

Project One

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Part I

Theoretical Part

Problem 3.1

Proof:

Obviously, since W is a matrix, then Wx is also a vector, so \forall vector x , $\|x\|_W = \|Wx\| \geq 0$, and if $x = 0$, $\|x\|_W = \|Wx\| = 0$. And if $\|x\|_W = \|Wx\| = 0$, then $Wx = 0$ by the definition of $\|\cdot\|$, because W is arbitrary nonsingular matrix, which means all of row vectors are linear independent, hence $x = 0$. So $\|x\|_W = 0$ if only and if $x = 0$;

Secondly, \forall vector x and y , $\|x + y\|_W = \|W(x + y)\| = \|Wx + Wy\| \leq \|Wx\| + \|Wy\| = \|x\|_W + \|y\|_W$;

Thirdly, for any scalar $\alpha \in \mathbb{C}$, $\|\alpha x\|_W = \|W(\alpha x)\| = \|\alpha Wx\| = \alpha \|Wx\| = \alpha \|x\|_W$. Thus, $\|\cdot\|_W$ is vector norm.

Problem 3.2

Proof:

Let λ denote arbitrary eigenvalue of A and x is the corresponding eigenvector, then we have

$$Ax = \lambda x$$

get norm of both sides, so

$$\|Ax\| = \|\lambda x\| = |\lambda| \|x\|$$

By the definition of induced matrix norm

$$\|A\| = \sup_{x \neq 0} \frac{\|Ax\|}{\|x\|}$$

thus

$$|\lambda| \|x\| = \|Ax\| \leq \|A\| \|x\|$$

$\Rightarrow |\lambda| \leq \|A\|$. Because λ is arbitrary eigenvalue of A , so $\rho(A) \leq \|A\|$.

Problem 3.6

Proof:

(a).

Obviously, for any vector x , $\|x\|' = \sup_{\|y\|=1} |y^*x| \geq 0$, and if $x = 0$, $\|x\|' = \sup_{\|y\|=1} |y^*0| = 0$. And when $\|x\|' = \sup_{\|y\|=1} |y^*x| = 0$, then

$$0 = \sup_{\|y\|=1} |y^*x| = \sup_{\|y\|=1} \|x\| \|y\| |\cos(\theta)|$$

where $\cos(\theta) = \frac{y^*x}{\|x\| \|y\|}$, so $0 = \sup_{\|y\|=1} \|x\| \|y\| |\cos(\theta)| = \|x\|$, (because $\|y\| = 1$ and $\sup \cos(\theta) = 1$), so $x = 0$. Thus $\|x\|' = 0$ if and only if $x = 0$;

Secondly, for any two vector x and z , $\|x+z\|' = \sup_{\|y\|=1} |y^*(x+z)| = \sup_{\|y\|=1} |y^*x + y^*z| \leq \sup_{\|y\|=1} |y^*x| + \sup_{\|y\|=1} |y^*z| = \|x\|' + \|z\|'$;

Thirdly, for any scalar $\alpha \in \mathbb{C}$, $\|\alpha x\|' = \sup_{\|y\|=1} |y^*(\alpha x)| = |\alpha| \sup_{\|y\|=1} |y^*x| = |\alpha| \|x\|'$.

Hence, $\|\cdot\|'$ is a norm.

(b).

Since x, y is give with $\|x\| = \|y\| = 1$, then to show there exists a rank one $B = yz^*$ such that $Bx = y$ and $\|B\| = 1$ is to show there is such a vector z^* satisfies

Since $Bx = y \iff Bx - y = 0$, then $\|Bx - y\| = 0 = \|yz^*x - y\| = \|y(z^*x - 1)\|$ since z^*x is scalar here, and $\|y\| = 1$ by given, so $|z^*x - 1| = 0$.

By the lemma, for any x , there exists a nonzero z s.t. $|z^*x| = \|z\|' \|x\|$, then for the given x , we have $\frac{|z^*x|}{\|z\|'} - 1 = 0$, to get rid of the absolute value sign, we let

$$z_o = \text{sign}(z^*x) \frac{z}{\|z\|'}$$

then this z_o satisfies $Bx = y$, and it is easy to verify that $\|B\| = \sup_{\|x\|=1} \|Bx\| =$

$\sup_{\|x\|=1} \|y\| = 1$. Besides, since both $y, z_o \in \mathbb{C}^m$, then $B = yz_o^*$ is always a rank-

one matrix, because all the row vectors of the matrix B are linear dependent, i.e. for any $i \neq j$, $1 \leq i, j \leq m$

$$\frac{\vec{b_i}}{\vec{b_j}} = \frac{y_i}{y_j}$$

where $\vec{b_i}, \vec{b_j}$ are two distinct row vectors of B and y_i, y_j are the corresponding entries of y .

Problem 5.3

Solution:

(a).

Since $A = \begin{bmatrix} -2 & 11 \\ -10 & 5 \end{bmatrix}$, then we denote $M \triangleq A^*A$, then

$$M = \begin{bmatrix} -2 & -10 \\ 11 & 5 \end{bmatrix} \begin{bmatrix} -2 & 11 \\ -10 & 5 \end{bmatrix} = \begin{bmatrix} 104 & -72 \\ -72 & 146 \end{bmatrix}$$

it is easy to compute the eigenvalues λ_1, λ_2 of M by $|M - \lambda I| = 0 \Rightarrow (\lambda_1 - 200)(\lambda_2 - 50) = 0$, thus $\lambda_1 = 200 > \lambda_2 = 50$. So the singular values in $\Sigma = \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix}$ are $\sigma_1 = \sqrt{200} = 14.1421$ and $\sigma_2 = \sqrt{50} = 7.0711$.

Now we compute V .

For M , find the corresponding eigenvectors of its eigenvalues λ_1, λ_2 , we denote them as $X = [x_1, x_2]^T$ and $Y = [y_1, y_2]^T$:

$$(M - \lambda_1 I) X = 0 \Rightarrow \begin{bmatrix} 104 - 200 & -72 \\ -72 & 146 - 200 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow x_1 = -\frac{3}{4}x_2$$

Since $x_1^2 + x_2^2 = 1$, then $x_1 = 0.6, x_2 = -0.8$. Similarly, we can get $Y = \begin{bmatrix} 0.8 & 0.6 \end{bmatrix}^T$. (Under the request that V has the minimal number of signs)

Thus

$$V = [X \ Y] = \begin{bmatrix} 0.6 & 0.8 \\ -0.8 & 0.6 \end{bmatrix}$$

Then we compute U by $U = A(V^*)^{-1}\Sigma^{-1} = AV\Sigma^{-1} = \begin{bmatrix} -2 & 11 \\ -10 & 5 \end{bmatrix} \begin{bmatrix} 0.6 & 0.8 \\ -0.8 & 0.6 \end{bmatrix} \begin{bmatrix} 14.1421 & 0 \\ 0 & 7.0711 \end{bmatrix}^{-1}$

$$\text{thus } U = \begin{bmatrix} -0.7071 & 0.7071 \\ -0.7071 & -0.7071 \end{bmatrix}$$

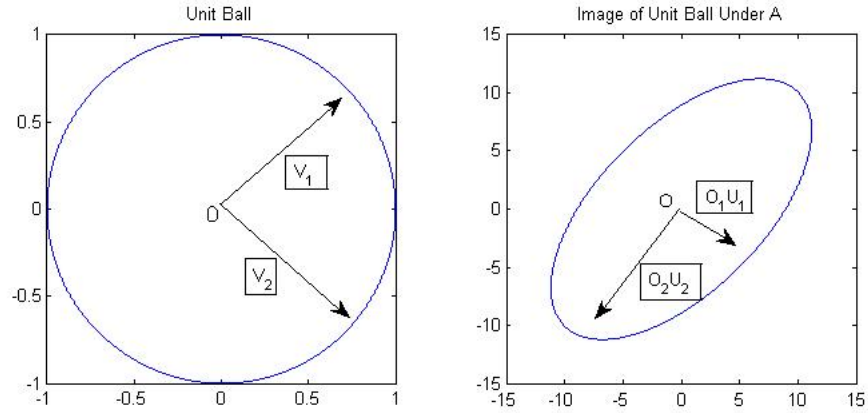
(b).

Please m-file: **5.3 .m**

The nonsingular values: $\Sigma = \begin{bmatrix} 14.1421 & 0 \\ 0 & 7.0711 \end{bmatrix}$;

The left nonsingular vectors u_1, u_2 are: $U = [u_1|u_2] = \begin{bmatrix} -0.7071 & 0.7071 \\ -0.7071 & -0.7071 \end{bmatrix}$;

The right nonsingular vectors v_1, v_2 are: $V = [v_1|v_2] = \begin{bmatrix} 0.6 & 0.8 \\ -0.8 & 0.6 \end{bmatrix}$.



(c).

$$\|A\|_1 = 16$$

$$\|A\|_2 = \sqrt{\rho(A^T A)} = \sqrt{200} = 14.1421$$

$$\|A\|_\infty = 15$$

(d).

Since $A = U\Sigma V^*$, then $(A)^{-1} = (U\Sigma V^*)^{-1} = (V^*)^{-1}\Sigma^{-1}U^{-1} = V\Sigma^{-1}U^*$,
then

$$A = \begin{bmatrix} 0.6 & 0.8 \\ -0.8 & 0.6 \end{bmatrix} \begin{bmatrix} 1/\sqrt{200} & 0 \\ 0 & 1/\sqrt{50} \end{bmatrix} \begin{bmatrix} -0.7071 & -0.7071 \\ 0.7071 & -0.7071 \end{bmatrix} = \begin{bmatrix} 0.05 & -0.11 \\ 0.1 & -0.02 \end{bmatrix}$$

(e).

Denote λ be the eigenvalues of matrix A , then let $|A - \lambda I| = 0 \Rightarrow \begin{vmatrix} -2 - \lambda & 11 \\ -10 & 5 - \lambda \end{vmatrix} = 0 \Rightarrow (\lambda - 5)(\lambda + 2) + 100 = 0$, then solve the equation, the roots are the eigenvalues of A : $\lambda_{1,2} = \frac{3 \pm \sqrt{-391}}{2} = 1.5 \pm 9.8869i$

(f).

Eigenvalues of A are $\lambda_{1,2} = \frac{3 \pm \sqrt{-391}}{2} = 1.5 \pm 9.8869i$, so

$$\lambda\lambda_2 = \frac{3 + \sqrt{-391}}{2} \cdot \frac{3 - \sqrt{-391}}{2} = 100$$

$$\text{while } \det(A) = -2 \times 5 - (-10) \times 11 = 100$$

thus

$$\det(A) = \lambda_1\lambda_2$$

And $|det(A)| = 100$, and $\sigma_1\sigma_2 = \sqrt{200}\sqrt{50} = 100$, so $|det(A)| = \sigma_1\sigma_2$.
(g).

The length of the long axis is $\|\sigma_1 u_1\|_2 = 10\sqrt{2}$ and the length of the short axis is $\|\sigma_2 u_2\|_2 = 5\sqrt{2}$, so the area is $S = \pi ab = 100\pi$.

Problem 5.4

Solution:

Suppose the eigenvalues of the hermitian matrix $M = \begin{bmatrix} 0 & A^* \\ A & 0 \end{bmatrix}_{2m \times 2m}$ in block form are $\lambda_i = \begin{bmatrix} \lambda_{(i-1)m+1} & 0 & \cdots & 0 \\ 0 & \lambda_{(i-1)m+2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_{(i-1)m+m} \end{bmatrix}_{m \times m}$, $i = 1, 2$, and denote $X = \begin{bmatrix} a & b \\ c & d \end{bmatrix}_{2m \times 2m}$ be the corresponding eigenmatrix of the eigenvalues matrix of $\Lambda = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$, where a, b, c, d are all $m \times m$ block matrixs, then the eigenvalue decomposition of M is $M = X\Lambda X^{-1}$. So our goal is to find such Λ and its corresponding X .

Since M is hermitian matrix, then by Theorem 5.5, the eigenvalues of M are real and the eigenmatrixs are unitary, which implies $X^{-1} = X^*$, so $M = X\Lambda X^*$. To find Λ , we compute the roots of $det(M - \Lambda I) = 0 = det\left(\begin{bmatrix} -\lambda & A^* \\ A & -\lambda \end{bmatrix}\right) \Rightarrow \lambda^2 = \Sigma^2$, so $\lambda_1 = \Sigma$ and $\lambda_2 = -\Sigma$ since λ_1, λ_2 are both real.

Next, we try to find X . We compute MM separately.

Since U, V are unitary, so in one way, we have:

$$MM = \begin{bmatrix} 0 & A^* \\ A & 0 \end{bmatrix} \begin{bmatrix} 0 & A^* \\ A & 0 \end{bmatrix} = \begin{bmatrix} A^*A & 0 \\ 0 & AA^* \end{bmatrix} = \begin{bmatrix} V\Sigma^2V^* & 0 \\ 0 & U\Sigma^2U^* \end{bmatrix}$$

In the other way, since X is also unitary, so we have:

$$MM = (X\Lambda X^*)(X\Lambda X^*) = X\Lambda^2 X^*$$

thus

$$M = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} \lambda_1^2 & 0 \\ 0 & \lambda_2^2 \end{bmatrix} \begin{bmatrix} a^* & c^* \\ b^* & d^* \end{bmatrix} = \begin{bmatrix} a\Sigma^2 a^* + b\Sigma^2 b^* & a\Sigma^2 c^* + b\Sigma^2 d^* \\ c\Sigma^2 a^* + d\Sigma^2 b^* & c\Sigma^2 c^* + d\Sigma^2 d^* \end{bmatrix}$$

so

$$\begin{bmatrix} V\Sigma^2V^* & 0 \\ 0 & U\Sigma^2U^* \end{bmatrix} = \begin{bmatrix} a\Sigma^2 a^* + b\Sigma^2 b^* & a\Sigma^2 c^* + b\Sigma^2 d^* \\ c\Sigma^2 a^* + d\Sigma^2 b^* & c\Sigma^2 c^* + d\Sigma^2 d^* \end{bmatrix}$$

$\Rightarrow a\Sigma^2a^* + b\Sigma^2b^* = V\Sigma^2V^*$, $a\Sigma^2c^* + b\Sigma^2d^* = 0$, $c\Sigma^2a^* + d\Sigma^2b^* = 0$, $c\Sigma^2c^* + d\Sigma^2d^* = U\Sigma^2U^*$. Since X is also a unitary matrix, which means $\begin{bmatrix} a & c \end{bmatrix}^T$ and $\begin{bmatrix} b & d \end{bmatrix}^T$ are mutually orthogonal and their norms should be 1. So we find :

$$X = \begin{bmatrix} \frac{\sqrt{2}}{2}V & \frac{\sqrt{2}}{2}V \\ \frac{\sqrt{2}}{2}U & -\frac{\sqrt{2}}{2}U \end{bmatrix} = \frac{\sqrt{2}}{2} \begin{bmatrix} V & V \\ U & -U \end{bmatrix}$$

Thus we get $M = X\Lambda X^{-1}$

Problem 6.3

Proof:

Since $A \in \mathbb{C}^{m \times n}$ is not a square matrix (suppose $m > n$), so we use the reduced singular value decomposition (SVD) of A , which is $A = \hat{U}\hat{\Sigma}V^*$ where $\hat{U} \in \mathbb{C}^{m \times n}$ and $V \in \mathbb{C}^{n \times n}$ are both unitary and $\hat{\Sigma} \in \mathbb{R}^{n \times n}$ is diagonal. Then

$$A^*A = (U\hat{\Sigma}V^*)^*(U\hat{\Sigma}V^*) = V\hat{\Sigma}^2V^*$$

(\Leftarrow) : If A^*A is nonsingular, then $\det(A^*A) = \det(V\hat{\Sigma}^2V^*) = \det(V)\det(\hat{\Sigma}^2)\det(V^*) = \det(\hat{\Sigma}^2) \neq 0$, then all the n entries of $\hat{\Sigma}$ are nonzero, which implies all of the n singular values of A are nonzero, then A is full rank.

(\Rightarrow) : Since A is full rank, then A has n nonzero singular values, then $\det(A^*A) = \det(\hat{\Sigma}^2) \neq 0$, so A^*A is nonsingular.

Problem 7.5

Proof:

(a).

(\Rightarrow) : Since A has rank n , then A is full rank, so by Theorem 7.2 we can easily conclude that the diagonal entries of \hat{R} are nonzero (positive).

(\Leftarrow) : From the Gram-Schmidt iteration, (7.8) and (7.6), we have

$$|r_{jj}| = \|a_j - \sum_{i=1}^{j-1} r_{ij}q_i\|$$

where

$$q_i = \frac{a_i - \sum_{k=1}^{i-1} r_{ki}q_k}{r_{ii}}$$

If all diagonal entries r_{jj} of \hat{R} are nonzero, then for any $j = 1, 2, 3 \dots n$, $\|a_j - \sum_{i=1}^{j-1} r_{ij}q_i\| \neq 0$, which implies that a_j cannot be written as the composition of q_1, q_2, \dots, q_{j-1} , and because each q_i can be written as composition of a_1, a_2, \dots, a_i , let $i = j - 1$, then a_j cannot be written as the composition of a_1, a_2, \dots, a_{j-1} , i.e. a_j is linear independent with a_1, a_2, \dots, a_{j-1} , thus all the n column vectors a_1, a_2, \dots, a_n of A are mutually linear independent. Thus A has full rank.

(b).

\hat{R} has k nonzero diagonal entries, then the rank of A is exactly k .

This follows from the (\Leftarrow) of part (a). Suppose that only $r_{11}, r_{22}, \dots, r_{kk}$ are nonzero. Then we can find, similar to part (a), at least a_1, a_2, \dots, a_k are mutually linear independent. Now we consider a_{k+1} :

Since $r_{k+1,k+1} = 0$, and $|r_{k+1,k+1}| = \|a_{k+1} - \sum_{i=1}^k r_{i,k+1} q_i\| = 0$, so

$$a_{k+1} = \sum_{i=1}^k r_{i,k+1} q_i$$

where $q_i = \frac{a_i - \sum_{k=1}^{i-1} r_{ki} q_k}{r_{ii}}$, since every q_i can be written as composition of a_1, a_2, \dots, a_i , so let $i = k$, then a_{k+1} can be written as the composition of a_1, a_2, \dots, a_k , thus

$$a_i \in \langle a_1, a_2, \dots, a_k \rangle \text{ for } k+1 \leq i \leq n$$

Thus A has exactly rank k .

2.

Proof:

Since $A \in \mathbb{C}^{m \times n}$ and $b \in \mathbb{C}^m$, so $b \notin \text{range}(A)$, thus this rectangular system of equations is overdetermined. Denote $r = b - Ax$ called the residual, then by Theorem 11.1 a vector x minimizes the residual norm $\|r\|_2 = \|b - Ax\|_2$ if and only if $r \perp \text{range}(A)$, that is $A^*r = 0$. Thus $A^*r = 0 \Leftrightarrow A^*Ax = A^*b$.

Let's compute x now. In proof of **problem 6.3** (see above), we have already proved that if A has full rank, then A^*A is nonsingular, thus A^*A 's inverse exists. By the given reduced SVD of $A = \hat{U}\hat{\Sigma}\hat{V}^*$, then we find x :

$$x = (A^*A)^{-1}A^*b = (\hat{V}\hat{\Sigma}\hat{U}^*\hat{U}\hat{\Sigma}\hat{V}^*)^{-1}(\hat{U}\hat{\Sigma}\hat{V}^*)^*b = \hat{V}\hat{\Sigma}^{-2}\hat{V}^*\hat{V}\hat{\Sigma}\hat{U}^*b = \hat{V}\hat{\Sigma}^{-1}\hat{U}^*b$$

thus

Part II

Numerical Experiments

1.

Please see the m-file: **Q1 of coding part.m**

Just copy the whole code and run it, we will get as follows:

*****to verify the unitary of Qs from clgs and msg *****

-All of column vectors are unit in Qs from clgs

-All of column vectors are unit in Qs from mgs

*****to verify the orthogonality of Qs from clgs and msg *****

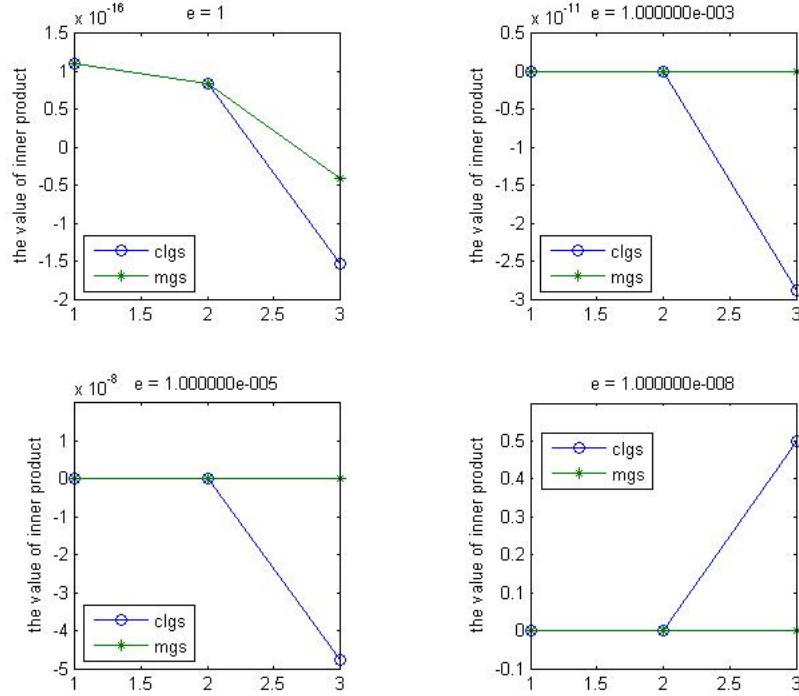
1.Qs from clgs are not orthogonal

it is not orthogonal when $\epsilon = 1.000000\text{e-}008$

the inner product of the two nonorthogonal vector is $5.000000\text{e-}001$, which is far away from 0

2.Qs from mgs are orthogonal

The observations are cited inside the graph below:



Conclusion: Classical G-S algorithm is not stable when the matrix contains some tiny values, that's to say the matrix is ill conditioned. While Modified G-S algorithm is more stable.

Problem 10.2

Please see the m-files: **house.m** and **formQ.m**

Actually, the R we get from house.m is m-by-n matrix.

Problem 10.3

Please see the m-file: **10.3.m**

Differences:

1. The diagonal entries of $R1$ by **mgs** are all positive, but the diagonal entries of $R2$ and $R3$ exist some negative ones.
2. $R2$ has the same column and row numbers as Z because householder projections are just kind of row operations, they don't change the shape of the original matrix. While $R1$ and $R3$'s column and row numbers are same with each other but not the same with Z .