SHUO YANG

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RESEARCH INTEREST

I have general interest in formal methods, learning, control, algorithmic game theory, and statistics, with their applications to robotic and multi-agents systems.

EDUCATION

University of Pennsylvania

Aug. 2021 - present Advisor: Prof. Rahul Mangharam

Ph.D. in Electrical and Systems Engineering xLAB for Safe Autonomous Systems

Shanghai Jiao Tong University

Sept. 2017 - June. 2021

Advisor: Prof. Xiang Yin

B.Eng. in Automation

Thesis: Verification and synthesis of opacity for cyber-physical systems [pdf]

Outstanding Bachelor Thesis Award of SJTU

PROFESSIONAL EXPERIENCE

Toyota Research Institute of North America

May 2023 - Aug. 2023

Research Scientist Intern Mentors: Dr. Bardh Hoxha & Dr. Georgios Fainekos

Future Mobility Research Department

Duke University

June. 2020 - Oct. 2020 (Remote)

Visiting Student Mentor: Prof. Michael Zavlanos

PUBLICATIONS

(* indicates equal contribution) [Google Scholar]

- 1. Luigi Berducci, Shuo Yang, Rahul Mangahram, Radu Grosu. "Learning Adaptive Safety for Multi-Agent Systems." submitted, 2023. [pdf]
- 2. Jiangwei Wang, Shuo Yang, Ziyan An, Songyang Han, Zhili Zhang, Rahul Mangharam, Meiyi Ma, Fei Miao. "Multi-Agent Reinforcement Learning Guided by Signal Temporal Logic Specifications." submitted, 2023. [pdf]
- 3. Xiatao Sun*, Shuo Yang*, Rahul Mangharam. "MEGA-DAgger: Imitation Learning with Multiple Imperfect Experts." submitted, 2023. [pdf]
- 4. Shuo Yang, George J. Pappas, Rahul Mangharam, Lars Lindemann. "Safe Perception-Based Control under Stochastic Sensor Uncertainty using Conformal Prediction." *IEEE Conference on Decision and Control (CDC)*, 2023. [pdf]
- 5. Zhijie Qiao, Xiatao Sun, Shuo Yang, Helen Loeb, Rahul Mangharam. "Autonomous Vehicle Education Using a Virtual Reality Driving Simulator." CPS-IoT Week Humans in Cyber-Physical Systems Workshop, 2023.
- 6. Yu Chen*, Shuo Yang*, Rahul Mangharam, Xiang Yin. "You Don't Know When I Will Arrive: Unpredictable Controller Synthesis for Temporal Logic Tasks." 22nd IFAC World Congress (IFAC WC), 2023. [pdf]
- 7. Hongrui Zheng*, Zirui Zang*, <u>Shuo Yang</u>*, Rahul Mangharam. "Towards Explainability in Modular Autonomous Vehicle Software." *IEEE Intelligent Vehicles Symposium* (*IV*), 2023. [pdf]

- 8. Xiatao Sun, Mingyan Zhou, Zhijun Zhuang, Shuo Yang, Johannes Betz, Rahul Mangharam. "A Benchmark Comparison of Imitation Learning-based Control Policies for Autonomous Racing." *IEEE Intelligent Vehicles Symposium (IV)*, 2023. [pdf]
- 9. <u>Shuo Yang</u>*, Shaoru Chen*, Victor M. Preciado, Rahul Mangharam. "Differentiable Safe Controller Design through Control Barrier Functions." *IEEE Control Systems Letters* (*L-CSS*), 2022. [pdf]
- 10. Shuo Yang, Xiang Yin. "Secure Your Intention: On Notions of Pre-Opacity in Discrete-Event Systems." (Full Paper), *IEEE Transactions on Automatic Control (TAC)*, 2022. [pdf]
- 11. Shuo Yang*, Junyao Hou*, Xiang Yin, Shaoyuan Li. "Opacity of Networked Supervisory Control Systems over Insecure Communication Channels." *IEEE Transactions on Control of Network Systems (TCNS)*, 2021. [pdf]
- 12. Shuo Yang, Xiang Yin, Shaoyuan Li, Majid Zamani. "Secure-by-Construction Optimal Path Planning for Linear Temporal Logic Tasks." *IEEE Conference on Decision and Control (CDC)*, 2020. [pdf]

TALKS AND PRESENTATIONS

- University of Pennsylvania (ASSET Seminar), Philadelphia, Sept 2023 with Prof. Rahul Mangharam (Host: Prof. Rajeev Alur)
 Safe and Performant Control for Learning-Enabled Autonomous Systems
- 2. University of Pennsylvania (FM & ML Seminar), Philadelphia, Sept 2023 (Host: Prof. Eric Wong) Safe Learning-Enabled Autonomous Systems
- 3. University of Michigan, Ann Arbor, July 2023 (Host: Prof. Necmiye Ozay) Safe Learning-Based Control for Autonomous Systems
- 4. American Control Conference, San Diego, May 2023

 Differentiable Safe Controller Design through Control Barrier Functions
- CPS-IoT Week Humans in CPS Workshop, San Antonio, May 2023
 MEGA-DAgger: Imitation Learning with Multiple Imperfect Experts
- 6. CPS-IoT Week Humans in CPS Workshop, San Antonio, May 2023

 Autonomous Vehicle Education Using a Virtual Reality Driving Simulator
- RTSS Explainability Workshop, remote, Dec 2022
 Towards Explainability in Modular Autonomous Vehicle Software
- 8. University of Michigan, remote, Nov 2022 (Host: Prof. Max Li)
 Opacity in Discrete Event Systems: Notions, Algorithms, and Applications
- 9. 59th IEEE Conference on Decision and Control (CDC), remote, Dec 2020 Secure-by-Construction Optimal Path Planning for Linear Temporal Logic Tasks

SELECTED HONORS AND AWARDS

ACC Student Travel Grant	2023
The Dean's Fellowship from University of Pennsylvania	2021
Solomon M. Swaab Fellowship from University of Pennsylvania	2021
Outstanding Graduate of SJTU	2021
Outstanding Bachelor Thesis Award of SJTU (top 1%)	2021
Person of the Year of SJTU (highest honor for SJTU students)	2020
COMAP Meritorious Winner in Mathematical Contest in Modelling (top 7.09%)	2020
3rd Prize of National College Student Physics Competition	2020

ACADEMIC SERVICES

Program Committee International Conference on Cyber-Physical Systems (ICCPS) 2023

Reviewer American Control Conference (ACC)

IEEE Conference on Decision and Control (CDC)

International Conference on Learning Representations (ICLR) Advances in Neural Information Processing Systems (NeurIPS)

AAAI Conference on Artificial Intelligence (AAAI) IEEE Transactions on Automatic Control (TAC) IEEE Transactions on Intelligent Vehicles (TIV) IEEE Robotics and Automation Letters (RA-L)

IEEE Control Systems Letters (L-CSS) Nonlinear Analysis: Hybrid Systems (NAHS)

IEEE International Conference on Robotics and Automation (ICRA) IROS 2023 Workshop on Multi-agent Dynamic Games (MAD-Games)

NeurIPS 2023 AI for Science Workshop (AI4Science)

etc.

TEACHING EXPERIENCES

Teaching Assitant Fall 2023, UPenn

ESE 5000: Linear Systems Theory (Instructor: Prof. George J. Pappas)

Teaching Assitant Fall 2023, UPenn

ESE 5420: Statistics for Data Science (Instructor: Prof. Hamed Hassani)

Teaching Assitant Fall 2020. SJTU

MA 238: Discrete Mathematics (Instructor: Prof. Xiang Yin)

Lecturer Summer 2018. High School Affiliated to SJTU

Mathematics Competition

SELECTED ACTIVITY EXPERIENCES

Global Education and Training at University of Illinois at Urbana-Champaign 2019 Volunteer of the Shanghai International Marathon 2018, 2019

LANGUAGE, SKILLS AND INTERESTS

Language Chinese (native), English (fluent), French (basic)

Programming Python, C++, R, MATLAB, LATEX

Framework & Toolkit NumPy, JAX, PyTorch, ROS, Docker, Git

Interests Basketball, Literature, Music, Board Games, Video Games, etc.

Last update: Sept 2023