Shun Zhang

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RESEARCH INTERESTS Reinforcement learning, robotics, theoretical machine learning, human cognition.

EDUCATION

University of Texas at Austin, Austin, TX

Integrated B.S./M.S. Program, Computer Science, Jan 2012 - May 2015 (Expected)

- Major G.P.A 3.8. Overall G.P.A 3.55.
- Master Thesis with Prof. Peter Stone.

Nanjing University of Aeronautics and Astronautics, Nanjing, China

Undergraduate program, Computer Science and Technology, Sep 2009 - Dec 2011

- G.P.A. 88/100.
- Transferred to University of Texas at Austin in Jan. 2012.

RESEARCH EXPERIENCE

Representation Learning in Reinforcement Learning

Fall 2014-Spring 2015

Department of Computer Science University of Texas at Austin

- Supervisor: Prof. Peter Stone.
- Research question: Reinforcement Learning requires abstraction for large-scale problems. Examples are feature extraction and hiarachical learning. Can the learning agent learn such abstraction on the fly?
- In progress for Master Thesis.

Modular Reinforcement Learning

Fall 2014

Department of Computer Science and Center for Perceptual Systems University of Texas at Austin

- Supervisor: Prof. Dana Ballard and Prof. Mary Hayhoe.
- Research question: Assume human already has Markov Decision Processes (MDP) trained for prelimary tasks, how would these MDPs contribute to the complicated behavior?
- Using Inverse Reinforcement Learning to interpret human's behavior, assuming that it is a combination of the MDPs for prelimary tasks.

Determining Placements of Influencing Agents in a Flock

Fall 2014

Department of Computer Science University of Texas at Austin

- Supervisor: Prof. Peter Stone.
- Research question: Where should influencing agents be initially located within a flock to maximize their influence on the flock?
- Using MASON simulator to evaluate different placements, including border of the flock, grid positions, graph-based positions in the flock.
- Paper in preparation: Determining Placements of Influencing Agents in a Flock. Katie Genter, Shun Zhang and Peter Stone.

Action Selection in Robotic Motion Learning

Fall 2013

Department of Computer Science University of Texas at Austin

- Supervisor: Prof. Peter Stone.
- Research question: Instead of uniformly randomly selecting actions to try, can a robot explicitly select actions to explore its belief state space?
- Implementing ASAMI (a model-learning algorithm) on Nao robot using bandit-based exploration.
- Archieved in Undergraduate Research Journal in University of Texas at Austin, 2014.

Semi-Autonomous Intersection Management

Summer, Fall 2012

Department of Computer Science University of Texas at Austin

- Supervisor: Prof. Peter Stone and Prof. Tsz-Chiu Au.
- Research question: Can we find a policy better than traffic signals, if human-driven, semi-autonomous and fully-autonomous vehicles are sharing the road?
- Designing and evaluating a policy that is competent with all three types of vehicles, and performs better than traffic signals.
- Related publication: Semi-Autonomous Intersection Management (Extended Abstract).
 Tsz-Chiu Au, Shun Zhang, and Peter Stone. Autonomous Agents and Multiagent Systems (AAMAS), 2014.

PUBLICATIONS

 Tsz-Chiu Au, Shun Zhang, and Peter Stone. Semi-Autonomous Intersection Management (Extended Abstract). Autonomous Agents and Multiagent Systems (AAMAS), 2014.

Papers in Preparation

1. Katie Genter, **Shun Zhang**, and Peter Stone. Determining Placements of Influencing Agents in a Flock.

AWARDS

Student Awards — University of Texas at Austin

• hold

time

time

Presentations

Statistical Meetings

• hold

TEACHING EXPERIENCE

Undergraduate Teaching Assistant (Proctor) CS 301K Foundations of Logical Thought

Fall 2013, Spring 2014

with Dr. Jacob Schrum

Department of Computer Science, University of Texas at Austin

Industrial Experience

SDE Intern at Amazon

Summer 2014

Seattle, WA

SDE Intern at Semantic Designs

Summer 2013

Seattle, WA

• Supervisor: Dr. Ira Baxter.