# Equivalence of Gradient BDT and Adaptive BDT

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#### Introduction

- Here is the comparison between Adaptive and Gradient BDT methods.
- These slides are to show the equivalence between AdaBDT and GradBDT methods.

Quantity	AdaBDT value	GradBDT value
input variables	$\vec{x} = (x_1, x_2, \cdots)$	same
true value $Y$	-1, 1	same
guess value $k_m$	-1, 1	none
guess weight $\alpha_{\it m}/{\it w_{\it m}}$	$\alpha_m = \frac{1}{2} \ln \frac{1 - \epsilon_m}{\epsilon_m}$	negative gradient, $w_m = -\frac{\partial L_m}{\partial y_{m-1}}$
tree update	apply a weight of $e^{\alpha_m}$ to wrong guess	fit the residues
final BDT score $y_m$	$y_m = y_{m-1} + \alpha_m k_m$	$y_m = y_{m-1} + w_m$
loss function	$L_m(\vec{x}, y_m) = \sum_{\vec{x}} e^{-Y(\vec{x})y_m(\vec{x})}$	any form

- Here  $\epsilon_m$  is the miscalssification rate for the m-th tree.
- $w_m$  is the weight at the m-th tree. It is roughly negative of the derivative of the loss function evaluated at  $y_{m-1}$ .
- For GradBDT, the loss function could be in any form. For example,  $L_m(\vec{x}, y_m) = \sum_{\vec{x}} \frac{1}{2} (y_m(\vec{x}) Y(\vec{x}))^2$ .

#### Review of Gradient BDT

Suppose we have m trees, the BDT score is

$$y_m(\vec{x}_i) = y_{m-1}(\vec{x}_i) + w_m(\vec{x}_i)$$
 (1)

Taking  $w_m(\vec{x_i})$  as a small quantity and expanding the *m*-th loss fuction around  $y_{m-1}(\vec{x_i})$ , we have

$$L_{m} \equiv \sum_{\vec{x}_{i}} I(y_{m}(\vec{x}_{i})) = \sum_{\vec{x}_{i}} I(y_{m-1}(\vec{x}_{i}) + w_{m}(\vec{x}_{i}))$$
 (2)

$$\approx \sum_{\vec{x}_i} l(y_{m-1}(\vec{x}_i)) + d_{m-1}(\vec{x}_i) w_m(\vec{x}_i) + \frac{1}{2} h_{m-1}(\vec{x}_i) w_m^2(\vec{x}_i)$$
(3)

with

$$d_{m-1} \equiv \frac{\partial l(y)}{\partial y}|_{y=y_{m-1}}, \quad h_{m-1} \equiv \frac{\partial^2 l(y)}{\partial y^2}|_{y=y_{m-1}}.$$
 (5)

In practice, each tree will only have limited number of terminal nodes (denoted by J). The events falling into the same terminal node (denoted by  $R_j$ ,  $j=1,2,\cdots,J$ ) will be given the same weight,  $w_m(R_j)$ . The loss function at the m-th three then becomes

$$L_{m} \approx \sum_{\vec{x}_{i}} l(y_{m-1}(\vec{x}_{i})) + d_{m-1}(\vec{x}_{i}) w_{m}(\vec{x}_{i}) + \frac{1}{2} h_{m-1}(\vec{x}_{i}) w_{m}^{2}(\vec{x}_{i})$$
 (6)

$$= L_{m-1} + \sum_{j=1}^{J} \left( \sum_{\vec{x}_{i} \in R_{j}} d_{m-1}(\vec{x}_{i}) \right) w_{m}(R_{j}) + \left( \sum_{\vec{x}_{i} \in R_{j}} h_{m-1}(\vec{x}_{i}) \right) w_{m}^{2}(R_{j})$$
 (7)

(4)

#### Review of Gradient BDT

$$L_{m} \approx L_{m-1} + \sum_{j=1}^{J} \left( \sum_{\vec{x}_{i} \in R_{j}} d_{m-1}(\vec{x}_{i}) \right) w_{m}(R_{j}) + \frac{1}{2} \left( \sum_{\vec{x}_{i} \in R_{j}} h_{m-1}(\vec{x}_{i}) \right) w_{m}^{2}(R_{j})$$
(8)

Minimizing the loss function gives

$$w_m(R_j) = -\frac{\sum_{\vec{x}_i \in R_j} d_{m-1}(\vec{x}_i)}{\sum_{\vec{x}_j \in R_j} h_{m-1}(\vec{x}_i)}.$$
 (9)

and the reduction of the loss function at this point is

$$\Delta L_m \equiv L_m - L_{m-1} = -\frac{1}{2} \sum_{j=1}^{J} \frac{\left(\sum_{\vec{x}_i \in R_j} d_{m-1}(\vec{x}_i)\right)^2}{\sum_{\vec{x}_j \in R_j} h_{m-1}(\vec{x}_i)} . \tag{10}$$

This is used to determine the splitting in building a tree, i.e., to maximize (Let  $R = R_l + R_r$  denote a node and its daughter nodes, left node  $R_l$  and right node  $R_r$ .)

$$\frac{1}{2} \frac{\left(\sum_{\vec{x}_{i} \in R_{i}} g(\vec{x}_{i})\right)^{2}}{\sum_{\vec{x}_{i} \in R_{i}} h(\vec{x}_{i})} + \frac{1}{2} \frac{\left(\sum_{\vec{x}_{i} \in R_{r}} g(\vec{x}_{i})\right)^{2}}{\sum_{\vec{x}_{i} \in R_{r}} h(\vec{x}_{i})} - \frac{1}{2} \frac{\left(\sum_{\vec{x}_{i} \in R} g(\vec{x}_{i})\right)^{2}}{\sum_{\vec{x}_{i} \in R} h(\vec{x}_{i})}$$
(11)

Let  $g_m(y_m)$  be the probability distribution function of the BDT score after m trees.

$$\int_{y}^{y+\delta} g_{m}(y_{m})dy_{m} = \int_{y < y_{m}(\vec{x}) < y+\delta} f(\vec{x})d\vec{x}$$
 (12)

This is difficult as  $y(\vec{x})$  is unknown. We use the iteration relation from (m-1)-th tree to the m-th tree

$$y_m(\vec{x}_i) = y_{m-1}(\vec{x}_i) + \sum_{j=1}^{J} \delta_{\vec{x}_j, R_j} w_m(R_j)$$
 (13)

Here  $\delta_{\vec{x}_i^i, R_j}$  is 1 if  $\vec{x}_i$  falls into the node  $R_j$  and 0 othrwise. Note that all terminal nodes  $R_j$  do not overlap.

$$w_m(R_j) = -\frac{\sum_{\vec{x}_i \in R_j} d_{m-1}(\vec{x}_i)}{\sum_{\vec{x}_i \in R_i} h_{m-1}(\vec{x}_i)}.$$
 (14)

For simplification, let us use the loss function  $I(y(\vec{x_i})) = \frac{1}{2}(y(\vec{x_i}) - Y(\vec{x_i}))^2$  where Y is the true value ( 1 for signal events and -1 for background events). Then (let  $N_{R_j}$  denote number of events in  $R_i$ )

$$d_{m-1}(\vec{x}_i) = y_{m-1}(\vec{x}_i) - Y(\vec{x}_i) , \quad h_{m-1}(\vec{x}_i) = 1, \quad w_m(R_j) = -\frac{1}{N_{R_j}} \sum_{\vec{x}_i \in R_i} y_{m-1}(\vec{x}_i) - Y(\vec{x}_i) . \quad (15)$$

$$y_{m}(\vec{x}_{i}) = y_{m-1}(\vec{x}_{i}) - \sum_{j=1}^{J} \delta_{\vec{x}_{j}, R_{j}} \frac{1}{N_{R_{j}}} \left( \sum_{\vec{x}_{i} \in R_{j}} y_{m-1}(\vec{x}_{i}) - Y(\vec{x}_{i}) \right)$$
(16)

Let  $p_{m,R_j}$  denote the signal fraction in the node  $R_j$  (the background fraction is  $1-p_{m,R_j}$ . Let  $f_{m,R_j}$  denote the fraction of total number of events in the node  $R_j$ . Let  $S\cap R_j$  and  $B\cap R_j$  denote the set of signal and background events in the node  $R_j$ . Then we have  $p_{m,R_j}=N_{S\cap R_j}/N_{R_j}$ ,  $\sum_j f_{m,R_j}=1$ ,  $\sum_j f_{m,R_j}p_{m,R_j}=\frac{1}{2}$  and  $\sum_j f_{m,R_j}(1-p_{m,R_j})=\frac{1}{2}$  (this is because we have renormalized all events to 1 for signal and background by definition).

$$-w_{m}(\vec{x}_{i}) = \sum_{j=1}^{J} \delta_{\vec{x}_{j}, R_{j}} \frac{1}{N_{R_{j}}} \left( \sum_{\vec{x}_{i} \in R_{j}} y_{m-1}(\vec{x}_{i}) - Y(\vec{x}_{i}) \right)$$

$$= \sum_{j=1}^{J} \delta_{\vec{x}_{i}, R_{j}} \frac{1}{N_{R_{j}}} \left( N_{S \cap R_{j}} \frac{\sum_{\vec{x}_{i} \in S \cap R_{j}} y_{m-1}(\vec{x}_{i}) - 1}{N_{S \cap R_{j}}} + N_{B \cap R_{j}} \frac{\sum_{\vec{x}_{i} \in B \cap R_{j}} y_{m-1}(\vec{x}_{i}) + 1}{N_{B \cap R_{j}}} \right)$$

$$= \sum_{i=1}^{J} \delta_{\vec{x}_{i}, R_{j}} \left[ p_{m, R_{j}}(z_{m-1, R_{j}}^{S} - 1) + (1 - p_{m, R_{j}})(z_{m-1, R_{j}}^{B} + 1) \right] ,$$

$$(17)$$

where

$$z_{m-1,R_{j}}^{S} \equiv \frac{\sum_{\vec{x}_{i} \in S \cap R_{j}} y_{m-1}(\vec{x}_{i})}{N_{S \cap R_{j}}}, \quad z_{m-1,R_{j}}^{B} \equiv \frac{\sum_{\vec{x}_{i} \in B \cap R_{j}} y_{m-1}(\vec{x}_{i})}{N_{B \cap R_{j}}}. \tag{20}$$

$$z_{m-1,R_j}^{S} \equiv \frac{\sum_{\vec{x}_i \in S \cap R_j} y_{m-1}(\vec{x}_i)}{N_{S \cap R_i}}, \quad z_{m-1,R_j}^{B} \equiv \frac{\sum_{\vec{x}_i \in B \cap R_j} y_{m-1}(\vec{x}_i)}{N_{B \cap R_i}}.$$
 (21)

Let  $\mu_{m-1}$  and  $\sigma_{m-1}$  denote the expectation value and variance of the distribution of  $y_{m-1}$ . They are different between signal and background generally. We assume they exist and also the Central Limit Theorem (CLT) applies here.  $z_{m-1,R_i}$  will abide by a Gaussian distribution (let

$$G(x|\mu,\sigma) \equiv \frac{1}{\sqrt{2\pi}\sigma}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$
).

$$z_{m-1,R_j}^S \sim G(\mu_{m-1}^S, \frac{\sigma_{m-1}^S}{\sqrt{N_{S \cap R_j}}}), \quad z_{m-1,R_j}^B \sim G(\mu_{m-1}^B, \frac{\sigma_{m-1}^B}{\sqrt{N_{B \cap R_j}}})$$
 (22)

In the limit of large sample size,  $\mathbf{z}_{m-1,R_i}^{S/B}$  would be very peaky around the mean value  $\mu_{m-1}^{S/B}$ .

$$w_m(\vec{x}_i) \approx -\sum_{j=1}^J \delta_{\vec{x}_j, R_j} \left[ p_{m, R_j} (\mu_{m-1}^S - 1) + (1 - p_{m, R_j}) (\mu_{m-1}^B + 1) \right]$$
 (23)

Let us consider the possible values for  $w_m(\vec{x_i})$  and the corresponding probilities. The probability of a signal event falling to the node  $R_j$  should be proportional to the fraction of signal events in  $R_j$ . This is  $f_{m,R_j}p_{m,R_j}/\sum_{j=1}^J f_{m,R_j}p_{m,R_j}=2f_{m,R_j}p_{m,R_j}$  (similar argument applies to background).

Let us only consider two ndoes, namely, J=2 (it will be shown to be equivalent to the Adaptive BDT).  $w_m(\vec{x_i})$  takes only two possible values. We have

$$-w_{m}(\vec{x}_{i})$$

$$\approx \delta_{\vec{x}_{i},R_{1}} \left[ p_{m,R_{1}}(\mu_{m-1}^{S} - 1) + (1 - p_{m,R_{1}})(\mu_{m-1}^{B} + 1) \right]$$

$$+\delta_{\vec{x}_{i},R_{2}} \left[ p_{m,R_{2}}(\mu_{m-1}^{S} - 1) + (1 - p_{m,R_{2}})(\mu_{m-1}^{B} + 1) \right]$$

$$= \delta_{\vec{x}_{i},R_{1}} \left[ p_{m,R_{1}}(\mu_{m-1}^{S} - 1) + (1 - p_{m,R_{1}})(\mu_{m-1}^{B} + 1) \right]$$
(26)

$$+\delta_{\vec{x}_{i}^{\prime},R_{2}}\left[\frac{1-2f_{m,R_{1}}p_{m,R_{1}}}{2(1-f_{m,R_{1}})}(\mu_{m-1}^{S}-1)+\frac{1-2f_{m,R_{1}}+2f_{m,R_{1}}p_{m,R_{1}}}{2(1-f_{m,R_{1}})}(\mu_{m-1}^{B}+1)\right](27)$$

and the probability for a signal event falling in  $\mathcal{R}_j$ 

$$Prob(\vec{x}_i \in R_1) = 2f_{m,R_1} p_{m,R_1}$$
(28)

$$Prob(\vec{x}_i \in R_2) = 1 - 2f_{m,R_1}p_{m,R_1}. \tag{29}$$

For convenience in the case of J=2, we can drop the subscripts, namely, letting  $f\equiv f_{m,R_1}$  and  $p\equiv p_{m,R_1}$ .

$$-w_{m}(\vec{x}_{i}) \approx \delta_{\vec{x}_{i},R_{1}} \left[ \rho(\mu^{S} - 1) + (1 - \rho)(\mu^{B} + 1) \right]$$

$$+\delta_{\vec{x}_{i},R_{2}} \left[ \frac{1 - 2fp}{2(1 - f)} (\mu^{S} - 1) + \frac{1 - 2f + 2fp}{2(1 - f)} (\mu^{B} + 1) \right]$$
(31)

$$-w_m(\vec{x_i}) \approx \delta_{\vec{x_i}, R_1} \left[ p(\mu^S - 1) + (1 - p)(\mu^B + 1) \right]$$
 (32)

$$+\delta_{\vec{x}_{f},R_{2}}\left[\frac{1-2fp}{2(1-f)}(\mu^{S}-1)+\frac{1-2f+2fp}{2(1-f)}(\mu^{B}+1)\right]$$
(33)

$$\approx \delta_{\vec{x}_{j},R_{1}} \left[ p(\mu^{S} - 1) + (1 - p)(-\mu^{S} + 1) \right]$$
 (34)

$$+\delta_{\vec{x}_{j},R_{2}}\left[\frac{1-2fp}{2(1-f)}(\mu^{S}-1)+\frac{1-2f+2fp}{2(1-f)}(-\mu^{S}+1)\right]$$
(35)

$$\approx \delta_{\vec{x}_j, R_1}(2p-1)(\mu^{S}-1) + \delta_{\vec{x}_j, R_2}\frac{-f}{1-f}(2p-1)(\mu^{S}-1)$$
 (36)

Here we used  $\mu^S = -\mu^B$ , which is expected as signal and background play an equal role. Keeping in mind that in Gradient BDT, the split into two nodes (this affects f and p) is determined by maximizing the reduction of the loss function, this is to maximize (from Eq.(11))

$$\frac{1}{2}fw_m(R_1)^2 + \frac{1}{2}(1-f)w_m(R_2)^2$$
 (37)

$$\approx \frac{1}{2}f(2p-1)^2(\mu^{S}-1)^2 + \frac{1}{2}(1-f)(\frac{-f}{1-f})^2(2p-1)^2(\mu^{S}-1)^2$$
 (38)

$$= \frac{1}{2} \frac{f}{1-f} (2p-1)^2 (\mu^S - 1)^2 \tag{39}$$

Noting that the split affects both f and p, we can take p as a function of f and  $p(1)=\frac{1}{2}$  (if a node has all the events, then the signal fraction in that node is  $\frac{1}{2}$  due to the initial renormalization). We assume all trees are weak learners. Under this assumption, we expect that p should be around  $\frac{1}{2}$  and has little dependence upon f actually. Expanding

$$p(f) \approx p(1) + \frac{dp}{df}(f-1) = \frac{1}{2} + \frac{dp}{df}(f-1)$$
, we have

$$\frac{1}{2}fw_m(R_1)^2 + \frac{1}{2}(1-f)w_m(R_2)^2 \tag{40}$$

$$\approx \frac{1}{2} \frac{f}{1-f} (2p(f)-1)^2 (\mu^{S}-1)^2$$
 (41)

$$\approx \frac{1}{2} \left(\frac{dp}{df}\right)^2 f(1-f)(\mu^S-1)^2. \tag{42}$$

We now see that the maximization gives  $f=\frac{1}{2}$ , which value is also consistent with our intuitive understanding. Ok, let us summarize all keys below (recovering the subscripts). For signal, we have

$$y_m(\vec{x}_i) = y_{m-1}(\vec{x}_i) + w_m(\vec{x}_i)$$
(43)

$$w_{m}(\vec{x}_{i}) = \begin{cases} -(2p_{m,R_{1}} - 1)(\mu_{m-1}^{S} - 1) & \text{Prob}(\vec{x}_{i} \in R_{1}) = p_{m,R_{1}} \\ (2p_{m,R_{1}} - 1)(\mu_{m-1}^{S} - 1) & \text{Prob}(\vec{x}_{i} \in R_{1}) = 1 - p_{m,R_{1}} \end{cases}$$
(44)

For signal, we have

$$y_m(\vec{x}_i) = y_{m-1}(\vec{x}_i) + w_m(\vec{x}_i)$$
 (45)

$$w_m(\vec{x}_i) = \begin{cases} -(2p_{m,R_1} - 1)(\mu_{m-1}^S - 1) & \operatorname{Prob}(\vec{x}_i \in R_1) = p_{m,R_1} \\ +(2p_{m,R_1} - 1)(\mu_{m-1}^S - 1) & \operatorname{Prob}(\vec{x}_i \in R_1) = 1 - p_{m,R_1} \end{cases}$$
(46)

Similarly, for background, we have

$$y_m(\vec{x}_i) = y_{m-1}(\vec{x}_i) + w_m(\vec{x}_i) \tag{47}$$

$$w_{m}(\vec{x_{i}}) = \begin{cases} -(2p_{m,R_{1}} - 1)(\mu_{m-1}^{B} + 1) & \operatorname{Prob}(\vec{x_{i}} \in R_{1}) = 1 - p_{m,R_{1}} \\ +(2p_{m,R_{1}} - 1)(\mu_{m-1}^{B} + 1) & \operatorname{Prob}(\vec{x_{i}} \in R_{1}) = p_{m,R_{1}} \end{cases}$$
(48)

Let us consider only the signal BDT score distribution,  $g_m(y_m)$ , for the moment. Taking  $y_{m-1}$  and  $w_m$  as random variales and assuming they are independent, we have

$$\int_{y}^{y+\delta} g_{m}(y_{m})dy_{m} = \int_{y < y_{m} < y+\delta} g_{m-1}(y_{m-1})f(w_{m})dy_{m-1}dw_{m}$$
 (49)

$$= \int_{y}^{y+\delta} \left[ g_{m-1}(y_m - w_m(R_1)) p_{m,R_1} + g_{m-1}(y_m - w_m(R_2)) (1 - p_{m,R_1}) \right]$$
 (50)

From the equation above, we derive that

$$g_m(y) = g_{m-1}(y + (2p_{m,R_1} - 1)(\mu_{m-1}^{\varsigma} - 1))p_{m,R_1} + g_{m-1}(y - (2p_{m,R_1} - 1)(\mu_{m-1}^{\varsigma} - 1))(1 - p_{m,R_1}).$$

$$g_{m}(y) = g_{m-1}(y + (2p_{m,R_{1}} - 1)(\mu_{m-1}^{S} - 1))p_{m,R_{1}} + g_{m-1}(y - (2p_{m,R_{1}} - 1)(\mu_{m-1}^{S} - 1))(1 - p_{m,R_{1}}).$$
(52)

This is actually equivalent to the iteration formula below in the Adaptive BDT method.

$$g_m(y) = g_{m-1}(y - \alpha_m)(1 - \epsilon_m) + g_{m-1}(y + \alpha_m)\epsilon_m$$
 (53)

The corresponding relation is

$$p_{m,R_1} = \epsilon_m \,, \tag{54}$$

$$(2p_{m,R_1} - 1)(\mu_{m-1}^S - 1) = \alpha_m. (55)$$

This shows the equivalence between the Adaptive BDT and the Gradient BDT. It is not difficult to derive the PDF for the GBDT score,  $g_m(y)$ . Let us investigate the mean value in the first place (because it has different behavior compared to AdaBDT).

$$\mu_m = \int_{-\infty}^{+\infty} y g_m(y) dy \tag{56}$$

Using the iteration formula, it is easy to find that

$$\mu_m^{S} = \mu_{m-1}^{S} - (2p_{m,R_1} - 1)^2 (\mu_{m-1}^{S} - 1)$$
(57)

$$\mu_m^S = \mu_{m-1}^S - (2p_{m,R_1} - 1)^2 (\mu_{m-1}^S - 1)$$
 (58)

$$\mu_m^S - 1 = \mu_{m-1}^S - 1 - (2p_{m,R_1} - 1)^2(\mu_{m-1}^S - 1)$$
 (59)

$$\mu_m^S - 1 = [1 - (2p_{m,R_1} - 1)^2](\mu_{m-1}^S - 1)$$
 (60)

$$\mu_m^S - 1 = 4p_{m,R_1}(1 - p_{m,R_1})(\mu_{m-1}^S - 1)$$
 (61)

$$= \Pi_{i=1}^{m} 4 p_{i,R_1} (1 - p_{i,R_1}) (\mu_0^{S} - 1)$$
 (62)

(63)

Therefore, we have

$$\mu_m^S = 1 + \prod_{i=1}^m 4p_{i,R_1}(1-p_{i,R_1})(\mu_0^S - 1).$$
 (64)

Noting that  $4p_{i,R_1}(1-p_{i,R_1}) \le 1$  (the equal sign holds only if  $p_{i,R_1}=\frac{1}{2}$ . If it happens, the training will stop because the loss function cannot be reduced further.), we thus have

$$\lim_{m \to +\infty} \mu_m^{\mathcal{S}} = 1 \,, \tag{65}$$

which is independent upon the choice of the intial value. Similarly, we can show that  $\lim_{m\to+\infty}\mu_m^B=-1$  .

$$(\sigma_m^S)^2 = \int_{-\infty}^{+\infty} (y - \mu_m^S) g_m(y) dy$$
 (66)

We can obtain

$$(\sigma_m^S)^2 = (\sigma_{m-1}^S)^2 + 4(p_{m,R_1} - 1)^2 \alpha_m^2$$
 (67)

$$= \sum_{i=1}^{m} 4(p_{i,R_1} - 1)^2 \alpha_i^2$$
 (68)

$$\approx \sum_{i=1}^{m} \alpha_i^2 . ag{69}$$

# BACK UP

BACK UP