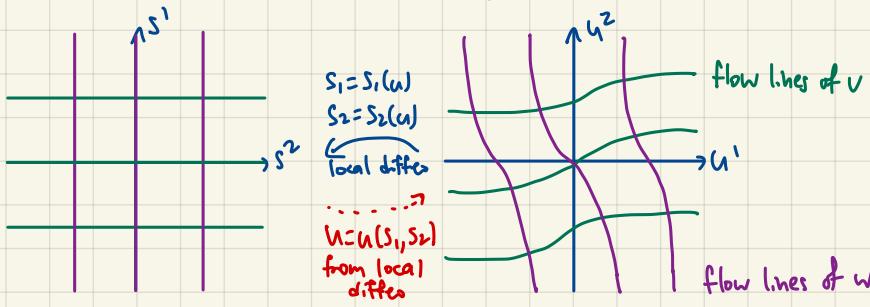


THEOREM

Let $\{v, w\}$ be linearly independent tangent vector fields on Σ near $p \in \Sigma$. Then, \exists local param of Σ near p , s.t. the coord lines are the flow lines of v, w $\{v(p), w(p)\}$



Proof level set val?

let S_1 = "index" of the flow lines of V
 S_2 = "index" of the flow lines of W

$$dS_1(V)|_p = 0, dS_1(W)|_p = 0 \Rightarrow dS_1|_p = 0 \quad (\because S_1 \text{ is a regular function})$$

$$\text{So, } dS_1(V)|_p = 0 \quad dS_2(V)|_p \neq 0$$

$$dS_1(W)|_p \neq 0 \quad dS_2(W)|_p = 0$$

$$\Rightarrow \begin{pmatrix} \frac{\partial S_1}{\partial u^1} & \frac{\partial S_1}{\partial u^2} \\ \frac{\partial S_2}{\partial u^1} & \frac{\partial S_2}{\partial u^2} \end{pmatrix} \begin{pmatrix} v^1 & w^1 \\ v^2 & w^2 \end{pmatrix} = \begin{pmatrix} 0 & * \\ * & 0 \end{pmatrix} \quad \square$$

REMARK

$$\frac{\partial}{\partial S_2} u(S_1, S_2) = Du\left(\frac{\partial}{\partial S_2}\right) = \lambda V(u)$$

$$\text{Similarly, } \frac{\partial}{\partial S_1} u(S_1, S_2) = \mu W(u)$$

COROLLARY

If $V \perp W$, then $X(u(S_1, S_2)) = \tilde{x}(S_1, S_2)$, $\frac{\partial \tilde{x}}{\partial S_1} \perp \frac{\partial \tilde{x}}{\partial S_2} \Rightarrow \tilde{g} = \begin{pmatrix} g_{11} & 0 \\ 0 & g_{22} \end{pmatrix}$

let u be local coords.

If $\{\frac{\partial}{\partial u^1}, \frac{\partial}{\partial u^2}\}$, then we perform Gram-Schmidt, so $V = \frac{\partial}{\partial u^1} = (1, 0)$, $W = \frac{\partial}{\partial u^2} - \frac{\langle \frac{\partial}{\partial u^2}, \frac{\partial}{\partial u^1} \rangle}{\|\frac{\partial}{\partial u^1}\|^2} \frac{\partial}{\partial u^1}$.

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} - \frac{(0, 1) \begin{pmatrix} g_{11}(u) & g_{12}(u) \\ g_{12}(u) & g_{22}(u) \end{pmatrix} (1, 0)}{(1, 0) \begin{pmatrix} g_{11}(u) & g_{12}(u) \\ g_{12}(u) & g_{22}(u) \end{pmatrix} (1, 0)}$$

EXAMPLE

let P be a nonumbilical point $(k, l, k_2) \Rightarrow V \perp W$ (principal directions)

ISOMETRIES**SETTING IN \mathbb{R}^3**

Let $\phi: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a diffeomorphism

If it is length-preserving, then ϕ must be a rigid motion, where $\phi(x) = Ax + b$, $A \in O_3$ orthog matrix

PROPERTY IN GENERAL Σ

Let $\phi: \Sigma \rightarrow \tilde{\Sigma}$ be a diffeomorphism. If it's length-preserving, i.e. $L(\phi(\gamma)) = L(\gamma) \forall \gamma$

Param γ w.r.t. t , $L(\phi(\gamma)) = L(\gamma) \Rightarrow \int_a^b \left| \frac{d}{dt}(\phi(\gamma(t))) \right| dt = \int_a^b |\gamma'(t)| dt \Rightarrow \left| \frac{d}{dt}(\phi(\gamma(t))) \right| = |\gamma'(t)|$

In other words, $|D\phi_p(v)| = |v| \quad \forall v \in T_p \Sigma$

DEFINITION

If $\forall v \in T_p \Sigma$, $|D\phi_p(v)| = |v|$, then $D\phi: T_p \Sigma \rightarrow T_{\phi(p)} \tilde{\Sigma}$ is a linear isometry

REMARK

$D\phi(v) \cdot D\phi(w) = v \cdot w \quad \forall v, w \in T_p \Sigma$ if $D\phi$ is an isometry

Proof

$$|D\phi(v+w)|^2 = |v+w|^2 \Rightarrow |D\phi(v)|^2 + |D\phi(w)|^2 + 2 D\phi(v) \cdot D\phi(w) = |v|^2 + |w|^2 + 2v \cdot w \quad \square$$

PROPERTY

$\phi: \Sigma \rightarrow \tilde{\Sigma}$ is an isometry

$\Leftrightarrow D\phi: T_p \Sigma \rightarrow T_{\phi(p)} \tilde{\Sigma}$ is a linear isometry (extrinsic POV)

$\Leftrightarrow \varphi^* \tilde{g} = g$ ← focus here below (recall: $\varphi^* g$ is the pull-back) (intrinsic POV)

$$\begin{array}{ccc} \Sigma & \xrightarrow{\phi} & \tilde{\Sigma} \\ x \uparrow & & \uparrow \tilde{x} \\ (\Sigma, g) & \dashrightarrow & (\tilde{\Sigma}, \tilde{g}) \\ \parallel & & \end{array}$$

pull-back of dot product by ϕ

$$g_{ij} = g(\partial_i, \partial_j) = \partial_i x \cdot \partial_j x$$

OBSERVE

$$D\phi(\partial_i x) \cdot D\phi(\partial_j x) = \partial_i x \cdot \partial_j x = g_{ij}$$

||

$$\partial_i(\phi(x)) \cdot \partial_j(\phi(x)) \quad (\text{if we rewrite } \phi(x) = \tilde{x}(\varphi), \text{ so } x(u^1, u^2) = \tilde{x}(\tilde{u}^1, \tilde{u}^2), (\tilde{u}^1, \tilde{u}^2) = \varphi(u^1, u^2))$$

||

$$\tilde{x}_k \tilde{x}_l(\varphi) \frac{\partial \tilde{u}^k}{\partial u^i} \cdot \tilde{x}_j \tilde{x}_l(\varphi) \frac{\partial \tilde{u}^l}{\partial u^j} = \tilde{g}_{kl}(\varphi) \frac{\partial \tilde{u}^k}{\partial u^i} \frac{\partial \tilde{u}^l}{\partial u^j} = \varphi^* \tilde{g}(\partial_i, \partial_j)$$

REMARK (COMPARISON WITH AREA-PRESERVATION)

$$\text{Recall, } \varphi: \Sigma \rightarrow \tilde{\Sigma} \text{ is area-preserving} \Leftrightarrow \int_{\Sigma} \sqrt{\det \tilde{g}} d\tilde{u}^1 d\tilde{u}^2 = \int_{\Sigma} \sqrt{\det g} du^1 du^2$$

|| $\tilde{u} = \varphi(u)$

$$\begin{aligned} & \int_{\Sigma} \sqrt{\det \tilde{g}(\varphi)} \left| \det \frac{\partial \tilde{u}}{\partial u} \right| du \\ \Leftrightarrow & \sqrt{\det \tilde{g}(\varphi)} \left| \det \frac{\partial \tilde{u}}{\partial u} \right| = \sqrt{\det g} \end{aligned}$$

||

$\sqrt{\det \varphi^* g}$ ← similar to the intrinsic POV above

Now, from the extrinsic POV, what we needed was:

$$\int_{\Sigma} |\partial_1(\phi(x)) \times \partial_2(\phi(x))| du^1 du^2 = A(\Sigma)$$

||

$$\int_{\Sigma} |\partial_1 X \times \partial_2 X| du^1 du^2 = A(\Sigma)$$

$$\Leftrightarrow |\partial_1(\phi(x)) \times \partial_2(\phi(x))| = |\partial_1 X \times \partial_2 X|$$

||

$$|D\phi(\partial_i x) \times D\phi(\partial_j x)|$$

(similar to extrinsic POV of isometry)

DEFINITION

Σ and $\tilde{\Sigma}$ are locally isometric if $\forall p \in \Sigma, \exists \tilde{p} \in \tilde{\Sigma}$ and local param $X: \Omega \rightarrow \Sigma$ and $\tilde{X}: \tilde{\Omega} \rightarrow \tilde{\Sigma}$, s.t. $\tilde{g} = g$

(Translation for stupid ppl like Shun himself: "Locally isometric" = w.r.t. the same coord space, they have the same first fund form)

PROPOSITION

Σ and $\tilde{\Sigma}$ are locally isometric $\Leftrightarrow \exists$ diffeo $\phi: X(\Omega) \longrightarrow \tilde{X}(\tilde{\Omega})$ that is an isometry

Proof

" \Leftarrow ": $\tilde{x} = \phi(x)$

$$\tilde{g}_{ij} = \partial_i \tilde{X} \cdot \partial_j \tilde{X} = \partial_i (\phi(x)) \cdot \partial_j (\phi(x)) = D\phi(\partial_i x) \cdot D\phi(\partial_j x) = \partial_i X \cdot \partial_j X = g_{ij}$$

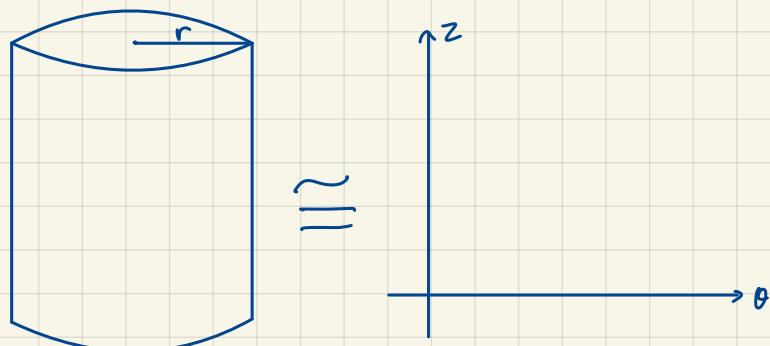
" \Rightarrow ": Let $\phi = \tilde{X} \circ x^{-1}$, which is a diffeo.

Then,

$$\begin{array}{ccc} \Sigma & \xrightarrow{\phi} & \tilde{\Sigma} \\ x \nearrow & & \searrow \tilde{x} \\ \Omega & & \end{array}$$

$$\text{Then, } D\phi(\partial_i x) \cdot D\phi(\partial_j x) = \partial_i \tilde{X} \cdot \partial_j \tilde{X} = \tilde{g}_{ij} = g_{ij} = \partial_i X \cdot \partial_j X \quad \square$$

$\partial_i \phi(x) = \partial_i \tilde{X}$

EXAMPLE

Consider the cylinder: $X = (r \cos \frac{\theta}{r}, r \sin \frac{\theta}{r}, z) = X(\theta, z)$

Then, $\partial_\theta X = (-\sin \frac{\theta}{r}, \cos \frac{\theta}{r}, 0)$

$$\partial_z X = (0, 0, 1)$$

$$\Rightarrow g = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = g_{\mathbb{R}^2} \Rightarrow \text{isometry!}$$

EXAMPLE

Catenoid \cong Helicoid !! (Aaaaaaa my fav example for years QwQ!!)

