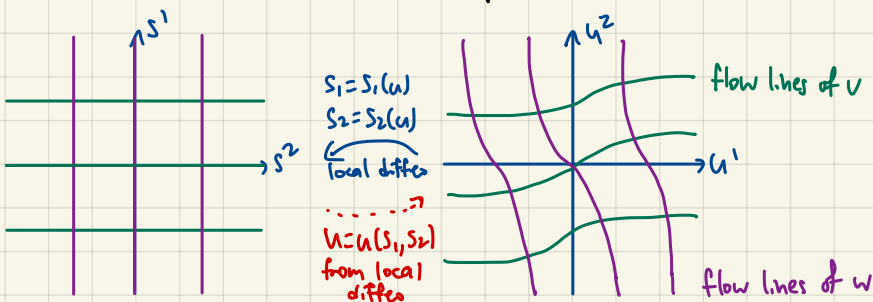


THEOREM

Let $\{v, w\}$ be linearly independent tangent vector fields on Σ near $p \in \Sigma$. Then, \exists local param of Σ near p , s.t. the coord lines are the flow lines of v, w $\{v(p), w(p)\}$



Proof — level set val?

Let $s_1 =$ "index" of the flow lines of v
 $s_2 =$ "index" of the flow lines of w

$$ds_1(v)|_p = 0, ds_1(w)|_p = 0 \Rightarrow ds_1|_p = 0 \quad * (\because s_1 \text{ is a regular function})$$

$$\text{So, } ds_1(v)|_p = 0 \quad ds_2(v)|_p \neq 0$$

$$ds_1(w)|_p \neq 0 \quad ds_2(w)|_p = 0$$

$$\Rightarrow \begin{pmatrix} \frac{\partial s_1}{\partial u^1} & \frac{\partial s_1}{\partial u^2} \\ \frac{\partial s_2}{\partial u^1} & \frac{\partial s_2}{\partial u^2} \end{pmatrix} \begin{pmatrix} v^1 & w^1 \\ v^2 & w^2 \end{pmatrix} = \begin{pmatrix} 0 & * \\ * & 0 \end{pmatrix} \quad \square$$

REMARK

$$\frac{\partial}{\partial s_2} u(s_1, s_2) = Du(\frac{\partial}{\partial s_2}) = \lambda v(u)$$

$$\text{Similarly, } \frac{\partial}{\partial s_1} u(s_1, s_2) = \mu w(u)$$

COROLLARY

$$\text{If } v \perp w, \text{ then } X(u(s_1, s_2)) = \tilde{X}(s_1, s_2), \quad \frac{\partial \tilde{X}}{\partial s_1} \perp \frac{\partial \tilde{X}}{\partial s_2} \Rightarrow \tilde{g} = \begin{pmatrix} g_{11} & 0 \\ 0 & g_{22} \end{pmatrix}$$

Let u be local coords.

If $\{\frac{\partial}{\partial u^1}, \frac{\partial}{\partial u^2}\}$, then we perform Gram-Schmidt, so $V = \frac{\partial}{\partial u^1} = (1, 0)$, $W = \frac{\partial}{\partial u^2} - \frac{\langle \frac{\partial}{\partial u^2}, \frac{\partial}{\partial u^1} \rangle}{\langle \frac{\partial}{\partial u^1}, \frac{\partial}{\partial u^1} \rangle} \frac{\partial}{\partial u^1}$

$$= \begin{pmatrix} 0 \\ 1 \end{pmatrix} - \frac{\begin{pmatrix} 0 & 1 \end{pmatrix} \begin{pmatrix} g_{11}(u) & g_{12}(u) \\ g_{12}(u) & g_{22}(u) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}}{\begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} g_{11}(u) & g_{12}(u) \\ g_{12}(u) & g_{22}(u) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}}$$

EXAMPLE

Let P be a nonumbilical point ($k_1 < k_2$) $\Rightarrow V \perp W$ (principal directions)

ISOMETRIES

SETTING IN \mathbb{R}^3

Let $\phi: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a diffeomorphism

If it is length-preserving, then ϕ must be a rigid motion, where $\phi(x) = Ax + b$, $A \in O_3$ orthon matrix

PROPERTY IN GENERAL Σ

Let $\phi: \Sigma \rightarrow \tilde{\Sigma}$ be a diffeomorphism. If it's length-preserving, i.e. $L(\phi(\gamma)) = L(\gamma) \quad \forall \gamma$

$$\text{Param } \gamma \text{ w.r.t. } t, L(\phi(\gamma)) = L(\gamma) \Rightarrow \int_a^b |\frac{d}{dt}(\phi(\gamma(t)))| dt = \int_a^b |\gamma'(t)| dt \Rightarrow |\frac{d}{dt} \phi(\gamma(t))| = |\gamma'(t)|$$

In other words, $|D\phi_p(v)| = |v| \quad \forall v \in T_p \Sigma$

DEFINITION

If $\forall v \in T_p \Sigma, |D\phi_p(v)| = |v|$, then $D\phi: T_p \Sigma \rightarrow T_{\phi(p)} \tilde{\Sigma}$ is a linear isometry

REMARK

$D\phi(v) \cdot D\phi(w) = v \cdot w \quad \forall v, w \in T_p \Sigma$ if $D\phi$ is an isometry

Proof

$$|D\phi(v+w)|^2 = |v+w|^2 \Rightarrow |D\phi(v)|^2 + |D\phi(w)|^2 + 2D\phi(v) \cdot D\phi(w) = |v|^2 + |w|^2 + 2v \cdot w \quad \square$$

PROPERTY

$\phi: \Sigma \rightarrow \tilde{\Sigma}$ is an isometry

$\Leftrightarrow D\phi: T_p \Sigma \rightarrow T_{\phi(p)} \tilde{\Sigma}$ is a linear isometry (extrinsic POV)

$\Leftrightarrow \psi^* \tilde{g} = g \leftarrow$ focus here below (recall: $\psi^* g$ is the pull-back) (intrinsic POV)

$$\begin{array}{ccc} \Sigma & \xrightarrow{\phi} & \tilde{\Sigma} \\ \uparrow x & & \uparrow \tilde{x} \\ (\Omega, g) & \dots\dots\dots & (\tilde{\Omega}, \tilde{g}) \\ \parallel & & \end{array}$$

pull-back of dot product by x

$$g_{ij} = g(\partial_i, \partial_j) = \partial_i x \cdot \partial_j x$$

OBSERVE

$$D\phi(\partial_i x) \cdot D\phi(\partial_j x) = \partial_i x \cdot \partial_j x = g_{ij}$$

$$\partial_i (\phi(x)) \cdot \partial_j (\phi(x)) \quad (\text{if we rewrite } \phi(x) = \tilde{x}(\psi), \text{ so } x(u^1, u^2) = \tilde{x}(\tilde{u}^1, \tilde{u}^2), (\tilde{u}^1, \tilde{u}^2) = \psi(u^1, u^2))$$

$$\tilde{\partial}_k \tilde{x}(\psi) \frac{\partial \tilde{u}^k}{\partial u^i} \cdot \tilde{\partial}_\ell \tilde{x}(\psi) \frac{\partial \tilde{u}^\ell}{\partial u^j} = \tilde{g}_{k\ell}(\psi) \frac{\partial \tilde{u}^k}{\partial u^i} \frac{\partial \tilde{u}^\ell}{\partial u^j} = \psi^* \tilde{g}(\partial_i, \partial_j)$$

REMARK (COMPARISON WITH AREA-PRESERVATION)

$$\text{Recall, } \phi: \Sigma \rightarrow \tilde{\Sigma} \text{ is area-preserving} \Leftrightarrow \int_{\tilde{\Sigma}} \sqrt{\det \tilde{g}} d\tilde{u}^1 d\tilde{u}^2 = \int_{\Sigma} \sqrt{\det g} du^1 du^2$$

$$\begin{aligned} & \int_{\tilde{\Sigma}} \sqrt{\det \tilde{g}(\psi)} \left| \det \frac{\partial \tilde{u}}{\partial u} \right| du \\ \Leftrightarrow & \int_{\Sigma} \sqrt{\det \tilde{g}(\psi)} \left| \det \frac{\partial \tilde{u}}{\partial u} \right| du = \int_{\Sigma} \sqrt{\det g} du \end{aligned}$$

$$\sqrt{\det \psi^*(\tilde{g})} \leftarrow \text{similar to the intrinsic POV above}$$

Now, from the extrinsic POV, what we needed was:

$$\int_{\Sigma} |\partial_1(\phi(x)) \times \partial_2(\phi(x))| du^1 du^2 = A(\tilde{\Sigma})$$

$$\int_{\Sigma} |\partial_1 x \times \partial_2 x| du^1 du^2 = A(\Sigma)$$

$$\Leftrightarrow |\partial_1(\phi(x)) \times \partial_2(\phi(x))| = |\partial_1 x \times \partial_2 x|$$

$$|D\phi(\partial_1 x) \times D\phi(\partial_2 x)|$$

(similar to extrinsic POV of isometry)

DEFINITION

Σ and $\tilde{\Sigma}$ are locally isometric if $\forall p \in \Sigma, \exists \tilde{p} \in \tilde{\Sigma}$ and local param $X: \Omega \rightarrow \Sigma$ and $\tilde{X}: \Omega \rightarrow \tilde{\Sigma}$, s.t. $\tilde{g} = g$

(Translation for stupid ppl like Shun himself: "locally isometric" = w.r.t. the same coord space, they have the same first fund form)

PROPOSITION

Σ and $\tilde{\Sigma}$ are locally isometric $\Leftrightarrow \exists$ diffeo $\phi: X(\Omega) \xrightarrow{\hookrightarrow \Sigma} \tilde{X}(\tilde{\Omega}) \xrightarrow{\hookrightarrow \tilde{\Sigma}}$ that is an isometry

Proof

" \Leftarrow ": $\tilde{X} = \phi(X)$

$$\tilde{g}_{ij} = \partial_i \tilde{X} \cdot \partial_j \tilde{X} = \partial_i (\phi(X)) \cdot \partial_j (\phi(X)) = D\phi(\partial_i X) \cdot D\phi(\partial_j X) = \partial_i X \cdot \partial_j X = g_{ij}$$

" \Rightarrow ": Let $\phi = \tilde{X} \circ X^{-1}$, which is a diffeo.

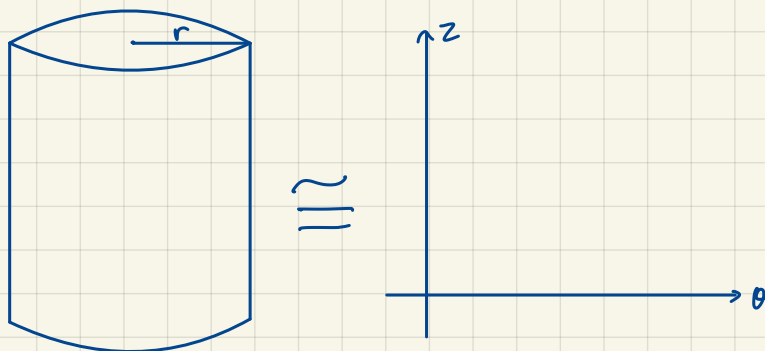
Then,

$$\begin{array}{ccc} \Sigma & \xrightarrow{\phi} & \tilde{\Sigma} \\ \nwarrow X & & \nearrow \tilde{X} \\ & \Omega & \end{array}$$

$$\text{Then, } D\phi(\partial_i X) \cdot D\phi(\partial_j X) = \partial_i \tilde{X} \cdot \partial_j \tilde{X} = \tilde{g}_{ij} = g_{ij} = \partial_i X \cdot \partial_j X \quad \square$$

$\partial_i \phi(X) = \partial_i \tilde{X}$

EXAMPLE



Consider the cylinder: $X = (r \cos \frac{\theta}{r}, r \sin \frac{\theta}{r}, z) = X(\theta, z)$

Then, $\partial_\theta X = (-\sin \frac{\theta}{r}, \cos \frac{\theta}{r}, 0)$

$$\partial_z X = (0, 0, 1)$$

$$\Rightarrow g = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = g_{\mathbb{R}^2} \Rightarrow \text{isometry!}$$

EXAMPLE

Catenoid \cong Helicoid !! (Aaaaaa my fav example for years QwQ!!)

