

Unit 2: Symbol Mapping and TX Filtering

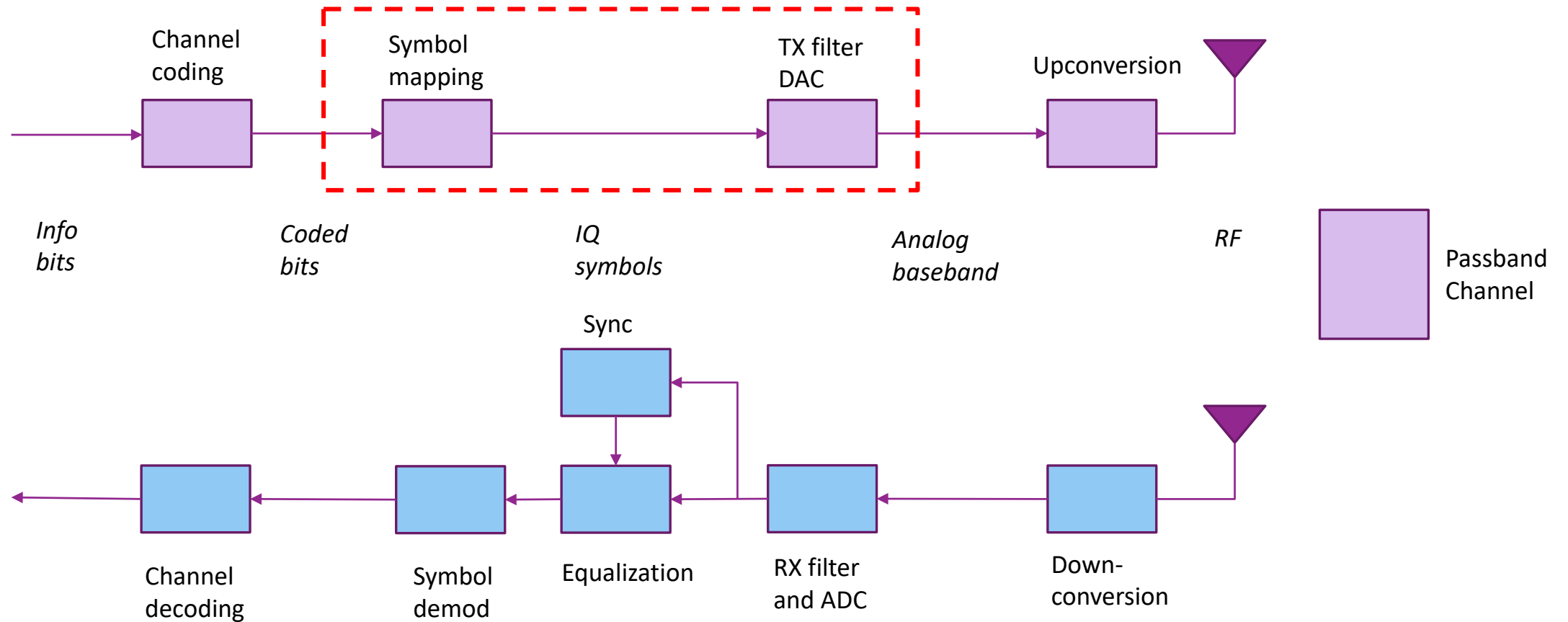
EL-GY 6013: DIGITAL COMMUNICATIONS

PROF. SUNDEEP RANGAN

Learning Objectives

- ❑ Describe the steps in symbol mapping and pulse shaping
- ❑ Describe the common modulation methods:
 - BPSK, QPSK, M-QAM.
 - For each, compute the minimum distance and symbol energy
- ❑ Compute the data rate as a function of the modulation and symbol rate
- ❑ Compute the TX spectrum given pulse shape and DTFT of the symbols
- ❑ Compute the PSD as a function of the pulse shape and symbol energy
- ❑ Specify TX filter requirements based on bandwidth and other requirements
- ❑ Describe the ideal sinc pulse in time domain and frequency domain
- ❑ Design a digital and analog filter given bandwidth constraints

This Unit



Outline



Symbol mapping

☐ DAC and pulse shaping

☐ Fourier analysis and bandwidth of TX filtering

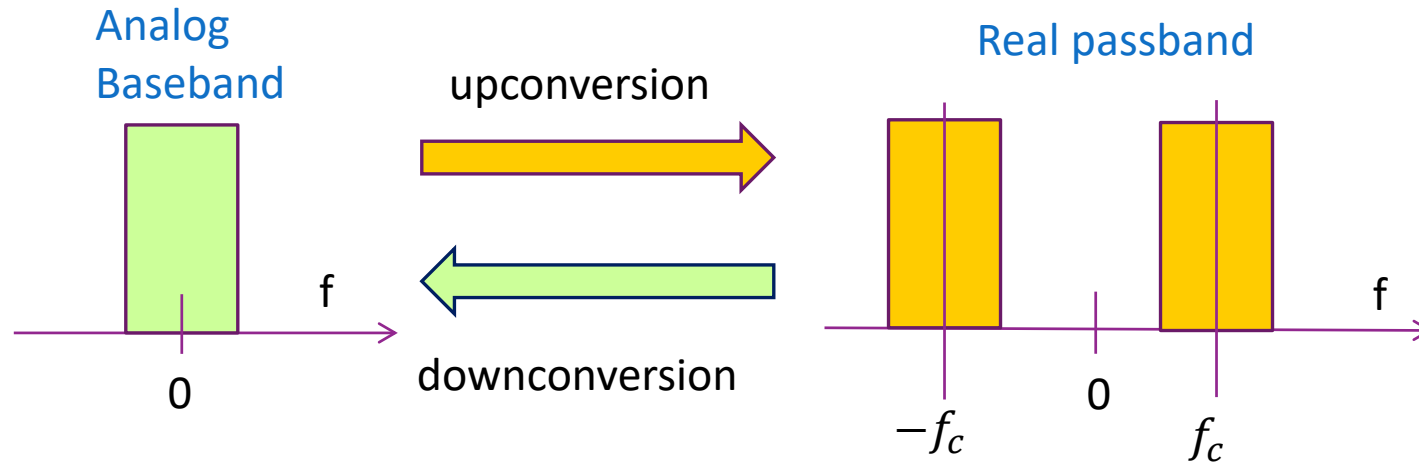
☐ Power spectral density analysis

☐ Sinc pulse and Ideal low pass filtering

☐ Digitally implementing pulse shaping



Last Unit: Up- and Down-Conversion



- ❑ Upconversion in TX: Convert an analog baseband IQ to real passband
- ❑ Downconversion in RX: Convert real passband to analog IQ
- ❑ But, baseband signal is complex and **analog**
- ❑ How do we transmit **digital** information?

Simple Idea

□ How do we transmit digital information over an analog channel?

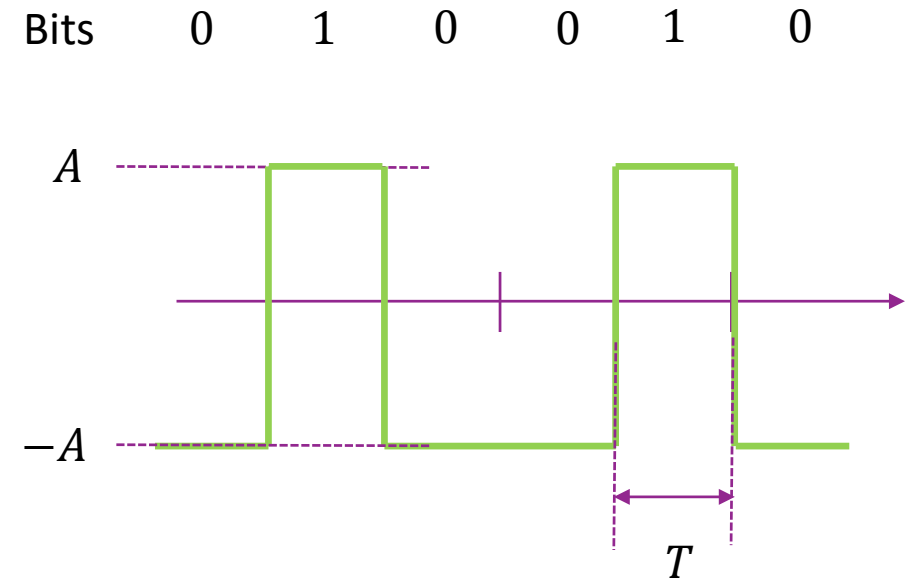
□ Simple idea: At the transmitter

- Take a sequence of bits $b[k] \in \{0,1\}$
e.g. 010010 ...
- Divide time into intervals T
- For $t \in [kT, (k+1)T)$:

$$u(t) = \begin{cases} A & \text{if } b_k = 1 \\ -A & \text{if } b_k = 0 \end{cases}$$

□ At the receiver:

- Measure $u(t)$ in interval $[kT, (k+1)T)$
- Determine if $b[k] = 0$ or 1



Simple Idea: Continued

□ Simple idea exhibits three key steps:

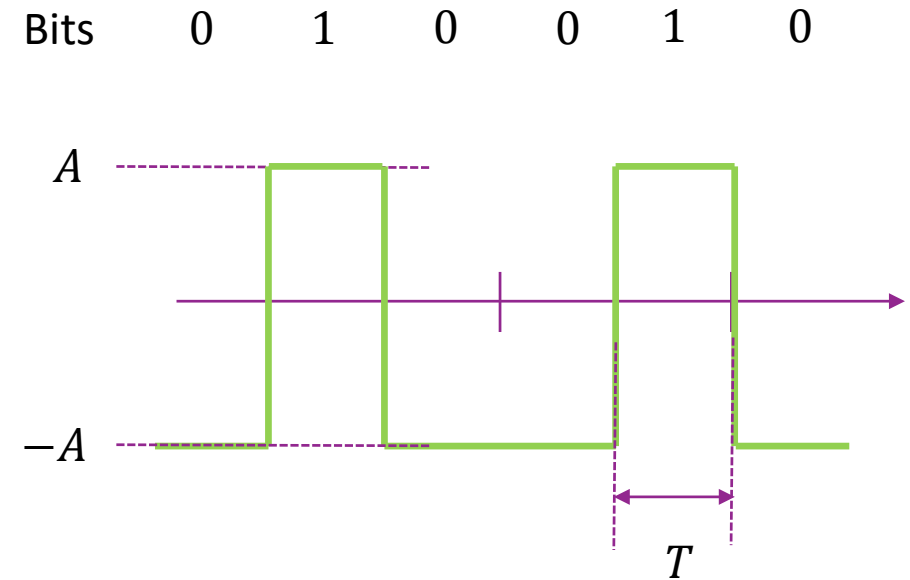
□ Step 1. Map bits to symbols:

$$s[n] = \begin{cases} A & \text{if } b[n] = 1 \\ -A & \text{if } b[n] = 0 \end{cases}$$

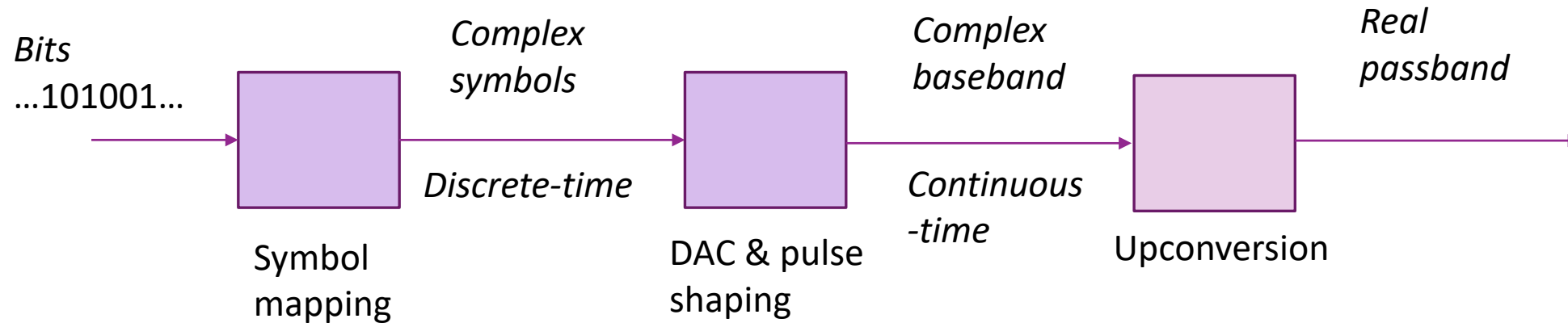
□ Step 2. Modulate to a pulse

$$u(t) = s[n] \quad \text{for } t \in [nT, (n+1)T)$$

□ Step 3. Upconvert



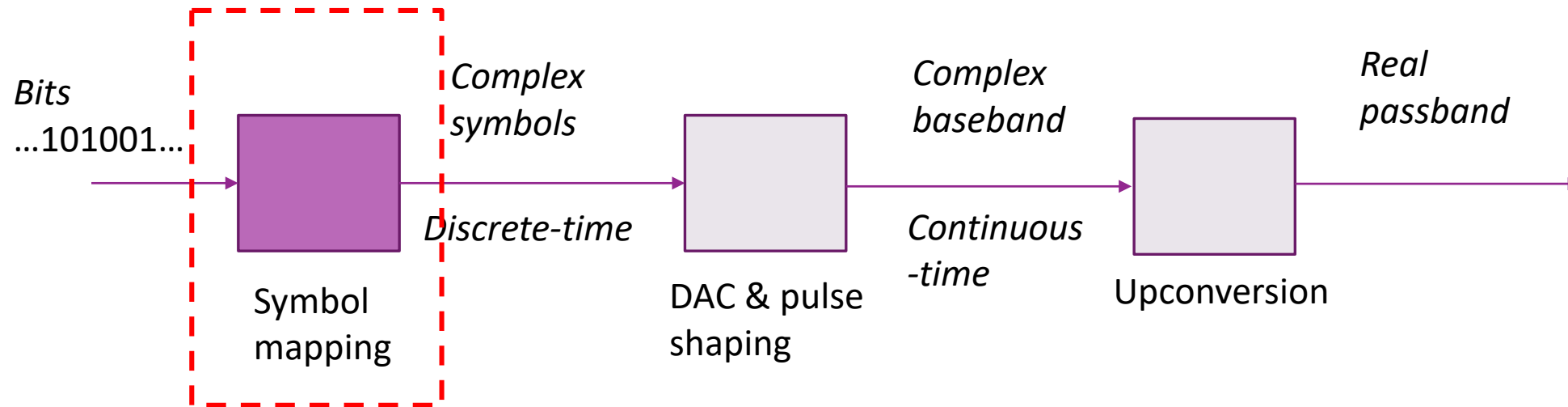
Digital Modulation General Procedure



□ Most communication systems follow the same three steps

- Step 1: Bit to symbol map
- Step 2: Pulse shaping
- Step 3: Upconversion (done in last class)

Step 1: Symbol Mapping

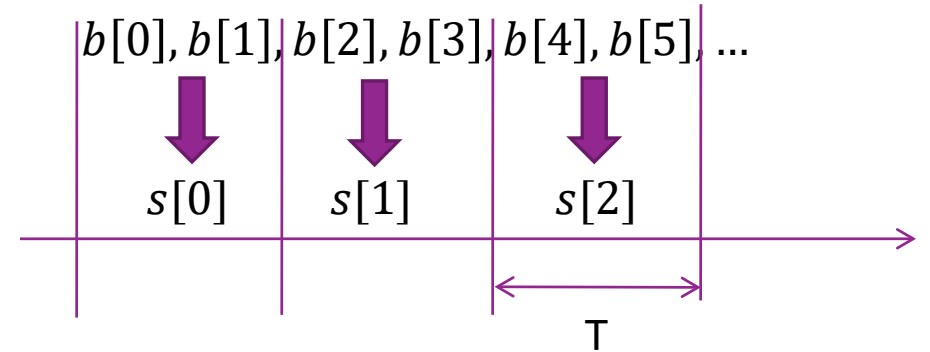


□ Generally done in three steps:

- Step 1: Bit to symbol map
- Step 2: Pulse shaping
- Step 3: Upconversion (done in last class)

Step 1: Bit to Symbol Mapping

- $b[k] \in \{0,1\}$ = sequence of bits.
- $x[n] \in \{0,1, \dots, M - 1\}$ = sequence of symbol indices
- $s[n] \in \{s_1, \dots, s_M\}$ = sequence of complex symbols
- **Modulation rate:** $R_{mod} = \log_2 M$ bits per symbol
- **Symbol period:** One symbol every T seconds.
- Bit rate of $R = R_{mod}/T$ bits per second



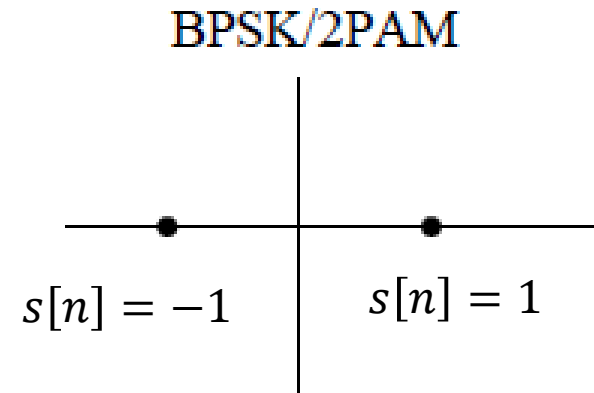
Ex. with $M=4$ symbols
 $R_{mod}=2$ bits per symbol

Example: BPSK

- 1 bit per symbol

- $s[n] = \begin{cases} 1 & x[n] = 1 \\ -1 & x[n] = 0 \end{cases}$

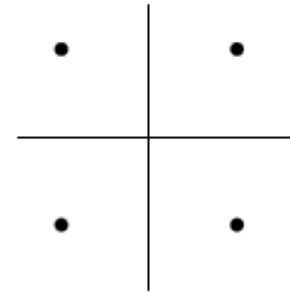
- Symbol is always real



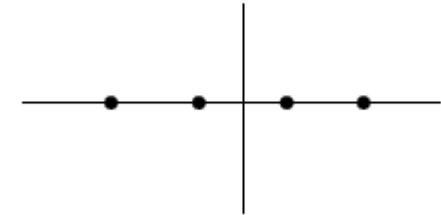
Example 2: 4-PAM and QPSK

- ❑ Two bits per symbol
- ❑ 4-PAM: Symbols are multi-level real.
- ❑ QPSK: Symbol is complex
 - $s[n] = s_c[n] + js_s[n]$
 - Has I and Q parts
- ❑ Draw bit to symbol mapping table on board

QPSK/4PSK/4QAM

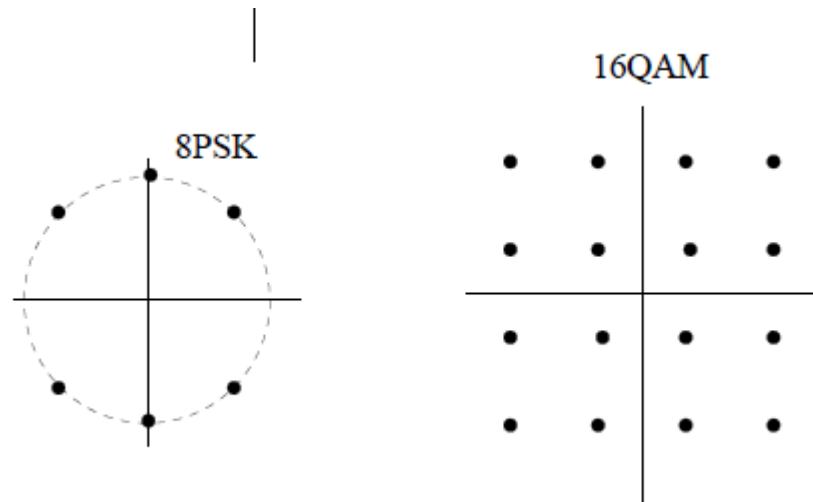


4PAM



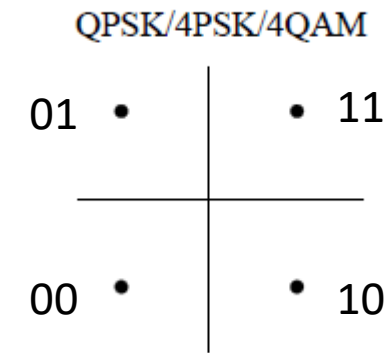
Higher-Order Modulation

- ❑ Constellations go up to 1024 in wireline communications
- ❑ Wireless is typically limited to 64-QAM (6 bits per symbol)
- ❑ High order modulation:
 - Will see need very low noise to detect high order modulation correctly




Example Problem

- Given bit sequence: $b = (1,0,0,1,1,1, \dots)$
- What are the first 3 symbols under the QPSK mapping
- Suppose the symbol rate is $f_{sym} = 1/T = 20 \text{ Msym/s}$.
- What is the data rate?



Outline

☐ Symbol mapping

 ☒ DAC and pulse shaping

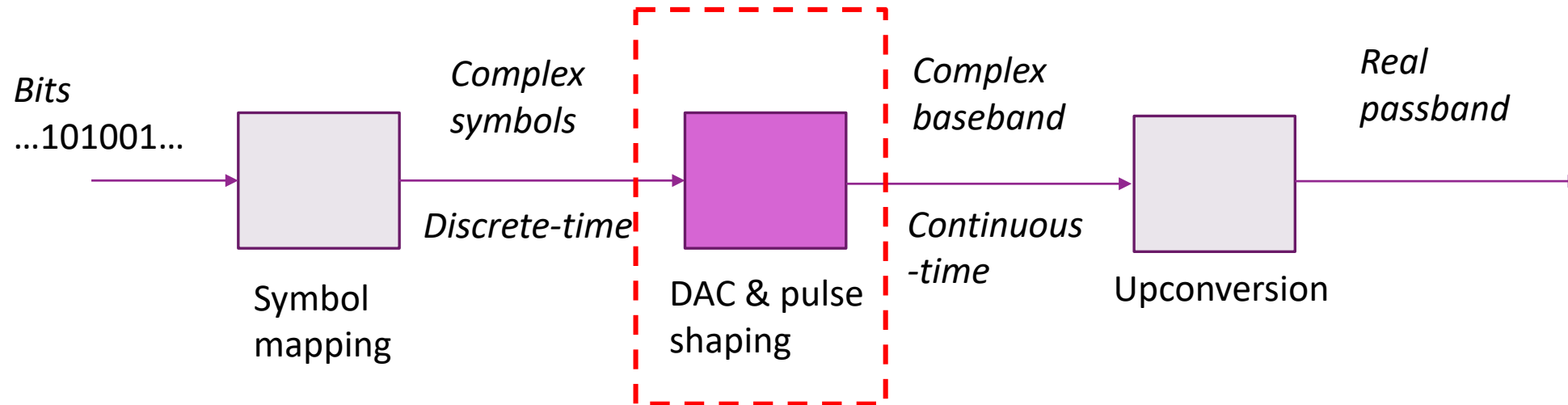
☐ Fourier analysis and bandwidth of TX filtering

☐ Power spectral density analysis

☐ Sinc pulse and Ideal low pass filtering

☐ Digitally implementing pulse shaping

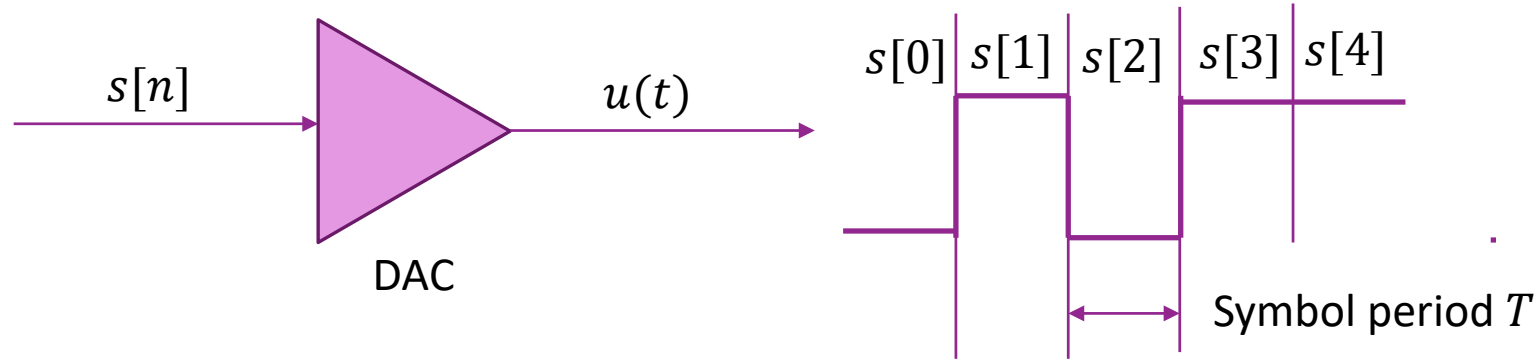
Step 2: DAC and Pulse Shaping



□ Generally done in three steps:

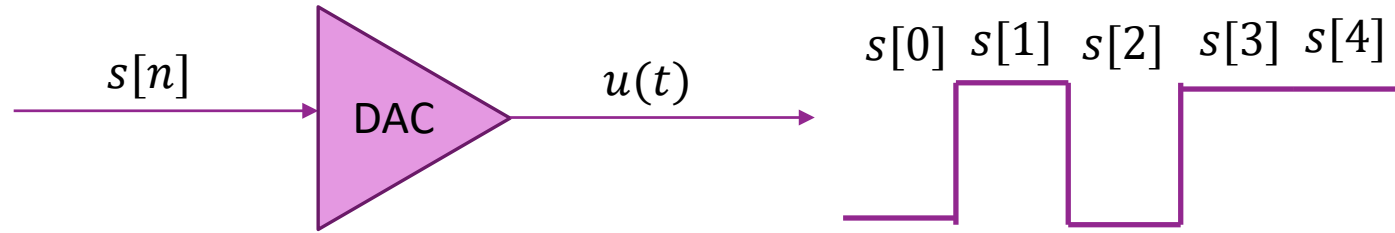
- Step 1: Bit to symbol map
- **Step 2: Pulse shaping**
- Step 3: Upconversion (done in last class)

Digital-Analog Conversion (DAC)



- ❑ Simplest idea for generating baseband signal:
- ❑ Send $s[n]$ during symbol n : $u(t) = s[n]$, $t \in [nT, (n+1)T)$
- ❑ Use DAC converter: Sometimes called zero-order-hold
- ❑ Symbol rate = $1/T$
- ❑ For complex symbols, use two DACs (one for I, one for Q)
 - Then upconvert in analog

Problem with DAC only solution



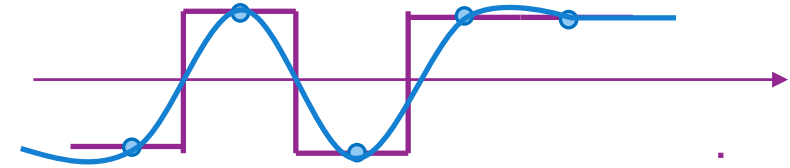
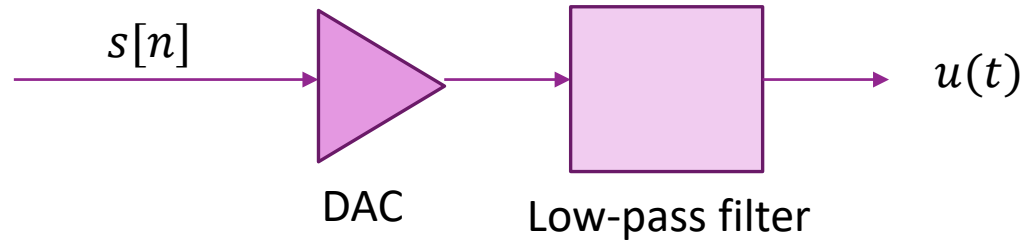
□ Benefits of using a DAC for modulation

- Simple to implement
- Easy to detect symbols at receiver (just sample in middle of symbol period)
- Used in many examples: e.g. digital signals in circuits. Modulate bits 0,1 to voltages 0, V

□ But, problems:

- Signal $u(t)$ requires high bandwidth due to fast transitions
- Not acceptable for bandlimited transmissions

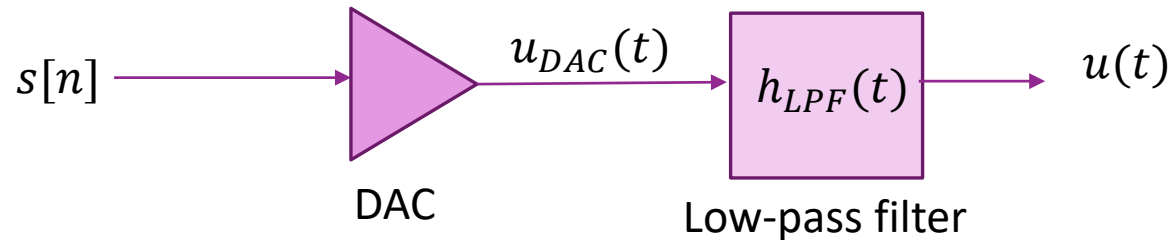
DAC + Filtering



DAC output before filtering
Filtered signal

- ❑ Solution: Add low-pass filter to DAC output.
- ❑ Removes high frequency components
- ❑ Questions:
 - Can we still recover $s[n]$ from signal $u(t)$?
 - How do we measure the bandwidth of the signal
 - What is the effect of the filter on the bandwidth

Infinite Pulse Series Representation



□ Can write DAC output as:

$$u_{DAC}(t) = \sum_{n=-\infty}^{\infty} s[n] h_{DAC}(t - nT), \quad h_{DAC}(t) = \text{Rect}(t/T)$$

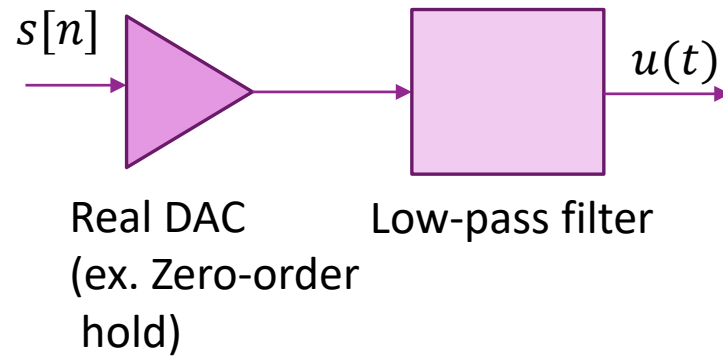
□ Then filtered output is:

$$u(t) = h_{LPF}(t) * u_{DAC}(t) = \sum_{n=-\infty}^{\infty} s[n] p(t - nT), \quad p(t) = h_{DAC}(t) * h_{LPF}(t)$$

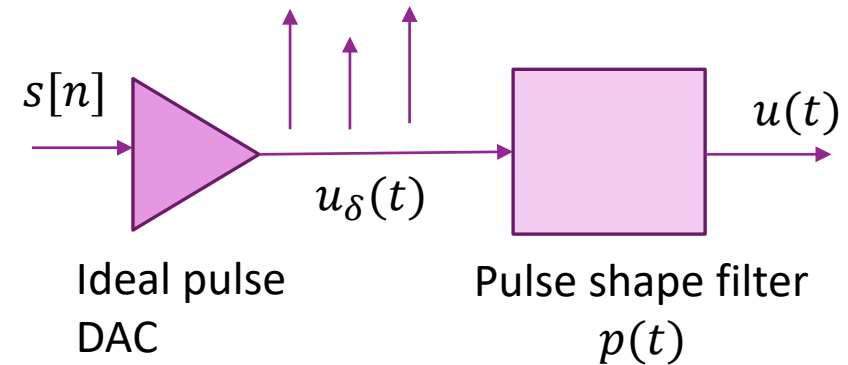
□ Pulse shape: $p(t) = h_{DAC}(t) * h_{LPF}(t)$

Theoretical Pulse Shape Model

Physical implementation



Model for analysis



□ Can model DAC + LPF via filtered pulse train

□ $u_\delta(t) = \sum_n s[n]\delta(t - nT), \quad u(t) = p(t) * u_\delta(t) = \sum_n s[n]p(t - nT)$

Zero ISI Pulse

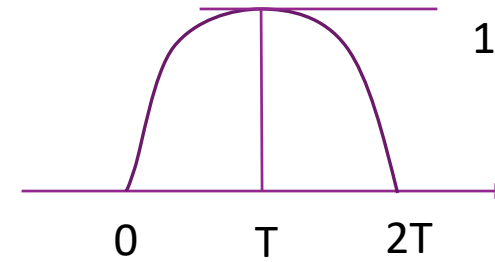
- ❑ Consider linear modulation: $u(t) = \sum_n s[n]p(t - nT)$
- ❑ Question: Can we recover $s[n]$ from $u(t)$?
- ❑ Definition: A pulse $p(t)$ is a **zero ISI** pulse if $p(0) = 1$ and $p(nT) = 0$ for all $n \neq 0$
 - ISI = intersymbol interference
- ❑ If $p(t)$ is a **zero ISI** then: $s[n] = u(nT)$
- ❑ Design idea: Find a zero ISI pulse, then recover symbols $s[n]$ by sampling $u(nT)$

Simple Pulse Shapes


- ❑ Pictures on board
- ❑ Rectangular pulse: Leads to zero-order-hold
- ❑ Triangular pulse: Leads to linear interpolation
- ❑ Zero ISI condition

Sample Problem

- ❑ Suppose the complex symbols are: $s[n] = (1 + j, 1 - j, -1 + j)$
- ❑ Given pulse $p(t)$ as shown to right
- ❑ Draw the real and imaginary components of $u(t)$
- ❑ Where would you sample $u(t)$ to recover $s[n]$?



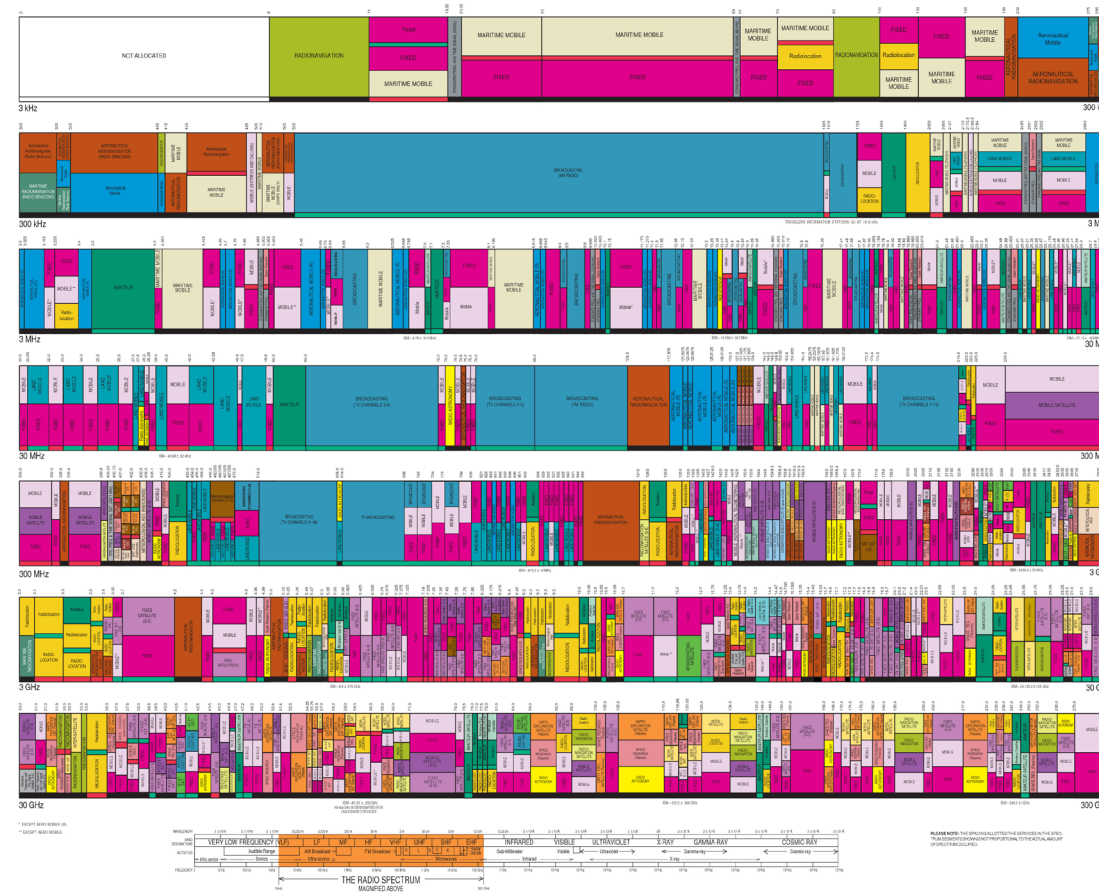
Outline

- ☐ Symbol mapping
- ☐ DAC and pulse shaping
-  ☐ Fourier analysis and bandwidth of TX filtering
- ☐ Power spectral density analysis
- ☐ Sinc pulse and Ideal low pass filtering
- ☐ Digitally implementing pulse shaping

Bandwidth and US Spectral Allocations

UNITED STATES FREQUENCY ALLOCATIONS

THE RADIO SPECTRUM



Bandwidth: A Basic Resource

❑ Limited by:

- Nature of the medium. Most channels can transmit only limited range of frequencies
- Ownership / allocations

❑ We will see that data rate is proportional to bandwidth

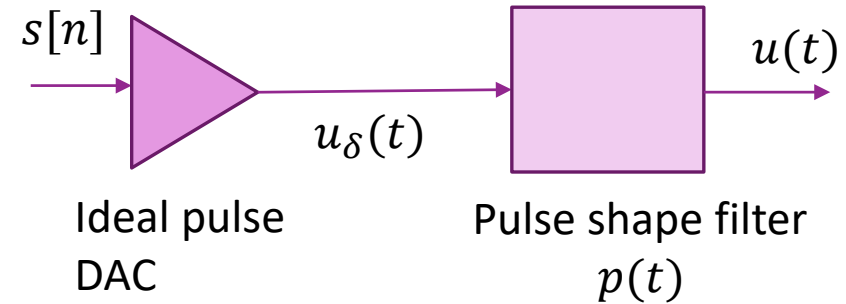
- Assuming power per unit bandwidth is constant

❑ Basic questions:

- How do we measure bandwidth?
- What is the bandwidth of linearly modulated signals?

Fourier Transform of Modulated Signal

- ❑ Want to measure occupied bandwidth of $u(t)$
- ❑ Look at FT $U(f)$
- ❑ Problem: How do we compute FT of $U(f)$?
- ❑ Depends on two factors:
 - DTFT of $s[n]$
 - Pulse shape filter response $P(f)$



Review of DTFT

- Given discrete-time sequence $s[n]$
- DTFT: $S(\Omega) = \sum_n s[n]e^{-j\Omega n}$
- Inverse DTFT: $s[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} S(\Omega)e^{j\Omega n} d\Omega$
- Note $S(\Omega)$ is always a 2π periodic signal
- Ω is the **discrete frequency**. Units is radians per sample.

Common DTFT Pairs

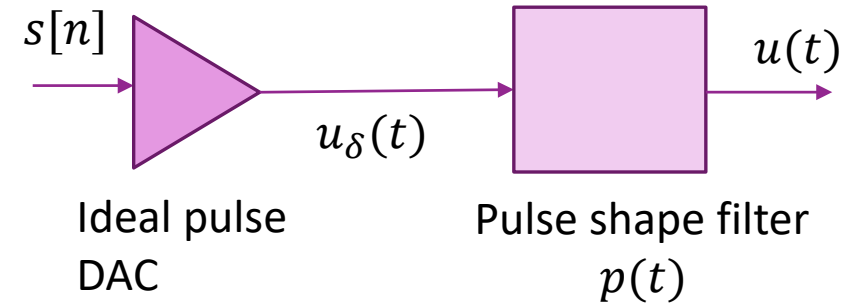
See Wikipedia

Time domain $x[n]$	Frequency domain $X_{2\pi}(\omega)$
$\delta[n]$	$X_{2\pi}(\omega) = 1$
$\delta[n - M]$	$X_{2\pi}(\omega) = e^{-i\omega M}$
$\sum_{m=-\infty}^{\infty} \delta[n - Mm]$	$X_{2\pi}(\omega) = \sum_{m=-\infty}^{\infty} e^{-i\omega Mm} = \frac{2\pi}{M} \sum_{k=-\infty}^{\infty} \delta\left(\omega - \frac{2\pi k}{M}\right)$ $X_o(\omega) = \frac{2\pi}{M} \sum_{k=-(M-1)/2}^{(M-1)/2} \delta\left(\omega - \frac{2\pi k}{M}\right) \quad \text{odd } M$ $X_o(\omega) = \frac{2\pi}{M} \sum_{k=-M/2+1}^{M/2} \delta\left(\omega - \frac{2\pi k}{M}\right) \quad \text{even } M$
$u[n]$	$X_{2\pi}(\omega) = \frac{1}{1 - e^{-i\omega}} + \pi \sum_{k=-\infty}^{\infty} \delta(\omega - 2\pi k)$ $X_o(\omega) = \frac{1}{1 - e^{-i\omega}} + \pi \cdot \delta(\omega)$
$a^n u[n]$	$X_{2\pi}(\omega) = \frac{1}{1 - ae^{-i\omega}}$
$e^{-i\omega n}$	$X_o(\omega) = 2\pi \cdot \delta(\omega + a), \quad -\pi < a < \pi$ $X_{2\pi}(\omega) = 2\pi \sum_{k=-\infty}^{\infty} \delta(\omega + a - 2\pi k)$

$\cos(a \cdot n)$	$X_o(\omega) = \pi [\delta(\omega - a) + \delta(\omega + a)],$ $X_{2\pi}(\omega) \triangleq \sum_{k=-\infty}^{\infty} X_o(\omega - 2\pi k)$
$\sin(a \cdot n)$	$X_o(\omega) = \frac{\pi}{i} [\delta(\omega - a) - \delta(\omega + a)]$
$\text{rect}\left[\frac{n - M/2}{M}\right]$	$X_o(\omega) = \frac{\sin[\omega(M+1)/2]}{\sin(\omega/2)} e^{-\frac{i\omega M}{2}}$
$\text{sinc}(W(n+a))$	$X_o(\omega) = \frac{1}{W} \text{rect}\left(\frac{\omega}{2\pi W}\right) e^{i\omega a}$
$\text{sinc}^2(Wn)$	$X_o(\omega) = \frac{1}{W} \text{tri}\left(\frac{\omega}{2\pi W}\right)$

Fourier Analysis of Modulation

- ❑ Computing $U(f)$ follows three steps:
- ❑ Compute $S(\Omega)$. This is 2π periodic
- ❑ Compute $U_\delta(f) = S(2\pi fT) = S\left(\frac{2\pi f}{f_s}\right)$
 - Vertical scale is unchanged
 - Digital frequency Ω mapped to $f = \frac{\Omega}{2\pi T} = \frac{\Omega f_s}{2\pi}$
 - This is periodic with period $\frac{1}{T} = f_s$
- ❑ Compute $U(f) = P(f)U_\delta(f)$



Example Problem: Part 1

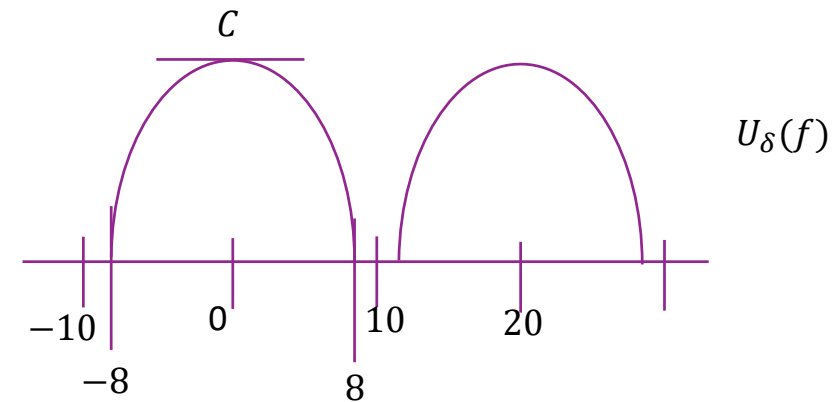
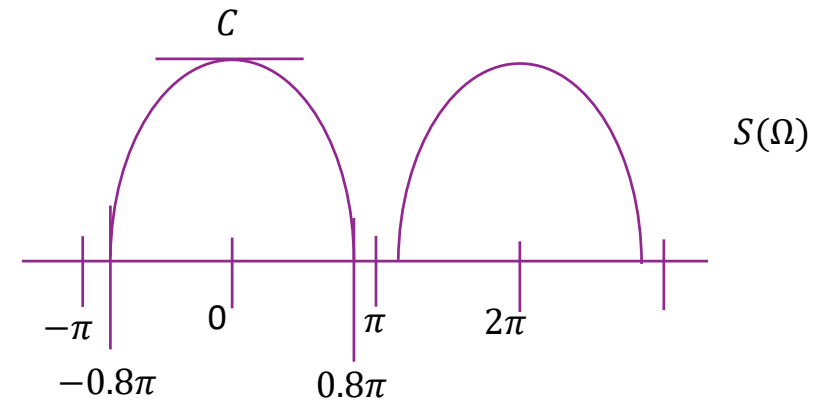
□ Given $S(\Omega)$ as shown

□ Suppose $f_s = \frac{1}{T} = 20$ MHz

□ Draw $U_\delta(f)$

□ Solution: $U_\delta(f) = S(2\pi fT)$

- $U_\delta(f)$ has period $f_s = 20$ MHz
- Same vertical scale as $S(\Omega)$
- $\Omega = 0.8\pi$ maps to $f = \frac{0.8\pi}{2\pi}(20) = 8$ MHz
- $\Omega = \pi$ maps to $f = \frac{\pi}{2\pi}(20) = 10$ MHz



Example Problem: Part 2

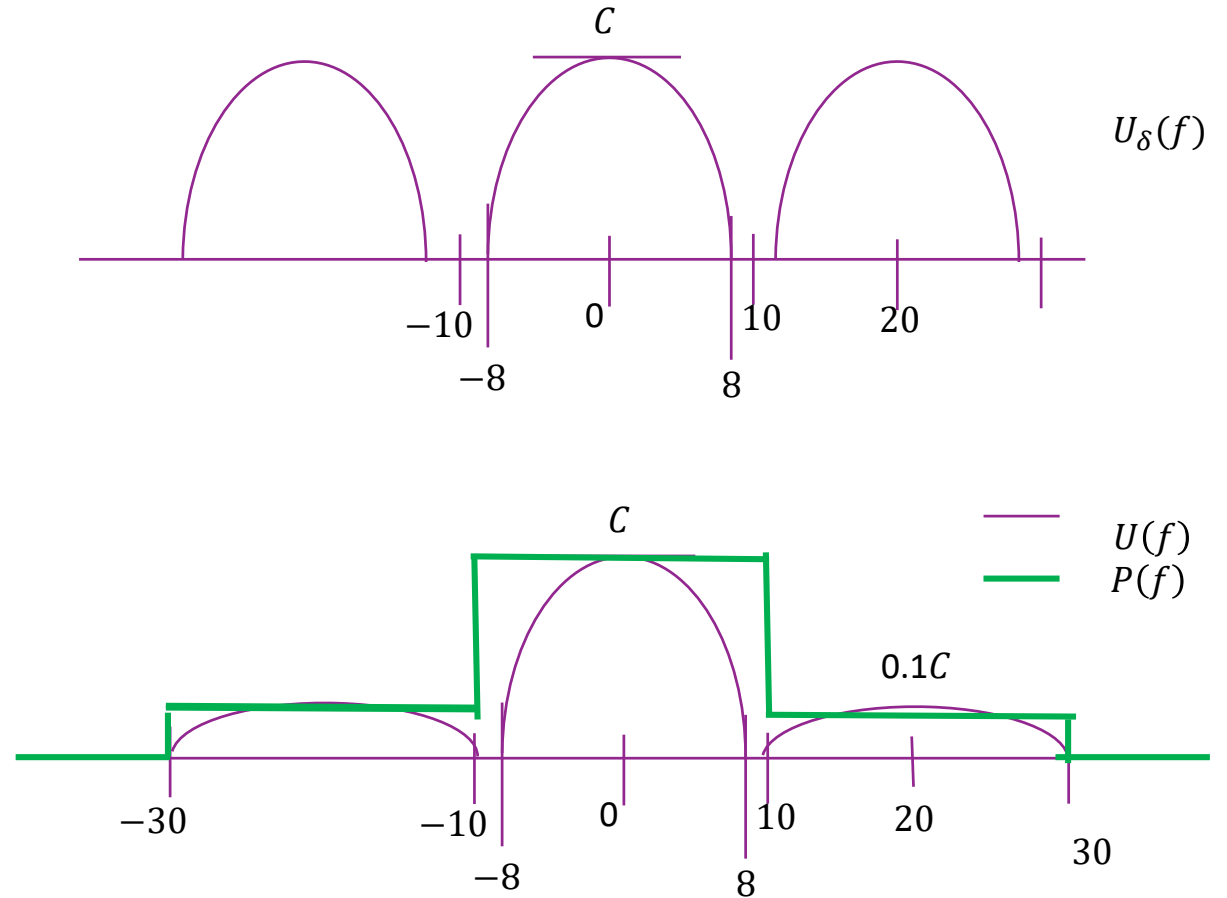
□ Suppose filter is:

$$P(f) = \begin{cases} 1 & |f| < 10 \\ 0.1 & |f| \in [10, 30) \\ 0 & \text{else} \end{cases}$$


□ Draw $P(f)$ and $U(f)$

□ Solution

- Use equation to draw $P(f)$
- Get $U(f)$ from $U(f) = P(f)U_\delta(f)$
- In this case, filter attenuates two sidelobes

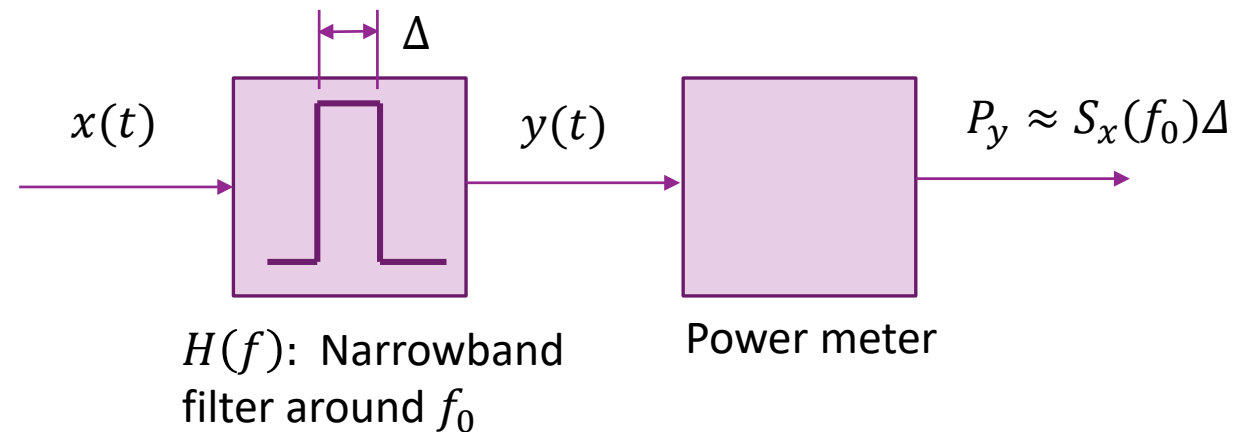


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Review: PSD of a Continuous-Time Signal

- ❑ Let $x(t)$ be a power signal
- ❑ Select frequency f_0 to measure PSD
- ❑ Filter with narrowband filter
 - $y(t) = h(t) * x(t)$
 - $H(f) = 1$ for $|f - f_0| \leq \Delta/2$
- ❑ Measure power P_y



- ❑ PSD at f_0 is defined as
$$S_x(f_0) := \lim_{\Delta \rightarrow 0} \frac{1}{\Delta} P_y$$
- ❑ Can show this is equivalent to window definition
- ❑ Reveals how much power is in a certain frequency

PSD of a Discrete-Time Signal

□ Can define PSD of a discrete-time power signal similarly

□ Let $x[n]$ be a discrete-time signal

□ Select frequency Ω_0 to measure PSD

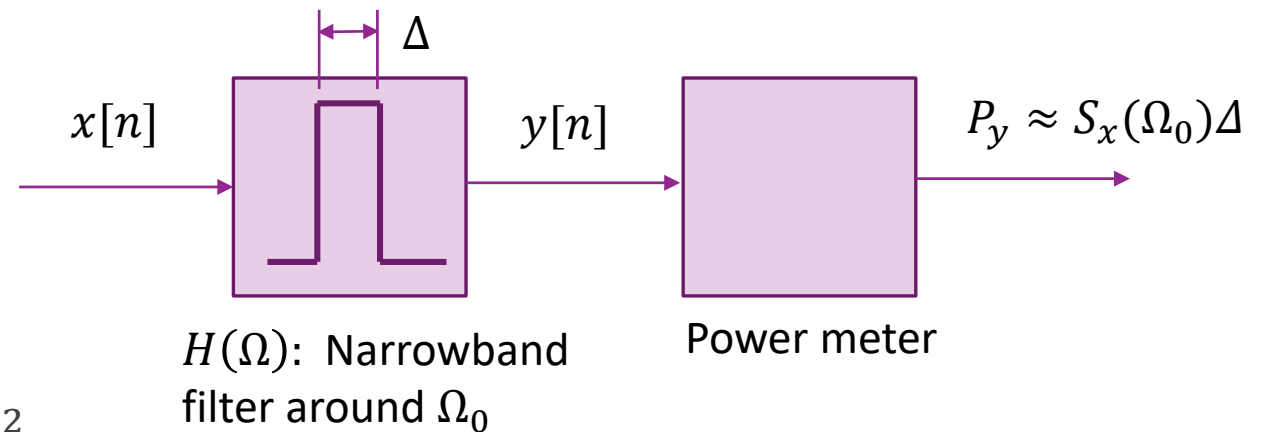
□ Filter with narrowband filter

- $y[n] = h[n] * x[n]$
- $H(\Omega) = 1$ for $|\Omega - \Omega_0| \leq \Delta/2$

□ Measure power $P_y = \lim_N \frac{1}{2N} \sum_{n=-N}^N |y[n]|^2$

□ PSD at Ω_0 is defined as

$$S_x(\Omega_0) := \lim_{\Delta \rightarrow 0} \frac{1}{\Delta} P_y$$



Symbol Mean and Energy

- Consider a linear modulated signal:

$$u(t) = \sum_{n=-\infty}^{\infty} s[n]p(t - nT)$$

- What is its PSD?
- Assume $s[n] \in \{s_1, \dots, s_M\}$. M constellation points
- Define **symbol mean** and **symbol energy**:

$$\bar{s} = \frac{1}{M} \sum_{m=1}^M s_m, \quad E_s = \frac{1}{M} \sum_{m=1}^M |s_m - \bar{s}|^2$$

PSD of a Linear Modulated Signal

□ Suppose: Output of ideal DAC is

$$u_{\delta}(t) = \sum_{n=-\infty}^{\infty} s[n]\delta(t - nT)$$

□ After pulse shaping:

$$u(t) = p(t) * u_{\delta}(t) = \sum_{n=-\infty}^{\infty} s[n]p(t - nT)$$

□ Suppose $s[n]$ is a discrete-time power signal with digital PSD $S_s(\Omega)$

□ **Theorem:** PSD of $u_{\delta}(t)$ and $u(t)$

$$S_{u_{\delta}}(f) = \frac{1}{T} S_s(2\pi fT), \quad S_u(f) = \frac{1}{T} S_s(2\pi fT) |P(f)|^2$$

- Note that $S_s(2\pi fT)$ is periodic with period $\frac{1}{T}$.

Special Case: IID Symbols

- Suppose: Output of ideal DAC is $u_\delta(t) = \sum_{n=-\infty}^{\infty} s[n]\delta(t - nT)$
- After pulse shaping: $u(t) = p(t) * u_\delta(t) = \sum_{n=-\infty}^{\infty} s[n]p(t - nT)$
- Suppose that:
 - Assume $s[n]$ are uncorrelated and zero mean
 - Average symbol energy: $E_s = E|s[n]|^2$
- Then $S_s(\Omega) = E_s$
- $S_{u_\delta}(f) = \frac{1}{T} E_s,$
- $S_u(f) = \frac{1}{T} E_s |P(f)|^2$
- Power $P_u = \frac{1}{T} E_s \|p\|^2$

Example Problem: Part 1

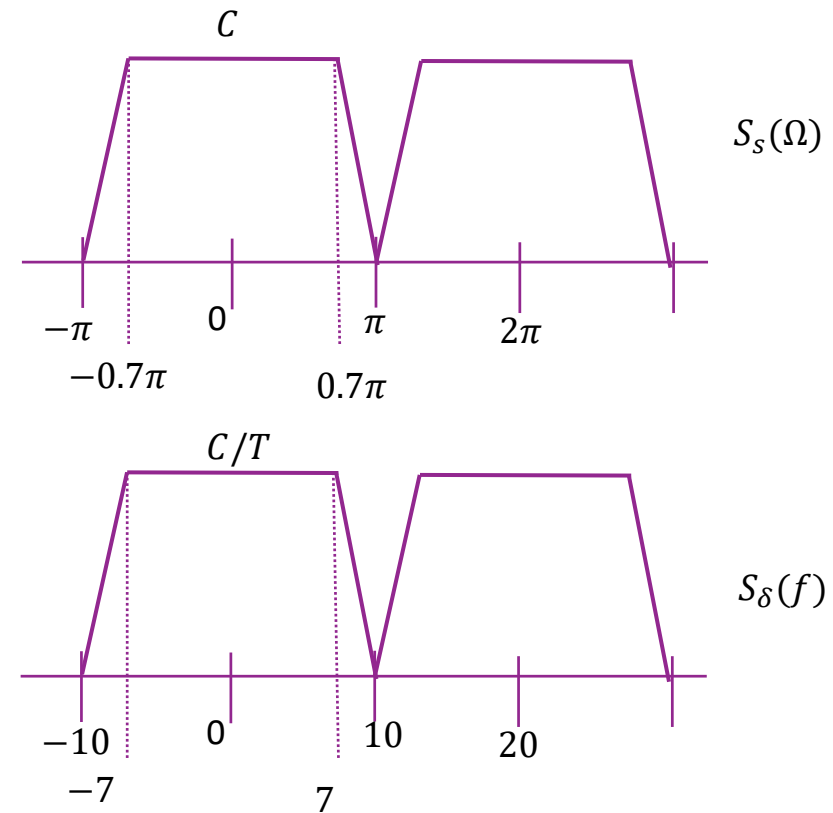
□ Given PSD of $s[n]$ $S_s(\Omega)$ as shown with $C = 0.1$

□ Suppose $f_s = \frac{1}{T} = 20$ MHz

□ Draw PSD of $U_\delta(f)$

□ Solution: $S_\delta(f) = \frac{1}{T} S(2\pi fT)$

- $S_\delta(f)$ has period $f_s = 20$ MHz
- Vertical scaled by $\frac{1}{T}$
- $\Omega = 0.7\pi$ maps to $f = \frac{0.7\pi}{2\pi} (20) = 7$ MHz
- $\Omega = \pi$ maps to $f = \frac{\pi}{2\pi} (20) = 10$ MHz



Example Problem: Part 2

□ Now suppose $p(t) = \text{sinc}\left(\frac{t}{T}\right)$

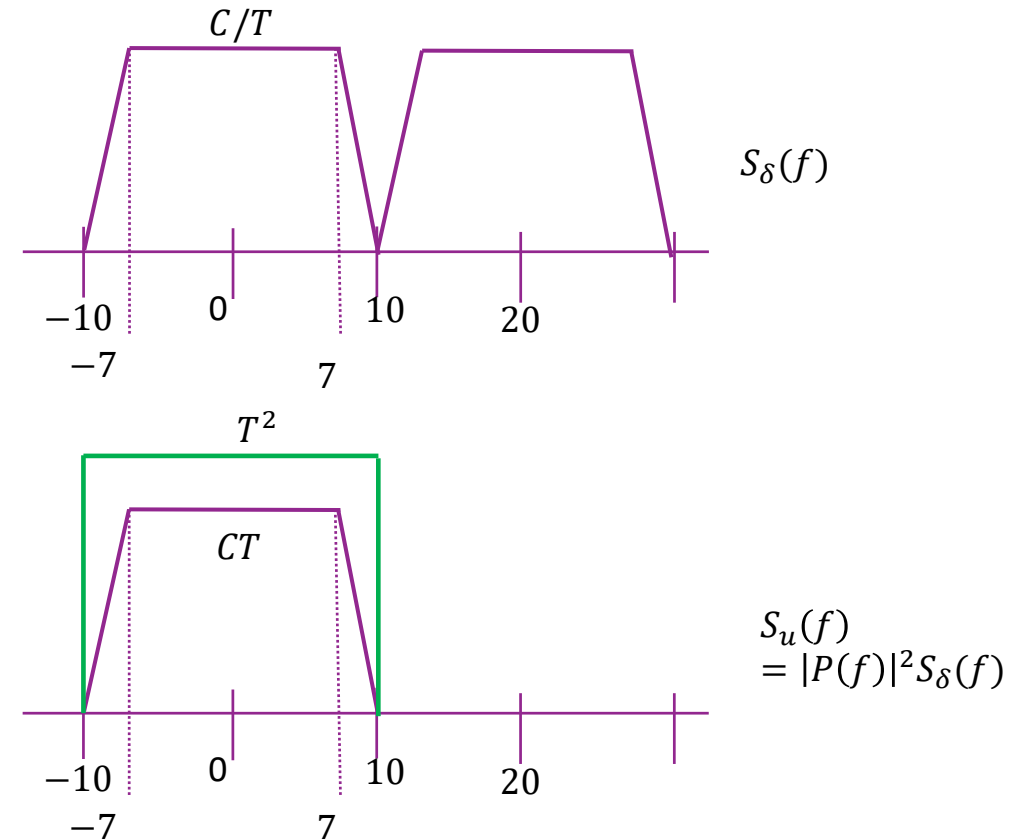
□ Draw $S_u(f)$

□ Solution:

- $P(f) = T\text{Rect}(fT)$
- $|P(f)|^2 = T^2\text{Rect}(fT)$
- Scales low-pass signal by T^2
- Removes all sidelobe

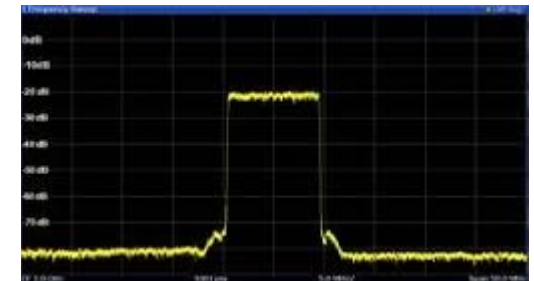
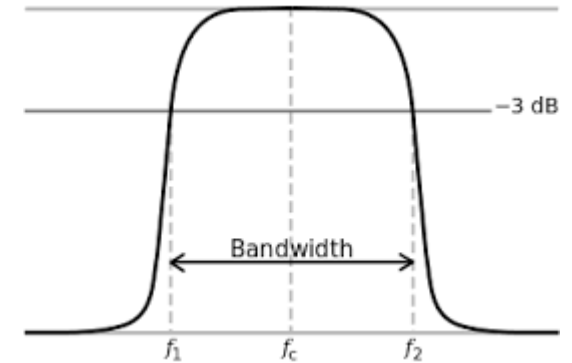
□ Total power in the signal:

- Area of a trapezoid
- $P_u = \int S_u(f)df = \frac{CT}{2T} [0.7 + 1] = 0.85C$



Measuring Bandwidth

- ❑ PSD of modulated bits is $S_u(f) = \frac{1}{T} E_s |P(f)|^2$
 - Complex baseband signal
 - After upconversion will be shifted to $\pm f_c$
- ❑ **Definition:** Signal is **exactly band-limited** to $|f| \leq W$
 - if $S_u(f) = 0$ for $|f| \geq W$
- ❑ Exact bandwidth = $2W$
- ❑ **Approximate BW:** Typically require $S_u(f) \approx 0$ for $|f| \geq W$
- ❑ Different measures of approximate bandwidth
 - 3 dB bandwidth
 - 98% bandwidth, ...



Examples

□ Rectangular pulse:

$$p(t) = \frac{1}{T} I_{[-\frac{T}{2}, \frac{T}{2}]} \Rightarrow |P(f)|^2 = \text{sinc}^2(fT)$$

- 99% bandwidth = $10.1/T$, 90% BW = $0.85/T$

□ Sinusoidal pulse (for $T = 1$):

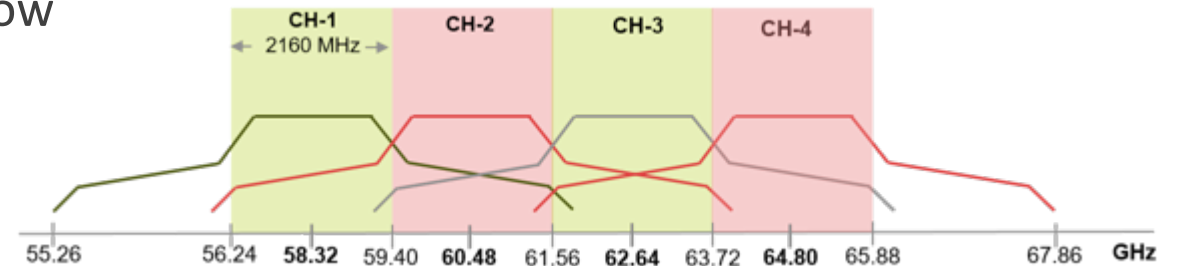
$$p(t) = \sqrt{2} \sin(\pi t) I_{[0,1]}(t)$$
$$|P(f)|^2 = \frac{8}{\pi^2} \frac{\cos^2 \pi f}{(1 - 4f^2)^2}$$

- No discontinuities. Less very high frequency components
- 99% bandwidth = $1.2/T$

Spectral Masks

- ❑ Bandwidths for wireless devices are regulated
 - Must transmit most energy in some specified band
 - Ensures no interference between channels
- ❑ Constraints are specified by a **spectral mask**
 - Represents maximum power level in each band
- ❑ Emissions outside the main band typically very low
 - At least 20 to 40 dB below main lobe

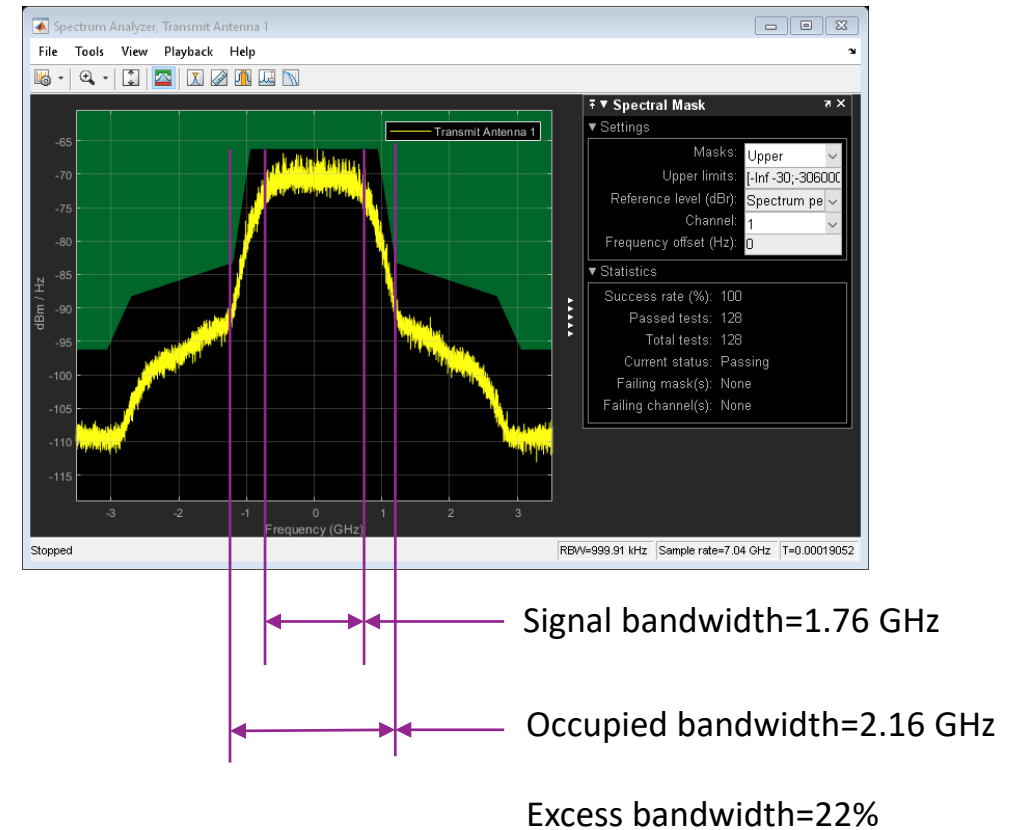
Channels for 802.11ad
Each channel is 2.16 GHz




Signal Bandwidth and Excess Bandwidth

- ❑ Usually, signal of interest is contained in smaller band
 - Signal bandwidth < occupied bandwidth
- ❑ Excess bandwidth = Occupied – Signal bandwidth
 - Allows a transition region
 - Filters cannot roll off infinitely fast
- ❑ 802.11ad example:
 - Sample rate typically 1.76 Gsamp/s
- ❑ Lower frequencies, excess bandwidth is even smaller
 - Ex. LTE 20 MHz channel
 - Signal bandwidth = 18 MHz
 - Excess bandwidth $\approx 10\%$

Spectral mask for 802.11ad



Outline

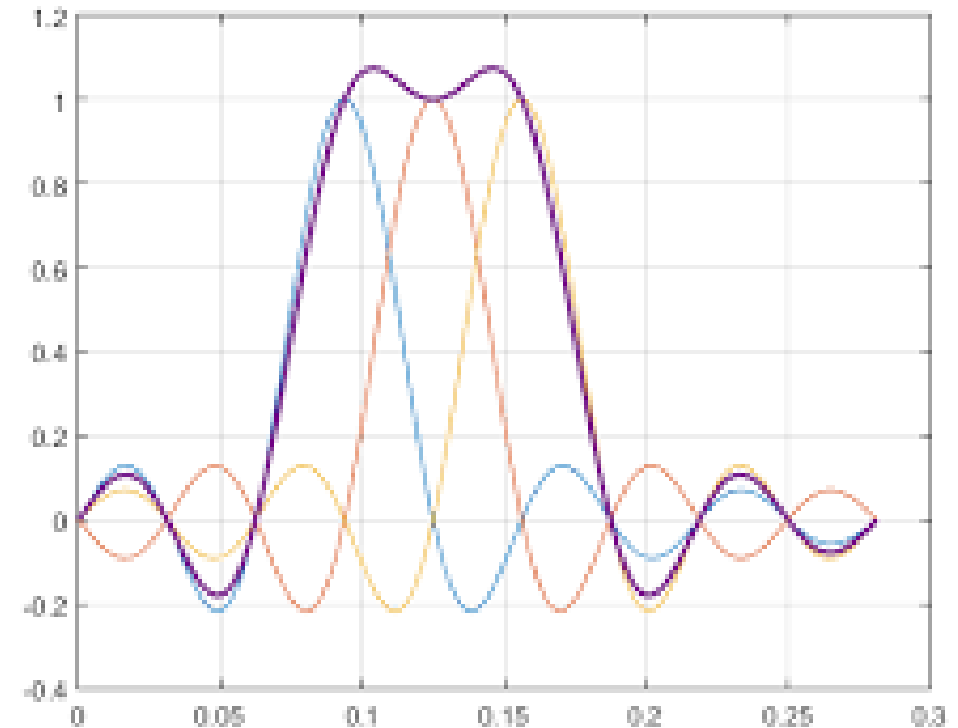
- ☐ Symbol mapping
- ☐ DAC and pulse shaping
- ☐ Fourier analysis and bandwidth of TX filtering
- ☐ Power spectral density analysis
-  ☐ Sinc pulse and Ideal low pass filtering
- ☐ Digitally implementing pulse shaping

Design Goals

- ❑ Want to design pulse with two goals
- ❑ Goal 1. Bandwidth limits:
 - Most systems (esp. RF) impose bandwidth limits on transmissions.
 - PSD of modulated bits is $S_u(f) = \frac{1}{T} E_s |P(f)|^2$
 - Want $|P(f)|^2 \approx 0$ for $|f| \geq W$ where W is (single-sided) bandwidth limit
- ❑ Goal 2: Recover symbols $s[n]$ from $u(t)$
 - Sufficient condition: Use zero ISI pulse
 - Then recover with correct sampling
- ❑ Can we find a pulse shape satisfying both goals?

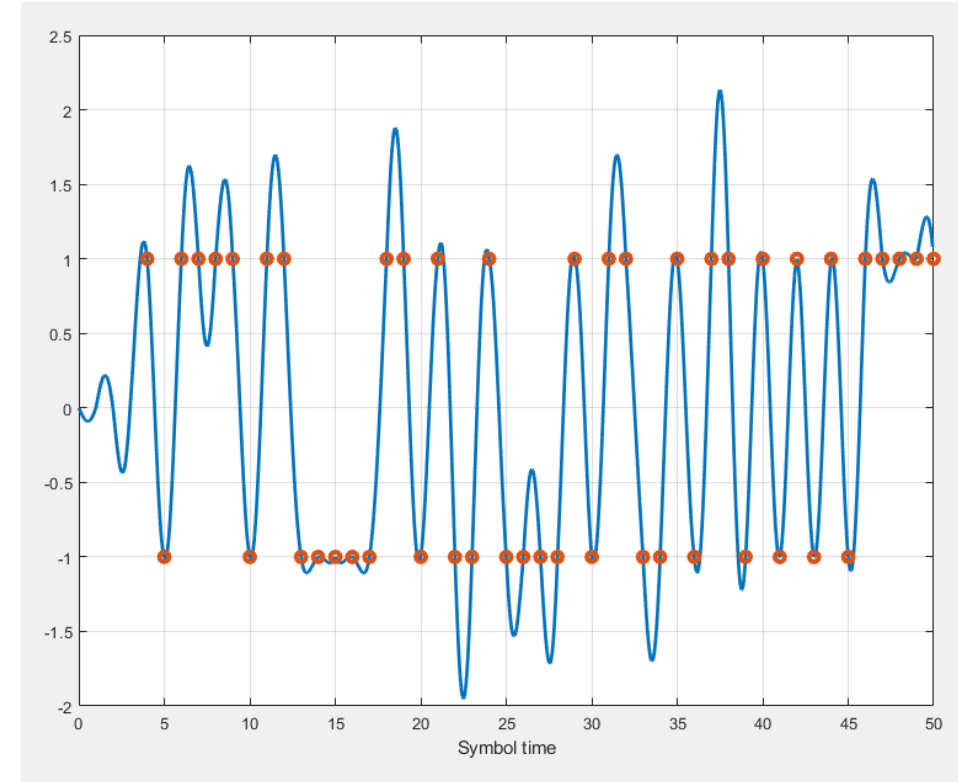
Sinc Pulse

- Use sinc pulse $p(t) = \text{sinc}(t/T)$
- Satisfies zero ISI condition:
 - $p(nT) = 0$ for $n \neq 0$
- Pulse shape frequency response:
$$P(f) = T \text{Rect}(fT)$$
 - $P(f) = 0$ for $|f| > 1/2T$
- Two-sided bandwidth is $= 1/T$
- Conclusion: sinc pulse satisfies two goals
 - If BW limit $> 1/T$



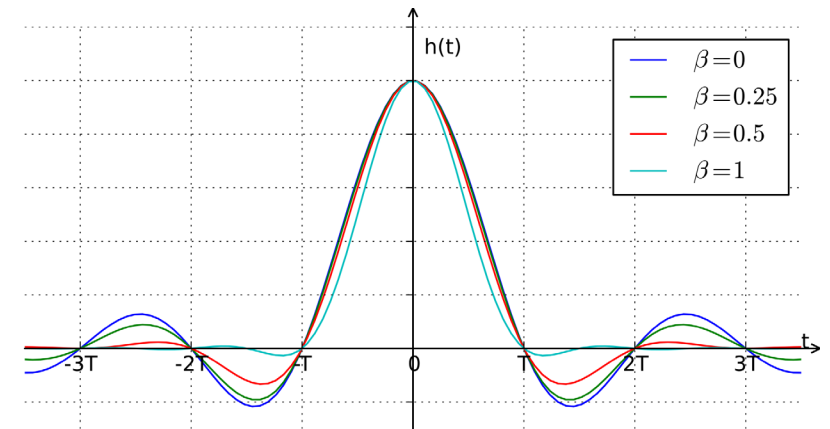
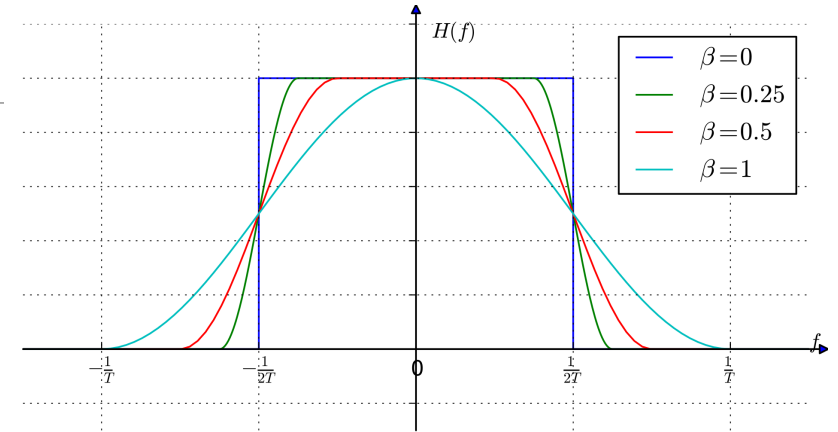
Sinc Pulse Shaping Illustrated

- ❑ BPSK symbols
- ❑ Sinc pulse interpolates the symbols exactly
- ❑ No out of band emissions
- ❑ But:
 - Waveform varies rapidly between samples
 - Synchronization offsets will cause errors
 - High peak-to-average ratio
 - Needs an infinite length to implement



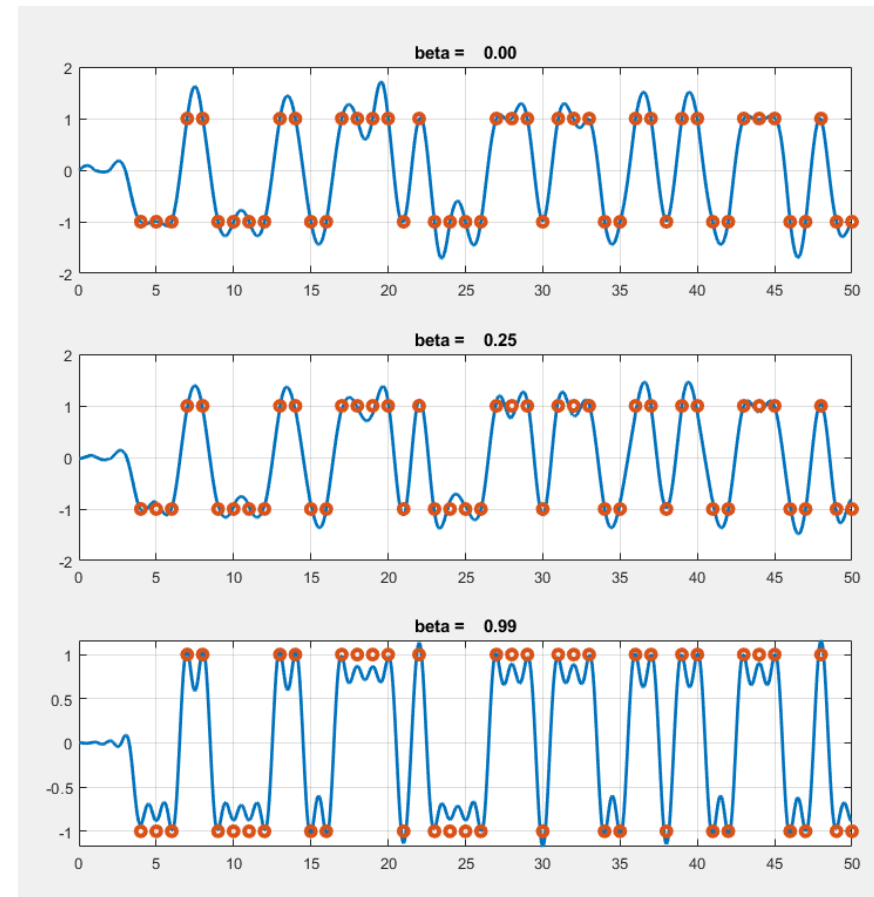
Cosine Filtering

- Set of filters parametrized by β
 - $\beta \in [0,1]$ is called the rolloff
- Excess bandwidth percentage β
- $\beta = 0 \Rightarrow$ Ideal sinc filter
 - No excess bandwidth.
- $\beta > 0$
 - Creates excess bandwidth
 - But, allows shorter filter

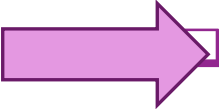


Cosine Filtering Illustrated

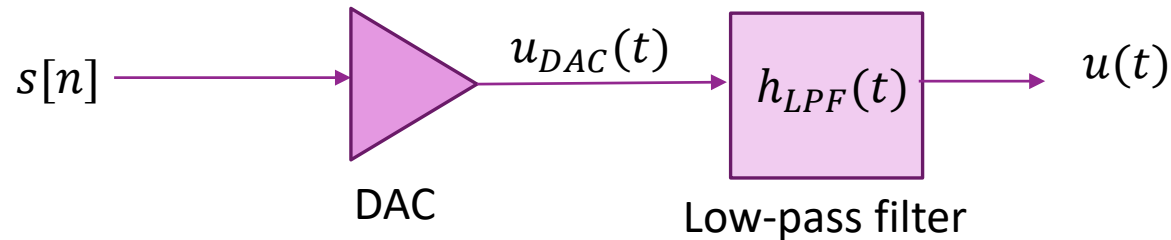
- Plotted to the right:
 - BPSK symbols filtered with raised cosine filters
- Higher values of β
 - Symbol transitions are faster
 - More out-of-band emissions
 - But, less peak-to-average
 - Less variations between symbols



Outline

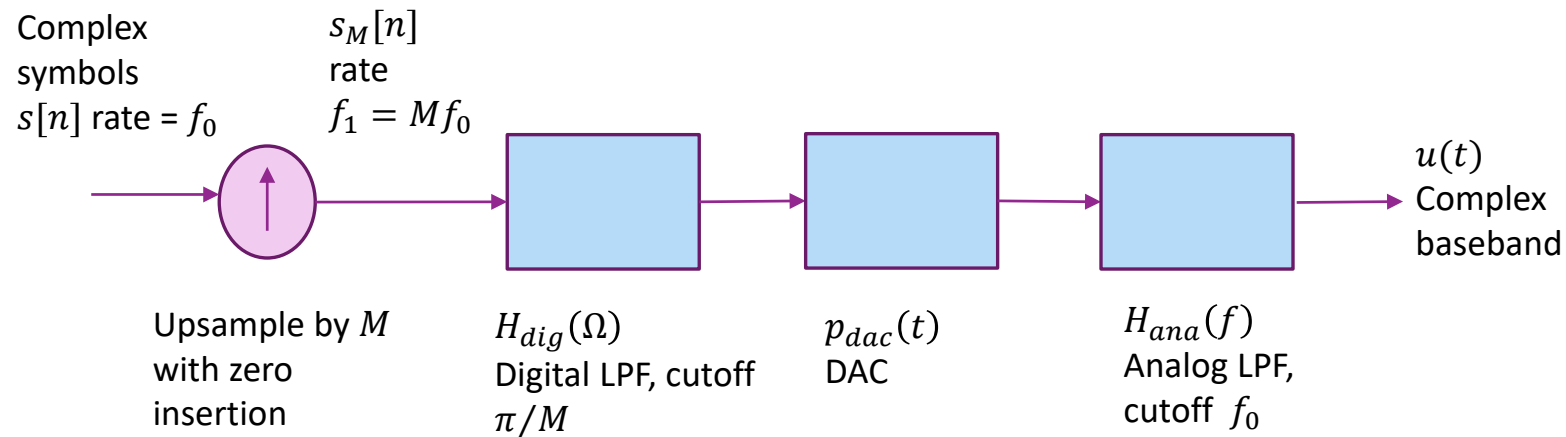
- ☐ Symbol mapping
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- ☐ Sinc pulse and Ideal low pass filtering
-  ☐ Digitally implementing pulse shaping

Problems with Analog LPF solution



- ❑ Up to now, we have assumed simple two stage linear modulation
 - DAC followed by LPF
- ❑ **Challenges:** LPF must be implemented in analog.
 - Want LPF filter to approximate ideal Rectangular response
 - Difficult to implement in analog
 - Analog filters typically have limited roll-off

Practical Pulse Shaping Block Diagram



□ Practical pulse shaping:

- Combination of analog and digital filtering

Practical Pulse Shaping

- ❑ Start with symbols $s[n]$ at f_0
- ❑ Upsample by M with zero insertion
 - $s_M[k] = \begin{cases} s[n] & k = Mn \\ 0 & k \neq Mn \end{cases}$
- ❑ Digitally filter with $H_{dig}(\Omega)$
- ❑ Pulse shape with DAC $p_{dac}(t)$
- ❑ Analog filter $H_{ana}(f)$

Frequency Domain Analysis 1

□ $S(\Omega)$ = DTFT of $s[n]$ at symbol rate f_0

□ Step 1: Upsample with zero insertion:

$$s_M[k] = \begin{cases} s[n] & k = Mn \\ 0 & k \neq Mn \end{cases} \quad S_M(\Omega) = S(M\Omega)$$

- Upsampled signal has symbol rate $f_{s1} = Mf_{s0}$

□ Step 2: Digital filter with DTFT $H_{dig}(\Omega)$

$$x[k] = h_{dig}[k] * s_M[k] \Rightarrow X(\Omega) = H_{dig}(\Omega)S_M(\Omega)$$

- Design filter to have cutoff at $\Omega = \pi/M$
- Theoretically, can use infinite sinc
- But, in practice use long FIR filter

Frequency Domain Interpretation 2

□ Step 3: DAC and analog filtering

- Create an impulse train

$$x_{\delta}(t) = \sum_k x[k] \delta(t - n T/M) \Rightarrow X_{\delta}(f) = X\left(\frac{2\pi f T}{M}\right)$$

- Repeated images once every $M/T = f_1 = Mf_0$
- Then,

$$U(f) = X_{\delta}(f) P_{dac}(f) H_{ana}(f)$$

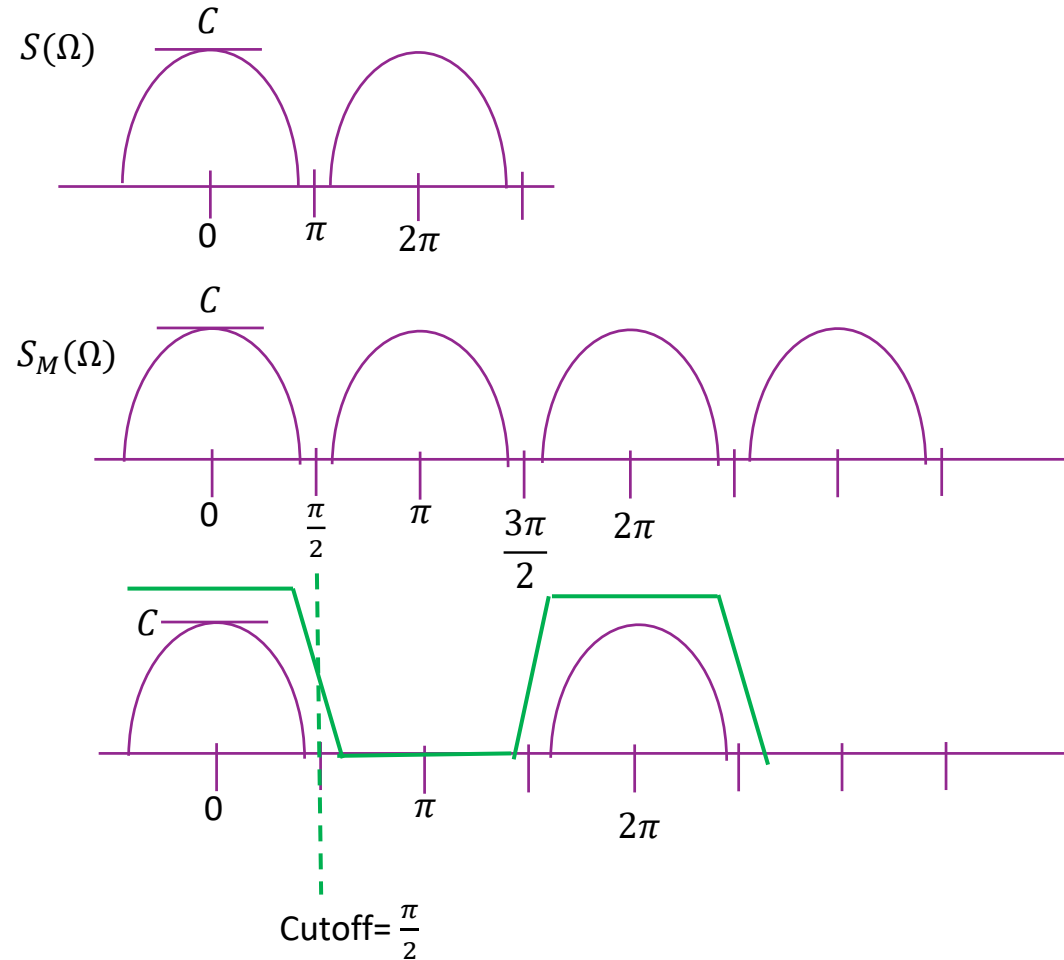
- Cut-off frequency of $H_{ana}(f)$ at f_0
- Removes images $f_1, 2f_1, \dots$

Images 1

Complex symbols

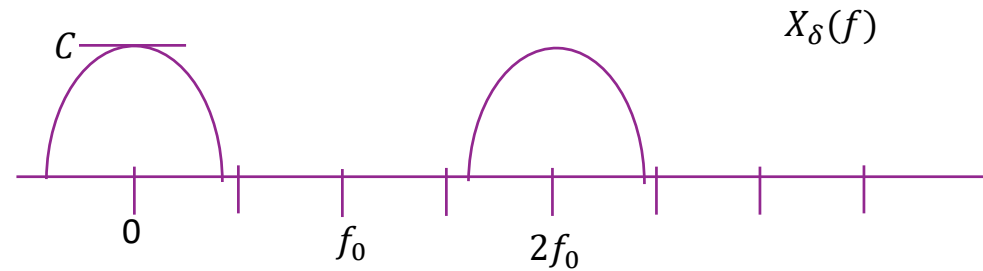
Upsampling w/
zero insertion
($M = 2$ shown)

Digital filtering

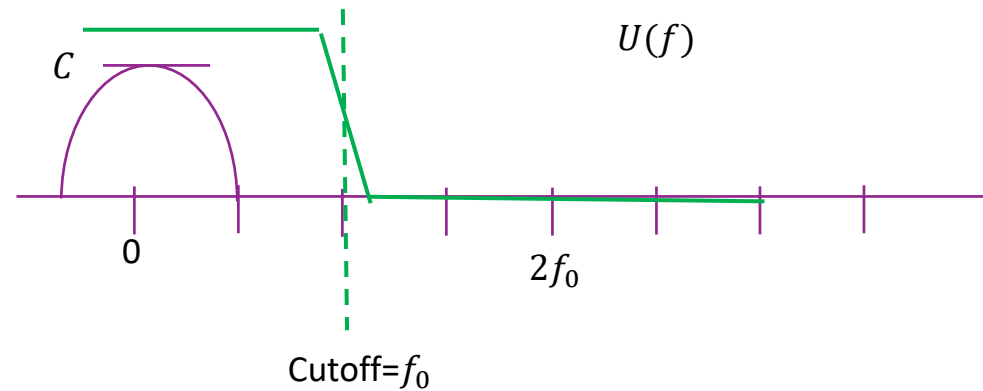


Images 2

□ Pulse train



□ DAC and analog filtering



Power Spectral Density

- Suppose symbols $s[n]$ are i.i.d. with
$$E(s[n]) = 0, \quad E|s[n]|^2 = E_s$$

- Can show PSD of $u(t)$ is:

$$S_u(f) = \frac{E_s}{MT_0} |P(f)|^2$$

- Effective pulse shape: $P(f) = H_{dig}\left(\frac{2\pi f}{Mf_0}\right) P_{dac}(f) H_{ana}(f)$

Effective Pulse Shape

- Can show that the resulting signal is

$$u(t) = \sum s[n]p(t - nT)$$

- Effective pulse shape is:

$$p(t) = \sum_k h_{dig}[k]g\left(t - \frac{k}{M}T\right)$$

- $g(t) = h_{ana}(t) * p_{dac}(t)$