

Bayesian Networks

Chapter 14

Bayes Nets (so far)

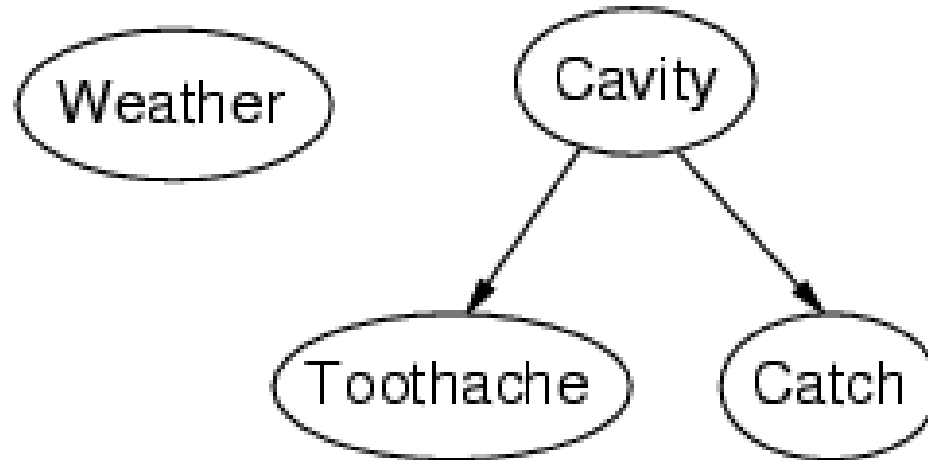
- A belief network is automatically acyclic by construction.
- A belief network is a directed acyclic graph (DAG) where nodes are random variables.
- The parents of a node n are those variables on which n directly depends.
- A belief network is a graphical representation of dependence and independence:
 - A variable is independent of its non-descendants given its parents.

Bayesian networks

- A simple, graphical notation for conditional independence assertions and hence for compact specification of full joint distributions
- Syntax:
 - a set of nodes, one per variable
 - a directed, acyclic graph (link \approx "directly influences")
 - a conditional distribution for each node given its parents:
$$P(X_i \mid \text{Parents}(X_i))$$
- In the simplest case, conditional distribution represented as a **conditional probability table** (CPT) giving the distribution over X_i for each combination of parent values

Example

- Topology of network encodes conditional independence assertions:

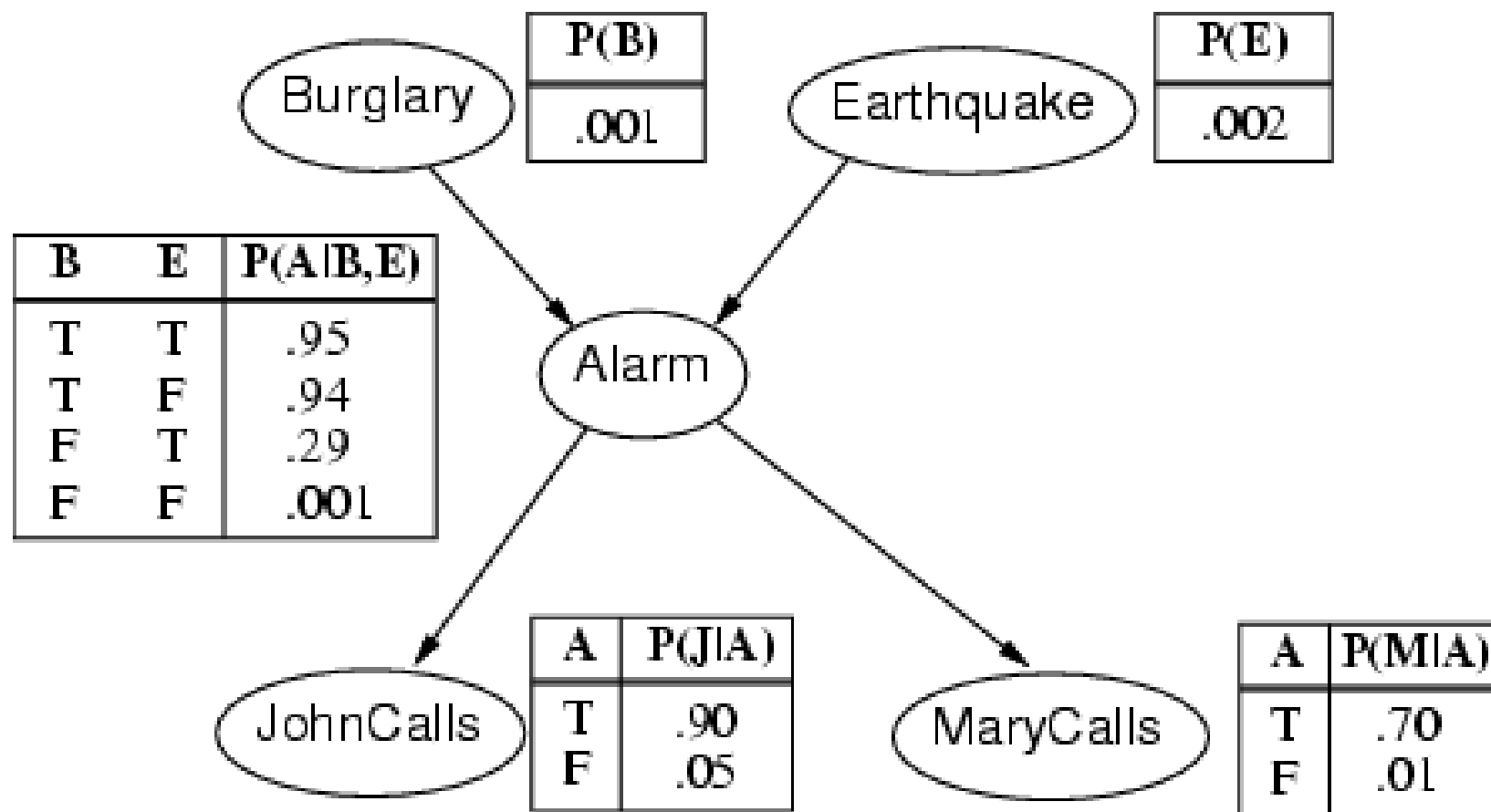


- *Weather* is independent of the other variables
- *Toothache* and *Catch* are conditionally independent given *Cavity*

Example

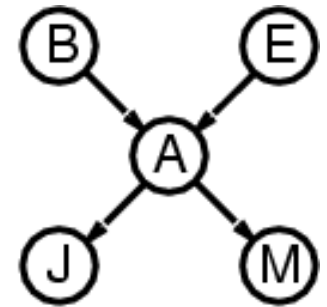
- I'm at work, neighbor John calls to say my alarm is ringing, but neighbor Mary doesn't call. Sometimes it's set off by minor earthquakes. Is there a burglar?
- Variables: *Burglary, Earthquake, Alarm, JohnCalls, MaryCalls*
- Network topology reflects "causal" knowledge:
 - A burglar can set the alarm off
 - An earthquake can set the alarm off
 - The alarm can cause Mary to call
 - The alarm can cause John to call

Example contd.



Compactness

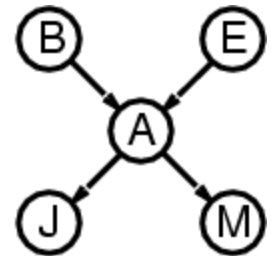
- A CPT for Boolean X_i with k Boolean parents has 2^k rows for the combinations of parent values
- Each row requires one number p for $X_i = \text{true}$ (the number for $X_i = \text{false}$ is just $1-p$)
- If each variable has no more than k parents, the complete network requires $O(n \cdot 2^k)$ numbers
- I.e., grows linearly with n , vs. $O(2^n)$ for the full joint distribution
- For burglary net, $1 + 1 + 4 + 2 + 2 = 10$ numbers (vs. $2^5 - 1 = 31$)



Semantics

The full joint distribution is defined as the product of the local conditional distributions:

$$P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i \mid \text{Parents}(X_i))$$



e.g., $P(j \wedge m \wedge a \wedge \neg b \wedge \neg e)$

$$= P(j \mid a) P(m \mid a) P(a \mid \neg b, \neg e) P(\neg b) P(\neg e)$$

Constructing Bayesian networks

1. Choose an ordering of variables X_1, \dots, X_n

2. For $i = 1$ to n

- add X_i to the network
- select parents from X_1, \dots, X_{i-1} such that

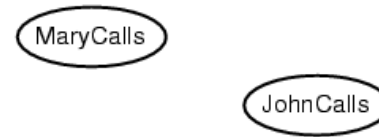
$$P(X_i \mid \text{Parents}(X_i)) = P(X_i \mid X_1, \dots, X_{i-1})$$

This choice of parents guarantees:

$$\begin{aligned} P(X_1, \dots, X_n) &= \pi_{i=1}^n P(X_i \mid X_1, \dots, X_{i-1}) \\ &\quad \text{(chain rule)} \\ &= \pi_{i=1}^n P(X_i \mid \text{Parents}(X_i)) \\ &\quad \text{(by construction)} \end{aligned}$$

Example

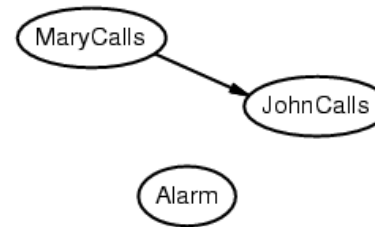
- Suppose we choose the ordering M, J, A, B, E



$$P(J \mid M) = P(J)?$$

Example

- Suppose we choose the ordering M, J, A, B, E



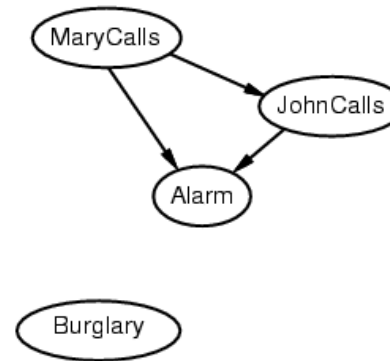
$$P(J \mid M) = P(J)?$$

No

$$P(A \mid J, M) = P(A \mid J)? \quad P(A \mid J, M) = P(A)?$$

Example

- Suppose we choose the ordering M, J, A, B, E



$$P(J \mid M) = P(J)?$$

No

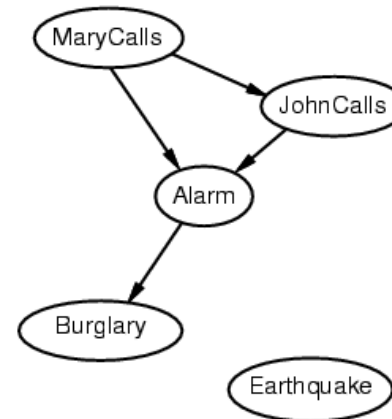
$$P(A \mid J, M) = P(A \mid J)? \quad P(A \mid J, M) = P(A)? \quad \text{No}$$

$$P(B \mid A, J, M) = P(B \mid A)?$$

$$P(B \mid A, J, M) = P(B)?$$

Example

- Suppose we choose the ordering M, J, A, B, E



$$P(J \mid M) = P(J)?$$

No

$$P(A \mid J, M) = P(A \mid J)? \quad P(A \mid J, M) = P(A)? \quad \text{No}$$

$$P(B \mid A, J, M) = P(B \mid A)? \quad \text{Yes}$$

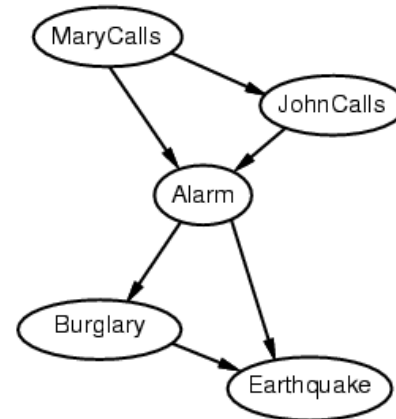
$$P(B \mid A, J, M) = P(B)? \quad \text{No}$$

$$P(E \mid B, A, J, M) = P(E \mid A)?$$

$$P(E \mid B, A, J, M) = P(E \mid A, B)?$$

Example

- Suppose we choose the ordering M, J, A, B, E



$$P(J \mid M) = P(J)?$$

No

$$P(A \mid J, M) = P(A \mid J)? \quad P(A \mid J, M) = P(A)? \quad \text{No}$$

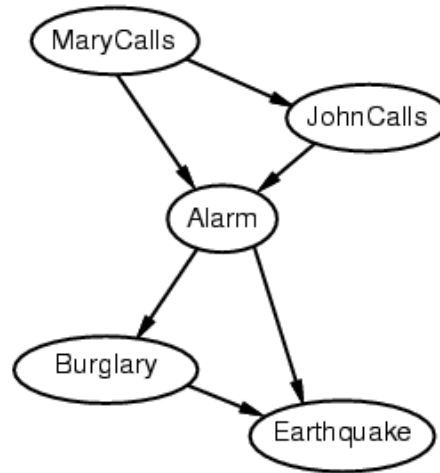
$$P(B \mid A, J, M) = P(B \mid A)? \quad \text{Yes}$$

$$P(B \mid A, J, M) = P(B)? \quad \text{No}$$

$$P(E \mid B, A, J, M) = P(E \mid A)? \quad \text{No}$$

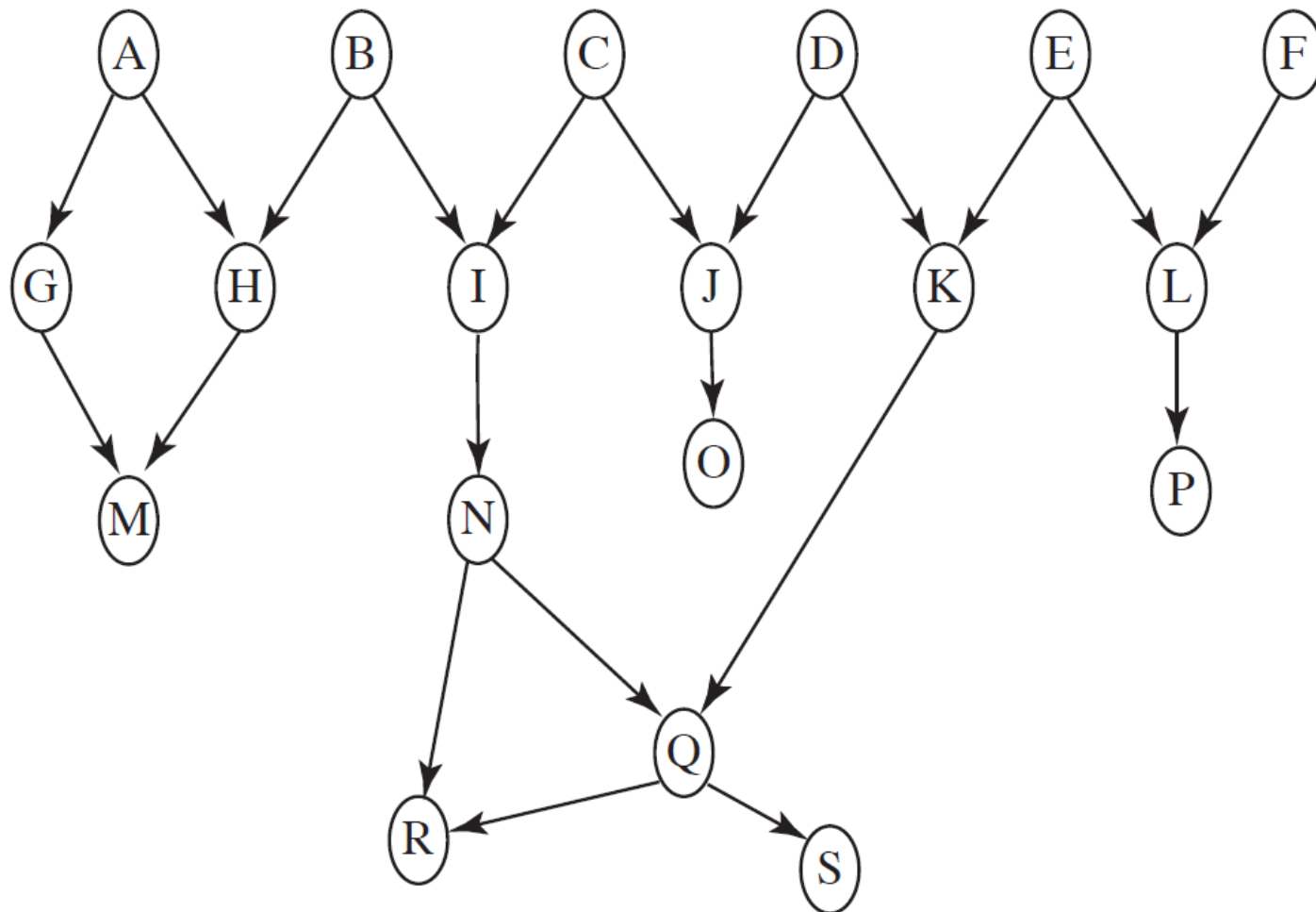
$$P(E \mid B, A, J, M) = P(E \mid A, B)? \quad \text{Yes}$$

Example contd.



- Deciding conditional independence is hard in noncausal directions
- (Causal models and conditional independence seem hardwired for humans!)
- Network is less compact: $1 + 2 + 4 + 2 + 4 = 13$ numbers needed

More on Conditional Independence - Example



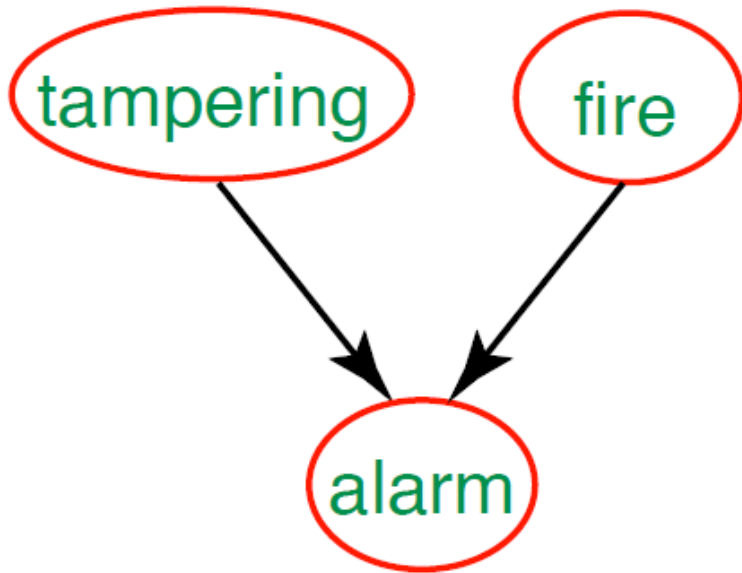
Conditional Independence

- On which given probabilities does $P(N)$ depend?
- If you were to observe a value for B , which variables' probabilities will change?
- If you were to observe a value for N , which variables' probabilities will change?
- Suppose you had observed a value for M ; if you were to then observe a value for N , which variables' probabilities will change?
- Suppose you had observed B and Q ; which variables' probabilities will change when you observe N ?

Conditional Independence

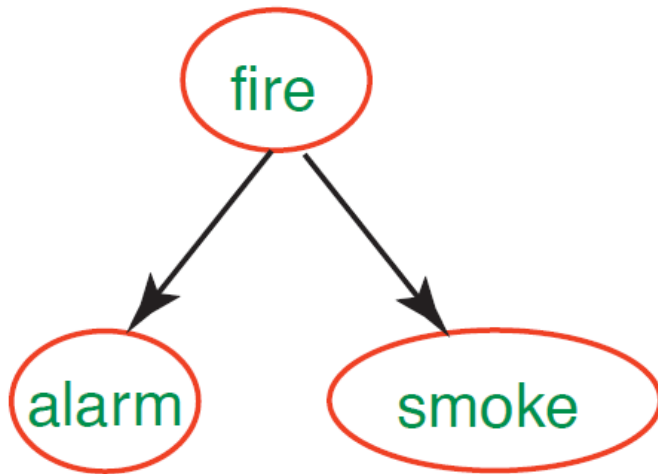
- If you observe variable Y , the variables whose posterior probability is different from their prior are:
 - The ancestors of Y and their descendants.
- Intuitively (if you have a causal belief network):
 - You do abduction to possible causes and prediction from the causes.
- **Three important** cases to consider

Case 1: Common Descendant



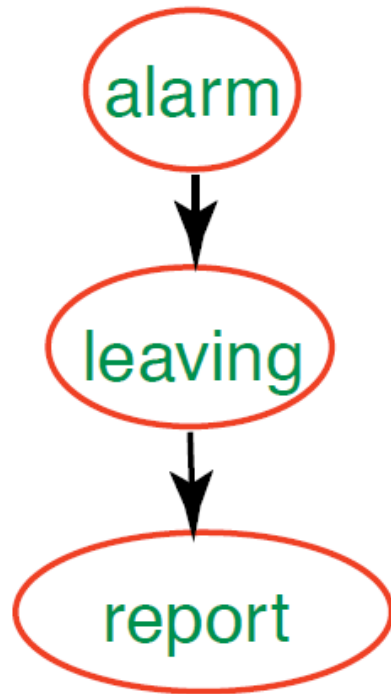
- tampering and fire are independent
- tampering and fire are dependent given alarm
- Intuitively, tampering can explain away fire

Case 2: Common Ancestor



- alarm and smoke are dependent
- alarm and smoke are independent given fire
- Intuitively, fire can explain alarm and smoke; learning one can affect the other by changing your belief in fire

Case 3: Chain



- alarm and report are dependent
- alarm and report are independent given leaving
- Intuitively, the only way that the alarm affects report is by affecting leaving .

Pruning Irrelevant Variables

- Suppose you want to compute $P(X_j/e_1 \dots e_k)$:
 - Prune any variables that have no observed or queried descendents.
 - Connect the parents of any observed variable.
 - Remove arc directions.
 - Remove observed variables.
 - Remove any variables not connected to X in the resulting (undirected) graph.