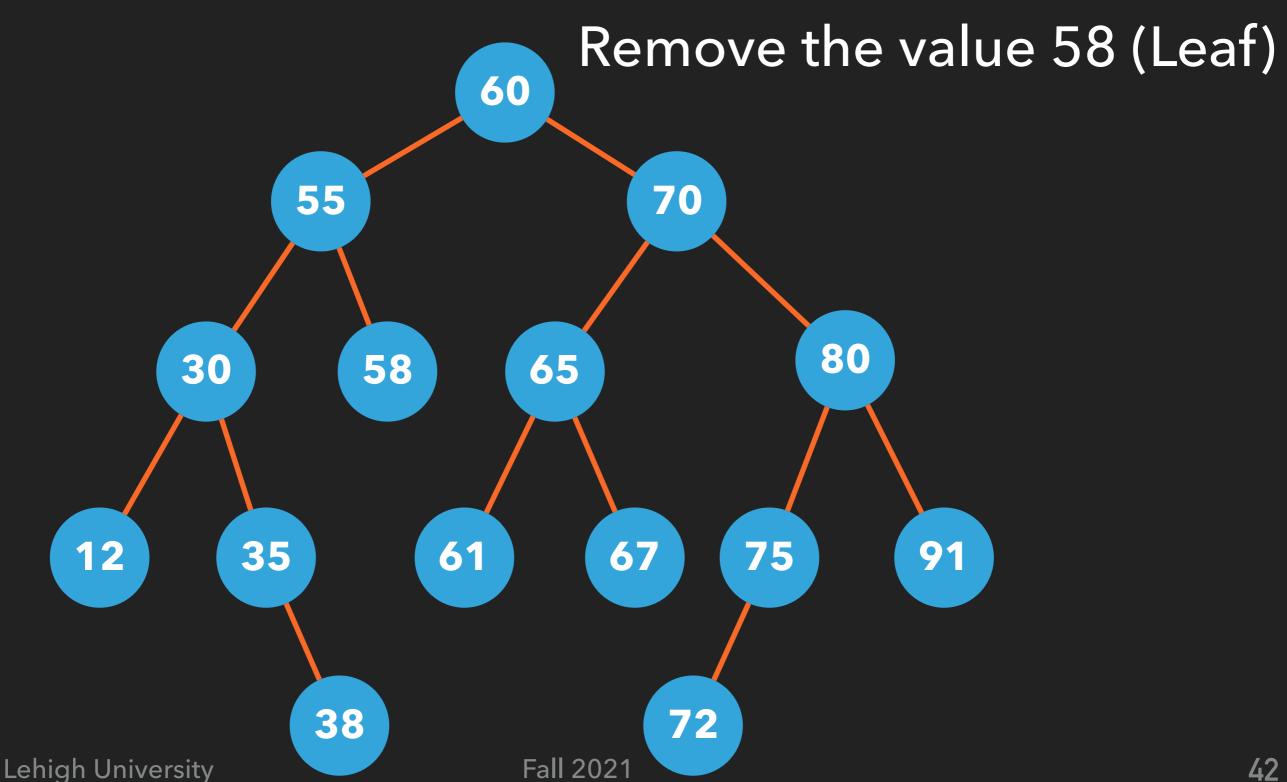


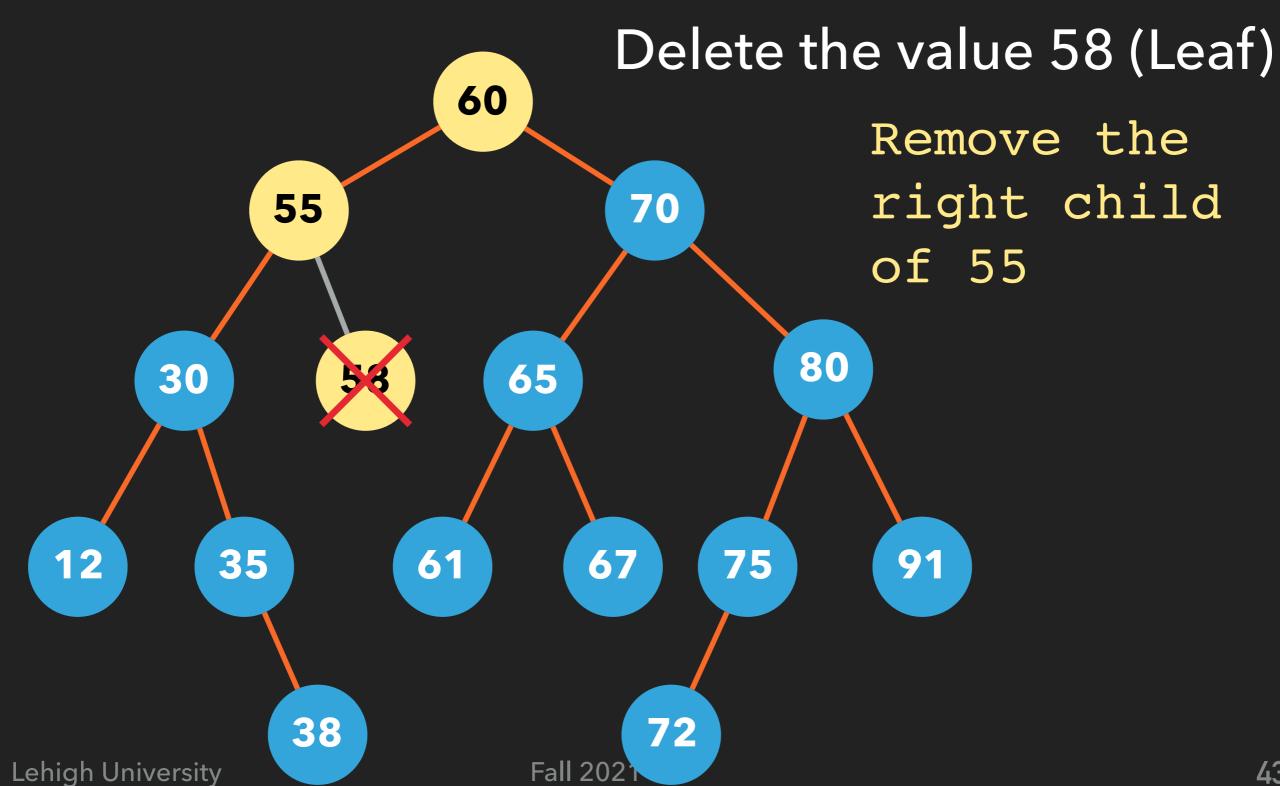


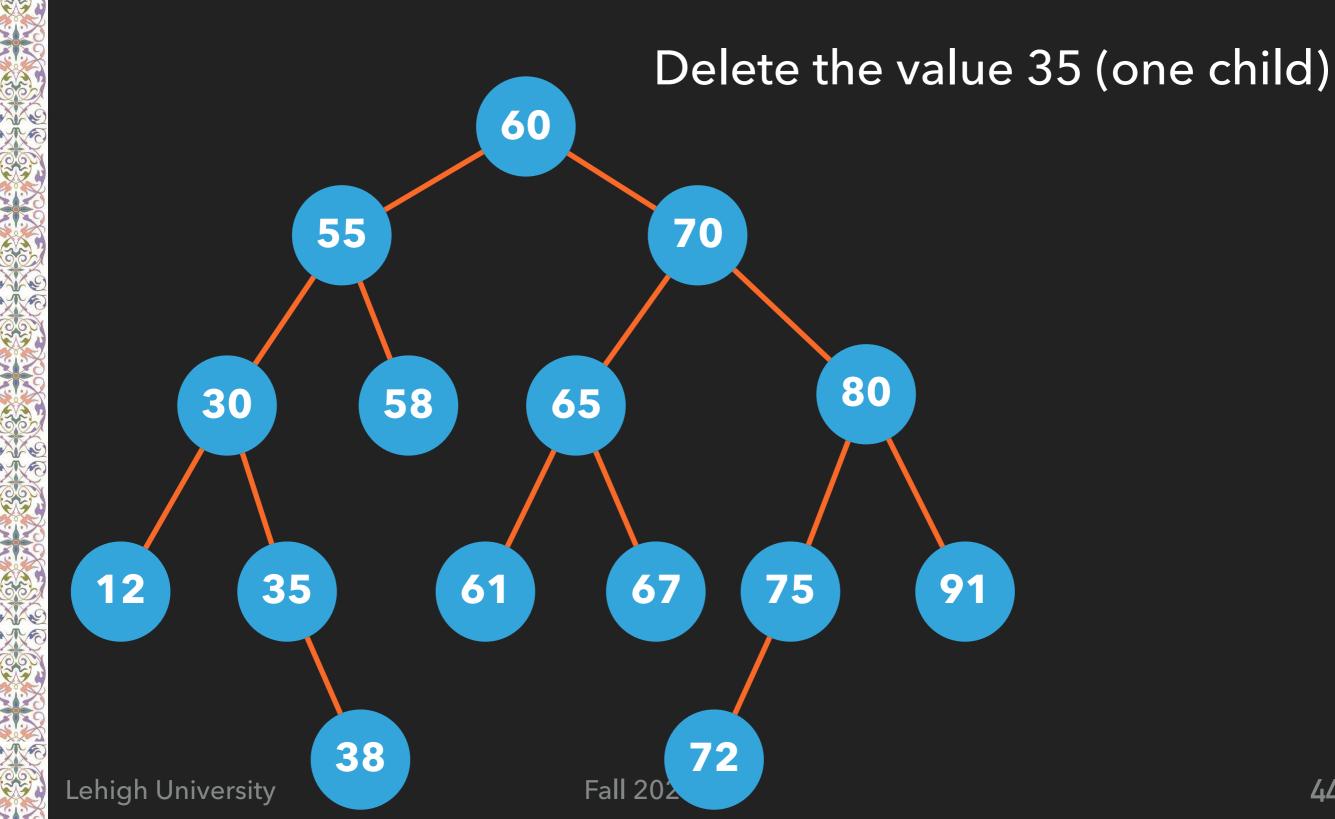
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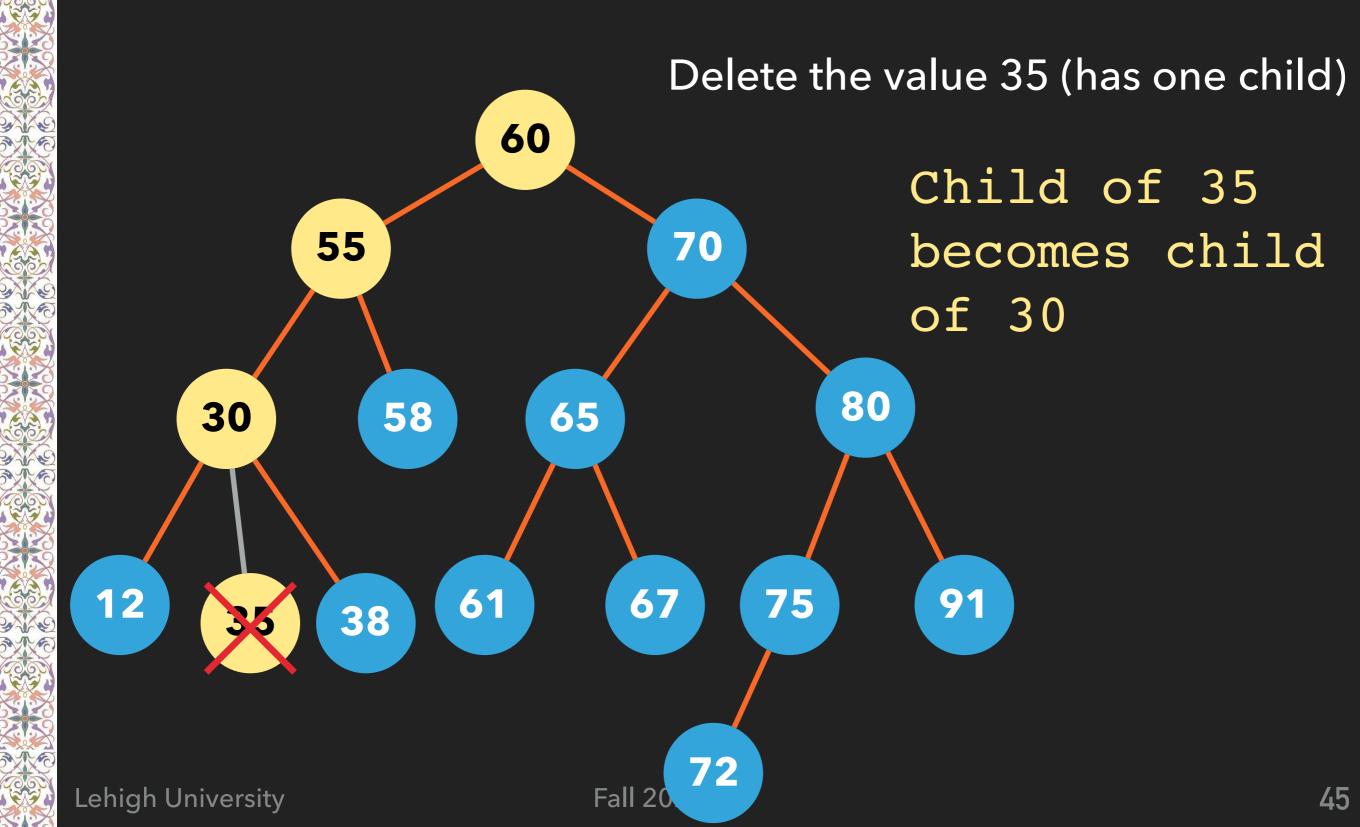
add

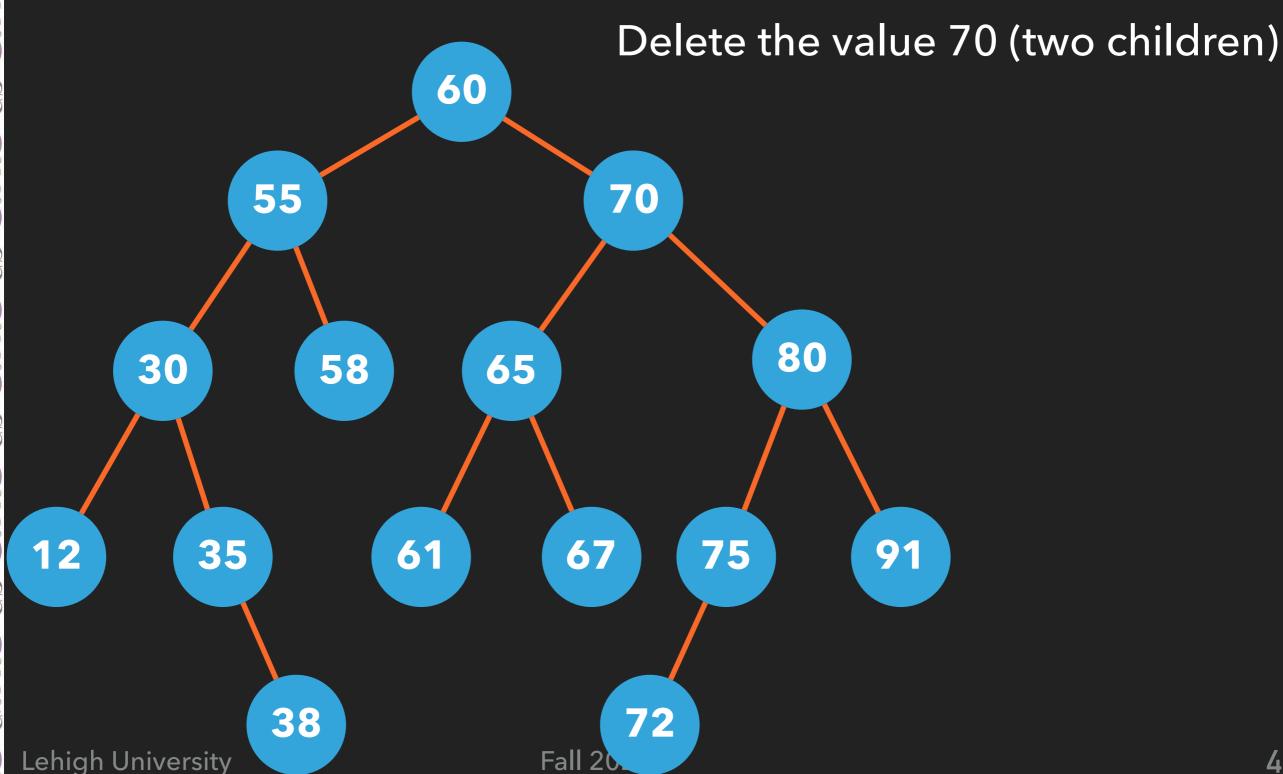
```
boolean add (item)
  current node = root
  while(current is not null){
    parent = current node
     if( the value of the current node == item)
        return false (duplicates are not allowed)
    else if (value of the current node > item)
        current is set to the left child
    else
        current node is set to the right child
   if (the value of the parent node > item)
      Create a left child to parent (value=item)
  else
      Create a right child to parent (value=item)
  end if
  return true
end add
```

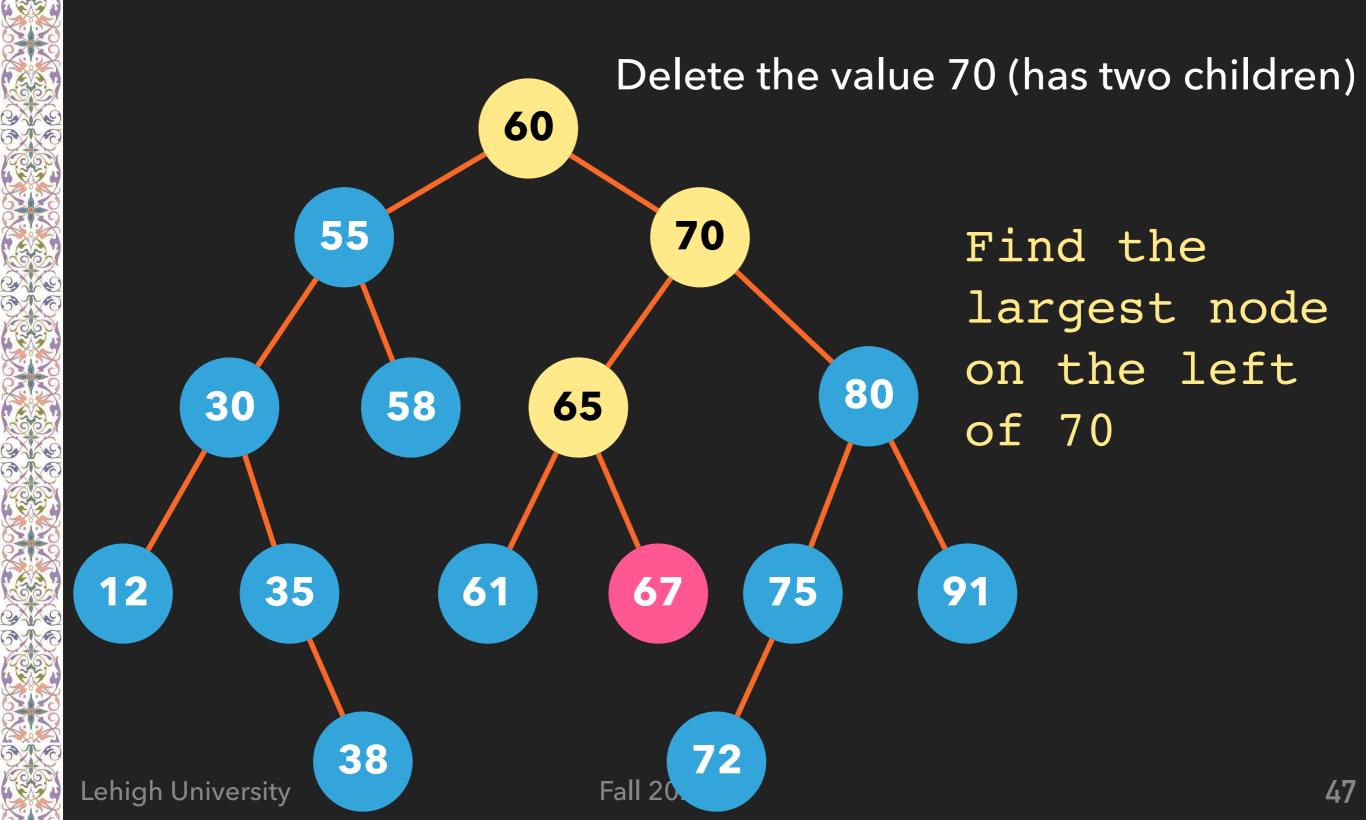


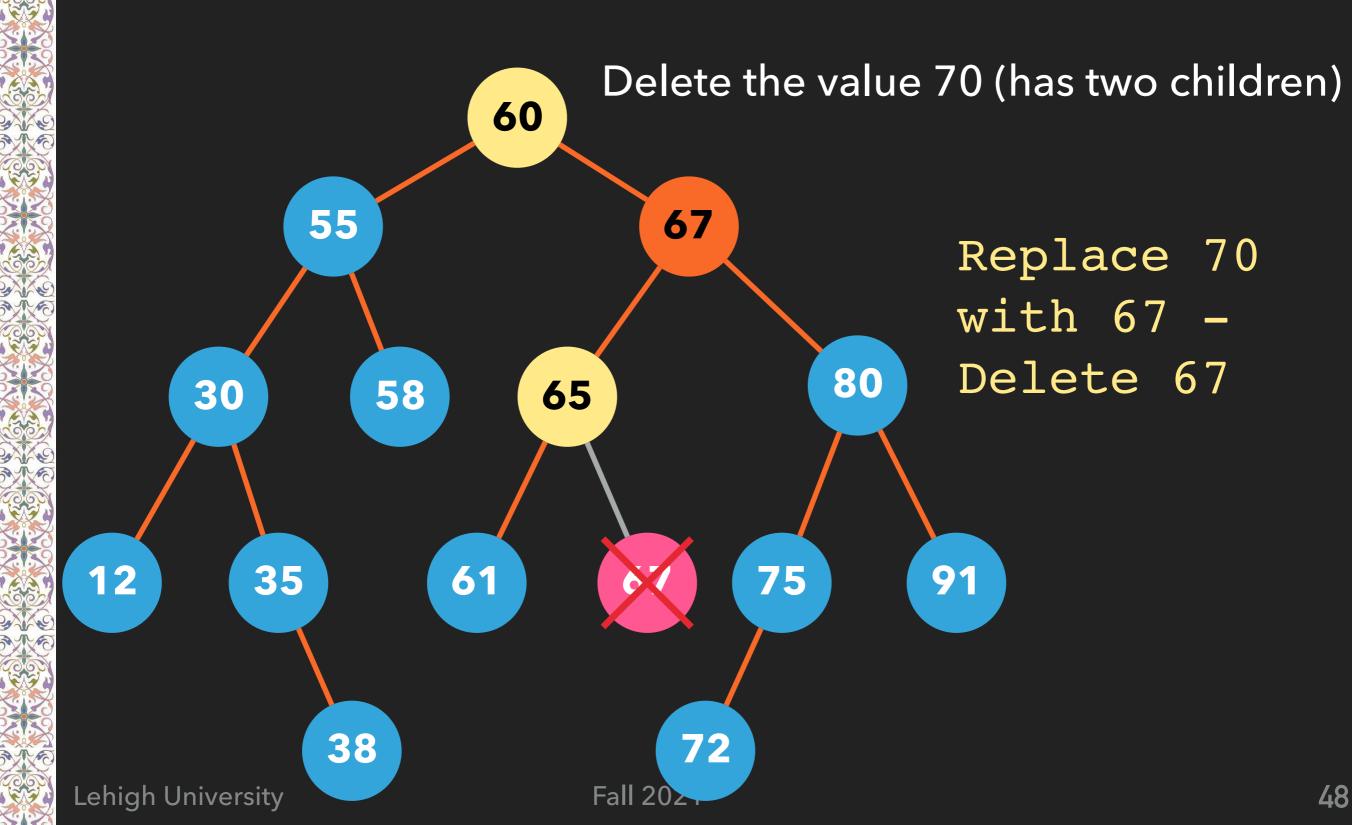












remove

```
boolean remove (item)
  node = search(item) // find node with value item first
  if (node == null)
     return false (item not found in the BST)
  else
   if (node has no children)
      remove link to node (parent points to null)
   else if (node has one child)
      replace node with node's child
   else if (node has two children)
      find the largest node on the left subtree of node
      copy the value of the largest node to node
      remove the largest node
   end if
  end if
  return true
end remove
```

Traversals

```
preorder(){
   preorder(root)}
preorder(node){
   print node
   preorder(left child of node)
   preorder(right child of node)}
```

```
inorder(){
  inorder(root) }
inorder(node){
  inorder(left child of node)
  Print node
  inorder(right child of node)}
```

```
postorder(){
  postorder(root)}
postorder(node){
  postorder(left child of node)
  postorder(right child of node)
  print node }
```

- BST may be implemented in two ways
 - Array Based BST
 - ◆ Linked BST

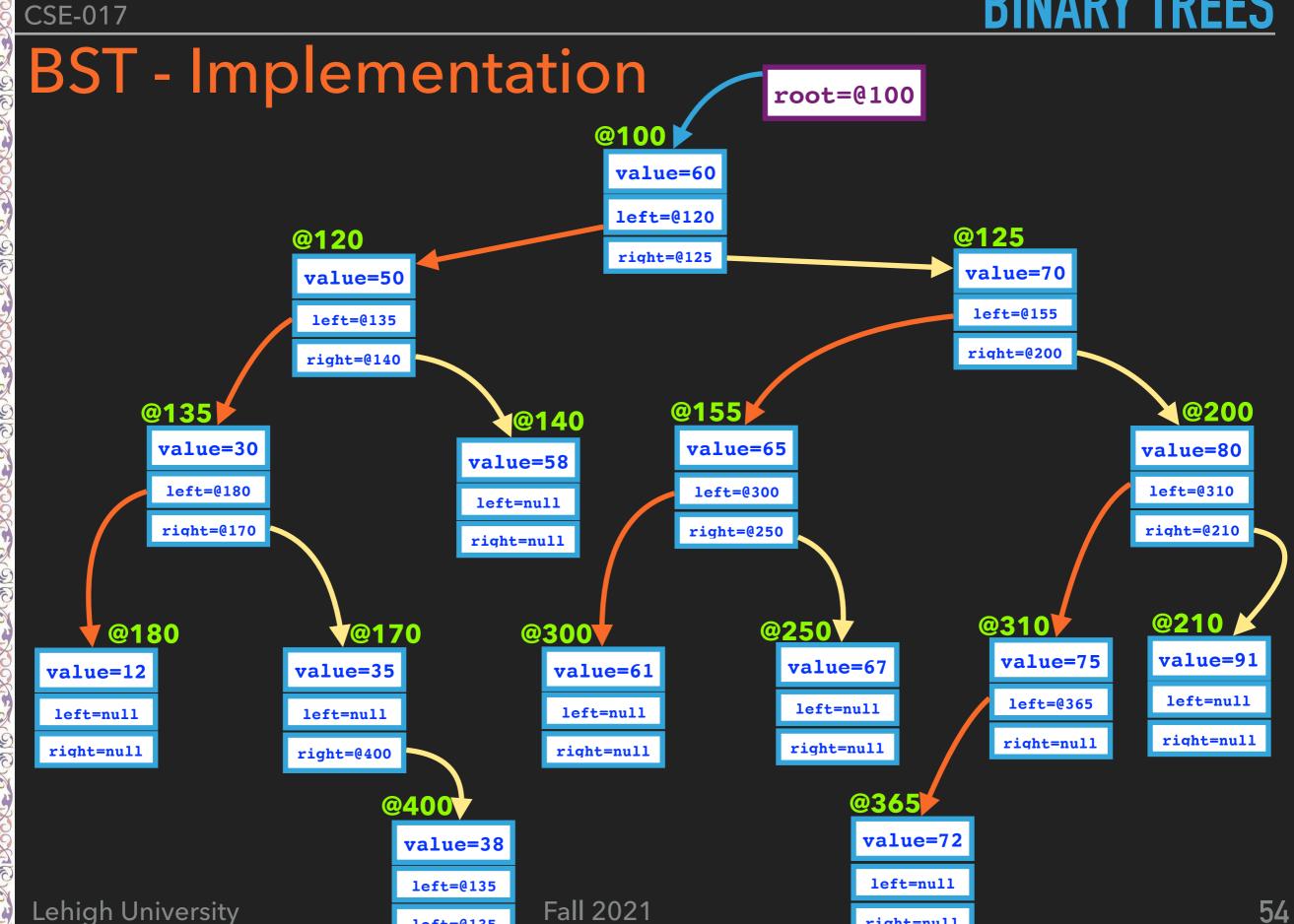
- Nodes of the tree are stored in an array
- Children of a node follow the node (at specific indices)

- ♦ Nodes of the tree are linked
- ◆ Every node has two references in addition to its value: left child and right child

TreeNode

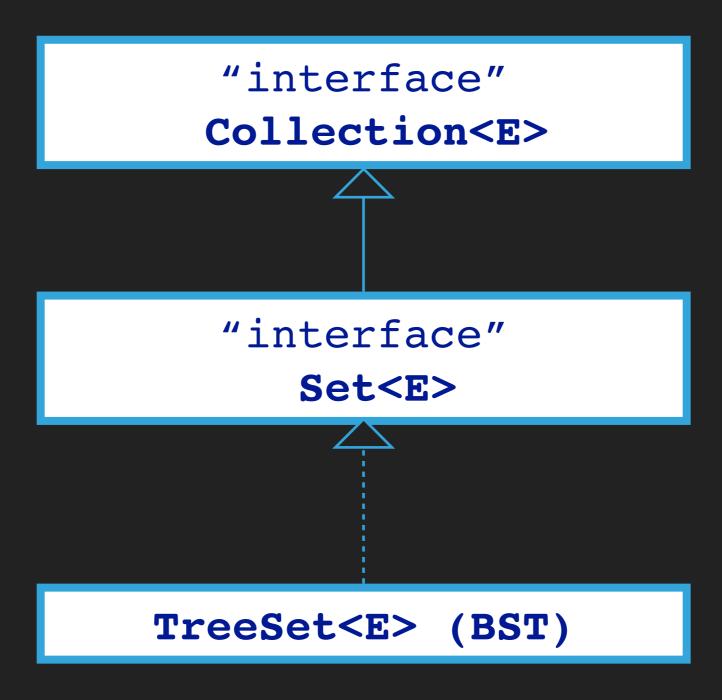
value left right

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right=null

left=@135



has

BST<E extends Comparable<E>>

-root: TreeNode
-size: int

```
+BST()
+size(): int
+isEmpty(): boolean
+clear(): void
+contains(E): boolean
+add(E): boolean
+remove(E): boolean
+inorder(): void
+preorder(): void
+postorder(): void
```

TreeNode

value: E

Left: TreeNode

Right: TreeNode

TreeNode(E val)

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```
public class BST<E extends Comparable<E>>> {
 private TreeNode root;
 private int size;
 private class TreeNode{
    E value;
    TreeNode left;
    TreeNode right;
    TreeNode(E val){
      value = val;
      left = right = null;
```

```
BST() {
   root = null;
   size = 0;
public int size() {
  return size;
public boolean isEmpty() {
  return (size == 0);
public void clear() {
  root = null;
```

```
// Search method
public boolean contains(E item) {
 TreeNode node = root;
 while (node != null) {
    if( item.compareTo(node.value) < 0)</pre>
      node = node.left;
    else if (item.compareTo(node.value)> 0)
      node = node.right;
    else
      return true;
  return false;
```

```
// Method add()
public boolean add(E item) {
  if (root == null) // first node to be inserted
     root = new TreeNode(item);
  else {
     TreeNode parent, node;
     parent = null; node = root;
    while (node != null) {// Looking for a leaf node
       parent = node;
       if(item.compareTo(node.value) < 0) {</pre>
          node = node.left; }
       else if (item.compareTo(node.value) > 0) {
          node = node.right; }
       else
          return false; // duplicates are not allowed
     if (item.compareTo(parent.value)< 0)</pre>
       parent.left = new TreeNode(item);
     else
       parent.right = new TreeNode(item);
  size++;
  return true;
```

```
// Method remove()
public boolean remove(E item) {
  TreeNode parent, node;
 parent = null; node = root;
 // Find item first
 while (node != null) {
      if (item.compareTo(node.value) < 0) {</pre>
        parent = node;
        node = node.left;
      else if (item.compareTo(node.value) > 0) {
        parent = node;
        node = node.right;
      else
        break; // item found
```

```
if (node == null) // item not in the tree
     return false;
// Case 1: node has no children
if(node.left == null && node.right == null){
   if(parent == null){ // delete root
     root = null;
   else{
     changeChild(parent, node, null);
```

```
// case 2: one right child
else if(node.left == null){
   if (parent == null){ // delete root
     root = node.right;
   else{
     changeChild(parent, node, node.right);
// case 2: one left child
else if(node.right == null){
   if (parent == null){ // delete root
     root = node.left;
   else{
     changeChild(parent, node, node.left);
```

```
// Case 3: node has two children
else {
   TreeNode rightMostParent = node;
   TreeNode rightMost = node.left;
   // go right on the left subtree
   while (rightMost.right != null) {
     rightMostParent = rightMost;
     rightMost = rightMost.right;
   // copy the value of rigthMost to node
   node.value = rightMost.value;
   //delete rigthMost
      changeChild(rightMostParent, rightMost,
                  rightMost.left);
size--;
return true;
```

```
private void changeChild(TreeNode parent,
      TreeNode node, TreeNode newChild) {
   if(parent.left == node)
    parent.left = newChild;
   else
    parent.right = newChild;
```

```
// Recursive method inorder()
public void inorder() {
 inorder(root);
private void inorder(TreeNode node) {
 if (node != null) {
   inorder(node.left);
   System.out.print(node.value + " ");
   inorder(node.right);
```

```
// Recursive method preorder()
public void preorder() {
 preorder(root);
private void preorder(TreeNode node) {
 if (node != null) {
   System.out.print(node.value + " ");
   preorder(node.left);
   preorder(node.right);
```

```
Recursive method postorder()
public void postorder() {
 postorder(root);
private void postorder(TreeNode node)
 if (node != null) {
   postorder(node.left);
   postorder(node.right);
   System.out.print(node.value + "
```

BST - Testing

Test.java

```
Testing the class BST
public static void main(String[] args){
  BST<String> bst = new BST<>();
  bst.add("Kiwi");
  bst.add("Strawberry");
  bst.add("Apple");
  bst.add("Banana");
  bst.add("Orange");
  bst.add("Lemon");
  bst.add("Watermelon");
  bst.inorder();
  bst.remove("Banana");
  System.out.println(bst.contains("Banana"));
  bst.inorder();
  bst.remove("Orange");
  bst.inorder();
  bst.remove("Kiwi");
  bst.inorder();
```

Performance of the BST operations

Method	Complexity
BST()	0(1)
size()	0(1)
clear()	0(1)
isEmpty()	0(1)
contains(E)	O(n) / O(log n)
add(E)	O(n) / O(log n)
remove(E)	O(n) / O(log n)
inorder()	O(n)
preorder()	O(n)
postorder()	O(n)

BST - Testing

Test.java

```
Testing the class BST
public static void main(String[] args){
  BST<String> bst = new BST<>();
  bst.add("Apple");
  bst.add("Banana");
  bst.add("Kiwi");
  bst.add("Lemon");
  bst.add("Orange");
  bst.add("Strawberry");
  bst.add("Watermelon");
  bst.inorder();
```

Order of the added values affects the shape of the tree

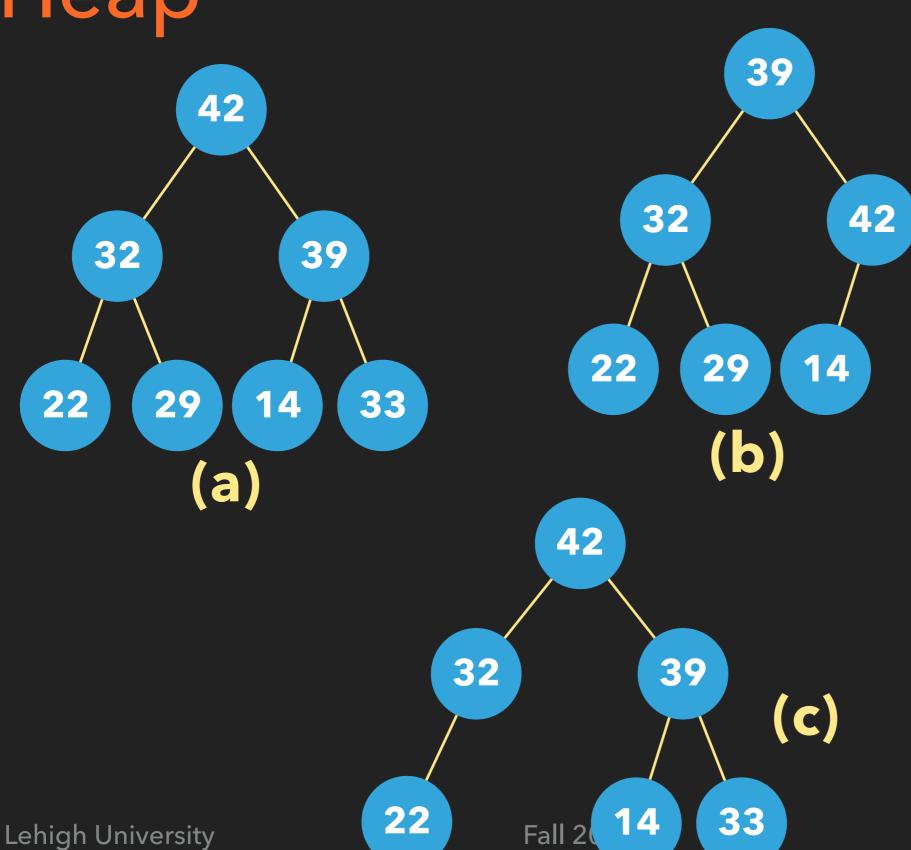
Summary

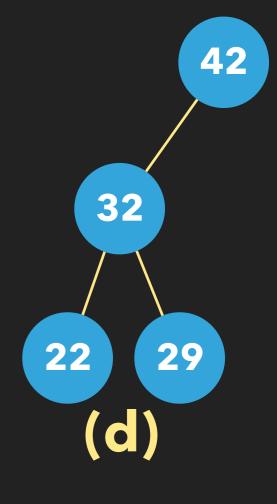
- Binary trees and binary search trees
- ♦ Operations: Search, Add, Remove, Traversals
- Implementation Linked Nodes
- Order of add operations has an effect on the shape of the BST

- Special binary tree
 - Complete binary tree All the levels are filled except the last level
 - All leaves on the last level are placed leftmost
 - ◆ Every node is greater than or equal to any of its children (Max Heap) [Min Heap: less than or equal]
 - Used for efficient sorting

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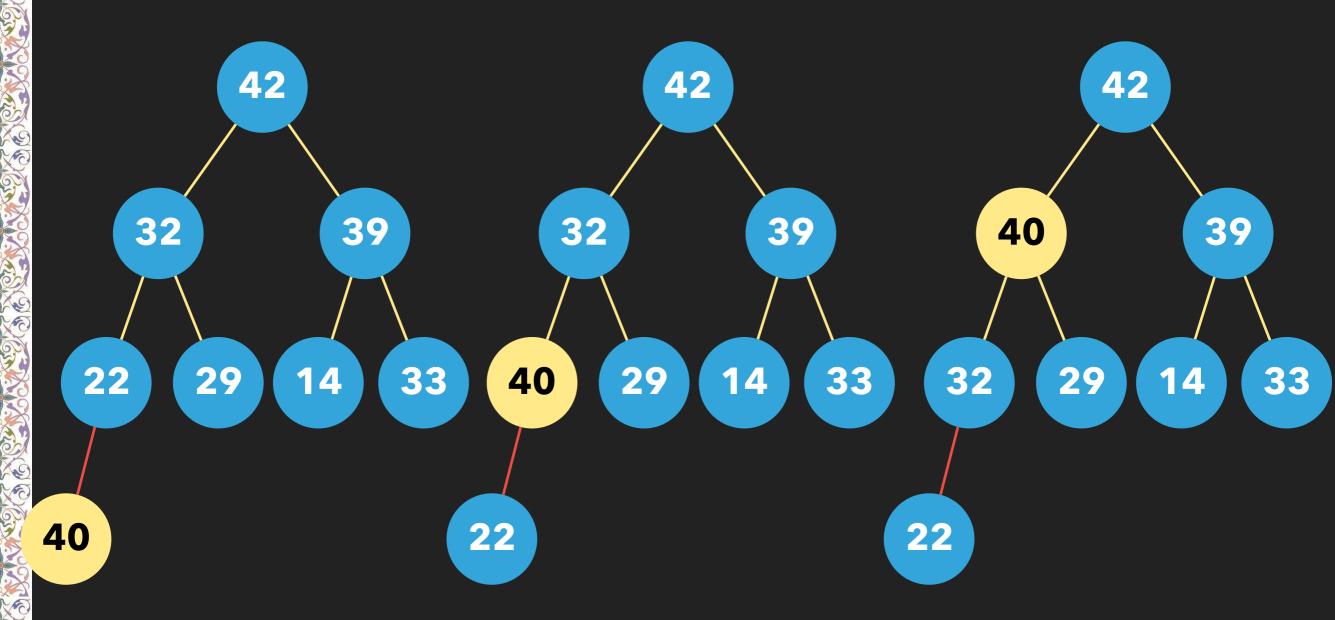


Two main operations on the Heap

Adding a new node while keeping the heap properties

Removing a node while keeping the heap properties

Adding a new node to the heap (40)



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Adding a new node to the heap

```
Algorithm add
```

Add the new node at the end of the heap

Current node = added node

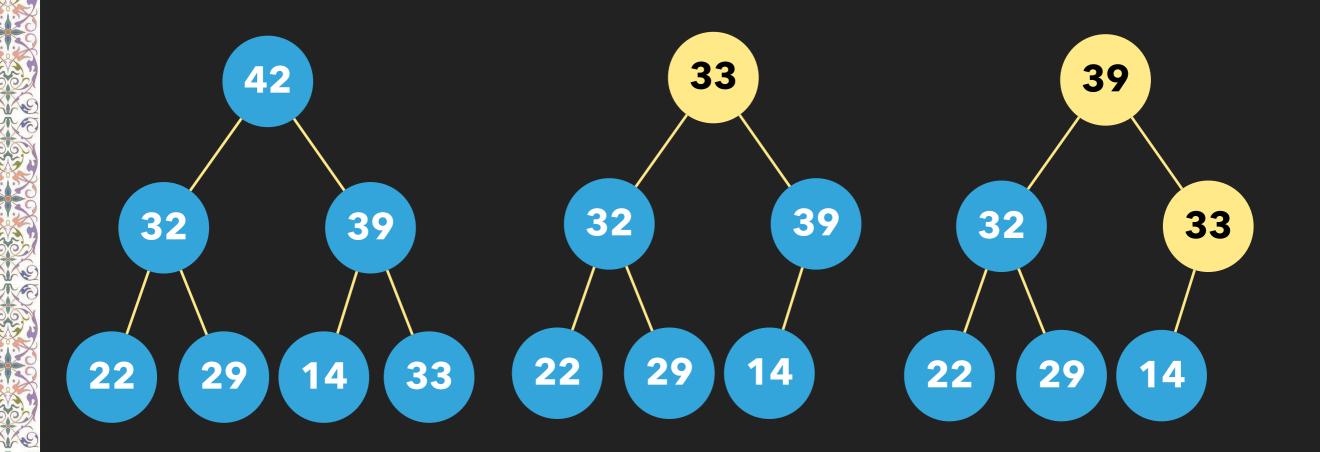
While (current node > its parent)

Swap current node with its parent

Current node becomes the parent

End

ightharpoonup Removing a node from the heap (42)



Removing a node from the heap (root)

Algorithm remove

Move the last node to replace the root

Current node = root

While (current node < its children)

Swap current node with the largest of its children

Current node becomes the largest child

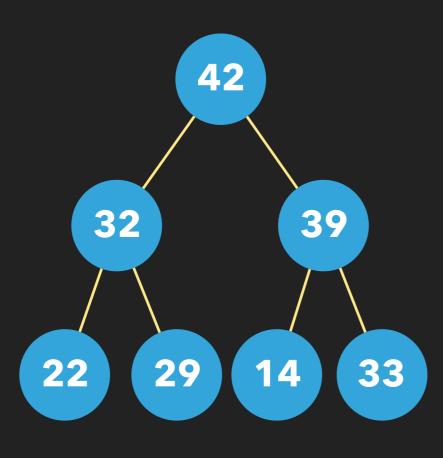
End

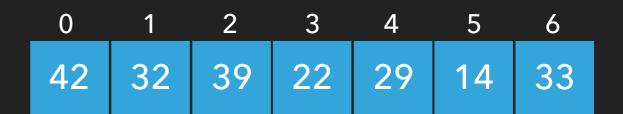
Heap implementation

ArrayList to store the heap nodes

Easy access to children and parent

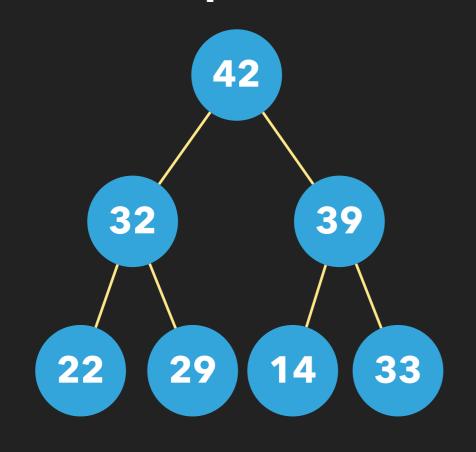
Heap implementation

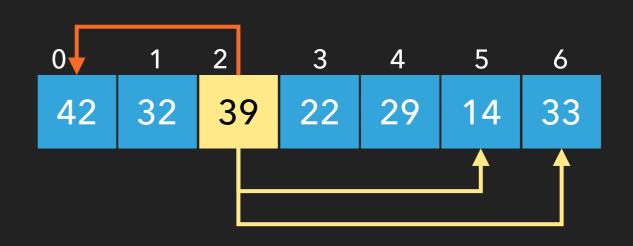




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Heap data structure





```
IndexOf(Parent) = (IndexOf(current) - 1) / 2
```

```
IndexOf(Left child) = 2 * IndexOf(current) + 1
IndexOf(Right child) = 2 * IndexOf(current) + 2
```

```
Heap<E extends Comparable<E>>
-list: ArrayList<E>
+Heap()
+add(E): void
+remove(): E
+contains(E): boolean
+size(): int
+isEmpty(): boolean
+clear(): void
+toString(): String
```

Heap.java

```
public class Heap<E extends Comparable<E>> {
  private ArrayList<E> list;
  public Heap(){
    list = new ArrayList<>();
  public int size(){
    return list.size();
 public boolean isEmpty(){
    return list.isEmpty();
 public void clear(){
     list.clear();
 public String toString(){
    return list.toString();
```

```
public boolean contains(E item) {
  for(int i=0; i<list.size(); i++) {
    if(list.get(i).equals(item))
      return true;
  }
  return false;
}</pre>
```

```
Heap.java
public void add(E item) {
    list.add(item); //append item to the heap
    int currentIndex = list.size()-1;
    //index of the last element
   while(currentIndex > 0) {
      int parentIndex = (currentIndex-1)/2;
      //swap if current is greater than its parent
        E current = list.get(currentIndex);
        E parent = list.get(parentIndex);
      if(current.compareTo(parent) > 0) {
        list.set(currentIndex, parent);
        list.set(parentIndex, current);
      else
        break; // the tree is a heap
      currentIndex = parentIndex;
```

```
public E remove() {
                                   Heap.java
 if(list.size() == 0) return null;
 //copy the value of the last node to root
 E removedItem = list.get(0);
 list.set(0, list.get(list.size()-1));
 //remove the last node from the heap
 list.remove(list.size()-1);
 int currentIndex = 0;
```

Heap.java

```
while (currentIndex < list.size()) {</pre>
  int left = 2 * currentIndex + 1;
  int right = 2 * currentIndex + 2;
  //find the maximum of the left and right nodes
  if (left >= list.size())
     break; // no left child
  int maxIndex = left;
  E max = list.get(maxIndex);
  if (right < list.size()) // right child exists</pre>
    if(max.compareTo(list.get(right)) < 0)</pre>
        maxIndex = right;
```

Heap.java

```
// swap if current is less than max
 E current = list.get(currentIndex);
 max = list.get(maxIndex);
 if(current.compareTo(max) < 0){</pre>
  list.set(maxIndex, current);
  list.set(currentIndex, max);
  currentIndex = maxIndex;
else
  break; // the tree is a heap
return removedItem;
```

Test.java

```
public class TestBST {
 public static void main(String[] args) {
    Heap<String> heap = new Heap<>();
    heap.add("Apple");
    heap.add("Banana");
    heap.add("Kiwi");
    heap.add("Lemon");
    heap.add("Orange");
    heap.add("Strawberry");
    heap.add("Watermelon");
    System.out.println("Heap: " + heap.toString());
    System.out.pritnln("Removed: " + heap.remove());
    System.out.println("Heap: " + heap.toString());
    System.out.println("Heap contains Pear?: "
                          + heap.contains("Pear"));
```

Performance of the Heap operations

Method	Complexity
Heap()	0(1)
size()	0(1)
clear()	0(1)
isEmpty()	0(1)
add(E)	O(log n)
remove(E)	O(log n)
contains(E)	O(n)
toString()	O(n)

Summary

- Binary trees Special binary trees: BST, Heap
- Operations: Search, Add, Remove, Traversals
- Implementation Linked Nodes for BST, ArrayList for Heap
- Performance of the operations on BST/Heap
- ST height determined by the order of insertion of the nodes
- Heap is a balanced binary tree (height = log(number of nodes))