A minimization algorithm for deterministic finite automata

The following algorithm takes as input a deterministic finite automaton (DFA) and produces an equivalent one (i.e. one accepting the same language) with a minimum number of states. The material is taken from [HU79, §3.4].

A DFA is given by a 5-tuple $M = \langle Q, \Sigma, \delta, q_0, F \rangle$, where

- Q is a finite set (of states)
- Σ is a finite set (of symbols, forming the alphabet)
- δ is the transition function, assigning to every state s and input symbol a the next state, $\delta(s, a) = s'$ (which may also be written as $s \stackrel{a}{\to} s'$).
- q_0 is a distinguished start state
- F is a subset of Q consisting of the final or accepting states

For the algorithm, we may represent Q by a collection of small integers $Q=\{1,\ldots,n\}$, the alphabet by an enumeration type $\Sigma=[a\ldots z]$ (achieved in Java say, by declaring a collection of integer constants corresponding to the symbols of Σ) and the transition function by an array of integers doubly indexed by Q and Σ (int[][]Delta), so that e.g. Delta[2][a] = 4 represents $2\stackrel{a}{\to} 4$. The final states F are organised into an array (or list) of integers.

What we need in order to minimize M is to recognize which pairs of states p,q are equivalent (i.e., recognize the same languages: for every string $\sigma \in \Sigma^*$, there is a path labelled σ starting at p and ending in a final state if and only if there is a path starting in q labelled σ which ends at a final state). We solve this problem by finding out which pair of states p,q are not equivalent: there is a string $\sigma \in \Sigma^*$ and a path labelled σ starting at p which ends in a final state, while there is no such path for q (or viceversa). We then say such p and q are distinguishable.

Notice that if p, q are distinguishable, then for any pair of states p', q' for which there is an input symbol a such that $\delta(p', a) = p$ and $\delta(q', a) = q, p', q'$ are distinguishable as well (if σ distinguishes p from q, $a\sigma$ distinguishes p' and q'). Clearly, the empty string distinguishes final states from non-final ones.

The algorithm uses two data structures:

- boolean[][]Distinguished: a boolean array indexed by pair of states, which records whether they are distinguished.
- (int[][])[][]Pending: array indexed by pair of states such that Pending[p][q] is an array (or list) of pair of states p', q' with the property:

if Distinguished[p][q] then Distinguished[p'][q']

Notice that Distinguished[p][q] if and only if Distinguished[q][p], and Distinguished[p][p] =false, so we only need information for Distinguished[p][q] for p < q. We express the algorithm in pseudo-algorithmic notation. Translation to actual Java code is fairly straightforward:

```
// initialization
for p \in F and q \in Q - F: Distinguished[p][q] = true;
for p, q \in (F \times F) \mid\mid (Q - F \times Q - F): Distinguished[p][q] = false;
//iteration
for p, q \in (F \times F) \mid\mid (Q - F \times Q - F) with p \neq q:
       for a \in \Sigma:
               ints = Delta[p][a];
               int t = Delta[q][a];
               if Distinguished[s][t]
                       then
                               // mark p, q as distinguished
                               Distinguished[p][q] = true;
                               (* recursively mark all pairs in Pending[p][q] and
                               in all the lists Pending[s][t] for the pairs s, t that get marked here *)
                        else
                               // no pair s, t reachable by a single input symbol
                               // from p, q is distinguished
                               for a \in \Sigma:
                                       ints = Delta[p][a];
                                       int t = Delta[q][a];
                                       if s \neq t then add [p][q] to Pending[s][t]
```

At the exit of the outermost loop, those pairs of states for which $\mathtt{Distinguished}[p][q] = \mathbf{false}$ can be collapsed (since we have failed to distinguish them), therefore reducing the number of states. The definition of the transition matrix $\mathtt{Delta}[\bar{p}][\bar{q}]$ for the equivalence classes of p and q respectively, is given by that of $\mathtt{Distinguished}[p][q]$. We thus get the minimized automaton.

References

[HU79] John E. Hopcroft and Jeffrey D. Ullman. Introduction to automata theory, languages, and computation. Addison-Wesley Publishing Co., Reading, Mass., 1979.