## Kaggle Digit Recognizer

sample\_submission

🖾 train

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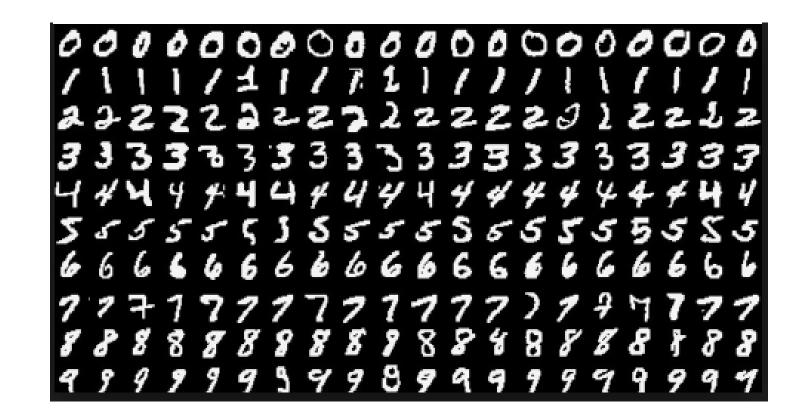
236 KB

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49.921 KB

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74,976 KB



### **Dataset Details**

- Goal
  - Recognition handwritten image of digit
- Task
  - image recognition(10 classes of digits)
- Training / Testing
  - around 42k / 28k
- Reference
  - <a href="https://www.kaggle.com/c/digit-recognizer/data">https://www.kaggle.com/c/digit-recognizer/data</a>

### Train.csv

- Each image is 28 pixels in height and 28 pixels in width, for a total of 784 pixels in total.
- This pixel-value is an integer between 0 and 255, inclusive.

label	pixel0	pi	ixel1	pixel2	pixel3	pixel4	pixel5	pixel6	pixel7	pixel8	pixel9	pixel10	pixel11	pixel12 pi
	1	0	0	0	0	0	C	0	C	0	0	0	0	0
	0	0	0	0	0	0	C	0	C	0	0	0	0	0
	1	0	0	0	0	0	C	0	C	0	0	0	0	0
	4	0	0	0	0	0	C	0	C	0	0	0	0	0
	0	0	0	0	0	0	C	0	C	0	0	0	0	0
	0	0	0	0	0	0	C	0	C	0	0	0	0	0
	7	0	0	0	0	0	C	0	C	0	0	0	0	0
	3	0	0	0	0	0	C	0	0	0	0	0	0	0
	5	0	0	0	0	0	C	0	C	0	0	0	0	0
	3	0	0	0	0	0	C	0	C	0	0	0	0	0
	8	0	0	0	0	0	C	0	C	0	0	0	0	0
	9	0	0	0	0	0	C	0	0	0	0	0	0	0
	1	0	0	0	0	0	C	0	0	0	0	0	0	0
	3	0	0	0	0	0	C	0	C	0	0	0	0	0
	3	0	0	0	0	0	C	0	0	0	0	0	0	0
	1	0	0	0	0	0	C	0	C	0	0	0	0	0

### Model Architecture

```
class LeNet(nn. Module):
  def __init__(self):
    super(LeNet, self).__init__()
    self.conv1 = nn.Conv2d(1, 6, (5,5), padding=2)
    self.conv2 = nn.Conv2d(6, 16, (5, 5))
    self.fc1 = nn.Linear(16*5*5, 120)
    self.fc2 = nn.Linear(120, 84)
    self.fc3 = nn.Linear(84, 10)
  def forward(self, x):
    x = F. \max_{pool2d}(F. relu(self. conv1(x)), (2,2))
    x = F. \max_{pool2d}(F. relu(self. conv2(x)), (2, 2))
    x = x.view(-1, self.num flat features(x))
    x = F.relu(self.fcl(x))
    x = F.relu(self.fc2(x))
    x = self. fc3(x)
    return x
  def num_flat_features(self, x):
    size = x. size()[1:]
    num_features = 1
    for s in size:
      num_features *= s
    return num features
net = LeNet()
#print (net)
use_gpu = torch.cuda.is_avai1able()
if use gpu:
  net = net.cuda()
  print ('USE GPU')
else:
  print ('USE CPU')
criterion = nn.CrossEntropyLoss()
optimizer = optim. SGD (net.parameters(), 1r=0.001)
```

#...t... ("1 Tolation acts")

use "LeNet" model

```
#print ("1. Loading data")
train = pd. read_csv('/content/drive/My Drive/train.csv').values
train = shuffle(train)
test = pd.read csv('/content/drive/My Drive/test.csv').values
#print ("2. Converting data")
X_data = train[:, 1:].reshape(train.shape[0], 1, 28, 28)
X_data = X_data.astype(float)
X data /= 255.0
X data = torch.from numpy(X data);
X \text{ label = train[:,0]};
X label = X label.astype(int);
X label = torch.from numpy(X label);
X label = X label.view(train.shape[0],-1);
#print (X_data.size(), X_label.size())
#print ("3. Training phase")
nb_train = train.shape[0]
nb_epoch = 30000
nb_index = 0
nb batch = 16
for epoch in range(nb_epoch):
 if nb_index + nb_batch >= nb_train:
    nb index = 0
  else:
   nb_index = nb_index + nb_batch
  mini_data = Variable(X_data[nb_index:(nb_index+nb_batch)].clone())
  mini_label = Variable(X_label[nb_index:(nb_index+nb_batch)].clone(), requires_grad = False)
  mini_data = mini_data.type(torch.FloatTensor)
  mini_label = mini_label.type(torch.LongTensor)
  if use gpu:
   mini data = mini data.cuda()
   mini label = mini label.cuda()
  optimizer.zero grad()
  mini out = net(mini data)
  mini label = mini label.view(nb batch)
 mini loss = criterion(mini out, mini label)
  mini loss.backward()
  optimizer.step()
  if (epoch + 1) % 10 == 0:
   print("Epoch = %d, Loss = %f" %(epoch+1, mini_loss.data))
```

```
#print ("4. Testing phase")
Y_data = test.reshape(test.shape[0], 1, 28, 28)
Y_data = Y_data.astype(float)
Y_data /= 255.0
Y_data = torch.from_numpy(Y_data);
#print (Y_data.size())
nb_test = test.shape[0]
net.eva1()
final prediction = np.ndarray(shape = (nb test, 2), dtype=int)
for each sample in range(nb test):
  sample data = Variable(Y data[each sample:each sample+1].clone())
  sample data = sample data.type(torch.FloatTensor)
  if use gpu:
    sample data = sample data.cuda()
  sample out = net(sample data)
  _, pred = torch.max(sample_out, 1)
  final_prediction[each_sample][0] = 1 + each_sample
  final_prediction[each_sample][1] = pred.data
  if (each sample + 1) % 1000 == 0:
    print("Total tested = %d" %(each sample + 1))
#print ('5. Generating submission file')
submission = pd. DataFrame(final prediction, dtype=int, columns=['ImageId', 'Labed'])
submission.to_csv('/content/drive/My Drive/pytorch_LeNet.csv', index=False, header=True)
# end
```

# Assignment #2 – CNN Modeling

#### • Requirement

- 1. Setup programming environment
  - Pytorch ` Python ` Cuda.....anything you need for deep learning modeling.
- 2. Given the dataset and the CNN sample code, run training and testing. Report your final testing accuracy
- 3. For the given CNN model, add one additional CNN layer and one fully connected layer. Compare the testing accuracy of the modified model to the original model.

## Assignment #2 – CNN Modeling

- You need to hand in your source code and report
- The report should cover:
  - Method description what are your reference codes? How to run your test?
  - Experimental results
    - The comparison of classification accuracy from validation
    - The comparison of ranking from Kaggle for each feature
  - Discussion
  - Problem and difficulties
- Deadline: 11:59 pm, 5/06(Mon).
- File format zip all your files into a single file: studentID\_hw1\_version, ex: 602410143\_hw1\_v1

## Assignment Rules

#### Late policy

- You will get 20% deduction of your scores per day.
- It means if the assignment is delayed one day for 80%, two days for 60%,..., five days for 0%.

#### No-copy policy

- Copying is strictly forbidden in our class.
- Once the assignment is confirmed by TA as COPY, the score will be 0%.