Semi-Autonomous Intersection Management

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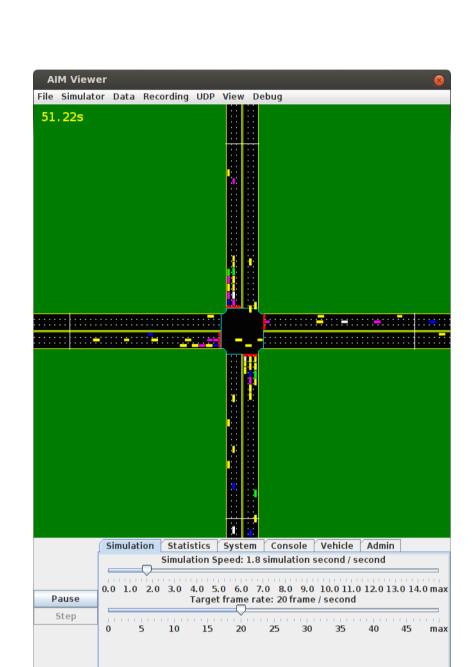


Previous Work: Autonomous Intersection Management (AIM)

The AIM protocol

- →Fine control of autonomous vehicles.
- →More vehicles can simultaneously cross an intersection.
- →Effectively reduces the delay of vehicles.





Limitations of AIM

- → Designed for the time when vehicles are autonomous.
- →A long transition period during which most vehicles have limited capabilities.
- →New term: **semi**autonomous vehicles
- →Vehicles with limited autonomous driving and wireless communication capabilities.

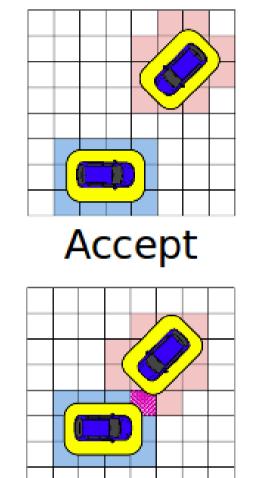
Semi-Autonomous Vehicles

- →General enough to accept reservation requests from any semi-autonomous vehicles.
- →We focus on the three types of semi-auto vehicles.

Vehicle Type	Communication	Cruise	Adaptive
	Device	Control	Cruise Control
SA-ACC	X	X	X
SA-CC	X	X	
SA-Com	Χ		

Constraint-Based Reservation

- →Intention: The direction in which the vehicle intends to move.
- →Vehicle Type: The type of vehicle.
- **→Entry Condition**: The condition under which the vehicle will enter the intersection.
- →Acceleration Profile List: The list of possible acceleration schedules from among which the vehicle will choose one to follow during the traversal of the intersection.



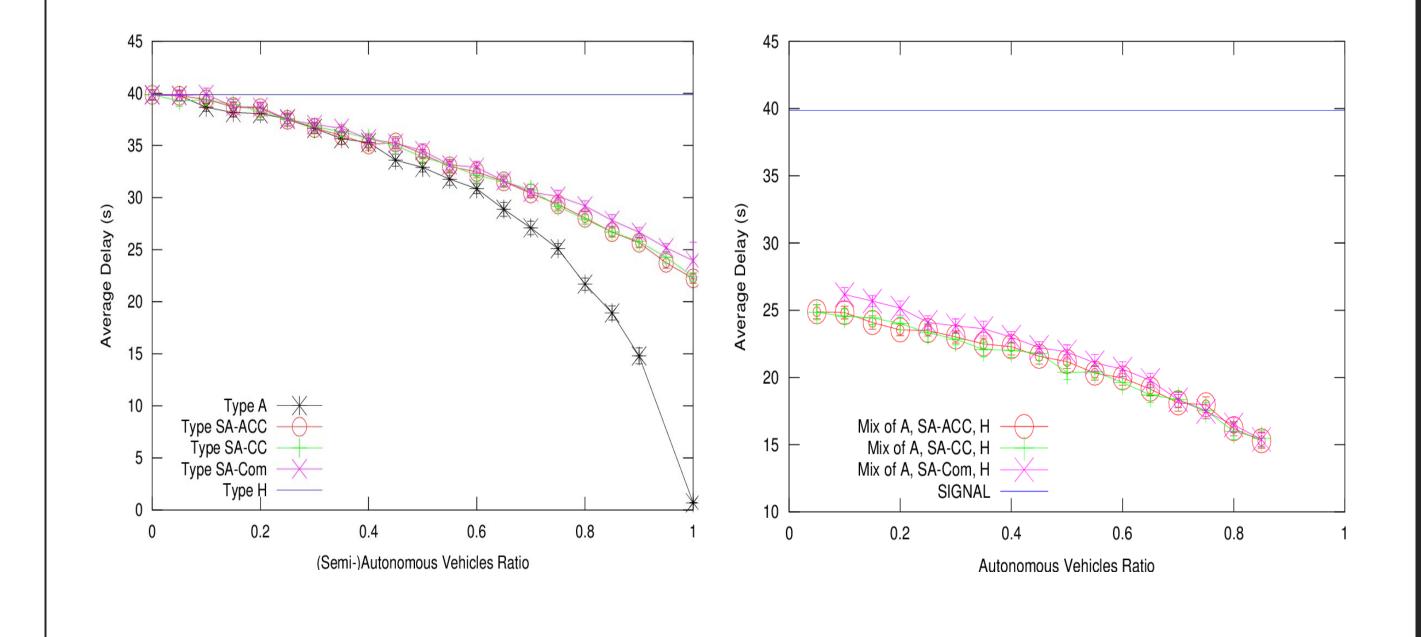
Reject

Experiment settings:

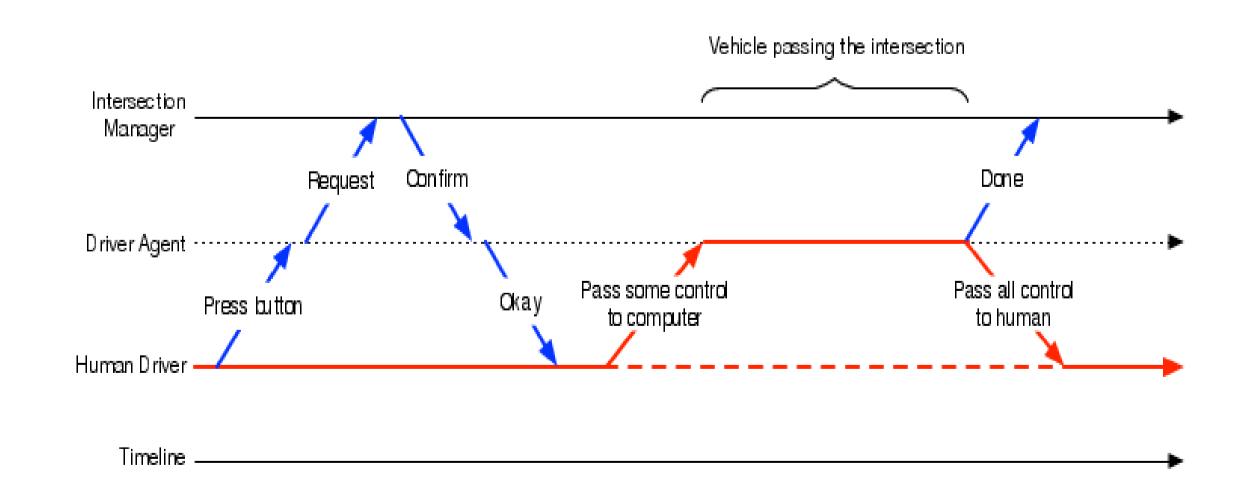
- →Intersection: 3 lanes on each road.
- →Traffic: 360 vehicles/hour/lane.
- → Type of vehicles: Fully Autonomous, Adaptive Cruise Control, Cruise Control, Communication Device and Traditional Human-driven.

Experiment results:

- →Semi-autonomous vehicles perform similarly to fully autonomous vehicles when the ratio to human-driven vehicles is below 40%.
- →Beyond 40%, fully autonomous vehicles increasingly outperform semi-autonomous vehicles.



Interaction Model



Conclusion

- →This is the first multiagent protocol to enable smooth interactions between human-driven, fully autonomous, and semi-autonomous vehicles.
- →Showed that our system can greatly decrease traffic delay when most vehicles are semi-autonomous.

References

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