CS 391L Machine Learning Assignment 3

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Problem 1

(a)

$$Cov(y) = E((y - E(y)(y - E(y)^{T}))$$

$$= E((Ax + b - E(Ax + b))(Ax + b - E(Ax + b))^{T})$$

$$= E((Ax - E(Ax))(Ax - E(Ax))^{T})$$

$$= AE((x - E(x))(x - E(x))^{T})A^{T}$$

$$= A\Sigma A^{T}$$
(4)
$$= A \Sigma A^{T}$$
Def. of Cov.
(5)

(b) Base case: by the definition of eigenvalue and eigenvector, $Ax = \lambda x$. Inductive hypothesis: assume $A^k x = \lambda^k x$ for some $k \in N$. Want to show $A^{k+1}x = \lambda^{k+1}x$.

$$A^k x = \lambda^k x I.H. (6)$$

$$A^{k+1}x = A\lambda^k x \tag{7}$$

$$A^{k+1}x = \lambda^k Ax \tag{8}$$

$$A^{k+1}x = \lambda^{k+1}x \qquad Ax = \lambda x \tag{9}$$

Problem 2

(a)

$$r = 1 - \frac{H(Y|X)}{H(X)} \tag{10}$$

$$=\frac{H(X) - H(Y|X)}{H(X)} \tag{11}$$

$$=\frac{I(Y|X)}{H(X)}$$
 Def. of Mutual Information (12)

(b)
$$H(Y|X) \ge 0$$
, $H(X) > 0$. So $\frac{H(Y|X)}{H(X)} \ge 0$, $1 - \frac{H(Y|X)}{H(X)} \le 1$.
 $H(Y|X) < H(X)$, so $\frac{H(Y|X)}{H(X)} <= 1$, $1 - \frac{H(Y|X)}{H(X)} \ge 0$.
 Therefore, $0 \le r \le 1$.

(c) r=0 when two variables are independent. r=1 when two variables are perfectly correlated.

Problem 3

(a) $\tanh x = \frac{\sinh x}{\cosh x} = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{1 - e^{-2x}}{1 + e^{-2x}}$. Compared to $\frac{1}{1 + e^{-x}}$, \tanh has a steeper slope.

To be an appropriate sigmoid function, tanh needs to be scaled to range of [0, 1].

(b) We know W^k is 2×2 .

$$\frac{\partial H}{\partial w_{ij}^k} = \frac{\partial}{\partial w_{ij}^k} (\lambda^{k+1})^T g(W^k x^k) \tag{13}$$

$$= \frac{\partial}{\partial w_{ij}^k} (\lambda_1^{k+1} g(w_{11} x_1^k + w_{12} x_2^k) + \lambda_2^{k+1} g(w_{21} x_1^k + w_{22} x_2^k))$$
 (14)

$$= \lambda_1^{k+1} \frac{\partial}{\partial w_{ij}^k} g(w_{11} x_1^k + w_{12} x_2^k) + \lambda_2^{k+1} \frac{\partial}{\partial w_{ij}^k} g(w_{21} x_1^k + w_{22} x_2^k) \quad (15)$$

Therefore, for $w_{11}, w_{12}, w_{21}, w_{22}$, there is $\frac{\partial H}{\partial w_{ij}^k} = \lambda^{k+1} x_j^k g'(w_i^k x^k)$.

Problem 4

(a) The code for computing these results is attached separately.

IG(Color) = 0.1043

IG(Size) = 0.4086

IG(Noise) = 0.0207

For small size,

IG(Color) = 0.3219

IG(Noise) = 0.0729

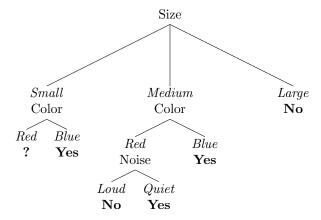
For medium size,

$$IG(Color) = 0.1226$$

 $IG(Noise) = 0.1226$

For large size, IG is clearly 0.

The decision tree is



(b) If the event of missing a datum is uniformly random over all the attributes, then it doesn't harm if we simply delete that line.

Problem 5

(a)
$$\min \frac{1}{3}\pi r^2 h$$
 such that $A=\pi rs+\pi r^2,\ s^2=r^2+h^2.$ Use Lagrange multiplier, $H=\frac{1}{3}\pi r^2 h+\lambda(\pi rs+\pi r^2-A)+\gamma(r^2+h^2-s^2).$
$$\frac{\partial H}{\partial r}=\frac{2}{3}\pi rh+\lambda(\pi s+2\pi r)+2\gamma r=0$$

$$\frac{\partial H}{\partial h}=\frac{1}{3}\pi r^2+2\gamma h=0$$

Problem 6

Each node has m possible attributes. So there are no more than m^n configuration of the decision tree. The number of different classifiers is also no more than m^n .

We know that for data set with size of k, a decision tree should have 2^k decisions. So the VC dimension is $\log_2 m^n = n \log_2 m = O(n \log(m))$.

Problem 7

The smallest positive integer p is 2.

When p=1, $k(x,x_i)=1+x^Tx_i=1+x_1x_{i1}+x_2x_{i2}$. So $\Phi(x)=(1,x_1,x_2)^T$. Clearly, as (x_1,x_2) cannot be separated by SVM, adding a bias of 1 doesn't help either.

either. When
$$p=2$$
 — same case as the class note — $k(x,x_i)=(1+x^Tx_i)^2=(1+x_1x_{i1}+x_2x_{i2})^2=1+x_1^2x_{i1}^2+x_2^2x_{i2}^2+2x_1x_{i1}+2x_2x_{i2}+2x_1x_{i1}x_2x_{i2}$. Then $\Phi(x)=(1,x_1^2,x_2^2,\sqrt{2}x_1,\sqrt{2}x_2,\sqrt{2}x_1x_2)^T$. Let $\lambda=\begin{pmatrix} \lambda_1\\ \lambda_2\\ \lambda_3\\ \lambda_4 \end{pmatrix}$. $Q(\lambda)=I\lambda-\frac{1}{2}\lambda^TA\lambda$, where $A=\begin{pmatrix} 9&-1&-1&1\\ -1&9&1&-1\\ -1&1&9&-1\\ 1&-1&-1&9 \end{pmatrix}$, the elements of which are computed by the kernel function. The solution is $\lambda_i=\frac{1}{8}$ for $i=1,2,3,4$. $Q(\lambda)=\frac{1}{4}$.

Using a value of p larger than minimum would unnecessarily map the data to higher dimension. The classifier becomes more nonlinear in lower dimension, and thus may overfit the data.