


CTowerControl::Loop



```
graph LR; A[CTowerControl::Loop] --> B[CGearMotor::stop]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'CTowerControl::Loop'. The right box is white and contains the text 'CGearMotor::stop'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

CGearMotor::stop