Pearl 110 - Intelligent Interaction

Boolean events

Discriminant functions, classifiers and decision boundaries

Yesterday's lecture

Estimation of probability of events:

- Prior
- Evidence
- Class-conditional
- Posterior

How to use probabilities to make decisions (e.g. *class with highest posterior probability*).

Event

We have a bucket with 10 fishes (4 salmon and 6 sea bass). We do an experiment, and obtain an outcome.

The outcome of the experiment is an event, and can be:

- We pick a salmon from the bucket
- We pick a fish of width 26cm
- We pick a sea bass of 25cm
- ...

To each of these events we can assign a probability



Different types of event

Terminology that we use in probabilistic decision theory.

- Prior: probability of an event to happen, before (prior) to measuring any characteristics (features) of the data
- **Evidence:** probability of *measuring a certain value of features* from all the samples
- **Class-conditional:** probability of *measuring a certain feature value* from samples that *belong to a certain class* (conditioned on the class)
- Posterior: probability of a sample to belong to a certain class, given that we have measured a certain feature value

Posterior probability with the **Bayes formula**

posterior
$$P(C|x) = \frac{P(x|C)P(C)}{P(x)}$$
 evidence

The evidence is computed as:
$$P(X) = P(X|C_1)P(C_1) + P(X|C_2)P(C_2) + \ldots$$

Naive Bayes

Independent Events

$$P(A,B) \longrightarrow P(A)P(B)$$

Naïve Bayes rule:

$$P(C|x_1,x_2,\dots,x_n) = rac{P(x_1|C)P(x_2|C)\dots P(x_n|C)P(C)}{P(x_1,x_2,\dots,x_n)}$$

What's for today?



Today's lecture

1. Estimating the probability of repeated binary events

Bernoulli trial experiment

2. How to build a classifier analytically?

Compute a decision boundary

Do it with Gaussian functions (the case of the Normal distribution)

A binary event

We make an experiment -> we have a certain outcome OR not (opposite outcome)

We toss a coin -> we get a tail or not a tail

We roll a dice -> we get a 5 or not a 5





Dice rolling/Coin tossing: Bernoulli Trial

If I toss a coin 5 times, what is the probability of getting 4 tails?

If I roll a dice 5 times, what is the probability of getting 3 four? ...or 3 four and 2 two?

Assumptions

The events are independent: one coin toss does not influence the next.

If I roll a dice and get a 4, the next dice roll does not depend on it.

The events are binary: If I toss a coin, I get a tail or I don't get a tail.

If I roll a dice, I can get a 5 or not.

Bernoulli Trial: probability estimation

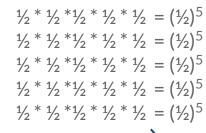
If I toss a coin 5 times, what is the probability of getting 4 tails?

The probability of tails is equal to the probability of heads (balanced coin)

$$P(T) = P(H) = \frac{1}{2}$$











Observation: the order of the events is not important for the experiment

$$P(t=4, \neg t=1) = 5 \cdot (\frac{1}{2})^5$$





If I roll a dice 5 times, what is the probability of getting 3 fours?

We want to compute P(F = 3, N=2) the probability of rolling 3 fours and 2 not four

$$\binom{5}{3} = \frac{5!}{3!(5-3)!} = \frac{5 \cdot 4 \cdot 3 \cdot 2 \cdot 1}{3 \cdot 2 \cdot 1 \cdot (2 \cdot 1)} = 10$$

10 combinations10 ways to obtain 3 F out of 5 events(having a four in 3 out of 5 dice rolls)

FNFNF

$$10 * [P(F)]^3 [P(N)]^2$$

Bernoulli Trial: formula

From N choose k
$$\binom{N}{k} = \frac{N!}{k!(N-k)!}$$

Binomial coefficient

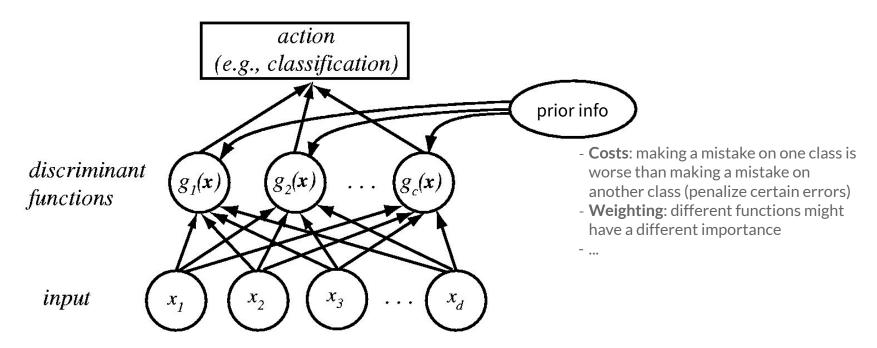
Probability of x=k successes given N trials (where p is the probability of a single success)

$$P(x=k)|_N = inom{N}{k} p^k (1-p)^{N-k}$$

Determining the decision boundary

How to build classifiers using probability distribution functions

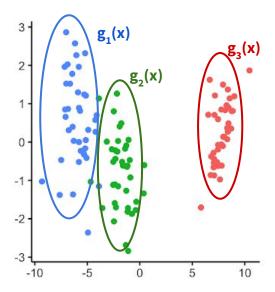
Structure of a classifier



Discriminant function

A function that models a set of data points.

Instead of working with single data points, we summarize/approximate them with a function, that describes their distribution.



x: a vector of measured features

[length, lightness] in the fish example

 $g_i(x)$ takes the feature vector as input

Discriminant functions

e.g. the function $\mathbf{g_1}(\mathbf{x})$ computes a score for the sample \mathbf{x} for belonging to the class $\mathbf{C_1}$

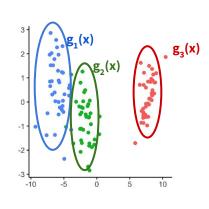
A classifier computes the value of discriminant functions $\mathbf{g}_{\mathbf{i}}(\mathbf{x})$ for several classes and assign to \mathbf{x} the class corresponding to the discriminant function with the largest score.

The classifier assigns a feature vector **x** to class **i** if

$$g_i(\mathbf{x}) > g_j(\mathbf{x})$$
, for all $j \neq i$

$$g_i(x) = P(C_i|x)$$

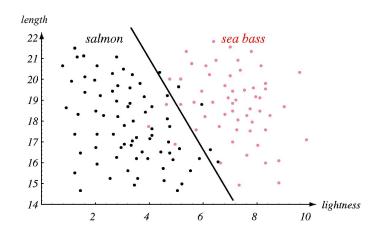
Posterior probability can be a discriminant function.

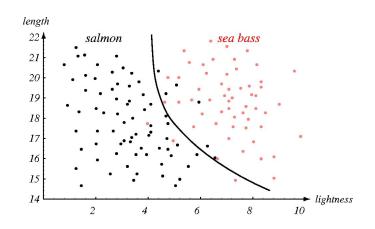


How to use discriminant functions?

Create a model of the samples in one class with a discriminant function (the distribution of these samples is described by the discriminant function)

Combine the discriminant functions of different classes to find the decision boundary (HOW???)





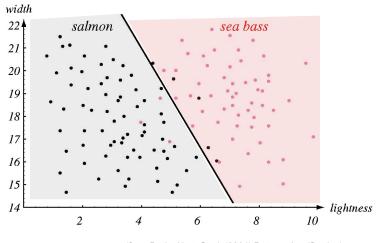
Dichotomizer: a two-class classifier

Classifies samples in two classes.

It is defined as:
$$g(x) = g_1(x) - g_2(x)$$

Discriminant function for class 1 class 2 (seabass)

Classify x into class C_1 if g(x) > 0

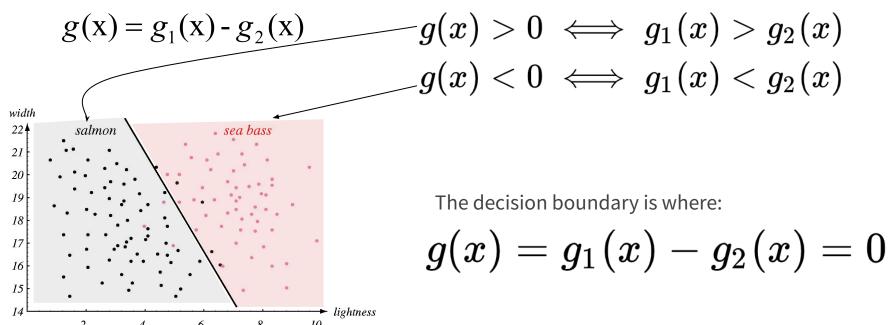


(from Duda, Hart, Stork (2001) Pattern classification)

We can use the posterior $g(x) = P(C_1|x) - P(C_2|x)$ probability

How to compute the decision boundary of a dichotomizer?

Decision regions



Probabilistic dichotomizer

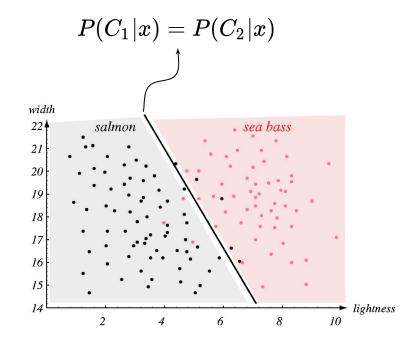
We use the <u>Posterior probability</u> as <u>discriminant function</u>.

We define the classifier as:

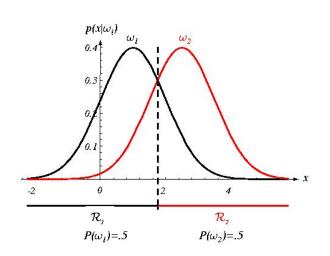
$$g(x) = g_1(x) - g_2(x) = P(C_1|x) - P(C_2|x)$$

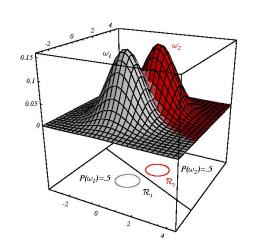
And the decision regions become:

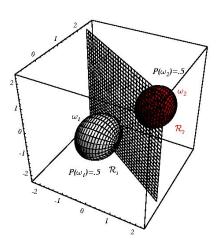
$$g(x)>0\iff P(C_1|x)>P(C_2|x)$$
 We decide for class 1 $g(x)<0\iff P(C_1|x)< P(C_2|x)$ We decide for class 2



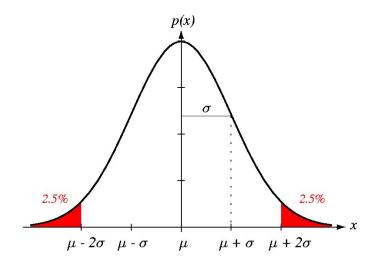
Dichotomizer: examples in higher dimensions







(from Duda, Hart, Stork (2001) Pattern classification)



Modeling using the normal distribution

An example

Given the sets (training data) S1 and S2

```
\mathbf{S_1} = [8.70, 3.31, -13.48, 15.48, -6.17, -6.99, -14.24, -1.10, -1.03, -3.23]
\mathbf{S_2} = [18.21, 1.79, 95.25, 65.02, 27.82, 32.70, 42.18, 34.76, 23.59, 53.68, 12.23, 74.15, -0.26, 28.53, 52.45]
```

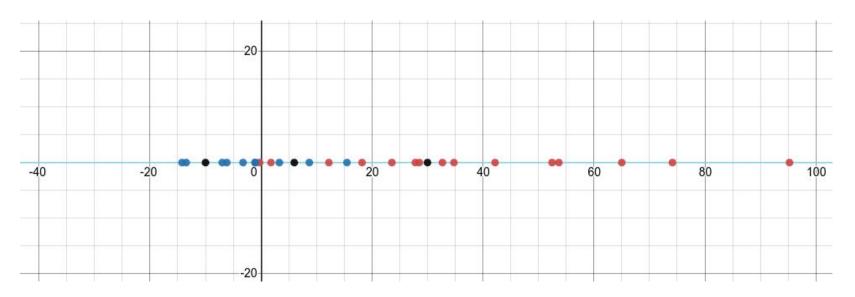
that come from two different classes.

Problem: we want to classify the following test points:

-10, 6, 30

...example...

Given the points in **Class 1** and **Class 2**, in which class should we classify the **black** points?



We look for the closest points

We count the **k=5 Nearest Neighbours**.

Test point x = -10.

The 5 nearest neighbors of this point are:

```
\mathbf{S_1} = [8.70, 3.31, \underline{\mathbf{-13.48}}, 15.48, \underline{\mathbf{-6.17}}, \underline{\mathbf{-6.99}}, \underline{\mathbf{-14.24}}, -1.10, -1.03, \underline{\mathbf{-3.23}}]
\mathbf{S_2} = [18.21, 1.79, 95.25, 65.02, 27.82, 32.70, 42.18, 34.76, 23.59, 53.68, 12.23, 74.15, -0.26, 28.53, 52.45]
```

All 5 nearest neighbors come from S_1 .

Hence, point **-10** is decided to belong to **Class 1**.

...another sample...

Test point x = 6.

The 5 nearest neighbors of this point are

```
S_1 = [8.70, 3.31, -13.48, 15.48, -6.17, -6.99, -14.24, -1.10, -1.03, -3.23]
S_2 = [18.21, 1.79, 95.25, 65.02, 27.82, 32.70, 42.18, 34.76, 23.59, 53.68, 12.23, 74.15, -0.26, 28.53, 52.45]
```

Most (3) of the 5 nearest neighbors come from S_2 (2 from S_1).

Hence, point 6 is decided to belong to **class 2**.

...and another...

Test point x = 30.

The 5 nearest neighbors of this point are:

```
S_1 = [8.70, 3.31, -13.48, 15.48, -6.17, -6.99, -14.24, -1.10, -1.03, -3.23]

S_2 = [18.21, 1.79, 95.25, 65.02, 27.82, 32.70, 42.18, 34.76, 23.59, 53.68, 12.23, 74.15, -0.26, 28.53, 52.45]
```

All 5 nearest neighbors come from **S**₂.

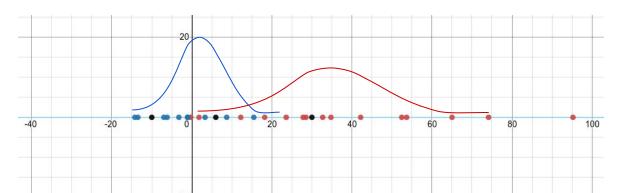
Hence, point **30** is decided to belong to **class 2**.

Observations on k-nearest classification

This counting of nearest neighbors seems a little shaky – if the votes are 3:2 and I move the test point a little bit, they may become 2:3. **How reliable is this?**

We will model the probabilities by some smooth, reliable and predictably changing functions. For instance, a **Gaussian function**!

Why? Because we can use it to compute the probability of measuring a certain value of the features also in domains in which we do not have precise (training) data.



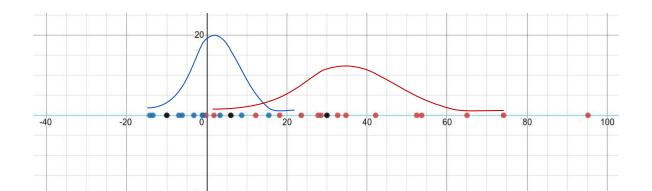
Where do we use the Gaussian function?

In the Bayes formula:

$$P(C_i|x) = P(x|C_i)P(C_i)$$

We model the data points (i.e. x) belonging to the class C_i with a function that describes the distribution of probability of their features.

The class-conditional probability is a function (probability density function). Instead of working with the single data points, we work with this function.



Univariate normal density (Gaussian function)

Univariate: we consider only one dimension (on feature)

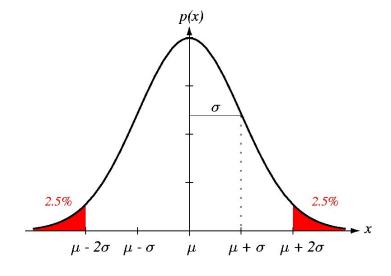
$$p(x)=rac{1}{\sqrt{2\pi}\sigma}e^{-rac{1}{2}rac{(x-\mu)^2}{\sigma^2}}$$

The Gaussian function has two parameters that can be estimated:

mean:
$$\mu=rac{1}{n}\sum_{k=1}^n x_k$$

variance:
$$\sigma^2 = rac{1}{n} \sum_{k=1}^n (x_k - \mu)^2$$

Standard deviation:
$$\sigma = \sqrt{\sigma^2}$$



Back to the example

 $\mathbf{S_1} = [8.70, 3.31, -13.48, 15.48, -6.17, -6.99, -14.24, -1.10, -1.03, -3.23]$ $\mathbf{S_2} = [18.21, 1.79, 95.25, 65.02, 27.82, 32.70, 42.18, 34.76, 23.59, 53.68, 12.23, 74.15, -0.26, 28.53, 52.45]$

We decide to model the two classes that generated this data by two normal distributions. What are the parameters of these normal distributions?

Estimation of the mean and variance

$$\mu = rac{1}{n} \sum_{k=1}^n x_k$$

$$\sigma^2=rac{1}{n}\sum_{k=1}^n(x_k-\mu)^2$$



We compute: $\mu_1 = 0$, $\sigma_1^2 = 10^2$ $\mu_2 = 35$, $\sigma_2^2 = 20^2$

Example: the class-conditional probability

We use Gaussian functions to model the class-conditional probability.

We have mean and standard deviation of the two classes!!!

$$\mu_1 = 0$$
, $\sigma_1^2 = 10^2$
 $\mu_2 = 35$, $\sigma_2^2 = 20^2$

$$P(x|C_1) = rac{1}{\sigma_1 \sqrt{2\pi}} e^{-rac{(x-\mu_1)^2}{2\sigma_1^2}} = rac{1}{10\sqrt{2\pi}} e^{-rac{x^2}{2\cdot 10^2}}$$

$$P(x|C_2) = rac{1}{\sigma_2\sqrt{2\pi}}e^{-rac{(x-\mu_2)^2}{2\sigma_2^2}} = rac{1}{20\sqrt{2\pi}}e^{-rac{x^2-35}{2\cdot 20^2}}$$

Example: estimating the prior probabilities

From class 1, we observe 10 values: $|S_1|=10$.

From class 2, we observe 15 values: $|S_2|=15$.

We estimate the prior probabilities of **class 1** and **class 2** by the their frequency of occurrence:

$$P(C_1) = rac{|S_1|}{|S_1| + |S_2|} = rac{10}{10 + 15} = 0.4$$

$$P(C_2) = rac{|S_2|}{|S_1| + |S_2|} = rac{15}{10 + 15} = 0.6$$

Example: the posterior probability

Estimation of the posterior probability using the Bayes rule (and the quantities we have computed earlier):

$$P(C_1|x) = rac{P(C_1)P(x|C_1)}{P(x)} = rac{0.4rac{1}{10\sqrt{2\pi}}e^{-rac{x^2}{2\cdot 10^2}}}{P(x)}$$

$$P(C_2|x) = rac{P(C_2)P(x|C_2)}{P(x)} = rac{0.6rac{1}{20\sqrt{2\pi}}e^{-rac{(x-35)^2}{2\cdot 20^2}}}{P(x)}$$

Note: for a new data point **x**' we can compute the posterior probability of it belonging to class 1 and the posterior probability of belonging to class 2. We select the class with highest posterior probability.

Computing the decision boundary

For the decision criterion (boundary), it holds $P(C_1|x) = P(C_2|x)$ This leads to the following equation:

$$rac{0.4rac{1}{10\sqrt{2\pi}}e^{-rac{x^2}{2\cdot 10^2}}}{P(x)}=rac{0.6rac{1}{20\sqrt{2\pi}}e^{-rac{(x-35)^2}{2\cdot 20^2}}}{P(x)}$$

After simplifying [P(x)] is on both sides, and the factors at the beginning can be manipulated, we have:

$$8e^{-\frac{x^2}{2\cdot 10^2}} = 6e^{-\frac{(x-35)^2}{2\cdot 20^2}}$$

The choice of discriminant functions is not unique!

The choice of discriminant functions is not unique!

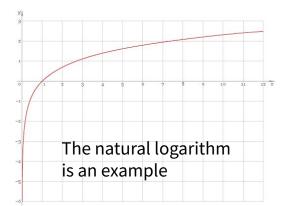
In general, if every discriminant function is replaced by a monotonically increasing function $f(g_i(x))$ the classification result does not change.

Motivation: other quantities, simpler to understand or to compute, lead to identical classification results.

The choice of discriminant functions is not unique!

In general, if every discriminant function is replaced by a monotonically increasing function $f(g_i(x))$ the classification result does not change.

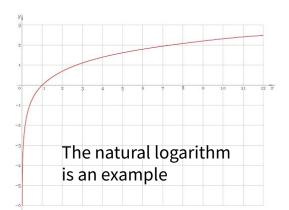
Motivation: other quantities, simpler to understand or to compute, lead to identical classification results.



The choice of discriminant functions is not unique!

In general, if every discriminant function is replaced by a monotonically increasing function $f(g_i(x))$ the classification result does not change.

Motivation: other quantities, simpler to understand or to compute, lead to identical classification results.



$$egin{aligned} g_i(x) &= P(x|C_i)P(C_i) \ f(g_i(x)) &= ln\left[P(x|C_i)P(C_i)
ight] \ f(g_i(x)) &= ln\left[P(x|C_i)
ight] + ln\left[P(C_i)
ight] \end{aligned}$$

(It is useful in the important case of normal distribution)

One step to simplify the decision boundary

We have stopped at this point, when computing the decision boundary:

$$8e^{-rac{x^2}{2\cdot 10^2}} = 6e^{-rac{(x-35)^2}{2\cdot 20^2}}$$

If we take the natural logarithm on both sides, we can have benefits:

$$ln\left[8e^{-rac{x^2}{2\cdot 10^2}}
ight] = ln\left[6e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight]$$

We can use the *natural logarithm* function ln(x) to further simplify the equation:

$$ln\left[8e^{-rac{x^2}{2\cdot 10^2}}
ight] = ln\left[6e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight]$$

We can use the *natural logarithm* function ln(x) to further simplify the equation:

$$ln\left[8e^{-rac{x^2}{2\cdot 10^2}}
ight] = ln\left[6e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight]
onumber \ ln\left[8
ight] + ln\left[e^{-rac{x^2}{2\cdot 10^2}}
ight] = ln\left[6
ight] + ln\left[e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight]$$

We can use the *natural logarithm* function ln(x) to further simplify the equation:

$$egin{align} ln\left[8e^{-rac{x^2}{2\cdot 10^2}}
ight] &= ln\left[6e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight] \ ln\left[8
ight] + ln\left[e^{-rac{x^2}{2\cdot 10^2}}
ight] &= ln\left[6
ight] + ln\left[e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight] \ ln8 - rac{x^2}{2\cdot 10^2} &= ln6 - rac{(x-35)^2}{2\cdot 20^2} \ \end{cases}$$

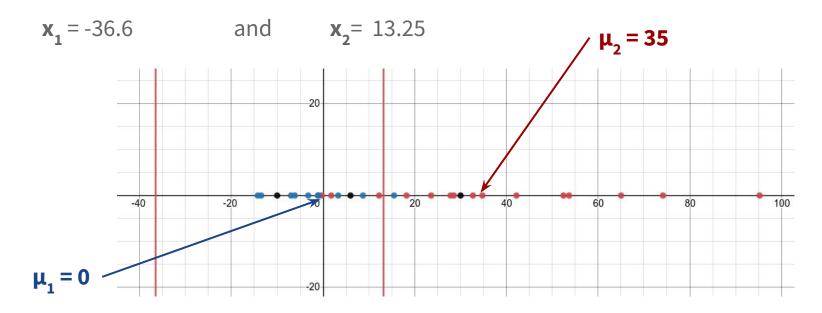
We can use the *natural logarithm* function ln(x) to further simplify the equation:

$$egin{align} ln\left[8e^{-rac{x^2}{2\cdot 10^2}}
ight] &= ln\left[6e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight] \ ln\left[8
ight] + ln\left[e^{-rac{x^2}{2\cdot 10^2}}
ight] &= ln\left[6
ight] + ln\left[e^{-rac{(x-35)^2}{2\cdot 20^2}}
ight] \ ln8 - rac{x^2}{2\cdot 10^2} &= ln6 - rac{(x-35)^2}{2\cdot 20^2} \ \end{cases}$$

And reduce it to: $3x^2+70x-1445.14=0$

The quadratic equation $3x^2 + 70x - 1445.14 = 0$

Has the following solutions:



The quadratic equation
$$3x^2 + 70x - 1445.14 = 0$$

Has the following solutions:

$$\mathbf{x_1} = -36.6$$

and
$$x_2 = 13.25$$

We use them to compute the decision regions:

$$g_1(x)>g_2(x)$$

If -36.6 < x < 13.25 then x belongs to Class 1

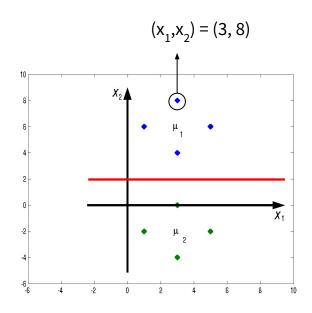
If x < -36.6 or x > 13.25, x belongs to Class 2

Our problem: -10 and 6 are Class 1, and 30 is Class 2

More advanced cases

When we have more dimension...

In the 2D case, a data point (sample) is described 2 features (arranged in a vector).



We need to work with vectors, and know how to multiply two vectors.

$$egin{pmatrix} (a & b) imes egin{pmatrix} e \ g \end{pmatrix} = a \cdot e + b \cdot g$$

equivalent to: $\begin{pmatrix} a & b \end{pmatrix} \cdot \begin{pmatrix} e & g \end{pmatrix} = a \cdot e + b \cdot g$

Many features: multivariate Gaussian

When you have **d** features, the Gaussian function becomes:

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} |\sum|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \mu) \sum_{k=0}^{-1} (\mathbf{x} - \mu)\right]$$

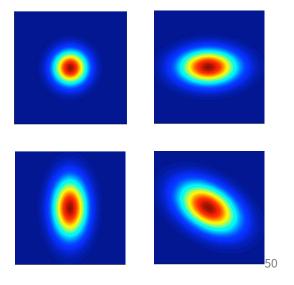
 $x \in \mathbb{R}^d$ is a d-dimensional vector

 μ is the mean (a d-dimensional vector itself)

 Σ is the covariance matrix

($|\Sigma|$ its determinant and Σ^{-1} its inverse)

It is important because it describes the shape of the distribution



Decision boundary for a simple 2D case

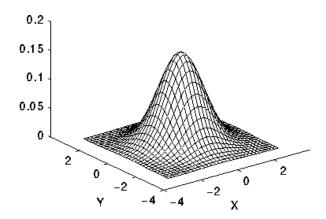
We consider statistical independence between features, i.e. $\Sigma_i = \sigma^2 I$

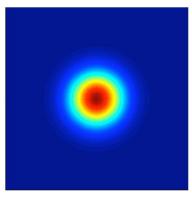
The form of the discriminant functions simplifies to:

$$g_i(x) = -rac{\left|\left|x-\mu_i
ight|
ight|^2}{2\sigma^2} + lnP(C_i)$$

where $\|\mathbf{x} - \mu_i\|^2 = (\mathbf{x} - \mu_i)^t (\mathbf{x} - \mu_i)$

t means the transpose operation





Let us see it with an example

$$\mu_1 = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$$
 $\mu_2 = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$ $\sigma_1 = \sigma_2 = \sqrt{2}$ $P(C_1) = P(C_2) = 0.5$

To determine the decision boundary we have to compute:

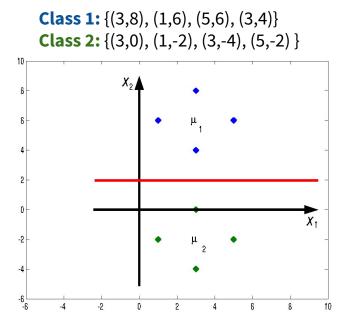
$$g_1(\mathbf{x}) = g_2(\mathbf{x})$$

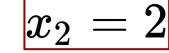
$$\Rightarrow \;\; -rac{\|x-\mu_1\|^2}{2\sigma^2} + lnP(C_1) = -rac{\|x-\mu_2\|^2}{2\sigma^2} + lnP(C_2)$$

$$\implies (x - \mu_1)^t (x - \mu_1) = (x - \mu_2)^t (x - \mu_2)$$

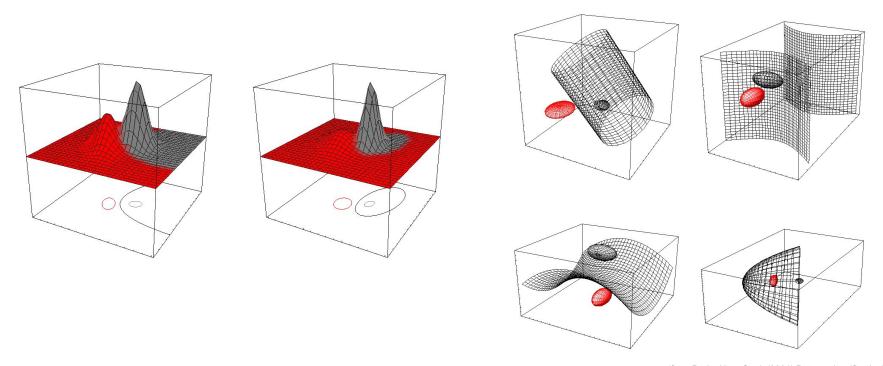
$$\implies \begin{bmatrix} x_1 - 3 & x_2 - 6 \end{bmatrix} \begin{bmatrix} x_1 - 3 \\ x_2 - 6 \end{bmatrix} = \begin{bmatrix} x_1 - 3 & x_2 + 2 \end{bmatrix} \begin{bmatrix} x_1 - 3 \\ x_2 + 2 \end{bmatrix}$$

$$\implies (x_1-3)^2+(x_2-6)^2=(x_1-3)^2\,+\,(x_2+2)^2$$





Possible boundary determined from data



Summary

How to estimate the probability of repeated boolean events (Bernoulli trials)

Discriminant functions, and how to use them to build a classifier

With accurate modeling of the class samples distributions you can define the analytical form of a classifier

How to construct a classifier (determining the decision boundary of a two-class problem) using the Gaussian distribution

Assignments

This afternoon, focus on the **preparative assignments 7.2 and 7.3**

You should also start working on the **pearl assignment 7.6**

Look also in the extra preparatory exercises and exam questions