# PULL-BACK AND PUSH-FORWARD

# COORDINATE TRANSFORMATION

For a surface Z, X:Ω → X(Ω) open ≤ Z as a local parametrization is a diffeomorphism (=> d(x-1)xrp==(dx)p-1)

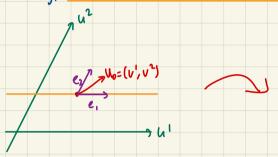
No ← > p

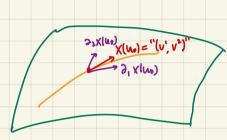
⇒ dX: Tu. Ω → Tp = 3 a linear nomorphism

Mr US3

- both are (v2)

Actually, v'e, +v'ez -> v'd, x(u0)+v202x(u0) as visible betw





Hence, we can simply use the same coordinates

### DEFINITION OF PULL-BACK/PUSH-FORWARD

Notation: We write F\*f=fof (dual space), then a pull back is f\*: T\*p1 \(\xi\_2\) \rightarrow Tp \(\xi\_1\), push forward: Ifp: Tp\(\xi\_1\) \rightarrow Tp\(\xi\_2\)

#### REMARK

Consider  $F: \mathbb{Z}_1 \longrightarrow \mathbb{Z}_1$   $\chi S \uparrow \qquad \chi S \uparrow$  $\Omega_1 \cdots \Omega_n$ 

dFp: TpZ, → TF(p) Zz, f: Zz → R, F\*f=foF: Z, → R

Then for WE TEXPI Zz (i.e. W: TEXPI Zz > IR 3 a linear function), F\* Wp (v) := WEXPI (dfp(v)) ER

We have: F\* wp(QV,+pVz) = QF\* wp(V,)+BF\* wp(Uz), so F\* cope Tp\*Z, (F\*:TFip) ∑z → Tp\*Z, 3 lnear)

# PROPERTIES OF PULL-BACK

For 1: 22 -> R = 2fe Trip, 22, pf2, Ap) & 22, (f\* 2f) (v) = (dfrip) odfp) (v) = d(fo F) (v)

Hence, we have this pull-back relationship: P\*df=d(foF)=dF\*f

Say 2, F > 22 6>23, f: Z3 -> R

Then, (6 · F)\*f = f · G · F = F\* · (f · G) = F\* · G\* · f => (6 · F)\*= F\* · G\*

Notice, this implies twe To-Fip Zs, G\*We Trip Zz, (G.F)\* wp(v)=F\*(G\*w), (v) (smilar derection tibrid (F.G))= dGrap od Fp)

## EXAMPLE

Consider  $\Sigma_1 \xrightarrow{\mathsf{F}} \Sigma_2$   $\times \uparrow S \xrightarrow{\mathsf{F}} Y \uparrow S$  $\Omega_1 \xrightarrow{\mathsf{M}} \Omega_2$ 

[ h/u', u2): Z, ->(R, then th= 3h, dn'+3h dn2

Here, for f: 22 > R, F\* df= d(f . F) = = (f . F) dn' = d; f d; F) dn'

In particular, take five. Then, F\*dvk= 8 to 3: Fidni = 0: F\*dni = F\*(w=F\*(w=dvi) = w; F\*(dvi) = Wj(2; Fidni)

Hence,  $\omega_j \longmapsto \partial_i F^j \omega_j$   $\omega \longmapsto \partial_i F^j \omega_j d\omega^i \Rightarrow (\omega_i) \longmapsto (dF)^T (\omega_i)$ 

A The pull-back corresponds to the transpose of tangent map!

# BILINEAR FORMS AND TENSOR PRODUCTS

#### DEFINITION

Say we have f, q ETp\* Z. Then, we define (f@g)(v, w)=(f(v), q(w)) for any v, weTp Z. This is a bilinear form by def.

In fact, from Linear Algebra (I), we know f &g can be generated by a basis: {dir &dui} > 7 t 2 ⊗ Tp\* Z = span{ f θ g | f, g ∈ Tp\* Σ]

## PROPERTIES

Say F: Z, → Sz, ME Tp = Zz @ Tp = Zz Define F\*m(v, w):=m(JF(v), JF(w)), then F\*: 7\*Ap, 22 @ T\*p, Z2 → T\*Fy, Z, Ø T\*p, Z, ⇒ T\*meTp Z, Ø TpZ,

# KEY EXAMPLE (INCLUSION MAP)

i: Z --- (R3 (mchson map) (u1, u2)

Then, di: T, 2 --> T, Z \( \text{R}^3\) v.9: ←→ v; 9: X

# FIRST FUNDAMENTAL FORM

Define h(V, W):= V·W, V, WER3

r Supposed to be dilu), dilw)

We say for g= ith, g(v, w)=h(dx(v), dx(w)) = dx(v). dx(w)

### DEFINITION

 $d(\Lambda'M) := qX(\Lambda) \cdot 7X(M)$ 

Hence, glv, w) = v'w' g(di, dj), '2 (x(di) = dix

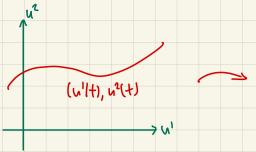
Actually, g is an inner product, i.e. it is a symmetric, positive definite. Also, (Tuo 1, guo) ⊆ (T, Z, -)

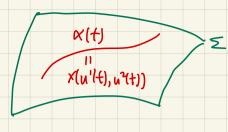
DEFINITION

We can define  $(v, w) = (v' v^2) \begin{pmatrix} g_1 & g_{12} \\ g_2 & g_{22} \end{pmatrix} \begin{pmatrix} w' \\ w^2 \end{pmatrix}$ 

In fact, the matrix can be rewritten as: (FE), E=D,X·D,X, F=D,X·DzX, G=DzX·DzX

Moreover, the first fundamental form is defined as (\(\frac{1}{2}\) \(\frac{1}{2}\), \(\frac{1}{2}\), \(\frac{1}{2}\) = \(\frac{1}{2}\) \(\frac{1}{2}\) \(\frac{1}{2}\).





Notice, a'(+)= \$ X(ul+)) = 22; X(ul+)) ui(+)

$$\int_a^b |\alpha'(+)| dt = \int_a^b \sqrt{Z(\partial_i X \dot{u}^i)(\partial_j X \dot{u}^j)} dt = \int_a^b \sqrt{g_{ij} \dot{u}^i \dot{u}^j} dt$$

In terms of inner product,
$$\int_{a}^{b} |\alpha'(t)| dt = \int_{a}^{b} \sqrt{(\dot{u}, \dot{u})} dt = \int_{a}^{b} |\dot{u}|_{q} dt$$

(In fact, the Jeterminant can be used to defermine area similarly)