# Shun Zhang

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RESEARCH INTERESTS

Reinforcement learning, robotics, multiagent systems, convex optimization, human cognition.

EDUCATION

University of Texas at Austin, Austin, TX

Integrated B.S./M.S. Program, Computer Science, Jan. 2012 - May. 2015 (Expected)

- Major G.P.A. 3.8. Overall G.P.A. 3.55.
- Master Thesis.

### Nanjing University of Aeronautics and Astronautics, Nanjing, China

Undergraduate program, Computer Science and Technology, Sep. 2009 - Dec. 2011

- G.P.A. 3.8/5.0.
- Transferred to University of Texas at Austin in Jan. 2012.

## RESEARCH EXPERIENCE

#### Modular Reinforcement Learning

Fall 2014 — Spring 2015

Department of Computer Science and Center for Perceptual Systems University of Texas at Austin

- Supervisor: Prof. Dana Ballard and Prof. Mary Hayhoe.
- Research question: Assume human already has Markov Decision Processes (MDP) trained for preliminary tasks, how would these MDPs contribute to complicated behaviors?
- Using Inverse Reinforcement Learning to interpret human's behavior, assuming that it is a combination of the MDPs for preliminary tasks.
- Master thesis. Part of the draft [link].

#### Determining Placements of Influencing Agents in a Flock

Fall 2014

Department of Computer Science University of Texas at Austin

- Supervisor: Prof. Peter Stone.
- Research question: Where should influencing agents be located within a flock to maximize their influence on the flock?
- Using MASON simulator to evaluate different placements of influencing agents, including border, grid, and graph-based placements.

#### Reinforcement Learning on Atari Games

Fall 2013

Department of Computer Science University of Texas at Austin

- Supervisor: Prof. Peter Stone.
- Research question: Can we apply TEXPLORE, a sample-efficient Reinforcement Learning algorithm, to complicated domains like Atari games?
- Undergraduate research course [link].

#### Action Selection in Robotic Motion Learning

Fall 2013

Department of Computer Science University of Texas at Austin

• Supervisor: Prof. Peter Stone.

- Research question: Instead of uniformly randomly selecting actions to try. can a robot explicitly select actions to explore its belief state space?
- Implementing ASAMI (a model-learning algorithm) on Nao robot using bandit-based exploration.
- Autonomous Robots course project. Achieved in Undergraduate Research Journal in University of Texas at Austin, 2014. [link]

## Structured Exploration for Relational Reinforcement Learning Spring 2013 Department of Computer Science

University of Texas at Austin

- Supervisor: Prof. Peter Stone.
- Research question: Can we improve the exploration efficiency of the Relational Reinforcement Learning algorithm?
- Applying the exploration mechanism in Rmax-Q to Relational Reinforcement Learning to improve the latter's sample efficiency.
- Reinforcement Learning course project. [link]

# Semi-Autonomous Intersection Management

Summer, Fall 2012

Department of Computer Science University of Texas at Austin

- Supervisor: Prof. Peter Stone and Prof. Tsz-Chiu Au.
- Research question: Can we find a policy better than traffic signals, if human-driven, semi-autonomous and fully-autonomous vehicles are sharing the road?
- Designing and evaluating a policy that is competent with all three types of vehicles, and performs better than traffic signals.

#### **Publications**

- Tsz-Chiu Au, Shun Zhang, and Peter Stone. Semi-Autonomous Intersection Management (Extended Abstract). Autonomous Agents and Multiagent Systems (AAMAS), 2014. [link]
- Tsz-Chiu Au, Shun Zhang, and Peter Stone. Autonomous Intersection Management for Semi-Autonomous Vehicles. In Handbook of Transportation, 2015. [link] <sup>1</sup>
- Katie Genter, Shun Zhang, and Peter Stone. Determining Placements of Influencing Agents in a Flock. Autonomous Agents and Multiagent Systems (AAMAS), 2015.

PAPER SUBMITTED • Shun Zhang, Matthew Tong, Mary Hayhoe, Dana Ballard. Modular Inverse Reinforcement Learning on Human Motion.

# Presentations

• Intersection Management with Constraint-Based Reservation Systems. Autonomous Robots and Multirobot Systems (ARMS), 2014.

#### Conference ATTENDANCE

- Autonomous Agents and Multiagent Systems (AAMAS), Paris, 2014.
- AAAI Conference, Austin, TX, 2015.

## Courses and Projects

#### Graduate Level

- Large Scale Optimization (EE 381V)
- Markov Chain and Mixing Time (M 394C)

Final Project: Mixing Time in Reinforcement Learning Convergence Analysis . [link]

• Machine Learning (CS 391L)

Project reports:

- Principal Component Analysis. [link]
- Independent Component Analysis. [link]

<sup>&</sup>lt;sup>1</sup>This is the extended version of the Semi-Autonomous Intersection Management paper.

- Approximate Inference in Bayesian Networks. [link]
- Reinforcement Learning. [link]
- Genetic Algorithm. [link]
- Autonomous Robots (CS 393R)
- Randomized Algorithms (CS 388R)
- Reinforcement Learning (CS 394R)

Project reports:

- N-armed bandit Problem. [link]
- Eligibility Traces. [link]
- Bootstrapping with Function Approximation. [link]
- Transfer Learning in Gridworld. [link]
- Introduction to Mathematical Logic (CS 388L)
- Automated Logical Reasoning (CS 395T)

## Undergraduate Level

- Artificial Intelligence (CS 343)
- Principles of Computer Systems (CS 439)
- Automata Theory (CS 341)
- Information Retrieval (CS 371R)
- Programming Languages (CS 345) Final Project: List Interpreter. [link]
- etc.

#### AWARDS

Student Awards — University of Texas at Austin

• Louis E. Rosier Memorial Endowment Scholarship.

2013-2014

Student Awards — Nanjing University of Aeronautics and Astronautics

• Department Scholarships.

2009-2011

# TEACHING EXPERIENCE

# Undergraduate Teaching Assistant (Proctor)

Fall 2013, Spring 2014

 $\operatorname{CS}$  301K Foundations of Logical Thought

with Dr. Jacob Schrum

Department of Computer Science, University of Texas at Austin

## Industry Experience

#### SDE Intern at Amazon

Summer 2014

Seattle, WA

- Created an internal tool that supports WebRTC in Firefox.
- Modifying an internal tool for visualizing customer data, using Scala on Spark.

#### SDE Intern at Semantic Designs

Summer 2013

Austin, TX

• Integrating a GUI viewer to Smart Differencer (TM) tools. Using JavaCC for parsing and Swing for GUI.

## Languages

- Natural languages: Mandarin Chinese (native), English (fluent), Japanese (preliminary).
- Programming languages: Proficient in programming in Python, Octave/Matlab, Java, C/C++; Familiar with Lisp, Oracle SQL, LaTeX, Web Development Languages (HTML, JavaScript, PHP), Perl, Scala.